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Modifying a biologically inspired retina simulator to reconstruct realistic responses to moving stimuli

Selma Souihel, Bruno Cessac selma.souihel@inria.fr, bruno.cessac@inria.fr

Abstract

The visual system constantly uses anticipation in everyday life, to compensate for the 30 to 150ms delay that exists between the perception of a visual stimulus and the neural responses it elicits. Without this anticipation, a tennisman, for instance, would be unable to hit a moving ball. Neurobiologists first believed that the anticipation only happens in the visual cortex, but recent studies have shown that it starts earlier, in the retina. To better understand the state of the art and possibly propose new experiments, we are working on a retina simulator reproducing anticipation. Ultimately, we would like to use our reconstructed retina spike trains as inputs to a primary visual cortex simulator, and understand all the mechanisms lying behind anticipation. This work is done within the ANR project : Trajectory.

Threshold Adaptation

Generating impulses at the level of ganglion cells relies on the leaky integrate and fire model discretisation. Its general equation is given by :

$$V(t+1) = \gamma V(t) + J_L dt + J(t) dt$$

with
$$\gamma = 1 - \frac{dt}{\tau_L}$$

For I(n) = I constant, the threshold below which the potential equation holds is the following :

Anticipating a car trajectory

We used a reconstruction algorithm to rebuild the stimulus from the obtained spike trains. The results show the original stimulus in pink and the activity it elicites in blue.

Without anticipation



Retina Simulator [3]

Virtual Retina is a software able to convert a visual scene into spike trains similar to those transmitted by the retina to the brain. It uses a three-processing-stage model mimicking photoreceptors, bipolar cells and ganglion cells.



$$\theta = V_L + (1 - \gamma^{t+1}) \frac{I}{g_L}$$

Adaptation of the threshold is then given by :

$$\theta = V_L + (1 - \gamma^{\frac{1000}{R_G(t)} + 1}) \frac{I}{q_L}$$



Moving bar results

Our implementation of the model recovers the anticipatory effect occuring in the case of smooth motion, as the shifted pic of response appears before the bar reaches the center of the receptive field. The alert response has also been reproduced, with an amplitude higher than smooth motion's or motion onset's. Finally, the motion onset effect appears in the fact that this type of stimulus elicites stronger response than smooth motion, shorter in time.

Conclusion & future work

- The gain control as implemented enabled us to reproduce simple motion features; anticipation, alert response and motion onset.
- The model has however an effect on the object form, as shown in the car trajectory results.
- Next step will be to improve the model in a way to denoise the reconstruction.

Gain control mechanism [2

Chen's & al. model contains two layers : bipolar and ganglion cells. Both layers implement a gain control mechanism through a feedback loop.





- More complex stimuli require the implementation of connectivity.
- Our current work aim to develop a biologically inspired model of connectivity.



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The results below show the neuronal activity in the case of smooth motion. The anticipation is reproduced though there is a strong inhibitory effect following the bar motion.



References

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