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Minkowski sums and Hadamard products of algebraic varieties

Netanel Friedenberg, Alessandro Oneto, and Robert L. Williams

Abstract We study Minkowski sums and Hadamard products of algebraic varieties. Specifically we explore when these are varieties and examine their properties in terms of those of the original varieties. This project was inspired by Problem 5 on Surfaces in [13].

1 Introduction

In algebraic geometry we have several constructions to build new algebraic varieties from given ones. Examples of classical, well-studied constructions are joins, secant varieties, rational normal scrolls, and Segre products. In these cases, it is very interesting to understand geometric properties, e.g., the dimension and the degree, of the variety constructed in terms of those of the original varieties. In this chapter we focus on the *Minkowski sum* and the *Hadamard product* of algebraic varieties. These are constructed by considering the entry-wise sum and multiplication, respectively, of points on the varieties. Due to the nature of these operations, there is a remarkable difference between the affine and the projective case.

The entry-wise sum is not well-defined over projective spaces. For this reason, we consider only Minkowski sums of affine varieties. However, in the case of affine cones, the Minkowski sum corresponds to the classical join of the corresponding

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projective varieties. Conversely, we focus on Hadamard products of projective varieties and, in particular, of varieties of matrices with fixed rank. This is because these Hadamard products parametrize interesting problems related to algebraic statistics and quantum information.

Our original motivating question was the following.

Question 1.1. Which properties do the Minkowski sum and the Hadamard product have with respect to the properties of the original varieties? In particular, what are their dimensions and degrees?

We now introduce these constructions. We work over an algebraically closed field k. We will add extra assumptions on k when needed. We use the notation $k^{\times} := k \setminus \{0\}$.

Definition 1.2. Let $X,Y \subset \mathbb{A}^n$ be affine varieties. We define the *Minkowski sum* of X and Y, denoted X+Y, as the Zariski closure of the image of $X\times Y$ under the entry-wise summation map

$$\phi_+: \mathbb{A}^n \times \mathbb{A}^n \to \mathbb{A}^n,$$

$$((a_1, \dots, a_n), (b_1, \dots, b_n)) \mapsto (a_1 + b_1, \dots, a_n + b_n)$$

Note that taking the Zariski closure of $\phi_+(X \times Y)$ is necessary to construct an algebraic variety, as explained in Example 3.1.

As far as we know there is no literature about Minkowski sums of varieties. We compute the dimension and degree of Minkowski sums of generic affine varieties.

Theorem 3.9. Let $X,Y \subset \mathbb{A}^n$ be varieties. Then, for X and Y in general position, $\dim(X+Y) = \min\{\dim(X) + \dim(Y), n\}.$

Corollary 3.12. Suppose \mathbb{k} has characteristic other than 2. Let $X,Y \subset \mathbb{A}^n$ be varieties whose projective closures $\overline{X}, \overline{Y} \subset \mathbb{P}^n$ are contained in complementary linear subspaces; equivalently, X,Y are contained in disjoint affine subspaces which are not parallel. Then for generic $\alpha \in \mathbb{k}^{\times}$, $\deg(\alpha X + Y) = \deg(X) \deg(Y)$.

A crucial observation in our computations is that the Minkowski sum of affine varieties disjoint at infinity can be described in terms of the join of their projectivizations, see Proposition 3.5 and Remark 3.6. This is a construction inspired by the combinatorial Cayley trick used to construct Minkowski sums of polytopes.

Definition 1.3. Let $X, Y \subset \mathbb{P}^n$ be projective varieties. We define the *Hadamard product* of X and Y, denoted by $X \star Y$, as the Zariski closure of the image of $X \times Y$ under the map

$$\phi_{\star}: \mathbb{P}^n \times \mathbb{P}^n \longrightarrow \mathbb{P}^n,$$

$$([a_0:\ldots:a_n],[b_0:\ldots:b_n]) \mapsto [a_0b_0:a_1b_1:\ldots:a_nb_n].$$

Let $\{x_0, ..., x_n\}$ be the homogeneous coordinates over \mathbb{P}^n . The map ϕ_* is not defined over the union of coordinate spaces $H_I \times H_{I^c}$, where $I \subset \{0, ..., n\}$, I^c is its complement, and H_I is the linear space defined by $\{x_i = 0 \mid i \in I\}$.

Thus, the Hadamard product of projective varieties $X, Y \subset \mathbb{P}^n$ is

$$X \star Y := \overline{\{p \star q : p \in X, q \in Y, p \star q \text{ is defined}\}} \subset \mathbb{P}^n$$

where $p \star q := [p_0 q_0 : \dots : p_n q_n]$ is the point obtained by entry-wise multiplication of the points $p = [p_0 : \dots : p_n]$ and $q = [q_0 : \dots : q_n]$. Also in this construction the operation of closure is crucial, as we show in Example 4.1.

In [1], the authors studied the geometry of Hadamard products, with a particular focus on the case of linear spaces. This work has been continued in [2].

In particular, we are interested in studying Hadamard products of varieties of matrices. The Hadamard product of matrices is a classical operation in matrix analysis [7]. Its most relevant property is that it is closed on positive matrices. The Hadamard product of tensors appeared more recently in quantum information [8] and in statistics [4, 11]. In the latter, the authors studied restricted Boltzmann machines which are statistical models for binary random variables where some are hidden. From a geometric point of view, this reduces to studying *Hadamard powers* of the first secant variety of Segre products of copies of \mathbb{P}^1 . An interesting question is to understand how to express matrices as Hadamard products of small rank matrices. We call these expressions *Hadamard decomposition*. We define *Hadamard ranks* of matrices by using a multiplicative version of the usual definitions used for additive tensor decompositions. The study of Hadamard ranks is related to the study of Hadamard powers of secant varieties of Segre products of projective spaces.

In Section 4, we focus in particular on the dimension of these Hadamard powers. We define the expected dimension and, consequently, we define the expected r-th Hadamard generic rank, i.e., the expected number of rank r matrices needed to decompose the generic matrix of size $m \times n$ as their Hadamard product. It is

$$\exp.\mathrm{Hrk}_r^\circ(m,n) = \left\lceil \frac{\dim \mathbb{P}(\mathrm{Mat}_{m,n}) - \dim(X_1)}{\dim(X_r) - \dim(X_1)} \right\rceil = \left\lceil \frac{mn - (m+n-1)}{r(m+n-r) - m - n + 1} \right\rceil.$$

We confirm this is correct for square matrices of small size using Macaulay2.

The paper is structured as follows. In Section 2, we present some explicit computations of these varieties. We use both *Macaulay2* [5] and *Sage* [12]. These computations allowed us to conjecture some geometric properties of Minkowski sums and Hadamard products of algebraic varieties. In Section 3, we analyze Minkowski sums of affine varieties. In particular, we prove that, under genericity conditions, the dimension of the Minkowski sum is the sum of the dimensions and we investigate the degree of the Minkowski sum. In Section 4, we study Hadamard products and Hadamard powers of projective varieties. In particular, we focus on the case of Hadamard powers of projective varieties of matrices of given rank. We introduce the notion of Hadamard decomposition and Hadamard rank of a matrix. These concepts may be viewed as the multiplicative versions of the well-studied *additive decomposition* of tensors and *tensor ranks*.

2 Experiments

Problem 5 on Surfaces in [13] asked the following:

Compute the Minkowski sum and the Hadamard product of two random circles in \mathbb{R}^3 . Try other curves.

In order to compute Minkowski sums and Hadamard products of circles and other curves, we used the algebra softwares *Macaulay2* and *Sage* to obtain equations and nice graphics. These also aided our general understanding of the geometric properties of these constructions. Via elimination theory, we can compute the ideals of Minkowski sums and Hadamard products. This is the script in *Macaulay2* to do so.

With *Sage*, we produced graphics of the real parts of Minkowski sums and Hadamard products of curves in \mathbb{A}^3 . This is the script we used.

```
A.<x1, x2, x3, y1, y2, y3, z1, z2, z3>=QQ[]
I=( \dots )*A \# ideal of X in the variables x;
J=( \dots )*A \# ideal of Y in the variables y;
# construct the ideals defining the graphs of the maps
# phi_+ and phi_star
S = I + J + (z1-(x1+y1), z2-(x2+y2), z3-(x3+y3)) *A
P = I + J + (z1-(x1*y1), z2-(x2*y2), z3-(x3*y3))*A
MSum = S.elimination_ideal([x1, x2, x3, y1, y2, y3])
HProd = P.elimination\_ideal([x1, x2, x3, y1, y2, y3])
# Assuming we get a surface, take the one generator of
# each ideal.
MSumGen=MSum.gens()[0]
HProdGen=HProd.gens()[0]
# We plot these surfaces.
# Because MSumGen and HProdGen are considered as elements of A,
# which has 9 variables, they take 9 arguments.
var('z1,z2,z3')
implicit_plot3d(MSumGen(0,0,0,0,0,0,z1,z2,z3) == 0,
                (z1, -3, 3), (z2, -3, 3), (z3, -3, 3))
implicit_plot3d(HProdGen(0,0,0,0,0,0,z1,z2,z3) == 0,
                (z1, -3, 3), (z2, -3,3), (z3, -3,3))
```

In Figs. 1, 2, 3 and 4 are some of the pictures we obtained. These experiments gave us a first idea about the properties of Minkowski sums and Hadamard products.

Note 2.1. The fact that X + Y and $X \star Y$ are the closures of images of $X \times Y$ under the maps ϕ_+ and ϕ_* immediately gives us that

$$\dim(X+Y), \dim(X\star Y) \leq \dim(X) + \dim(Y)$$

and that if *X* and *Y* are irreducible, so are X + Y and $X \star Y$.

Also, the fact that X + Y and $X \star Y$ are linear projections of $X \times Y \subset \mathbb{A}^n \times \mathbb{A}^n$ and of $X \times Y \subset \mathbb{P}^n \times \mathbb{P}^n \subset \mathbb{P}^{n^2+2n}$, respectively, leads us to expect other geometric properties of X + Y and $X \star Y$.

Because the projection of a variety $Z \subset \mathbb{P}^N$ in generic position from a linear space L with $\dim(Z) + \dim(L) < N-1$ is generically one-to-one, we naïvely expect that, for X and Y in general position, with $\dim(X) + \dim(Y) < n$,

$$\begin{split} \dim(X+Y), \dim(X\star Y) &= \dim(X) + \dim(Y), \\ \deg(X+Y) &= \deg(X\times Y) = \deg(X) \deg(Y), \quad (X\times Y\subset \mathbb{A}^n) \\ \deg(X\star Y) &= \deg(X\times Y) = \binom{\dim(X) + \dim(Y)}{\dim(X)} \deg(X) \deg(Y), \ (X\times Y\subset \mathbb{P}^{n^2+2n}). \end{split}$$

These expectations, however, do not follow directly from the projections of the varieties in general position because, even for X and Y in general position, $X \times Y$ is not in general position. Hence, we need further analysis as in the following sections.



Fig. 1 Minkowski sum of a circle of radius 1 in the x, y-plane and a circle of radius 2 in the x, z-plane. This is a degree four surface.



Fig. 2 Minkowski sum of the two parabolas $x = y^2$ in the x,y-plane and $y = z^2$ in the y,z-plane. This is a degree four surface.

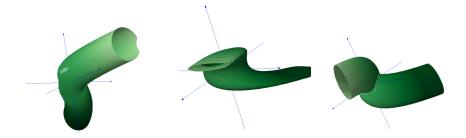


Fig. 3 Minkowski sum of the twisted cubic $(xz - y^2, y - x^2, z - xy)$ with the unit circle in the x,y-plane, y,z-plane, and x,z-plane from left to right, respectively. Each of these are a degree six surface, but only the middle one is smooth.



Fig. 4 The real part of the Hadamard product of (left) the unit circle in the z = 1 plane and the unit circle in the y = 1 plane and (right) the circles $x^2 + (y+z)^2 = 1, z-y = 1$ and $x^2 + (z-y)^2 = 1, y+z = 1$. The surface on the left is of degree four, and the surface on the right is of degree two.

3 Minkowski sum of affine varieties

Recall the definition of the Minkowski sum of two affine varieties X and Y as the closure of the image of $X \times Y$ under the map

$$\phi_+: \mathbb{A}^n \times \mathbb{A}^n \to \mathbb{A}^n, \ ((a_1, \dots, a_n), (b_1, \dots, b_n)) \mapsto (a_1 + b_1, \dots, a_n + b_n)$$

The operation of closure is needed in order to get an algebraic variety. Indeed, we can give an example where $X +_{\text{set}} Y := \phi_+(X \times Y) = \{p+q \mid p \in X, q \in Y\}$, the *setwise Minkowski sum* of X and Y, is not closed.

Example 3.1. In the affine plane \mathbb{A}^2 with coordinates $\{x,y\}$, consider the plane curves $X=\{xy=1\}$ and $Y=\{xy=-1\}$. We claim that $\phi_+(X\times Y)$ contains the torus $(\mathbb{k}^\times)^2$, so $X+Y=\mathbb{A}^2$. For if $(\alpha,\beta)\in (\mathbb{k}^\times)^2$ and $(p,q)\in X\times Y$ then $\phi_+(p,q)=$

 (α,β) if and only if we can write p and q in the forms $p=(\alpha+a,\frac{1}{\alpha+a})$ and $q=(-a,\frac{1}{a})$ for some scalar $a\neq 0,-\alpha$ such that $\beta=\frac{1}{\alpha+a}+\frac{1}{a}$. Clearing denominators in this last expression, we find the requirement is that $\beta a(\alpha+a)=a+(\alpha+a)$, i.e. a is a zero of the quadratic polynomial $f_{\alpha,\beta}(t)=\beta t^2+(\beta\alpha-2)t-\alpha$. Note that $f_{\alpha,\beta}(0)=-\alpha$ and $f_{\alpha,\beta}(-\alpha)=\beta\alpha^2-\beta\alpha^2+2\alpha-\alpha=\alpha$. So if we let a be a zero of $f_{\alpha,\beta}$ then with p and q as above we have $\phi_+(p,q)=(\alpha,\beta)$.

On the other hand $X +_{\text{set}} Y$ is not all of \mathbb{A}^2 . If the characteristic of the base field is not 2, then $X +_{\text{set}} Y$ does not contain the origin (though it does contain the punctured axes). In characteristic 2 we find that $X +_{\text{set}} Y$ contains no point of the punctured axes $\{x = 0\} \setminus \{(0,0)\}$ and $\{y = 0\} \setminus \{(0,0)\}$.

One of our main tools for proving results about the Minkowski sum is an alternative description of it in terms of the join of the two varieties.

For X,Y subvarieties of \mathbb{A}^n or \mathbb{P}^n , we let $J_{\text{set}}(X,Y)$ be the *setwise join* of X and Y, i.e., the union of the lines connecting distinct points $x \in X$ and $y \in Y$. This space is usually not closed and its Zariski closure J(X,Y) is the classical *join* of X and Y.

Our analysis of the Minkowski sum of affine algebraic sets X and Y via a join will involve hyperplanes positioned as in Lemma 3.2 below. For an intuitive sense of the statement of the lemma, one may consider the case where L, M, and N are the projectivizations of parallel affine hyperplanes.

Lemma 3.2. Let L, M, N be three distinct hyperplanes in \mathbb{P}^n with $E := L \cap M = L \cap N = M \cap N$. Say $X \subset M$ and $Y \subset N$ are nonempty disjoint subvarieties. Let $X^a = X \setminus E$, $Y^a = Y \setminus E$, $\partial X = X \cap E$, and $\partial Y = Y \cap E$. Then:

- (i) $J(X,Y) = J_{\text{set}}(X,Y)$,
- (ii) $J(X,Y) \cap L = (J_{\text{set}}(X^a,Y^a) \cap L) \cup J_{\text{set}}(\partial X,\partial Y) \cup \partial X \cup \partial Y$, and
- (iii) $J(X,Y) \cap L \setminus E = J_{set}(X^a,Y^a) \cap L$.

In particular, if X and Y have positive dimension then

$$J(X,Y) \cap L = (J_{set}(X^a,Y^a) \cap L) \cup J_{set}(\partial X,\partial Y).$$

Proof. (i) Because X and Y are disjoint, we have $J_{set}(X,Y)$ is Zariski closed, so $J(X,Y) = J_{set}(X,Y)$ [see Example 6.17 on p.70 of [6]].

(ii) From the first part, we have

$$J(X,Y) = J_{\text{set}}(X^a, Y^a) \cup J_{\text{set}}(X^a, \partial Y) \cup J_{\text{set}}(\partial X, Y^a) \cup J_{\text{set}}(\partial X, \partial Y).$$

So to get the claimed expression for $J(X,Y) \cap L$ it suffices to show

- (a) $J_{\text{set}}(X^a, \partial Y) \cap L, J_{\text{set}}(\partial X, Y^a) \cap L \subset \partial X \cup \partial Y$ and
- (b) $J_{\text{set}}(\partial X, \partial Y) \cup \partial X \cup \partial Y \subset L$.
- (a) By symmetry it is enough to show that $J_{\text{set}}(X^a, \partial Y) \cap L \subset \partial Y$. Say $x \in X^a$ and $y \in \partial Y$. So $y \in L$ but $x \notin L$. Thus, the line between x and y intersects L in exactly $\{y\} \subset \partial Y$.

(b) We show that $J_{\text{set}}(\partial X, \partial Y) \cup \partial X \cup \partial Y \subset E$.

By definition, $\partial X, \partial Y \subset E$. So, because E is a linear space, for any $x \in \partial X$ and $y \in \partial Y$, the line between x and y is contained in E.

(iii) First, note that because $J_{\text{set}}(\partial X, \partial Y) \cup \partial X \cup \partial Y \subset E$, we have

$$(J(X,Y)\cap L)\setminus E\subset (J_{\text{set}}(X^a,Y^a)\cap L)\setminus E.$$

Hence, we just need to show that $J_{\text{set}}(X^a, Y^a) \cap L$ is disjoint from E.

Considering any $x \in X^a$ and $y \in Y^a$, it suffices to show that the line ℓ between x and y does not meet E. If we assume, towards a contradiction, that there is some $z \in \ell \cap E$, then z and x would be distinct points on the hyperplane M, so the line ℓ between them would be contained in M. But $y \in Y^a \subset N \setminus E = N \setminus M$, so ℓ cannot be contained in M.

Finally, if *X* and *Y* are positive dimensional then $\partial X = X \cap L$ and $\partial Y = Y \cap L$ are nonempty, so ∂X , $\partial Y \subset J_{\text{set}}(\partial X, \partial Y)$.

Our alternative description of the Minkowski sum will give us cases in which $X +_{\text{set}} Y$ is already closed. Recall from Example 3.1 that for the two plane curves $X = \{xy = 1\}$ and $Y = \{xy = -1\}$, $X +_{set} Y$ is not Zariski closed. Note that in this example, X and Y have a common asymptote, or equivalently, that their projective closures meet at the line at infinity. We will see that when the characteristic of the base field is not 2, all cases where $X +_{set} Y$ is not closed share an analogous property.

Definition 3.3. Let $X,Y \subset \mathbb{A}^n$ be varieties and denote the projective closures of Xand Y in \mathbb{P}^n by \overline{X} and \overline{Y} , respectively. Let $H_0 = \{[x_0 : \cdots : x_n] \in \mathbb{P}^n \mid x_0 = 0\}$ be the hyperplane at ∞ . We say that X and Y are disjoint at infinity if $\overline{X} \cap \overline{Y} \cap H_0 = \emptyset$.

Remark 3.4. If X and Y are disjoint at infinity then $\dim(X \cap Y) < 1$, thus we get that $\dim X + \dim Y < n$.

Proposition 3.5. Assume that the characteristic of \mathbb{k} is not 2. Suppose $X,Y \subset \mathbb{A}^n$ are varieties that are disjoint at infinity. Let z_0, z_1 be distinct scalars and let $\tilde{X}, \tilde{Y} \subset \mathbb{P}^{n+1}$ be the projective closures of $X \times \{z_0\}$ and $Y \times \{z_1\}$, respectively. Let $x_0, x_1, \dots, x_n, z_n$ be the coordinates on \mathbb{P}^{n+1} .

If we identify $S = \{z = \frac{z_0 + z_1}{2} x_0\} \subset \mathbb{P}^{n+1}$ with \mathbb{P}^n and $S \setminus H_0$ with \mathbb{A}^n , then:

- $\begin{array}{ll} (i) & J_{\rm set}(\tilde{X},\tilde{Y}) = J(\tilde{X},\tilde{Y}); \\ (ii) & \frac{1}{2}(X+Y) = J(\tilde{X},\tilde{Y}) \cap S \setminus H_0; \end{array}$
- (iii) $X +_{\text{set}} Y = X + Y$, namely, $X +_{\text{set}} Y$ is Zariski closed.

Proof. (i) Let $E = \{x_0 = 0\} \subset \mathbb{P}^{n+1}$ be the hyperplane at ∞ in \mathbb{P}^{n+1} . Note that

$$E \cap \{z = z_0 x_0\} = E \cap \left\{z = \frac{z_0 + z_1}{2} x_0\right\} = E \cap \{z = z_1 x_0\} = \{z = 0, x_0 = 0\},$$

which is identified with H_0 . Therefore the statement that X and Y are disjoint at infinity is equivalent to

$$\tilde{X} \cap \tilde{Y} \cap E = \emptyset$$
.

On the other hand, $\tilde{X} \setminus E = X \times \{z_0\}$ and $\tilde{Y} \setminus E = Y \times \{z_1\}$, and so we see that $\tilde{X} \cap \tilde{Y} = \emptyset$. So, by Lemma 3.2 applied to $S = \{z = \frac{z_0 + z_1}{2}x_0\}$, $\tilde{X} \subset \{z = z_0x_0\}$, and $\tilde{Y} \subset \{z = z_1x_0\}$, we find that

$$J_{\text{set}}(\tilde{X}, \tilde{Y}) = J(\tilde{X}, \tilde{Y})$$
 and $J(\tilde{X}, \tilde{Y}) \cap S \setminus H_0 = J_{\text{set}}(X \times \{z_0\}, Y \times \{z_1\}) \cap S$.

(iii) & (iii) For any $x \in X$ and $y \in Y$, the line between the points $(x, z_0) \in X \times \{z_0\}$ and $(y, z_1) \in Y \times \{z_1\}$ meets the affine hyperplane $S \setminus E = \{z = \frac{z_0 + z_1}{2}\}$ in exactly the point $(\frac{x+y}{2}, \frac{z_0+z_1}{2})$. So, we have shown that $J(\tilde{X}, \tilde{Y}) \cap S \setminus H_0 = \frac{1}{2}(X +_{\text{set}} Y)$. In particular, because $J(\tilde{X}, \tilde{Y})$ is closed, this tells us that $X +_{\text{set}} Y$ is a closed subset of $S \setminus H_0 \cong \mathbb{A}^n$. Hence, $\frac{1}{2}(X + Y) = \frac{1}{2}(X +_{\text{set}} Y) = J(\tilde{X}, \tilde{Y}) \cap S \setminus H_0$.

Remark 3.6. We call the construction $\frac{1}{2}(X+Y) = J(\tilde{X},\tilde{Y}) \cap S \setminus H_0$ the Cayley trick, as the underlying idea is exactly the same as that of the Cayley trick used to construct Minkowski sums of polytopes.

As a consequence of the following lemma, if we restrict to the cases with $\dim X + \dim Y \le n$, then the hypothesis that X and Y are disjoint at infinity is a *genericity condition*.

Lemma 3.7. Let $X,Y \subset \mathbb{P}^n$ be varieties with $\dim X + \dim Y < n$. Then, we have that the set $\{g \in GL_{n+1} \mid gX \cap Y = \emptyset\}$ is a nonempty open subset of GL_{n+1} . That is, for generic $g \in GL_{n+1}$, gX and Y do not intersect.

Proof. First, note that for any point $p \in \mathbb{P}^n$ the stabilizer of p in GL_{n+1} has dimension $n^2 + n + 1$. This is because any two point stabilizers in GL_{n+1} are conjugate and the stabilizer of $[1:0:0:\cdots:0] \in \mathbb{P}^n$ is the set of all $g \in GL_{n+1}$ with first column of the form $[*0 \ 0 \ \cdots \ 0]^T$, which has dimension (n+1)n+1.

Let $Z = \{(g, x, y) \in GL_{n+1} \times X \times Y \mid gx = y\}$ which is a subvariety of $GL_{n+1} \times X \times Y$. Let $\pi_1 : Z \to GL_{n+1}$ and $\pi_2 : Z \to X \times Y$ be the restrictions of the canonical projections from $GL_{n+1} \times X \times Y$. Note that π_2 is surjective, because for any $x, y \in \mathbb{P}^n$ there exists some $g \in GL_{n+1}$ taking x to y. Further, the fiber over any point $(x, y) \in X \times Y$ is a left coset of a point stabilizer in GL_{n+1} and so has dimension $n^2 + n + 1$. Thus, $\dim Z = n^2 + n + 1 + \dim X + \dim Y < n^2 + 2n + 1 = \dim GL_{n+1}$.

Because $X \times Y$ is projective, the projection $GL_{n+1} \times X \times Y \to GL_{n+1}$ is a closed map, so $\pi_1(Z)$ is a closed subset of GL_{n+1} . Since $\dim \pi_1(Z) \le \dim Z < \dim GL_{n+1}$, $\pi_1(Z)$ is a proper closed subset of GL_{n+1} . So,

$$\{g \in GL_{n+1} | gX \cap Y = \emptyset\} = GL_{n+1} \setminus \pi_1(Z)$$

is a nonempty open subset of GL_{n+1} .

Now, we claim that if $X, Y \subset \mathbb{A}^n$ are varieties with $\dim X + \dim Y \leq n$, then

for general $g \in GL_n$, gX and Y are disjoint at infinity.

To see this, note that, considering $H_0 = \{x_0 = 0\}$,

$$\dim(\overline{X}\cap H_0) + \dim(\overline{Y}\cap H_0) \leq \dim X - 1 + \dim Y - 1 < \dim X + \dim Y - 1 \leq n - 1.$$

The action of GL_n on \mathbb{A}^n extends to an action on \mathbb{P}^n , and the identification $H_0 \cong \mathbb{P}^{n-1}$ is GL_n -equivariant. So we have

$$\overline{gX} \cap \overline{Y} \cap H_0 = (\overline{gX} \cap H_0) \cap (\overline{Y} \cap H_0) = g(\overline{X} \cap H_0) \cap (\overline{Y} \cap H_0).$$

By Lemma 3.7, for general $g \in GL_n$ this is empty.

Remark 3.8. We could have used the group of affine transformations $Aff_n = \mathbb{A}^n \times GL_n$. Indeed, shifting an affine variety does not change the part at infinity of its projective closure.

When a result holds under the same conditions as Lemma 3.7, i.e., if we fix X and Y then it holds for gX and Y, for general $g \in Aff_n$, we shall say that the result holds for X and Y in general position.

We are now ready to compute the dimension of Minkowski sums. Based on the examples in Section 2, it seems that for $\dim X + \dim Y \le n$, we get $\dim(X + Y) = \dim X + \dim Y$. This does happen generically.

Theorem 3.9. Let $X,Y \subset \mathbb{A}^n$ be varieties. Then for X and Y in general position, $\dim(X+Y) = \min\{\dim X + \dim Y, n\}.$

Proof. As observed in Note 2.1, we have that, for any $X,Y \subset \mathbb{A}^n$,

$$\dim(X+Y) \le \min\{\dim(X) + \dim(Y), n\}.$$

So, we need to prove the converse for X, Y in general position.

Let $k = \dim(X)$ and $l = \dim(Y)$.

Note that because (X + v) + Y = (X + Y) + v for any vector v, it suffices to show that for general $g \in GL_n$, $\dim(gX + Y) \ge \min\{\dim(X) + \dim(Y), n\}$. We consider the case $\dim(X) + \dim(Y) \le n$, the case $\dim(X) + \dim(Y) \ge n$ being analogous.

Note that by just looking at full-dimensional irreducible components of X and Y, we may assume without loss of generality that X and Y are irreducible.

We denote by $T_p(X)$ the tangent space to the variety X at the point p.

For now fix $g \in GL_n$. If $(p,q) \in \mathbb{A}^n \times \mathbb{A}^n$ then

$$(d\phi_+)_{(p,q)}: T_p\mathbb{A}^n \times T_q\mathbb{A}^n \to T_{p+q}\mathbb{A}^n$$

is simply the addition map ϕ_+ , and so we see that if $p \in gX$ and $q \in Y$ then $T_p(gX) + T_qY \subseteq T_{p+q}(gX+Y)$. So to conclude that $\dim(gX+Y) \ge \dim(X) + \dim(Y)$ it suffices to show that there is a dense subset Ξ of gX+Y such that for each $\xi \in \Xi$ there exist $p \in gX$ and $q \in Y$ with $\xi = p+q$ and $T_p(gX) \cap T_qY = 0$, for then

$$\dim(T_{\xi}(gX+Y)) \ge \dim(T_{p}(gX) + T_{q}Y)$$

$$= \dim(T_{p}(gX)) + \dim(T_{q}Y) \ge \dim(X) + \dim(Y),$$

and because Ξ is dense some $\xi \in \Xi$ is a smooth point of gX + Y. Also, because the image of a dense subset under a continuous function is a dense subset of the image, we see that it suffices to show that there is a nonempty open subset of $gX \times Y$ such that for (p,q) in this set, $T_p(gX) \cap T_qY = 0$.

For any variety $Z \subset \mathbb{A}^n$ let Z_{sm} denote the smooth locus of Z. So we have the morphism $\psi_Z : Z_{sm} \to Gr(\dim(Z), \mathbb{A}^n)$, $p \mapsto T_p Z$, and we let Ψ_Z denote the image of this morphism inside the Grassmannian.

Consider

$$U = \{ (V, W) \in \operatorname{Gr}(k, \mathbb{A}^n) \times \operatorname{Gr}(l, \mathbb{A}^n) | V \cap W \neq 0 \},$$

which is an open subset of $Gr(k, \mathbb{A}^n) \times Gr(l, \mathbb{A}^n)$. In particular, if we let

$$\varphi_g := \psi_{gX} \times \psi_Y : gX_{sm} \times Y_{sm} \to Gr(k, \mathbb{A}^n) \times Gr(l, \mathbb{A}^n),$$

then $\varphi_g^{-1}(U)$ is a (possibly empty) open subset of $gX \times Y$, and if $(p,q) \in \varphi_g^{-1}(U)$ then $T_p(gX) \cap T_qY = 0$. Also, $\varphi_g^{-1}(U)$ is nonempty if and only if $(\Psi_{gX} \times \Psi_Y) \cap U$ is nonempty. So we conclude that to show that $\dim(gX + Y) \ge \dim(X) + \dim(Y)$, it suffices to show that $(\Psi_{gX} \times \Psi_Y) \cap U \ne \emptyset$.

Now we let $g \in GL_n$ vary. Fix $p \in X_{\rm sm}$ and $q \in Y_{\rm sm}$. So for $g \in GL_n$, $gp \in (gX)_{\rm sm}$ with $T_{gp}(gX) = g(T_pX)$. Now T_qY is an l-dimensional subspace of \mathbb{A}^n and so because $k+l \leq n$, $\{V \in {\rm Gr}(k,\mathbb{A}^n)|V \cap T_qY=0\}$ is a nonempty open subset of the Grassmannian. So because GL_n acts transitively on ${\rm Gr}(k,\mathbb{A}^n)$ we conclude that for generic $g \in GL_n$, $T_{gp}(gX) \cap T_qY = g(T_pX) \cap T_qY = 0$. Thus $(gp,q) \in (\Psi_{gX} \times \Psi_Y) \cap U$, and so $\dim(gX+Y) \geq \dim(X) + \dim(Y)$.

For the case where $\dim(X) + \dim(Y) \ge n$ the same proof works upon replacing the condition that tangent spaces intersect trivially with the condition that they intersect transversely.

Further, when the characteristic of the base field is not 2 we can use the Cayley trick to show that the condition of *disjoint at infinity* is sufficient to have additivity of dimension.

Theorem 3.10. Assume the characteristic of the base field is not 2. Let $X,Y \subset \mathbb{A}^n$ be varieties which are disjoint at infinity. Then $\dim(X+Y) = \dim X + \dim Y$.

Proof. As observed in Note 2.1, we have that for any $X,Y \subset \mathbb{A}^n$,

$$\dim(X + Y) \le \dim(X) + \dim(Y)$$
.

If either X or Y has dimension zero then X + Y is a union of finitely many shifts of the other and so has dimension $\dim X + \dim Y$.

Assume *X* and *Y* have both positive dimension. Then, by Proposition 3.5 (with any z_0, z_1) and Lemma 3.2, we have that

$$J(\tilde{X}, \tilde{Y}) \cap S = \frac{1}{2}(X+Y) \cup J(\partial X, \partial Y)$$

where $\partial X = \overline{X} \cap H_0$ and $\partial Y = \overline{Y} \cap H_0$ are the parts at infinity of the projective closures of X and Y, and $\frac{1}{2}(X+Y)$ is an open subset of $J(\tilde{X},\tilde{Y})$ while $J(\partial X,\partial Y)$ is closed. Hence, we have

$$\begin{split} \dim X + \dim Y &= \dim J(\tilde{X}, \tilde{Y}) - 1 \leq \dim(J(\tilde{X}, \tilde{Y}) \cap S) \\ &= \dim\left(\frac{1}{2}(X+Y) \cup J(\partial X, \partial Y)\right) \\ &= \max\left\{\dim(X+Y), \dim J(\partial X, \partial Y)\right\} \\ &= \max\left\{\dim(X+Y), \dim X + \dim Y - 1\right\}, \end{split}$$

where last equality follows since

$$\dim J(\partial X, \partial Y) = \dim X - 1 + \dim Y - 1 + 1 = \dim X + \dim Y - 1.$$

So
$$\dim(X+Y) = \dim X + \dim Y$$
.

We now consider the degree of Minkowski sums. Recall that the *degree* of a variety X of dimension d in \mathbb{A}^n or \mathbb{P}^n is the number of points in the intersection of X and a general linear subspace of dimension n-d.

Proposition 3.11. Let \mathbb{k} be the ground field with characteristic other than 2. Let $X,Y \subset \mathbb{A}^n$ be varieties which are disjoint at infinity. Then, for generic $\alpha \in \mathbb{k}^{\times}$, in the same notation as in Proposition 3.5, we have that $\deg(\alpha X + Y) = \deg(J(\tilde{X}, \tilde{Y}))$.

Proof. The proof will go in three main steps.

- (i) Show that, up to projective equivalence, dilating X by a generic $\alpha \in \mathbb{k}^{\times}$ and then applying the Cayley trick is the same as intersecting $J(\tilde{X}, \tilde{Y})$ with a generic hyperplane whose affine part is parallel to $S \setminus H_0$.
- (ii) Prove that for generic α the corresponding hyperplane intersects $J(\tilde{X}, \tilde{Y})$ generically transversely.
- (iii) Apply Bézout's theorem and show that the part of the intersection that is at infinity does not contribute to the degree.

Once again we use our Cayley trick and, to simplify computations, we fix $z_0 = 0$ and $z_1 = 1$. Note that, for any $\alpha \in \mathbb{k}^{\times}$, αX and Y are disjoint at infinity so we still get the conclusions of Proposition 3.5 and Theorem 3.10.

(i) For $\alpha \in \mathbb{k}^{\times}$, let

$$\Phi_{lpha}=egin{pmatrix} 1&0&\cdots&0&lpha-1\ 0&&&0\ dots&lpha I_n&dots\ 0&&&0\ 0&0&\cdots&0&lpha \end{pmatrix}\in GL_{n+2}.$$

We consider GL_{n+2} as acting on \mathbb{P}^{n+1} with coordinates x_0, x_1, \dots, x_n, z . For $\alpha, \beta \in \mathbb{R}^{\times}$ we have

$$\Phi_{lpha}\Phi_{eta}=egin{pmatrix}1&lpha-1&lpha-1&lpha&l$$

so $\alpha \mapsto \Phi_{\alpha}$ is a group homomorphism $\mathbb{k}^{\times} \to GL_{n+2}$. Note that Φ_{α} acts on the hyperplane $\{z=0\}$ as

$$\Phi_{\alpha} \begin{bmatrix} 1 \\ \underline{x} \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ \alpha \underline{x} \\ 0 \end{bmatrix} \quad \text{and} \quad \Phi_{\alpha} \begin{bmatrix} 0 \\ \underline{x} \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ \alpha \underline{x} \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ \underline{x} \\ 0 \end{bmatrix}.$$

Similarly, Φ_{α} fixes the hyperplane $\{z = x_0\}$ pointwise. Thus, $\Phi_{\alpha}(\tilde{X}) = \widetilde{\alpha X}$ and $\Phi_{\alpha}(\tilde{Y}) = \tilde{Y}$. Since Φ_{α} acts as a projective transformation, and so takes lines to lines, $\Phi_{\alpha}(J(\tilde{X},\tilde{Y})) = J(\widetilde{\alpha X},\tilde{Y})$. In particular,

$$\deg\left(J\left(\widetilde{\alpha X},\widetilde{Y}\right)\right)=\deg\left(J(\widetilde{X},\widetilde{Y})\right).$$

We know that $\frac{1}{2}(\alpha X + Y) = J(\widetilde{\alpha X}, \widetilde{Y}) \cap S \setminus H_0$, so we consider $\Phi_{\alpha}^{-1}(S \setminus H_0)$. We get

$$S \setminus H_0 = \left\{ z = \frac{1}{2} x_0 \right\} \setminus \left\{ z = 0, x_0 = 0 \right\} = \left\{ x_0 = 1, z = \frac{1}{2} \right\},$$

and we find that, for $\alpha \neq -1$,

$$\boldsymbol{\Phi}_{\boldsymbol{\alpha}}^{-1} \begin{bmatrix} 1 \\ \underline{w} \\ 1/2 \end{bmatrix} = \begin{pmatrix} 1 & \boldsymbol{\alpha}^{-1} - 1 \\ \boldsymbol{\alpha}^{-1} I_n & \\ \boldsymbol{\alpha}^{-1} \end{pmatrix} \begin{bmatrix} 1 \\ \underline{w} \\ 1/2 \end{bmatrix} = \begin{bmatrix} \frac{\alpha^{-1} + 1}{2} \\ \boldsymbol{\alpha}^{-1} \underline{w} \\ \boldsymbol{\alpha}^{-1} / 2 \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{2\alpha^{-1}}{\alpha^{-1} + 1} \underline{w} \\ \frac{\alpha^{-1}}{\alpha^{-1} + 1} \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{1}{2 + \alpha} \underline{w} \\ \frac{1}{1 + \alpha} \end{bmatrix}.$$

Thus $\Phi_{\alpha}^{-1}(S \setminus H_0) = \{x_0 = 1, z = \frac{1}{1+\alpha}\} = \{z = \frac{1}{1+\alpha}x_0\} \setminus H_0.$

(ii) We claim that, for generic α ,

$$\left\{z = \frac{1}{1+\alpha}x_0\right\}$$
 intersects $J(\tilde{X},\tilde{Y})$ generically transversely.

First, note that it suffices to only consider the *affine points* of $J(\tilde{X}, \tilde{Y})$, i.e. those with $x_0 = 1$, because

$$\dim \left(J(\tilde{X}, \tilde{Y}) \cap \left\{ z = \frac{1}{1+\alpha} x_0 \right\} \setminus H_0 \right) = \dim \left(J\left(\widetilde{\alpha X}, \widetilde{Y}\right) \cap S \setminus H_0 \right)$$

$$= \dim(\alpha X + Y) = \dim X + \dim Y$$

$$> \dim J(\partial X, \partial Y) = \dim(J(\tilde{X}, \tilde{Y}) \cap H_0),$$

But $\mathbb{A}^{n+1} \subset \mathbb{P}^{n+1}$ is the disjoint union of $\{x_0=1,z=a\}$ as a ranges over \mathbb{k} , so for all but finitely many $a \in k$, $\{x_0=1,z=a\} \cap J(\tilde{X},\tilde{Y})$ must not be contained in the singular locus of $J(\tilde{X},\tilde{Y})$. So, for all but finitely many $\alpha \in \mathbb{k}^{\times}$, we have that $\{x_0=1,z=\frac{1}{1+\alpha}\} \cap J(\tilde{X},\tilde{Y})$ must not be contained in the singular locus of $J(\tilde{X},\tilde{Y})$. So for generic $\alpha \in \mathbb{k}^{\times}$, the general point of $\{z=\frac{1}{1+\alpha}x_0\} \cap J(\tilde{X},\tilde{Y})$ is a smooth

point of $J(\tilde{X}, \tilde{Y})$. In order to check transversality, we need another description of this intersection, which we compute now.

$$\begin{split} J(\tilde{X},\tilde{Y}) \cap \left\{z &= \frac{1}{1+\alpha}\right\} &= \varPhi_{\alpha}^{-1} \left(J\left(\widetilde{\alpha X},\tilde{Y}\right) \cap S \setminus H_{0}\right) \\ &= \varPhi_{\alpha}^{-1} \left(J(\alpha X \times \{0\}, Y \times \{1\}) \cap S \setminus H_{0}\right) \\ &= J(X \times \{0\}, Y \times \{1\}) \cap \left\{z = \frac{1}{1+\alpha}\right\} \end{split}$$

where the second equality follows from Lemma 3.2.

Thus, considering $p \in J(\tilde{X}, \tilde{Y}) \cap \{z = \frac{1}{1+\alpha}\}$, we have that p is on the line between the points (x,0) and (y,1), for some $x \in X$ and $y \in Y$. Since this line intersects $S = \{z = \frac{1}{1+\alpha}x_0\}$ transversely and $T_pJ(\tilde{X},\tilde{Y})$ contains this line, if p is a smooth point of $J(\tilde{X},\tilde{Y})$ then we have that $\{z = \frac{1}{1+\alpha}x_0\}$ and $J(\tilde{X},\tilde{Y})$ intersect transversely at p. Thus, for generic α , $\{z = \frac{1}{1+\alpha}x_0\}$ intersects $J(\tilde{X},\tilde{Y})$ generically transversely. (iii) For such an α , applying Bézout's theorem gives us that

$$\deg\left(J\left(\tilde{X},\tilde{Y}\right)\cap\left\{z=\frac{1}{1+\alpha}x_0\right\}\right)=\deg\left(J(\tilde{X},\tilde{Y})\right).$$

We can write $J(\tilde{X},\tilde{Y})\cap\{z=\frac{1}{1+\alpha}x_0\}$ as the disjoint union of the open subset $J(\tilde{X},\tilde{Y})\cap\{x_0=1,z=\frac{1}{1+\alpha}\}$ and the closed subset $J(\tilde{X},\tilde{Y})\cap H_0$. Now,

$$J(\tilde{X}, \tilde{Y}) \cap \left\{ x_0 = 1, z = \frac{1}{1+\alpha} \right\} = \Phi_{\alpha}^{-1} \left(J\left(\widetilde{\alpha X}, \tilde{Y}\right) \cap S \setminus H_0 \right)$$
$$= \Phi_{\alpha}^{-1} \left(\frac{1}{2} (\alpha X + Y) \right)$$

has dimension dim X + dim Y and $J(\tilde{X}, \tilde{Y}) \cap H_0 = J(\partial X, \partial Y)$ has dimension dim X + dim Y - 1. Therefore,

$$\deg\left(J\left(\tilde{X},\tilde{Y}\right)\cap\left\{x_{0}=1,z=\frac{1}{1+\alpha}\right\}\right)=\deg\left(J\left(\tilde{X},\tilde{Y}\right)\cap\left\{z=\frac{1}{1+\alpha}x_{0}\right\}\right)$$
$$=\deg\left(J\left(\tilde{X},\tilde{Y}\right)\right).$$

Finally, since

$$\frac{1}{2}(\alpha X + Y) = \Phi_{\alpha}\left(J\left(\tilde{X}, \tilde{Y}\right) \cap \left\{x_0 = 1, z = \frac{1}{1 + \alpha}\right\}\right),\,$$

we get $\deg(\alpha X + Y) = \deg(J(\tilde{X}, \tilde{Y}))$.

Corollary 3.12. Suppose \mathbb{k} has characteristic other than 2. Let $X,Y \subset \mathbb{A}^n$ be varieties whose projective closures $\overline{X}, \overline{Y} \subset \mathbb{P}^n$ are contained in complementary linear

subspaces; equivalently, X,Y are contained in disjoint affine subspaces which are not parallel. Then for generic $\alpha \in \mathbb{k}^{\times}$, $\deg(\alpha X + Y) = \deg(X) \deg(Y)$.

Proof. Since \overline{X} and \overline{Y} are contained in complementary linear spaces they are disjoint, so, in particular, X and Y are disjoint at infinity.

By Proposition 3.11, for a generic $\alpha \in \mathbb{k}^{\times}$, we have $\deg(\alpha X + Y) = \deg(J(\tilde{X}, \tilde{Y}))$. Moreover, $\overline{X}, \overline{Y}$ contained in complementary linear spaces also gives us that \tilde{X} and \tilde{Y} are contained in complementary linear spaces, so $\deg(J(\tilde{X}, \tilde{Y})) = \deg(\tilde{X}) \deg(\tilde{Y})$; see [6, Example 18.17]. So, for generic $\alpha \in \mathbb{k}^{\times}$,

$$\deg(\alpha X + Y) = \deg\left(J(\tilde{X}, \tilde{Y})\right) = \deg(\tilde{X}) \deg(\tilde{Y}) = \deg(X) \deg(Y).$$

4 Hadamard products of projective varieties

We defined the Hadamard product of projective varieties $X, Y \subset \mathbb{P}^n$ as

$$X \star Y := \overline{\{p \star q : p \in X, q \in Y, p \star q \text{ is defined}\}} \subset \mathbb{P}^n$$

where $p \star q$ is the point obtained by entry-wise multiplication of the points p,q. Also in this case the operation of closure is crucial.

Example 4.1. Consider the Hadamard product between the rational normal curve $\mathscr{C}_3 = \{[a^3:a^2b:ab^2:b^3] \mid [a:b] \in \mathbb{P}^1\}$ in \mathbb{P}^3 and the point P = [0:1:1:0]. Now, we obviously have $\mathscr{C}_3 \star P \subset \{z_0 = z_3 = 0\}$. The equality follows because, if $ab \neq 0$, then we have that $[0:a:b:0] = [a^3:a^2b:ab^2:b^3] \star [0:1:1:0]$. However, in this case the operation of taking the closure is needed in order to get the entire line; indeed, the points [0:1:0:0] and [0:0:1:0] cannot be written as the Hadamard product of a point in \mathscr{C}_3 and the point P.

Another useful way to describe the Hadamard product of projective varieties is as a linear projection of the Segre product of X and Y, i.e., the variety obtained as the image of $X \times Y$ under the map

$$\psi_{n,n}: \qquad \mathbb{P}^n \times \mathbb{P}^n \longrightarrow \qquad \mathbb{P}^{n^2+2n},$$
$$([a_0:\ldots:a_n], [b_0:\ldots:b_n]) \mapsto [a_0b_0:a_0b_1:a_0b_2:\ldots:a_nb_{n-1}:a_nb_n].$$

If z_{ij} , with i = 0, ..., n, j = 0, ..., n, are the coordinates of the ambient space of the Segre product \mathbb{P}^{n^2+2n} , then the Hadamard product $X \star Y$ is the projection of $X \times Y$ with respect to the linear space $\{z_{ii} = 0 \mid i = 0, ..., n\}$.

Therefore, as observed in Note 2.1, if X and Y are irreducible, then $X \star Y$ is irreducible and the dimension of their Hadamard product is at most the sum of the dimensions of the original varieties, i.e., $\dim(X \star Y) \leq \dim(X) + \dim(Y)$.

Example 4.2. It is easy to find examples where equality does not hold. Actually, the dimension of the Hadamard product of two varieties can be arbitrary small. E.g.,

consider two skew lines in \mathbb{P}^3 as $H_{01} = H_0 \cap H_1 = \{[0:0:a:b] \mid [a:b] \in \mathbb{P}^1\}$ and $H_{23} = H_2 \cap H_3 = \{[c:d:0:0] \mid [c:d] \in \mathbb{P}^1\}$. Then $H_{01} \star H_{23}$ is empty.

A classic approach to compute the dimension of projective varieties is to look at their tangent space. From now, we consider $\mathbb C$ as the ground field in order to avoid fuzzy behaviors caused by positive characteristics or non algebraically closed fields. Also, this is the case we want to consider in our applications.

In the case of joins, there is a result by A. Terracini [14] which describes the tangent space of the join at a generic point in terms of the tangent spaces of the original varieties. In [1], the authors proved a version of this result for Hadamard products of projective varieties.

Lemma 4.3. [1, Lemma 2.12] Let $p \in X$ and $q \in Y$ be generic points, then the tangent space to the Hadamard product $X \star Y$ at the point $p \star q$ is given by

$$T_{p\star q}(X\star Y) = \langle p\star T_q Y, T_p X\star q \rangle.$$

Another powerful tool to study Hadamard products of projective varieties is tropical geometry. In particular, we have the following relation. Since we are not using tropical geometry elsewhere, here we assume the reader to be familiar with the concept of *tropicalization of a variety*. For the inexperienced reader, we suggest to read [10] for an introduction of the topic.

Proposition 4.4. [10, Proposition 5.5.11] Given two irreducible varieties $X, Y \subset \mathbb{P}^n$, the tropicalization of the Hadamard product of X and Y is the Minkowski sum of their tropicalizations, i.e.,

$$trop(X \star Y) = trop(X) + trop(Y)$$
.

Applying this result, in [1], the authors gave an upper-bound for the dimension of the Hadamard product of two varieties.

Proposition 4.5. [1, Proposition 5.4] Let $X,Y \subset \mathbb{P}^n$ be irreducible varieties. Let $H \subset (\mathbb{C}^*)^{n+1}/\mathbb{C}^*$ be the maximal subtorus acting on both X and Y and let $G \subset (\mathbb{C}^*)^{n+1}/\mathbb{C}^*$ be the smallest subtorus having a coset containing X and a coset containing Y. Then

$$\dim(X \star Y) \le \min\{\dim(X) + \dim(Y) - \dim(H), \dim(G)\}.$$

We call this upper bound *expected dimension* and denote it $\exp.\dim(X \star Y)$. However, this is not always the correct dimension. In [1], the authors present an example of a Hadamard product of two projective varieties with dimension strictly smaller than the expected dimension.

From the definition of the Hadamard product of two varieties, it makes sense also to analyze self Hadamard products of a projective variety. We call them *Hadamard powers* of a projective variety.

Definition 4.6. We define the s-th Hadamard power of a projective variety X as

$$X^{\star s} := X \star X^{\star (s-1)}$$
, for $s > 0$,

where $X^{\star 0} := [1 : ... : 1]$.

In general, a projective variety is not contained in its Hadamard powers. However, if $1_n = [1 : ... : 1] \in \mathbb{P}^n$ lies in the variety X, we get the following chain of non necessary strict inclusions

$$X \subset X^{\star 2} \subset \cdots \subset X^{\star s} \subset \cdots \subset \mathbb{P}^n. \tag{1}$$

Therefore, it becomes very natural to check if the Hadamard powers of a projective variety *X* eventually fill the ambient space. In general, the answer is no.

Proposition 4.7. Let X be a toric variety in \mathbb{P}^n . Then, $X = X^{*2}$.

Proof. Since any toric variety contains the point [1:...:1], it follows that $X \subset X^{*2}$. The other inclusion follows by applying Proposition 4.5 to the case X = Y = H. \square

Remark 4.8. Recently, C. Bocci and E. Carlini gave a necessary and sufficient condition for a plane irreducible curve $C \subset \mathbb{P}^2$ to have its *t*-th Hadamard power equal to the curve itself. This result has been shared with us in private communication and will appear in [3].

Remark 4.9. Proposition 4.7 can be proved directly by recalling that the ideals defining toric varieties are given by binomial ideals, namely ideals whose generators are differences of monomials as $f_{\alpha,\beta} = x^{\alpha} - x^{\beta}$, where $\alpha,\beta \in \mathbb{N}^{n+1}$ and we use the multi-index notation $x^{\alpha} := x_0^{\alpha_0} \cdots x_n^{\alpha_n}$.

Now, consider two points of X, $p = [p_0 : ... : p_n]$ and $q = [q_0 : ... : q_n]$. For any generator $f_{\alpha,\beta}$ of the ideal defining X, we have $p^{\alpha} - p^{\beta} = q^{\alpha} - q^{\beta} = 0$. Therefore,

$$\begin{split} (p\star q)^\alpha - (p\star q)^\beta &= p^\alpha q^\alpha - p^\beta q^\beta = p^\alpha q^\alpha - p^\alpha q^\beta + p^\alpha q^\beta - p^\beta q^\beta = \\ &= p^\alpha (q^\alpha - q^\beta) - q^\beta (p^\alpha - p^\beta) = 0; \end{split}$$

hence, $p \star q \in X$.

Remark 4.10. Given a projective variety $X \subset \mathbb{P}^n$, the *s-th secant variety* $\sigma_s(X)$ is the Zariski closure of the union of linear spaces spanned by *s* points lying on *X*. This is a very classical object that has been studied since the second half of 19-th century. In particular, we have a chain of non necessary strict inclusions given by

$$X \subset \sigma_2(X) \subset \ldots \subset \sigma_s(X) \subset \ldots \subset \mathbb{P}^n$$
.

Therefore, we can ask if the secant varieties of a variety X eventually fill the ambient space. It is not difficult to prove that the answer is no. Indeed, if H is a linear space, then $\sigma_2(H) = H$ and, therefore, if X is degenerate, i.e., it is contained in a proper linear subspace of \mathbb{P}^n , then its secant varieties do not fill the ambient space.

Hadamard powers of projective varieties may be viewed as the multiplicative version of the classical notion of secant varieties where instead of looking at the linear span of points lying on a variety we consider their Hadamard product. Moreover, by Proposition 4.7, we have that the role played by linear spaces in the case of secant varieties is taken by toric varieties in the case of Hadamard products.

Example 4.11. A concrete example satisfying the assumptions of Proposition 4.7 is the variety $X_1 \subset \mathbb{P}(\mathrm{Mat}_{m,n})$ of rank 1 matrices of size $m \times n$. Indeed, it is generated by the 2×2 minors of the generic matrix $(z_{ij})_{i=1,\dots,m}^{j=1,\dots,n}$. Therefore, $X_1^{\star 2} = X_1$. This gives another proof of the well-known fact that the Hadamard product of two rank 1 matrices is still of rank 1.

The latter example rises a very interesting question.

Question 4.12. What if we consider matrices of rank higher than 1? Can we decompose all matrices as Hadamard products of rank r > 1 matrices?

The answer is positive, as we show in the following proposition.

Proposition 4.13. Let M be a matrix of size $m \times n$ and fix $2 \le r \le \min\{m,n\}$. Then, M can be written as the Hadamard product of at most $\left\lceil \frac{\min\{m,n\}}{r-1} \right\rceil$ matrices of rank less or equal than r.

Proof. Without loss of generality, we may assume that $m \le n$ and let $\{v_1, \dots, v_m\}$ be the rows of the matrix M. Then, consider the following matrices $\left(N = \left\lceil \frac{m}{r-1} \right\rceil\right)$:

$$A_{1} = \begin{pmatrix} v_{1} \\ \vdots \\ v_{r-1} \\ 1_{n-r+1,n} \end{pmatrix}, A_{2} = \begin{pmatrix} 1_{r-1,n} \\ v_{r} \\ \vdots \\ v_{2r-1} \\ 1_{n-2r+1,n} \end{pmatrix}, \dots, A_{N} = \begin{pmatrix} 1_{(N-1)r-1,n} \\ v_{(N-1)r} \\ \vdots \\ v_{n} \end{pmatrix}.$$

Then, it is easy to check that $M = A_1 \star \cdots \star A_N$.

If $n \le m$, we do the same constructions, considering columns instead of rows.

Therefore, it makes sense to give the following definitions.

Definition 4.14. Let M be a matrix and fix $r \ge 2$. We call an r-th Hadamard decomposition of M an expression of the type $M = A_1 \star \ldots \star A_s$, where $\operatorname{rk}(A_i) \le r$. We define the r-th Hadamard rank of M as the smallest length of such a decomposition, i.e.,

$$\operatorname{Hrk}_r(M) = \min\{s \mid \text{there exist } A_1, \dots, A_s, \operatorname{rk}(A_i) \leq r, M = A_1 \star \dots \star A_s\}.$$

We define the *generic r-th Hadamard rank* of matrices of size $m \times n$ as

$$\operatorname{Hrk}_r^{\circ}(m,n) = \min\{s \mid X_r^{\star s} = \mathbb{P}(\operatorname{Mat}_{m,n})\},\$$

and the maximal r-th Hadamard rank of matrices of size $m \times n$ as

$$\operatorname{Hrk}_r^{\max}(m,n) = \max\{\operatorname{Hrk}_r(M) \mid M \in \operatorname{Mat}_{m,n}\}.$$

We remark that these definitions may be seen as the multiplicative versions of the more common notion of *tensor ranks*, where we consider *additive decompositions* of tensors as sums of decomposable tensors. In terms of matrices, we look at decomposition as sums of rank 1 matrices. A massive amount of work has been devoted to problems related to tensor ranks during the last few decades, especially due to their applications to statistics, data analysis, signal process, and others. See [9] for a complete exposition of the current state of the art.

Hadamard product of matrices, i.e., the entrywise product, is the naïve definition for matrix multiplication that any school student would hope to study. Even if it is not the standard multiplication we have been taught, it is a very interesting operation, with nice properties and applications in matrix analysis, statistics and physiscs. As mentioned in the introduction, the generalization to the case of tensors has been used in data mining and quantum information [4, 8]. We look at it from a geometric point of view, by studying Hadamard powers of varieties of matrices.

For a fixed positive integer $r \le \min\{m, n\}$, we denote by $X_r \subset \mathbb{P}(\mathrm{Mat}_{m,n})$ the variety of matrices of size $m \times n$ with rank at most r. In other words, X_r is the r-th secant variety of the Segre product $\mathbb{P}^{m-1} \times \mathbb{P}^{n-1}$. These are well-studied classic objects. Since $1_{m,n}$, the matrix of all 1's, which is the identity element for the Hadamard product, is contained in the variety X_r , we have a chain of inclusions as in (1).

Remark 4.15. Our aim is to study Hadamard powers of the varieties X_r of matrices with rank at most r. As we observed before, we can view the Hadamard power $X_r^{\star 2}$ as a linear projection of the Segre product $X_r \times X_r$. In terms of matrices, this is the geometric translation of the well-known fact that the Hadamard product of two matrices is a submatrix of their Kronecker product. Indeed, if $M = (m_{i,j}) \in \operatorname{Mat}_{m,n}$ and $N = (n_{i,j}) \in \operatorname{Mat}_{m,n}$, we define the Kronecker product as $M \otimes N = (m_{i,j}n_{h,k}) \in \operatorname{Mat}_{m^2,n^2}$. Then, $M \star N = (M \otimes N)|_{I,J}$, where $(M \otimes N)|_{I,J}$ denotes the restriction on the indexes $I = \{1, m+2, 2m+3, \ldots, m^2\}$ and $J = \{1, n+2, 2n+3, \ldots, n^2\}$.

Hadamard powers of a specific space of tensors has been considered in [4] as the geometric interpretation of a particular statistical model. Therefore, we believe that the definitions of Hadamard ranks of matrices, and more generally of tensors, are very natural and may be an interesting area of research from several perspectives.

Proposition 4.13 gives us an upper bound on the r-th Hadamard rank, i.e.,

$$\operatorname{Hrk}_r^{\max}(m,n) \leq \left\lceil \frac{\min\{m,n\}}{r-1} \right\rceil.$$

We can also give a lower bound on the generic rank as a straightforward application of the following well-known property of Hadamard product of matrices.

Lemma 4.16. Given two matrices A, B, we have that $\operatorname{rk}(A \star B) < \operatorname{rk}(A)\operatorname{rk}(B)$.

Proof. Say that $rk(A) = r_1$ and $rk(B) = r_2$. Consider the additive decomposition of A and B as sums of rank 1 matrices, i.e.,

$$A = \sum_{i=1}^{r_1} a_i \cdot b_i^{\mathrm{T}} \text{ and } B = \sum_{j=1}^{r_2} c_j \cdot d_j^{\mathrm{T}},$$

where a_i, b_i, c_j, d_j are column vectors. Then, we get that

$$A \star B = \sum_{i=1}^{r_1} \sum_{j=1}^{r_2} (a_i \star c_j) \cdot (b_i \star d_j)^{\mathrm{T}}.$$

Therefore, we have that $\operatorname{rk}(A \star B) \leq r_1 r_2$.

As an immediate consequence of this lemma we see that that $X_r^{\star 2} \subset X_{r^2}$, for any r. In particular, we obtain a lower bound on the generic Hadamard rank.

Corollary 4.17. Fix $r \ge 2$. Then, the generic r-th Hadamard rank of matrices of size $m \times n$ is at least $\lceil \log_r(\min\{m,n\}) \rceil$.

Proof. If $s < \lceil \log_r(\min\{m,n\}) \rceil$, then $r^s < \min\{m,n\}$. Hence, the Hadamard product of s matrices of rank r cannot have maximal rank and, therefore, it cannot be enough to cover all the space of matrices of size $m \times n$.

Therefore, we have the following chain of inequalities.

$$\lceil \log_r(\min\{m,n\}) \rceil \le \operatorname{Hrk}_r^{\circ}(m,n) \le \operatorname{Hrk}_r^{\max}(m,n) \le \left\lceil \frac{\min\{m,n\}}{r-1} \right\rceil. \tag{2}$$

By this chain of inclusions we get the following result.

Proposition 4.18. *Let* $m \le n$ *and consider* r = m - 1. *Then, we have*

$$\operatorname{Hrk}_{m-1}^{\circ}(m,n) = \operatorname{Hrk}_{m-1}^{\max}(m,n) = 2.$$

Proof. On the left hand side of (2) we have $\lceil \log_{m-1}(m) \rceil = 2$.

On the right hand side, we have $\lceil \frac{m}{m-2} \rceil$, which is equal to 2 if $m \ge 4$. Then, in order to conclude, we just need to prove the case m = 3.

Let m = 3. If we consider a matrix M of rank ≤ 2 , then it lies on X_2 . Assume that M has rank 3 and let $v_i = (v_{i,1}, \dots, v_{i,n})$, for i = 1, 2, 3, be the rows of M. Consider the first two rows. If $v_{1,j}$ and $v_{2,j}$ are not both equal to zero, for all $j = 1, \dots, n$, then there exists a linear combination of $\lambda v_1 + \mu v_2$ with all entries different from zero and, therefore, we can decompose M as follows

$$M = \begin{pmatrix} v_{1,1} & \dots & v_{1,n} \\ v_{2,1} & \dots & v_{2,n} \\ \lambda v_{1,1} + \mu v_{2,1} & \dots & \lambda v_{1,n} + \mu v_{2,n} \end{pmatrix} \star \begin{pmatrix} 1 & \dots & 1 \\ 1 & \dots & 1 \\ \frac{v_{3,1}}{\lambda v_{1,1} + \mu v_{2,1}} & \dots & \frac{v_{3,n}}{\lambda v_{1,n} + \mu v_{2,n}} \end{pmatrix}.$$

If we have $v_{1,j} = v_{2,j} = 0$, for some j = 1, ..., n, any linear combination of v_1 and v_2 will have the *j*-th entry equal to zero. Therefore, we cannot use the previous

algorithm. Hence, we define \tilde{v}_i , for i = 1, 2, as

$$\widetilde{v}_{i,j} = \begin{cases} v_{i,j} & \text{if } v_{1,j} \neq 0 \text{ or } v_{2,j} \neq 0; \\ 1 & \text{if } v_{1,j} = v_{2,j} = 0. \end{cases}$$

Now, there exists a linear combination of $\lambda \tilde{v}_1 + \mu \tilde{v}_2$ with all entries different from zero. Therefore, if we define a row u as

$$u_i = \begin{cases} 1 & \text{if } v_{1,j} \neq 0 \text{ or } v_{2,j} \neq 0; \\ 0 & \text{if } v_{1,j} = v_{2,j} = 0, \end{cases}$$

we can decompose M as

$$M = \begin{pmatrix} \widetilde{v}_{1,1} & \dots & \widetilde{v}_{1,n} \\ \widetilde{v}_{2,1} & \dots & \widetilde{v}_{2,n} \\ \lambda \widetilde{v}_{1,1} + \mu \widetilde{v}_{2,1} & \dots & \lambda \widetilde{v}_{1,n} + \mu \widetilde{v}_{2,n} \end{pmatrix} \star \begin{pmatrix} u_1 & \dots & u_n \\ u_1 & \dots & u_n \\ \frac{v_{3,1}}{\lambda \widetilde{v}_{1,1} + \mu \widetilde{v}_{2,1}} & \dots & \frac{v_{3,n}}{\lambda \widetilde{v}_{1,n} + \mu \widetilde{v}_{2,n}} \end{pmatrix}.$$

Therefore, $Hrk_2^{max}(3, n) = 2$.

Example 4.19. Consider the matrix $M = \begin{pmatrix} 1 & 2 & 0 & 1 \\ -1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 2 \end{pmatrix}$. Then, we consider

$$\tilde{v}_1 = (1, 2, 1, 1), \ \tilde{v}_2 = (-1, 1, 1, 0), \ u = (1, 1, 0, 1).$$

Hence,

$$M = \begin{pmatrix} 1 & 2 & 1 & 1 \\ -1 & 1 & 1 & 0 \\ 1 & 5 & 3 & 2 \end{pmatrix} \star \begin{pmatrix} 1 & 1 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & \frac{1}{5} & \frac{1}{3} & 1 \end{pmatrix}.$$

Remark 4.20. We proved that for $r = \min\{m, n\} - 1$, the r-th Hadamard rank is equal to 2. Actually, the upper-bound in (2) let us be more precise. Indeed, we can say that for any $\frac{\min\{m, n\} + 2}{2} < r < \min\{m, n\}$, we get $\operatorname{Hrk}_r^{\circ}(m, n) = 2$.

In other cases, we need a more geometric approach in order to understand the generic Hadamard rank. By using Proposition 4.5, we can define the expected dimension for the s-th Hadamard power of the variety X_r of rank r matrices.

Proposition 4.21. *In the same above notation,*

$$\dim(X_r^{\star s}) \le \min\left\{s\dim(X_r) - (s-1)\dim(X_1), \dim \mathbb{P}(\mathrm{Mat}_{m,n})\right\}. \tag{3}$$

Proof. We proceed by induction on *s*. For s = 1, it follows trivially from definitions. Consider s > 1. Then, since $X_r^{\star s} = X_r^{\star (s-1)} \star X_r$, by Proposition 4.5 and by inductive hypothesis, we get

$$\begin{split} \dim(X_r^{\star s}) &\leq \min \big\{ \dim(X_r^{\star (s-1)}) + \dim(X_r) - \dim(X_1), \dim \mathbb{P}(\mathrm{Mat}_{\mathrm{m,n}}) \big\} \\ &= \min \big\{ s \dim(X_r) - (s-1) \dim(X_1), \dim \mathbb{P}(\mathrm{Mat}_{\mathrm{m,n}}) \big\}. \end{split}$$

We refer to the formula on the right hand side of (3) as the *expected dimension* of $X_r^{\star s}$. More precisely, we have the following

exp. dim
$$(X_r^{*s})$$
 = min $\{s \operatorname{dim}(X_r) - (s-1) \operatorname{dim}(X_1), \operatorname{dim} \mathbb{P}(\operatorname{Mat}_{m,n})\}$
= min $\{sr(n+m-r) - (s-1)(n+m-1), mn\} - 1$.

Therefore, the expected generic r-th Hadamard rank is

$$\exp.\operatorname{Hrk}_{r}^{\circ}(m,n) = \left\lceil \frac{\dim \mathbb{P}(\operatorname{Mat}_{m,n}) - \dim(X_{1})}{\dim(X_{r}) - \dim(X_{1})} \right\rceil = \left\lceil \frac{mn - (m+n-1)}{r(m+n-r) - m - n + 1} \right\rceil \tag{4}$$

Remark 4.22. A very important concept in the world of tensors additive decomposition is the idea of *identifiability*, namely, we say that a tensor is *identifiable* if it has a unique decomposition as sum of decomposable tensors. Since we are viewing Hadamard decomposition as a multiplicative version of tensor decomposition, we might look for identifiability also in this set up. However, in this case, we cannot have identifiability for any matrix. Indeed, consider a r-th Hadamard decomposition of a matrix M, i.e., we have

$$M = A_1 \star \cdots \star A_s$$
, with $\operatorname{rk}(A_i) = r$;

then, for any (s-1)-tuple of rank 1 matrices R_1, \dots, R_{s-1} , all with non-zero entries, we can construct a different r-th Hadamard decomposition as

$$M = (R_1 \star A_1) \star \cdots \star (R_{s-1} \star A_{s-1}) \star ((R_1 \star \cdots \star R_{s-1})^{\star (-1)} \star A_s),$$

where $R^{\star(-1)}$ denotes the Hadamard inverse of the matrix R. Here, we have to recall that $\operatorname{rk}(R_i \star A_i) \leq \operatorname{rk}(A_i)$, for any $i = 1, \dots, s-1$, by Lemma 4.16, and, similarly, we have $\operatorname{rk}\left((R_1 \star \cdots \star R_{s-1})^{\star(-1)} \star A_s\right) \leq \operatorname{rk}(A_s)$, because $\operatorname{rk}(R_1 \star \cdots \star R_{s-1})^{\star(-1)} = 1$.

We can check that (3) is the actual dimension and, consequently, (4) gives the correct generic r-th Hadamard rank for matrices of small size.

Here we describe an algorithm written with *Macaulay2* to compute the dimensions of Hadamard powers of varieties of square matrices of given rank. This allows us to compute the corresponding generic Hadamard ranks (Table 1). We reduced to square matrices for simplicity of exposition, but the code can be easily generalized.

The key point is to use Lemma 4.3 which states that the tangent space to $X_r^{\star s}$ at a generic point $A_1 \star \cdots \star A_s$ is given by

$$T_{A_1 \star \dots \star A_s}(X_r^{\star s}) = \langle T_{A_1}(X_r) \star A_2 \star \dots \star A_s, \dots, A_1 \star \dots \star A_{s-1} \star T_{A_s}(X_r) \rangle \tag{5}$$

Hence, we first need to construct the tangent spaces at s random points of X_r .

П

Recall that, if *A* is a matrix of rank *r* written as $A = \sum_{i=1}^{r} u_i \cdot v_i^T$, $u_i, v_i \in \mathbb{C}^n$, the tangent space of X_r at *A* is given by

$$T_A(X_r) = \left\langle u_1 \cdot (\mathbb{C}^n)^T + (\mathbb{C}^n) \cdot v_1^T, \dots, u_r \cdot (\mathbb{C}^n)^T + (\mathbb{C}^n) \cdot v_r^T \right\rangle.$$

Here is Macaulay2 code.

```
______
INPUT: n = sizes of matrices;
       r = rank of matrices;
       s = Hadamard power to compute;
OUTPUT: D = dimension of the s-th Hadamard power of
          the variety of rank r matrices of size nxn.
   S := QQ[z_{1},1)..z_{n},
            a_{(1,1)}..a_{(n,r)}, b_{(1,1)}..b_{(n,r)},
           c_{(1,1)..c_{(2*r,n)}};
---- Construct s random matrices of rank r
   u = for i from 1 to s list
            for j from 1 to 2*r list
                random(S^n, S^{\{0\}});
   A = for i from 0 to (s-1) list sum (
            for j from 0 to (r-1) list
                 u_i_(2*j) * transpose(u_i_(2*j+1))
       );
---- Construct their tangent spaces
   C = for i from 1 to 2*r list
            genericMatrix(S,c_(i,1),n,1);
    TA = for i from 0 to (s-1) list sum
             for j from 0 to (r-1) list
                 u_i_(2*j) * transpose C_(2*j) +
                     C_{(2*j+1)} * transpose(u_{i_{(2*j+1)}});
```

Now, we construct the vector spaces spanning the tangent space of $X_r^{\star s}$ as in (5). First, we define a function HP to compute the Hadamard product of two matrices.

```
---- Method to construct the Hadamard product of a
---- list of matrices of same size;
  HP = method();
  HP List := L \rightarrow (
    s := \#L;
   r := numRows(L_0);
   c := numColumns(L_0);
    for i from 1 to (s-1) do
      if (numRows(L_i)!=r or numColumns(L_i)!=c) then
          return << "error";</pre>
    H := for i from 0 to (r-1) list
           for j from 0 to (c-1) list product (
              for h from 0 to (s-1) list (L_h)_{j-1}
              );
   return matrix H
---- Construct the two vector spaces spanning the tangent
---- space of the Hadamard power and find their equations
---- in the space of matrices
```

In E, we have the list of the equations of the tangent spaces to the variety X_r at the s random points. From these, we can construct a vector basis for each tangent space. Now, in order to compute the dimension of their span it is enough to compute the rank of the matrix obtained by collecting all these vector basis together.

In the following table, we list the generic r-th Hadamard ranks that we have computed for square matrices of small size.

n	r	r-th Hadamard rank	n	r	r-th Hadamard rank	n	r	r-th Hadamard rank
3	2	2	9	4	2	12	5	2
4	2	2		5	2		6	2
5	2	3	10	2	5	13	2	7
	3	2		3	3		3	4
6	2	3		4	2		4	3
	3	2		5	2		5	2
7	2	4	11	2	6		6	2
	3	2		3	3		7	2
	4	2		4	2	14	2	7
8	2	4		5	2		3	4
	3	3		6	2		4	3
	4	2	12	2	6		5	2
9	2	5		3	4		6	2
	3	3		4	3		7	2

Table 1 Generic *r*-th Hadamard ranks of square matrices of size $n \times n$ with $n \le 14$. By Remark 4.20, we could restrict to the cases $r < \frac{n+2}{2}$; for $r \ge \frac{n+2}{2}$, we know that $\operatorname{Hrk}^{\circ}_{r}(n,n) = 2$. This computation required less than 9 minutes on a laptop with a processor 2,2GHs Intel Core i7.

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