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Memoryless Determinacy of Finite Parity Games: Another Simple Proof $\stackrel{\bigstar, \bigstar}{\Rightarrow}$

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Abstract

Memoryless determinacy of (infinite) parity games is an important result with numerous applications. It was first independently established by Emerson and Jutla [1] and Mostowski [2] but their proofs involve elaborate developments. The elegant and simpler proof of Zielonka [3] still requires a nested induction on the finite number of priorities and on ordinals for sets of vertices. There are other proofs for finite games like the one of Björklund, Sandberg and Vorobyovin [4] that relies on relating infinite and finite duration games. We present here another simple proof that finite parity games are determined with memoryless strategies using induction on the number of relevant states. The closest proof that relies on induction over non absorbing states is the one of Grädel [5]. However instead of focusing on a single appropriate vertex for induction as we do here, he considers two reduced games per vertex, for all the vertices of the game. The idea of reasoning about a single state has been inspired to me by the analysis of finite stochastic priority games by Karelovic and Zielonka [6].

Keywords: Game Theory, Determinacy, Memoryless Strategy

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1. Parity Games

A parity game is a graph where vertices have integer priorities. In addition every vertex is owned by one of the two players and has at least one successor.

Definition 1. A parity game $G = (V, E, \pi)$ is defined by:

- A finite set of vertices $V = V_0 \uplus V_1$;
- A set of edges $E \subseteq V \times V$ such that for all $v \in V$ there exists $(v, w) \in E$;
- A priority mapping $\pi: V \to \mathbb{N}$.

The set of players is $\{0, 1\}$. The parity of an integer p (i.e. $p \mod 2$) will be denoted more concisely by \hat{p} . Given a vertex v, player P_v is the owner of v: $\mathsf{P}_v = 0$ if and only if $v \in V_0$.

Example 1. Figure 1 describes a parity game. The vertices owned by Player 0 (resp. 1) are represented by circles (resp. squares). The priorities are noted inside vertices.



Figure 1: A parity game.

A play is a non empty finite or infinite sequence $v_0v_1...$ such for all *i* if v_{i+1} is defined then $(v_i, v_{i+1}) \in E$. Consider an infinite play $\rho \in V^{\omega}$. Then $\max(\rho)$ is the maximal priority occurring infinitely often along the vertices of ρ . The winner of the play ρ is Player $\max(\rho)$.

Example 2. $\rho = v_4 v_2 (v_1 v_0)^{\omega}$ is a play of the game of Figure 1 winning for Player 1.

A strategy σ for player P is a mapping from finite plays ending in V_{P} to V such that $(v_n, \sigma(v_0 \dots v_n)) \in E$. An infinite play $\rho = v_0 v_1 \dots$ is σ -compatible if for all $v_n \in V_{\mathsf{P}}, v_{n+1} = \sigma(v_0 \dots v_n)$. A strategy is *memoryless* if it only depends on the last state of the play. **Definition 2.** Let G be a parity game. Then the winning set $W_P(G)$ of a player P is the set of vertices v for which there exists a strategy σ of P such that all σ -compatible (infinite) plays starting in v are winning for P.

Example 3. $W_1(G) = \{v_0, v_1\}$ with Player 1 choosing the edge (v_0, v_1) in v_0 while $W_0(G) = \{v_2, v_3, v_4\}$ with Player 0 choosing the edge (v_2, v_4) in v_2 . Thus these winning strategies are memoryless.

A vertex v of G is absorbing if $\{v\} = \{w \mid (v, w) \in E\}$. A vertex v of G is vanishing if $\{w \mid (w, v) \in E\} = \emptyset$. A vertex is relevant if it is neither absorbing nor vanishing. Given a game, we split V in the set of absorbing states $V_{\rm a}$, the set of vanishing states $V_{\rm v}$ and the set of relevant states $V_{\rm r}$.

2. Memoryless determinacy

Theorem 1. For all parity games G, $V = W_0(G) \uplus W_1(G)$ and furthermore:

- The corresponding strategies σ_0 and σ_1 are memoryless;
- For all P ∈ {0,1},
 a σ_P-compatible play starting in W_P(G) never leaves W_P(G).

Proof. The proof is done by induction on the size of $|V_r|$.

• When $|V_{\rm r}| = \emptyset$, by definition of $V_{\rm v}$ and $V_{\rm a}$ all strategies are memoryless and the winning sets are defined as follows.

$$W_{\mathsf{P}}(G) = \{ v \in V_{\mathsf{a}} \mid \widehat{\pi(v)} = \mathsf{P} \}$$
$$\cup \{ v \in V_{\mathsf{v}} \cap V_{\mathsf{P}} \mid \exists (v, w) \in E \ \widehat{\pi(w)} = \mathsf{P} \}$$
$$\cup \{ v \in V_{\mathsf{v}} \setminus V_{\mathsf{P}} \mid \forall (v, w) \in E \ \widehat{\pi(w)} = \mathsf{P} \}$$

• Otherwise pick some $v \in V_r$ with maximal priority, denoted p. Let G^+ be the game obtained from G by adding an absorbing state \tilde{v} with priority and owner of v and then redirecting incoming edges of v to \tilde{v} (see Figure 2).

- $V_{\mathbf{r}}^+ = V_{\mathbf{r}} \setminus \{v\}, V_{\mathbf{a}}^+ = V_{\mathbf{a}}^+ \cup \{\tilde{v}\} \text{ and } V_{\mathbf{v}}^+ = V_{\mathbf{v}} \cup \{v\};$
- The owners of vertices are unchanged and $\mathsf{P}_{\tilde{v}} = \mathsf{P}_{v}$.
- For all $(u, u') \in E \cap V \times V \setminus \{v\}, (u, u') \in E^+;$

- $(\tilde{v}, \tilde{v}) \in E^+$ and for all $(u, v) \in E$, $(u, \tilde{v}) \in E^+$;
- The priorities are unchanged and $\pi(\tilde{v}) = p$.

The graph G^+ fulfills: $|V_r^+| = |V_r| - 1$. So the induction applies. Given a player P, let σ_{P}^+ be a memoryless winning strategy of P in G^+ .



Figure 2: From G to G^+

We claim that $W_{1-\hat{p}}(G^+) \subseteq W_{1-\hat{p}}(G)$. Consider in G, a $\sigma^+_{1-\hat{p}}$ -compatible play ρ starting in $W_{1-\hat{p}}(G^+)$. Then it will never visit v except possibly initially. So ρ is a $\sigma^+_{1-\hat{p}}$ -compatible play in G^+ starting in $W_{1-\hat{p}}(G^+)$. Hence ρ is winning for Player $1 - \hat{p}$.

• Case $v \in W_{\hat{p}}(G^+)$. Consider ρ a $\sigma_{\hat{p}}^+$ -compatible play in G starting in $W_{\hat{p}}(G^+) \setminus \{\tilde{v}\}$. By definition of G^+ and the property of strategy $\sigma_{\hat{p}}^+$, it will never leave $W_{\hat{p}}(G^+)$.

- Either ρ visits finitely often v and then some suffix is a $\sigma_{\hat{p}}^+$ -compatible play of G^+ starting in $W_{\hat{p}}(G^+)$. So this suffix and ρ are winning for Player \hat{p} .
- Or ρ visits infinitely often v and thus never visits $V_{\rm a}$. Also observe that it may only initially visit $V_{\rm v}$. So the maximal priority of ρ is p and thus is winning for Player \hat{p} .

So $W_{\hat{p}}(G^+) \setminus {\tilde{v}} \subseteq W_{\hat{p}}(G)$. Since $W_{1-\hat{p}}(G^+) \subseteq W_{1-\hat{p}}(G)$ memoryless determinacy is established.

• Case $v \in W_{1-\hat{p}}(G^+)$. Let us build an auxiliary game G^- from G by making v absorbing and changing its priority to p+1 (see Figure 3):



Figure 3: From G to G^-

The graph G^- fulfills: $|V_r^-| < |V_r|$. Thus the induction applies. We claim that for all player P, $W_P(G) = W_P(G^-)$. Given a player P, let σ_P^- be a memoryless winning strategy of P in G^- .

• Define a memoryless strategy $\sigma_{\hat{p}}$ obtained by arbitrarily modifying $\sigma_{\hat{p}}^-$ for v if $\mathsf{P}_v = \hat{p}$. Consider in G, a $\sigma_{\hat{p}}$ -compatible play ρ starting in $\mathsf{W}_{\hat{p}}(G^-)$. Then ρ will never visit v otherwise there would be a $\sigma_{\hat{p}}^-$ -compatible play in G^- reaching v. So ρ is a play in G^- and thus winning for Player \hat{p} .

• Define a memoryless strategy $\sigma_{1-\hat{p}}$ by $\sigma_{1-\hat{p}}^+$ over $V_{1-\hat{p}} \cap W_{1-\hat{p}}(G^+)$ and by $\sigma_{1-\hat{p}}^-$ over $V_{1-\hat{p}} \setminus W_{1-\hat{p}}(G^+)$. Consider in G, a $\sigma_{1-\hat{p}}$ -compatible play ρ starting in $W_{1-\hat{p}}(G^-)$.

- Either ρ never visits $W_{1-\hat{p}}(G^+)$. Then ρ is a $\sigma_{1-\hat{p}}^-$ -compatible play in G^- and so winning for Player $1-\hat{p}$.
- Or a suffix of ρ is a $\sigma^+_{1-\hat{p}}$ -compatible play in G^+ and so ρ is winning for Player $1 \hat{p}$.

Observations. There are two main differences with the proof in [5]. First we pick a single vertex in G for the induction but more importantly G^+ is somewhat a partial unfolding of G while the reduced graphs considered in [5] only consist in making some vertex w absorbing and possibly changing its priority (like G^-). In particular, the winning sets of G^+ allow to decide the status of v in G while a graph where w has been made absorbing may provide information for the status of any vertex but w (and this is the way it is exploited in [5]). From an algorithmic point of view, the above proof leads to a (highly inefficient) recursive algorithm in $O(2^{|V|}D)$ where D is the outgoing degree of G.

3. Illustration



Figure 4: The favourable case.

We illustrate the favourable case (i.e. without use of G^-) and the unfavourable case on the game of Figure 1. The relevant vertex with maximal priority is v_4 . The corresponding graph G^+ is depicted in Figure 4 obtained by "duplicating" v_4 . Since $v_4 \in W_0(G^+)$, the strategies for G^+ can be applied to G. The thick edges are the ones selected by the strategies; the dotted edges are the discarded ones and the other ones are irrelevant for the winning sets.

Let us apply our proof on the intermediate graph depicted in Figure 4. To obtain its winning sets, one duplicates v_2 as depicted in Figure 5 producing the graph $(G^+)^+$. Since $v_2 \in W_0((G^+)^+)$, one needs to build the graph $(G^+)^-$ as depicted in Figure 6. Observe that after solving this game, v_3 and v_4 have moved from one winning set to another one.

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Figure 5: The unfavourable case.



Figure 6: The graph $(G^+)^-$.

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