



Resource aggregation in task-based applications over accelerator-based multicore machines SIAM PP16

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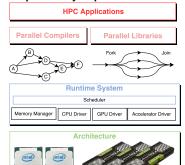
Current Computing Platforms and Runtime Systems



Clusters are increasingly:

- Using CPUs with more cores
- Using GPUs/Accelerators
- Heterogeneous

Design of runtime systems For portability of performances



Current Computing Platforms and Compute Grain

- 0 1 2 3 4 5 12 13 14 15 16 17
 - Intel® Xeon® Processor F5-2600 v3

- Few independent cores
- Low computing power
 ⇒ Need many small computation
- All at once
- · High computing power
- ⇒ Need one big computation

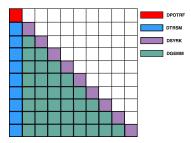


How to meet both CPU and GPU's needs when used concurrently?

Usual approach: trade-off between CPU and GPU cases

Example with a cholesky factorization

For CPUs

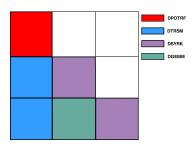


Cholesky Factorization with k = 0 and MT = 10

Usual approach: trade-off between CPU and GPU cases

Example with a cholesky factorization

For a GPU

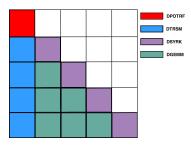


Cholesky Factorization with k = 0 and MT = 3

Usual approach: trade-off between CPU and GPU cases

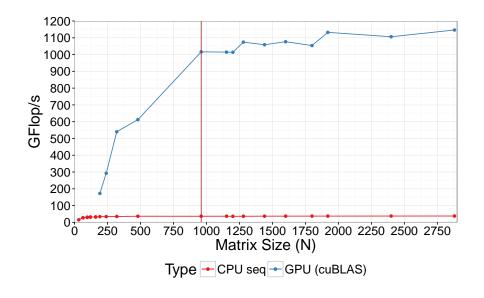
Example with a cholesky factorization

For both: use an intermediate block size

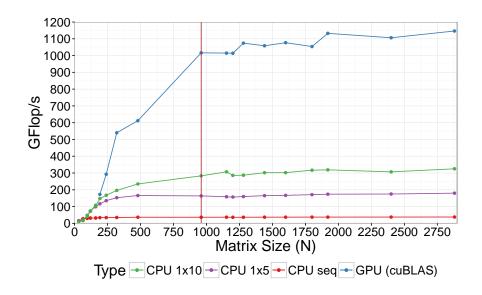


Cholesky Factorization with k=0 and MT=5

Case study: DGEMM CPU vs GPU performance

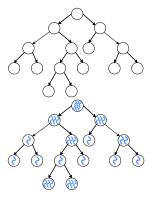


Case study: DGEMM CPU vs GPU performance



Another approach: parallel tasks

Proposed solution



Two parallelism levels

- Task parallelism
- Internal-task parallelism

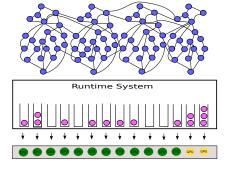
A task has a new parameter: the amount of threads it can run on.

Here:

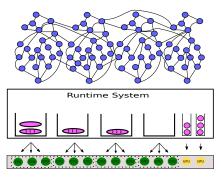
- Task parallelism: StarPU
- Internal parallelism: can be anything.
 Good candidate: OpenMP (Parallel MKL)

Clustering CPU cores

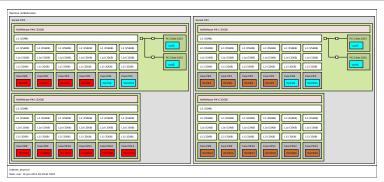
Usual StarPU use case



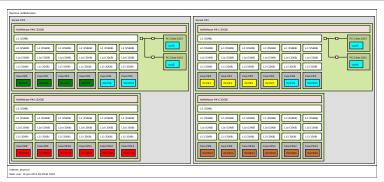
StarPU with clustered cores



Example: clustering inside processors' sockets



Example: clustering inside processors' NUMA nodes



Example: GNU OpenMP for internal parallelism

Aim: ensure the internal runtime uses the StarPU assigned resources for the task.

Before task execution

```
void starpu_gnu_openmp_mkl_prologue(void *ctx)
{
   /* get the CPUs of the current context */
   int cpus[MAX_WORKERS];
   int ncpus = starpu_get_cpus(ctx, cpus);

/* bind openmp threads to CPUs */
   #pragma omp parallel num_threads(ncpus)
   bind_to_cpu(cpus[omp_get_thread_num()]);
}
```

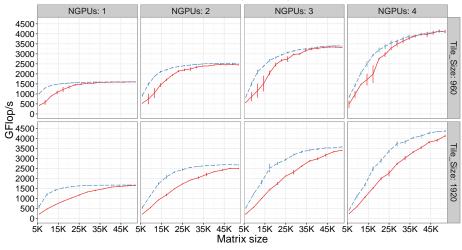
Fetch available resources

Create and bind thread team

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Exhaustive study

2 Xeon E5-2680 v3 @ 2.5GHz (12 cores) + 4 GPUs K40m



Type - 20x1 -- 2x10

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Why are we better?

Some answers or guesses come naturally:

		DPOTRF	DTRSM	DSYRK	DGEMM
960	1 core	1.8	8.8	25.4	28.6
	5 cores	0.42	2.0	5.4	6.3
	10 cores	0.34	1.3	3.7	3.6
1920	1 core	5.8	18.5	30.3	30.7
	5 cores	1.28	4.0	6.6	6.5
	10 cores	0.78	2.1	3.5	3.6

- Homogeneization of CPU and GPU granularity of computations
- New compromises on tile size

But to really understand, we tried several things.

- Scheduling study
- Bounds computation

Scheduling: dmda with tile size of 1920 and 12 tiles

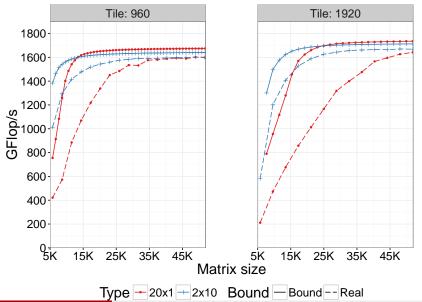




Parallel tasks

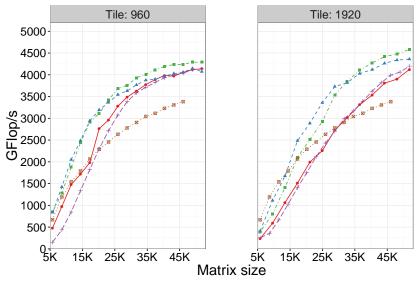


2 Xeon E5-2680 v3 @ 2.5GHz (12 cores) + 1 GPU K40m



Comparison with existing frameworks

2 Xeon E5-2680 v3 @ 2.5GHz (12 cores) + 4 GPUs K40m



Conclusion

Summary

- Implementation of parallel tasks model in StarPU
- Interface to manage a static partition/clustering of the machine
- Good performance obtained on sirocco with cholesky
- Looked at several aspects to understand the gains
 - Scheduling study
 - Bounds computation

Future/Ongoing works

- Use Intel KNL as soon as available!
- Schedulers able to manage resource size?
- Tests on more algorithms/kernels to come!
- Explore the "opposite": splitting tasks.

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