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Nullable Type Inference

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We present type inference algorithms for nullable types in ML-like programming languages. Starting with a simple system, presented as an algorithm, whose only interest is to introduce the formalism that we use, we replace unification by subtyping constraints and obtain a more interesting system. We state the usual properties for both systems. This is work in progress.

1 Nullable vs. option types

Impressive programming languages, such as C or Java derivatives, make abundant use of NULL either as a value for unknown or invalid references, or as failure return values. Using NULL is rather practical, since the if statement suffices for checking NULL-ity. Of course, the downside of having NULL as a possible value is that, without further support, it could accidentally be confused with a legal value, leading to execution errors [7].

In languages using the ML type discipline, the option type

    type α option = None | Some of α

injects regular values and the nullary data constructor None, into a single type that could be thought as a nullable type. The type system guarantees that options cannot be confused with regular values, and pattern-matching is used to check and extract regular values from options. In Haskell, the “maybe” data type is heavily used for representing successes and failures. The JaneStreet Core library [9] uses the option type to show possible failures in function types: it purposely and fails. The JaneStreet Core library [9] uses the and extract regular values from options. In Haskell, the with regular values, and pattern-matching is used to check into a single type that could be thought as a nullable type.

For instance, unaligned addresses on 64-bits architectures, which may refrain experienced programmers from heavily using options. Avoiding those memory allocations is not really difficult: if Some(v) is represented as v itself, that is, without allocating a block tagged as Some, we need a special representation for None, distinct from the representation of v, for any v. Of course, when v is None itself, it then becomes impossible to distinguish Some(None) from None. Therefore, None is not the only special case that needs a special treatment: the whole range of Some(n) values, for n ≥ 0 needs a special representation such that Some(None) cannot be confused with None(n) when i ≠ j.

For instance, unaligned addresses on 64-bits architectures, or a statically pre-allocated array of a sufficient size could do the job.

Now, the compilation of Some(expr) needs to generate a test, in order to use the special representation of Some(None) when expr evaluates to None, and pattern-matching against Some/None also needs to be adjusted.

This paper does not aim at opposing nullable types to option types. Options, in the Hindley-Milner type discipline, offer not only type safety, but also precision by distinguishing Some(None) from None, but at the price of a memory allocation or a dynamic test for Some. On the other hand, nullable types extend any classical type i into i?, to include NULL. Such “nullable values” are easier to represent and compile than options, but offer less precision since it makes no sense to extend further ?i. Also, their static inference haven’t received much attention, so far. Indeed, although quite a few recent programming languages statically check the safety of NULL [3, 2, 11, 1], none of them really performs type inference in the ML sense, but rather local inference, propagating mandatory type annotations of function parameters inside the function bodies.

2 Nullable type inference

The purpose of this work is to study type inference of nullable types, by adding them as a feature in a small functional language. The language that we consider, given in figure 1, is a classical mini-ML, extended with NULL test and creation. Section 3 starts with a naïve approach, where the types

![Figure 1: The language](image)

(1) Although polymorphic recursion theoretically allows for unbounded depth of Some(α)?(None) while this representation allows for representing only a finite number of n, this limitation should never be met in practice.
TConst
\[ \Phi \vdash \tau = \Gamma(c) \triangleright \Phi' \]

\[ \Phi, \Gamma \vdash c : \tau \triangleright \Phi' \]

TInstVar
\[ \Phi \vdash t' \equiv \tau \triangleright \Phi' \]

\[ \Phi, \Gamma \vdash x : \tau' \triangleright x : \tau \triangleright \Phi' \]

TInst(\(a\))
\[ \text{let } a' \text{ fresh } \quad \Phi, \Gamma \vdash a[a' \rightarrow \tau] \triangleright x : \tau \triangleright \Phi' \]

\[ \Phi, \Gamma \vdash x : \forall \beta,\sigma \triangleright x : \tau \triangleright \Phi' \]

TInst(\(b\))
\[ \text{let } \delta' \text{ fresh } \quad \Phi, \Gamma \vdash x : e[\delta \rightarrow \delta'] \triangleright x : \tau \triangleright \Phi' \]

\[ \Phi, \Gamma \vdash \forall \delta,\sigma \triangleright x : \tau \triangleright \Phi' \]

TLambda
\[ \text{let } a_1, a_2, \delta \text{ fresh } \quad \Phi, \Gamma \vdash x : (a_1, a_2) \triangleright \Phi' \quad \Phi \vdash \tau = (a_1, a_2) \triangleright \Phi'' \]

\[ \Phi, \Gamma \vdash \lambda x.e : \tau \triangleright \Phi'' \]

TApp
\[ \text{let } a, \delta \text{ fresh } \quad \Phi, \Gamma \vdash e_1 : (a, \delta) \triangleright \Phi' \quad \Phi' \vdash (a, \delta) \triangleright \Phi'' \]

\[ \Phi, \Gamma \vdash e_2 : \tau \triangleright \Phi'' \]

\[ \Phi, \Gamma \vdash e_1 \in e_2 : \tau \triangleright \Phi'' \]

TLet
\[ \text{let } a, \delta \text{ fresh } \quad \Phi, \Gamma \vdash e_1 : (a, \delta) \triangleright \Phi' \quad \Phi' \vdash e_2 : \tau \triangleright \Phi'' \]

\[ \Phi, \Gamma \vdash \phi \text{ fresh } \quad \Phi \vdash \tau = (a, \delta) \triangleright \Phi' \]

\[ \Phi, \Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau \triangleright \Phi'' \]

TThenElse
\[ \Phi, \Gamma \vdash e_1 : (\text{bool}, \Delta) \triangleright \Phi' \quad \Phi' \vdash e_2 : \tau \triangleright \Phi'' \quad \Phi'' \vdash e_3 : \tau \triangleright \Phi''' \]

\[ \Phi, \Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau \triangleright \Phi''' \]

TCase
\[ \text{let } \delta \text{ fresh } \quad \Phi, \Gamma \vdash (t, \tau) \triangleright \Phi' \quad \Phi', \Gamma \vdash e_2 : \tau \triangleright \Phi'' \quad \Phi'', \Gamma \vdash e_3 : \tau \triangleright \Phi''' \]

\[ \Phi, \Gamma \vdash \text{case } e_1 \text{ of } \text{NULL} \rightarrow e_2 \parallel x \rightarrow e_3 : \tau \triangleright \Phi''' \]

Figure 3: Typing rules

\[ \tau ::= (t, v) \quad t ::= b \mid a \mid \tau_1 \rightarrow \tau_2 \mid \mu \alpha.t \]

\[ t_b ::= \text{unit} \mid \text{bool} \mid \text{int} \quad v ::= \text{?} \mid \delta \mid \Delta \]

Figure 2: The types

3 A simple type system

We first present a rather simple type system, where the types carry a “nullability information” saying whether the value of an expression may be NULL or not.

The judgements of our language’s type system are of the form \( \Phi, \Gamma \vdash e : \tau \triangleright \Phi' \), where \( \Phi \) and \( \Phi' \) are substitutions, \( \Gamma \) is a type environment that maps program identifiers to type schemes (types with a prenex universal quantification of type and nullability variables). Such a judgement should be read as: given \( \Phi \) under assumption \( \Gamma \), the expression \( e \) has type \( \tau \) with substitution \( \Phi' \).

The rules should be read as the different cases of an algorithm that, given \( \Phi, \Gamma, e, \) and \( \tau \), computes substitution \( \Phi' \) which, when applied to \( \tau \) and \( \Gamma \), assign the type \( \Phi'(\tau) \) to \( e \). In other words, under assumptions \( \Phi'(\Gamma) \), \( e \) has type \( \Phi'(\tau) \).

Because we have two kinds of variables, we have two instantiation mechanisms, in distinct rules: TInst(\(a\)) for universally quantified type variables, and TInst(\(b\)) for universally quantified nullability variables.

Type equality constraints, introduced by typing rules, are solved using a set of rules displayed in figure 5. The only interesting resolution rules are the ones that introduce (EQNEW) or merge (EQMERGE) variable bindings in the \( \Phi \) substitution.

EQNEW(\(a\)) installs a binding \( a = t' \) in the substitution \( \Phi[a \rightarrow t'] \) (that is, \( \Phi \) in which free occurrences of \( a \) are replaced by \( t' \)) when there is no previous binding about \( a \) in \( \Phi \). Here, \( t' \) is either \( \mu \alpha.t \) or \( t \), depending on whether \( a \) occurs or not in \( t \).

EQNEW(\(\delta\)) does the same, in a simpler context, on nullability variables.

EQMERGE(\(a\)) merges a new constraint \( a = t' \) to a previous \( a = t \) occurring in \( \Phi \). Here, the resulting substitution \( \Phi' \) is obtained by resolving the constraint \( t = t' \). EQMERGE(\(\delta\)) does the same for nullability variables.

Correctness. The operational semantics needed for stating the correctness of the type system is also classical. NULL cannot handle operations such as being called as a function, tested as a boolean, added as an integer, etc. The typing of values, procuded by correct executions, is also slightly changed: the type \( (t, \tau) \) includes NULL as well as regular values. The correctness property can be stated as follows:

If \( \Phi, \Gamma \vdash e : \tau \triangleright \Phi' \), then the evaluation of \( e \) in an execution environment compatible with \( \Phi'(\Gamma) \) produces a value typable with \( \Phi'(\tau) \), if evaluation terminates.

Although this type system is simple and may seem practical,
it imposes a certain style of programming where NULL values are as much isolated as possible from other parts of the program. In a ML-like language, where NULL (or similar construct such as None) are not as commonly used as in C or Java, this might be acceptable. Still, one might want the following example to be typable:

```ocaml
let f b k =
  let p = k + 1 in
  if b then k else NULL in ...
```

This program cannot typecheck since the k parameter must at the same time have type (int,Δ) in order to be sent to + and (int,?) in order to have the same type as NULL.

## 4 Encoding nullability as variants

### Table 9: Encoding of NULL as variants

<table>
<thead>
<tr>
<th>NULL</th>
<th>'None</th>
</tr>
</thead>
<tbody>
<tr>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>c</td>
<td>'Some(c)</td>
</tr>
<tr>
<td>if c1 then c2 else c3</td>
<td>if match [c1] with 'Some(b) -&gt; b then [c2] else [c3]</td>
</tr>
<tr>
<td>λx.e</td>
<td>'Some(λx.[ e ])</td>
</tr>
<tr>
<td>case c1 of NULL -&gt; c2</td>
<td></td>
</tr>
<tr>
<td>c1 c2</td>
<td>(match [c1] with 'Some(f) -&gt; f) [c2]</td>
</tr>
</tbody>
</table>

Typing nullability of our language can be easily performed by a typechecker for polymorphic variants such as those provided by OCaml. The trick is to encode NULL as 'None, other values as 'Some(_), and computations must assume that only definite functions, that is, with shape 'Some(_), can be applied without further tests. In the same vein, primitive operations, such as +, accept only definite arguments. The translation, given in figure 9, shows that the typability of nullable values can trivially be reduced to the typing of polymorphic variants. Not a big deal, but improving the latter improves also the former.

As expected, the translation of the above example does not pass OCaml typechecking:

```ocaml
let f = 'Some (fun b k ->
  let p = (match (+) with
    | 'Some f_0 -> f_0) k ('Some 1) in
  if match b with 'Some b_0 -> b_0 then k else 'None) in ...
```

Error: this expression has type ['Some None] but an expression was expected of type ['Some of int].

This is due to the fact that the type inference of OCaml polymorphic variants use unification, even though it emulates some form of subtyping with a rich type algebra [6].

We have extended the work of Garrigue in order to have a more flexible and powerful type system for polymorphic variants. Although this is still work in progress, we show here how to apply this result to nullable types.

## 5 A subtyping approach

We saw in the example above that the propagation of information “backwards”, by unification in the typing environment, prevents typing some programs that could be perfectly acceptable.

Replacing unification, which comes from type equality constraints, by inequality constraints, that is, by subtyping, relaxes the programming style imposed by using type unification. While this is clearly more permissive, the resolution of inequality constraints may still fail. On the one hand, some unification constraints remain hidden as double inequalities (e.g. when trying to type 1 + "hello"). On the other hand, some inequalities are clearly not satisfiable, such as those produced when typing a conditional if NULL then ... else ..., where one fails to prove a? ∈ bool, or an application NULL(...), failing to prove a? ∈ τ1 → τ2. Also, many primitive operations (like (+)) won’t accept nullable arguments.

We start to change the type algebra of our language and introduce the syntax “?!” for nullable types, figure 10.

The new set of typing rules is given in figure 9. The essential change that we bring to our initial system is in the TAPP...
rule, where the domain type of the function is constrained to be “larger” than the type of the argument in order to accept it. Intuitively, a function accepting a possibly null value as argument, accepts also a provably non-null argument.

The inequality constraints, written \( \tau_1 \gg \tau_2 \), are integrated in the \( \Phi \) component of the typing rules by the set of resolution rules given in figure 7. At resolution time, newly integrated constraints are checked to be consistent with constraints existing in \( \Phi \). In particular, resolution performs the basic subtyping checks through rules \texttt{LEQBASENULL} and \texttt{LEQARROWNULL}, on figure 7(b).

When a type variable \( \alpha \) has to be “smaller” (resp. “greater”) than two types \( \tau_1 \) and \( \tau_2 \), the \( \tau_i \) become constrained to be “compatible” (see figure 8), that is to differ only in their (possibly internal) “\( \partial \)” annotations.

Generalization (figure 11) universally quantifies type variables \( \alpha \) together with its associated constraints, written \( \Phi_{\alpha} \), when the set \( \{ \alpha \} \cup \text{FTV}(\Phi_{\alpha}) \) does not intersect the set of free type variables occurring in \( \Gamma \).

At instantiation time, a fresh instance of constraints is re-injected in \( \Phi \).

Another important change in the new system concerns the conditional, case selection (and, more generally pattern-matching constructs). Instead of unifying the types of all branches, each of them is constrained to be “smaller” than the type of the construct itself. This forces all types of the branches to be compatible, but no more. See for instance rules \texttt{TIFTHENELSE} and \texttt{TCASE} on figure 6. This is precisely the reason why the example given at the end of section 3 is accepted by the new system.

6 Properties

We have a prototype implementation of this typing algorithm, and the proof of correctness of the extension of Garrigue’s typing of polymorphic variants, in which this algorithm can easily be translated. The proof is available online at [https://github.com/bvaugon/variants/](https://github.com/bvaugon/variants/).

7 Conclusion

We have presented two type systems and a translation algorithm aiming at inferring nullable types in ML-like languages. The first type system, rather naive and interesting by its simplicity, is probably too restrictive to be usable by daily programmers. The translation technique using standard polymorphic variants has the same weakness. However, exchanging unification against subtyping provides us with a more expressive type system. Soundness and termination properties have been checked.
(a) Main comparison rules

<table>
<thead>
<tr>
<th>GEQ</th>
<th>EQ</th>
<th>LEQNEW</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\Phi \vdash t_2 \leq t_1 \Rightarrow \Phi'$</td>
<td>$\Phi \vdash t_1 \leq t_2 \Rightarrow \Phi'$</td>
<td>$\Phi, t_1 \vdash t_2 \not\in \Phi$</td>
</tr>
<tr>
<td>$\Phi \vdash t_1 \Rightarrow t_2 \Rightarrow \Phi'$</td>
<td>$\Phi \vdash t_1 \Rightarrow t_2 \Rightarrow \Phi'$</td>
<td>$\Phi, t_1 \vdash t_2 \not\in \Phi$</td>
</tr>
<tr>
<td>$\Phi \vdash t_1 = t_2 \Rightarrow \Phi'$</td>
<td>$\Phi \vdash t_1 = t_2 \Rightarrow \Phi'$</td>
<td></td>
</tr>
</tbody>
</table>

- LEQALREADYPROVED
  - $\Phi, t_1 \vdash t_2 \not\in \Phi, t_1 \vdash t_2 \not\in \Phi$ |

(b) Standard comparison rules

<table>
<thead>
<tr>
<th>LEQBASETy</th>
<th>LEQARROW</th>
<th>LEQBASENULL</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\Phi \vdash t_1 \leq t_2 \Rightarrow \Phi$</td>
<td>$\Phi \vdash t_1 \leq t_2 \Rightarrow \Phi'$</td>
<td>$\Phi \vdash t_1 \leq t_2 \Rightarrow \Phi'$</td>
</tr>
</tbody>
</table>

- LEQARROW
  - $\Phi \vdash t_1 \leq t_2 \Rightarrow \Phi$, $\Phi \vdash t_2 \leq t_1 \Rightarrow \Phi'$ |

- LEQARROWNULL
  - $\Phi \vdash t_1 \leq t_2 \Rightarrow \Phi$, $\Phi \vdash t_2 \leq t_1 \Rightarrow \Phi'$ |

(c) Type-variable comparison rule

<table>
<thead>
<tr>
<th>LEQSAMEVAR</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\Phi \vdash a \leq a \Rightarrow \Phi$</td>
</tr>
</tbody>
</table>

- LEQVARLEOTy
  - when $\tau' \neq \alpha$ and $\tau \leq \tau' \Rightarrow \Phi$
  - $\Phi, \alpha \leq t \Rightarrow \tau' \Rightarrow \alpha \leq \tau \Rightarrow \Phi'$ |

- GEOVARLEOTy
  - when $\tau' \neq \alpha$ and $\tau \leq \tau' \Rightarrow \Phi$
  - $\Phi, \alpha \leq t \Rightarrow \tau' \Rightarrow \alpha \leq \tau \Rightarrow \Phi'$ |

- LEQTYLEQVAR
  - when $\tau' \neq \alpha$ and $\tau \leq \tau' \Rightarrow \Phi$
  - $\Phi, \alpha \leq t \Rightarrow \tau' \Rightarrow \alpha \leq \tau \Rightarrow \Phi'$ |

- GEOQTYLEQVAR
  - when $\tau' \neq \alpha$ and $\tau \leq \tau' \Rightarrow \Phi$
  - $\Phi, \alpha \leq t \Rightarrow \tau' \Rightarrow \alpha \leq \tau \Rightarrow \Phi'$ |

- LEQVARCPTTy
  - when $\tau' \neq \alpha$ and $\tau \leq \tau' \Rightarrow \Phi$
  - $\Phi, \alpha \leq t \Rightarrow \tau' \Rightarrow \alpha \leq \tau \Rightarrow \Phi'$ |

- GEOQVARCPTTy
  - when $\tau' \neq \alpha$ and $\tau \leq \tau' \Rightarrow \Phi$
  - $\Phi, \alpha \leq t \Rightarrow \tau' \Rightarrow \alpha \leq \tau \Rightarrow \Phi'$ |

- LEQVARENt
  - when $\tau' \neq \alpha$
  - when $(\forall \tau \mid \alpha \leq t \Rightarrow \tau \Rightarrow \tau' \Rightarrow \Phi)$ |

- GEOQVARENt
  - when $\tau' \neq \alpha$
  - when $(\forall \tau \mid \alpha \leq t \Rightarrow \tau' \Rightarrow \tau \Rightarrow \Phi)$ |

Figure 7: Comparison rules
References


