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Polynomial-exponential decomposition from moments

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Abstract

We analyze the decomposition problem of multivariate polynomial-exponential functions from their truncated series and present new algorithms to compute their decomposition.

Using the duality between polynomials and formal power series, we first show how the elements in the dual of an Artinian algebra correspond to polynomial-exponential functions. They are also the solutions of systems of partial differential equations with constant coefficients. We relate their representation to the inverse system of the isolated points of the characteristic variety.

Using the properties of Hankel operators, we establish a correspondence between polynomial-exponential series and Artinian Gorenstein algebras. We generalize Kronecker theorem to the multivariate case, by showing that the symbol of a Hankel operator of finite rank is a polynomial-exponential series and by connecting the rank of the Hankel operator with the decomposition of the symbol.

A generalization of Prony's approach to multivariate decomposition problems is presented, exploiting eigenvector methods for solving polynomial equations. We show how to compute the frequencies and weights of a minimal polynomial-exponential decomposition, using the first coefficients of the series. A key ingredient of the approach is the flat extension criteria, which leads to a multivariate generalization of a rank condition for a Carathéodory-Fejér decomposition of multivariate Hankel matrices. A new algorithm is given to compute a basis of the Artinian Gorenstein algebra, based on a Gram-Schmidt orthogonalization process and to decompose polynomial-exponential series.

A general framework for the applications of this approach is described and illustrated in different problems. We provide Kronecker-type theorems for convolution operators, showing that a convolution operator (or a cross-correlation operator) is of finite rank, if and only if, its symbol is a polynomial-exponential function, and we relate its rank to the decomposition of its symbol. We also present Kronecker-type theorems for the reconstruction of measures as weighted sums of Dirac measures from moments and for the decomposition of polynomial-exponential functions from values. Finally, we describe an application of this method for the sparse interpolation of polylog functions from values.

AMS classification: 14Q20, 68W30, 47B35, 15B05

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1 Introduction

Sensing is a classical technique, which is nowadays heavily used in many applications to transform continuous signals or functions into discrete data. In other contexts, in order to analyze physical phenomena or the evolution of our environments, large sequences of measurements can also be produced from sensors, cameras or scanners to discretize the problem.

An important challenge is then to recover the underlying structure of the observed phenomena, signal or function. This means to extract from the data, a structured or sparse representation of the function, which is easier to manipulate, to transmit or to analyze. Recovering this underlying structure can boil down to compute an explicit representation of the function in a given functional space. Usually, a “good” numerical approximation of the function as a linear combination of a set of basis functions is sufficient. The choice of the basis functions is very important from this perspective. It can lead to a representation, with many non-zero coefficients or a sparse representation with few coefficients, if the basis is well-suited. To illustrate this point, consider a linear function over a bounded interval of \mathbb{R} . It has a sparse representation in the monomial basis since it is represented by two coefficients. But its description as Fourier series involves an infinite sequence of (decreasing) Fourier coefficients.

This raises the questions of how to determine a good functional space, in which the functions we consider have a sparse representation, and how to compute such a decomposition, using a small (if not minimal) amount of information or measurements.

In the following, we consider a special reconstruction problem, which will allow us to answer these two questions in several other contexts. The functional space, in which we are going to compute sparse representations is the space of polynomial-exponential functions. The data that we use corresponds to the Taylor coefficients of these functions. Hereafter, we call them *moments*. They are for instance the Fourier coefficients of a signal or the values of a function sampled on a regular grid. It can also be High Order Statistical moments or cumulants, used in Signal Processing to perform blind identification [40]. Many other examples of reconstruction from moments can be found in Image Analysis, Computer Vision, Statistics ... The reconstruction problem consists in computing a polynomial-exponential representation of the series from the (truncated) sequence of its moments. We will see that this problem allows us to recover sparse representations in several contexts.

With the multi-index notation: $\forall \alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n, \forall \mathbf{u} \in \mathbb{C}^n, \alpha! = \prod_{i=1}^n \alpha_i!, \mathbf{u}^\alpha = \prod_{i=1}^n u_i^{\alpha_i}, \mathbf{e}_\xi(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \frac{1}{\alpha!} \xi^\alpha \mathbf{y}^\alpha = e^{\langle \xi, \mathbf{y} \rangle} = e^{\xi_1 y_1 + \dots + \xi_n y_n}$ for $\xi = (\xi_1, \dots, \xi_n) \in \mathbb{C}^n$, and for $\mathbb{C}[[\mathbf{y}]] = \mathbb{C}[[y_1, \dots, y_n]]$ the ring of formal power series in y_1, \dots, y_n , this decomposition problem can be stated as follows.

Polynomial-exponential decomposition from moments: *Given coefficients σ_α for $\alpha \in \mathbf{a} \subset \mathbb{N}^n$ of the series*

$$\sigma(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{C}[[\mathbf{y}]],$$

recover r points $\xi_1, \dots, \xi_r \in \mathbb{C}^n$ and r polynomial coefficients $\omega_i(\mathbf{y}) \in \mathbb{C}[[\mathbf{y}]]$ such that

$$\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y}). \quad (1)$$

A function of the form (1) is called a *polynomial-exponential* function. We aim at recovering the minimal number r of terms in the decomposition (1). Since only the coefficients σ_α for $\alpha \in \mathbf{a}$ are known, computing the decomposition (1) means that the coefficients of \mathbf{y}^α are the same in the series on both sides of the equality, for $\alpha \in \mathbf{a}$.

1.1 Prony's method in one variable

One of the first work in this area is probably due to Gaspard-Clair-François-Marie Riche de Prony, mathematician and engineer of the École Nationale des Ponts et Chaussées. He was working on Hydraulics. To analyze the expansion of various gases, he proposed in [21] a method to fit a sum of exponentials at equally spaced data points in order to extend the model at intermediate points. More precisely, he was studying the following problem:

Given a function $h \in C^\infty(\mathbb{R})$ of the form

$$x \in \mathbb{R} \mapsto h(x) = \sum_{i=1}^r \omega_i e^{f_i x} \in \mathbb{C} \quad (2)$$

where $f_1, \dots, f_r \in \mathbb{C}$ are pairwise distinct, $\omega_i \in \mathbb{C} \setminus \{0\}$, the problem consists in recovering

- the distinct *frequencies* $f_1, \dots, f_r \in \mathbb{C}$,
- the *coefficients* $\omega_i \in \mathbb{C} \setminus \{0\}$,

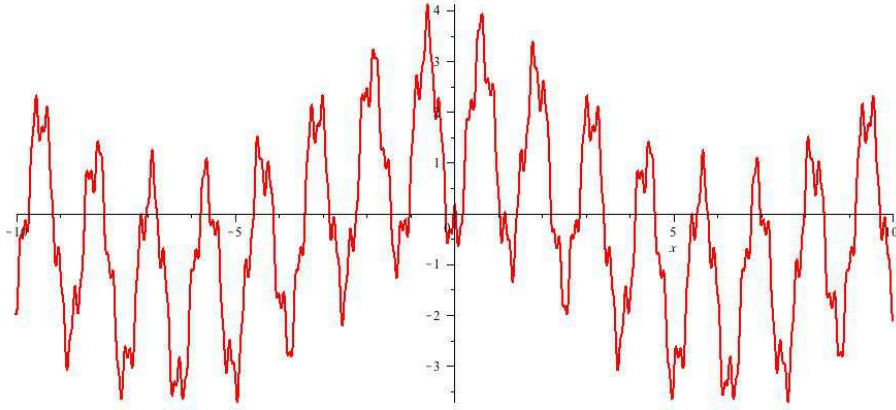


Figure 1: A superposition of oscillations with different frequencies

Figure 1 shows an example of such a signal, which is the superposition of several “oscillations” with different frequencies.

The approach proposed by G. de Prony can be reformulated into a truncated series reconstruction problem. By choosing an arithmetic progression of points in \mathbb{R} , for instance the integers \mathbb{N} , we can associate to h , the generating series:

$$\sigma_h(y) = \sum_{a \in \mathbb{N}} h(a) \frac{y^a}{a!} \in \mathbb{C}[[y]],$$

where $\mathbb{C}[[y]]$ is the ring of formal power series in the variable y . If h is of the form (2), then

$$\sigma_h(y) = \sum_{i=1}^r \sum_{a \in \mathbb{N}} \omega_i \xi_i^a \frac{y^a}{a!} = \sum_{i=1}^r \omega_i e^{\xi_i y} \quad (3)$$

where $\xi_i = e^{f_i}$. Prony’s method consists in reconstructing the decomposition (3) from a small number of coefficients $h(a)$ for $a = 0, \dots, 2r - 1$. It performs as follows:

- From the values $h(a)$ for $a \in [0, \dots, 2r - 1]$, compute the polynomial

$$p(x) = \prod_{i=1}^r (x - \xi_i) = x^r - \sum_{j=0}^{r-1} p_j x^j,$$

which roots are $\xi_i = e^{f_i}$, $i = 1, \dots, r$ as follows. Since it satisfies the recurrence relations

$$\forall j \in [0, \dots, r - 1], \quad \sum_{i=0}^{r-1} \sigma_{j+i} p_i - \sigma_{j+r} = - \sum_{i=1}^r \omega_i \xi_i^j p(\xi_i) = 0,$$

it is the unique solution of the system:

$$\begin{pmatrix} \sigma_0 & \sigma_1 & \dots & \dots & \sigma_{r-1} \\ \sigma_1 & & & \ddots & \\ \vdots & & \ddots & & \vdots \\ \sigma_{r-1} & & \dots & \dots & \sigma_{2r-2} \end{pmatrix} \begin{pmatrix} p_0 \\ p_1 \\ \vdots \\ \vdots \\ p_{r-1} \end{pmatrix} = \begin{pmatrix} \sigma_r \\ \sigma_{r+1} \\ \vdots \\ \vdots \\ \sigma_{2r-1} \end{pmatrix}. \quad (4)$$

- Compute the roots ξ_1, \dots, ξ_r of the polynomial $p(x)$.
- To determine the weight coefficients w_1, \dots, w_r , solve the following linear (Vandermonde) system:

$$\begin{pmatrix} 1 & 1 & \dots & 1 \\ \xi_1 & \xi_2 & \dots & \xi_r \\ \vdots & \vdots & & \vdots \\ \xi_1^{r-1} & \xi_2^{r-1} & \dots & \xi_r^{r-1} \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_r \end{pmatrix} = \begin{pmatrix} h_0 \\ h_1 \\ \vdots \\ h_{r-1} \end{pmatrix}.$$

This approach can be improved by computing the roots ξ_1, \dots, ξ_r , directly as the generalized eigenvalues of a pencil of Hankel matrices. Namely, Equation (4) implies that

$$\overbrace{\begin{pmatrix} \sigma_0 & \sigma_1 & \dots & \sigma_{r-1} \\ \sigma_1 & & \dots & \\ \vdots & & \dots & \vdots \\ \sigma_{r-1} & \dots & \sigma_{2r-2} \end{pmatrix}}^{H_0} \overbrace{\begin{pmatrix} 0 & & & p_0 \\ 1 & \dots & & p_1 \\ & \dots & \dots & \vdots \\ & & \dots & 0 \\ & & & 1 & p_{r-1} \end{pmatrix}}^{M_p} = \overbrace{\begin{pmatrix} \sigma_1 & \sigma_2 & \dots & \sigma_r \\ \sigma_2 & & \dots & \\ \vdots & & \dots & \vdots \\ \sigma_r & \dots & \sigma_{2r-1} \end{pmatrix}}^{H_1}, \quad (5)$$

so that the generalized eigenvalues of the pencil (H_1, H_0) are the eigenvalues of the companion matrix M_p of $p(x)$, that is, its the roots ξ_1, \dots, ξ_r . This variant of Prony's method is also called the *pencil method* in the literature.

For numerical improvement purposes, one can also chose an arithmetic progression $\frac{a}{T}$ and $a \in [0, \dots, 2r - 1]$, with $T \in \mathbb{R}^+$ of the same order of magnitude as the frequencies f_i . The roots of the polynomial p are then $\xi_i = e^{\frac{if_i}{T}}$.

1.2 Related works

The approximation of functions by a linear combination of exponential functions appears in many contexts. It is the basis of Fourier analysis, where infinite series are involved in the decomposition of functions. The frequencies of these infinite sums of exponentials belong to an infinite grid on the imaginary axis in the complex plane.

An important problem is to represent or approximate a function by a sparse or finite sum of exponential terms, removing the constraints on the frequencies. This problem has a long history and many applications, in particular in signal processing [29], [52].

Many works have been developed in the one dimensional case, which refers to the well-known problem of *parameter estimation for exponential sums*. A first family of methods can be classified as Prony-type methods. To take into account the problem of noisy data, the recurrence relation is computed by minimization techniques [52][chap. 1]. Another type of methods is called Pencil-matrix [52][chap. 1]. Instead of computing a recurrence relation, the generalized eigenvalues of a pencil of Hankel matrices are computed. The survey paper [29] describes some of these minimization techniques implementing a variable projection algorithm and their applications in various domains, including antenna analysis with so-called MUSIC [64] or ESPRIT [60] methods. In [14], another approach based on conjugate-eigenvalue computation and low rank Hankel matrix approximation is proposed. The extension of this method in [55], called Approximate Prony Method, is using controlled perturbations.

More recently the problem was studied in the multi-dimensional case [5], [56], [36]. These methods project the problem in one dimension by sampling data along a line. They recover the

multivariate solutions from projections along several directions. Even more recently, techniques for solving polynomial equations, which rely on the computation of H -bases, have been exploited in this context [62].

The theory builds on the properties of Hankel matrices of finite rank, starting with a result due to [35] in the one variable case. This result states that there is an explicit correlation between polynomial-exponential series and Hankel operators of finite rank. The literature on Hankel operators is huge and mainly focus on one variable (see e.g. [51]). Kronecker’s result has been extended to several variables for multi-index sequences [57], [7], [4], for non-commutative variables [27], for integral cross-correlation operators [3]. In some cases as in [3], methods have been proposed to compute the rank in terms of the polynomial-exponential decomposition.

Hankel matrices are central in the theory of Padé approximants for functions of one variable. Here also a large literature exists for univariate Padé approximants: see e.g. [6] for approximation properties, [8] for numerical stability problems, [9], [66] for algorithmic aspects. The extension to multivariate functions is much less developed [57], [20].

This type of approaches is also used in sparse interpolation of black box polynomials. In the methods developed in [10], [68], further improved in [28], the sparse polynomial is evaluated at points of the form $(\omega_1^k, \dots, \omega_n^k)$ where ω_i are prime numbers or primitive roots of unity of co-prime order. The sparse decomposition of the black box polynomial is computed from its values by a univariate Prony-like method.

Hankel matrices and their kernels also play an important role in error correcting codes. Reed-Solomon codes, obtained by evaluation of a polynomial at a set of points and convolution by a given polynomial, can be decoded from their syndrome sequence by computing the error locator polynomial [42][chap. 9]. This is a linear recurrence relation between the syndrome coefficients, which corresponds to a non-zero element in the kernel of a Hankel matrix. Berlekamp [11] and Massey [44] proposed an efficient algorithm to compute such polynomials. Sakata extended the approach to compute Gröbner bases of polynomials in the kernel of a multivariate Hankel matrix [61]. The computation of multivariate linear recurrence relations have been further investigated, e.g. in [26] and more recently in [13].

Computing polynomials in the kernel of Hankel matrices and their roots is also the basis of the method proposed by J.J. Sylvester [65] to decompose binary forms. This approach has been extended recently to the decomposition of multivariate symmetric and multi-symmetric tensors in [15], [12].

A completely different approach, known as *compressive sensing*, has been developed over the last decades to compute sparse decompositions of functions (see e.g. [16]). In this approach, a (large) dictionary of functions is chosen and a sparse combination with few non-zero coefficients is computed from some observations. This boils to find a sparse solution X of an underdetermined linear system $Y = AX$. Such a solution, which minimizes the L_0 “norm” can be computed by L_1 minimization, under some hypothesis.

For the sparse reconstruction problem from a discrete set of frequencies, it is shown in [16] that the L_1 minimization provides a solution, for enough Fourier coefficients (at least $4r$) chosen at random. As shown in [54], this problem can also be solved by a Prony-like approach, using only $2r$ Fourier coefficients.

1.3 Contributions

In this paper, we analyze the problem of sparse decomposition of series from an algebraic point of view and propose new methods to compute such decompositions.

We exploit the duality between polynomials and formal power series. The formalism is strongly connected to the inverse systems introduced by F.S Macaulay [41]: evaluations at points correspond to exponential functions and the multiplication to derivation. We give an explicit form for the elements in the dual of an Artinian algebra, in terms of polynomial-

exponential functions and show how their polynomial coefficients correspond to elements in the inverse systems of the roots of the characteristic variety. This gives a new and complete description of the solutions of partial differential equations with constant coefficients for zero-dimensional partial differential systems (Theorem 2.18).

The sparse decomposition problem is tackled by studying the Hankel operators associated to the generating series. We show that polynomial-exponential series are in correspondence with Artinian Gorenstein algebras. We prove an extension of Kronecker theorem to the multivariate case (Theorem 3.1), describing the symbol associated to a Hankel operator of finite rank as a polynomial-exponential series. We show moreover that the rank of an Hankel operator associated to a polynomial-exponential series is the sum of the dimensions of the vector spaces spanned by all the derivatives of the polynomial weights, providing a direct and simple generalisation of Kronecker univariate theorem.

Exploiting classical eigenvector methods for solving polynomial equations, we show how to compute a polynomial-exponential decomposition, using the first coefficients of the generating series (Algorithms 3.1 and 3.2). In particular, we show how to recover directly the weights in the decomposition from the eigenspaces, for simple roots and multiple roots. A key ingredient of the approach is the flat extension criteria, which leads to a multivariate generalization of Carathéodory-Fejér decomposition. We provide a flat extension criteria (Theorem 4.2), which extends the results in [39], [4].

A new algorithm is described to compute a basis of the Artinian Gorenstein algebra (Algorithm 4.1), which applies a Gram-Schmidt orthogonalization process and computes pairwise orthogonal polynomial bases. This leads to a new method to compute a polynomial-exponential decomposition, which generalizes Prony's method to several variables. It applies to general polynomial-exponential series, with polynomial weights of any degree. It also provides a new algorithm to compute linear recurrence relations and polynomial-exponential decompositions of multi-index series.

A general framework for the application of this approach based on generating series is described, extending the construction of [53] to the multivariate setting. We illustrate it in different problems, showing that several results in analysis are consequences of the algebraic multivariate Kronecker theorem (Theorem 3.1). In particular, we provide Kronecker-type theorems (Theorems 5.6, 5.7 and 5.9) for convolution operators (or cross-correlation operators), considered in [3], [4]. Theorem 3.1 implies that the rank of a convolution (or correlation) operator with a polynomial-exponential symbol is the sum of the dimensions of the space spanned by all the derivatives of the polynomial weights of the symbol. By Lemma 2.6, this gives a simple description of the output of the method proposed in [3] to compute the rank of convolution operators. We also deduce Kronecker-type theorems for the reconstruction of measures as weighted sums of Dirac measures from moments and the decomposition of polynomial-exponential functions from values. Finally, we describe a new approach for the sparse interpolation of polylog functions from values, with Kronecker-type results on their decomposition.

2 Duality and Hankel operators

In this section, we consider polynomials and series with coefficients in a field K of characteristic 0. In the applications, we are going to take $K = \mathbb{C}$ or $K = \mathbb{R}$.

We are going to use the following notation: $K[x_1, \dots, x_n] = K[\mathbf{x}] = R$ is the ring of polynomials in the variable x_1, \dots, x_n with coefficients in the field K , $K[[y_1, \dots, y_n]] = K[[\mathbf{y}]]$ is the ring of formal power series in the variables y_1, \dots, y_n with coefficients in K . For a set $B \subset K[\mathbf{x}]$, $B^+ = \cup_{i=1}^n x_i B \cup B$, $\partial B = B^+ \setminus B$. For $\alpha, \beta \in \mathbb{N}^n$, we say that $\alpha \ll \beta$ if $\alpha_i \leq \beta_i$ for $i = 1, \dots, n$.

2.1 Duality

In this section, we describe the natural isomorphism between the ring of formal power series and the dual of $R = \mathbb{K}[x_1, \dots, x_n]$. It is given by the following pairing:

$$\begin{aligned} \mathbb{K}[[y_1, \dots, y_n]] \times \mathbb{K}[x_1, \dots, x_n] &\rightarrow \mathbb{K} \\ (\mathbf{y}^\alpha, \mathbf{x}^\beta) &\mapsto \langle \mathbf{y}^\alpha | \mathbf{x}^\beta \rangle = \begin{cases} \alpha! & \text{if } \alpha = \beta \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

Namely, if $\Lambda \in \text{Hom}_{\mathbb{K}}(\mathbb{K}[\mathbf{x}], \mathbb{K}) = R^*$ is an element of the dual of $\mathbb{K}[\mathbf{x}]$, it can be represented by the series:

$$\Lambda(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \Lambda(\mathbf{x}^\alpha) \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{K}[[y_1, \dots, y_n]], \quad (6)$$

so that we have $\langle \Lambda(\mathbf{y}) | \mathbf{x}^\alpha \rangle = \Lambda(\mathbf{x}^\alpha)$. The map $\Lambda \in R^* \mapsto \sum_{\alpha \in \mathbb{N}^n} \Lambda(\mathbf{x}^\alpha) \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{K}[[\mathbf{y}]]$ is an isomorphism and any series $\sigma(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{K}[[\mathbf{y}]]$ can be interpreted as a linear form

$$p = \sum_{\alpha \in A \subset \mathbb{N}^n} p_\alpha \mathbf{x}^\alpha \in \mathbb{K}[\mathbf{x}] \mapsto \langle \sigma | p \rangle = \sum_{\alpha \in A \subset \mathbb{N}^n} p_\alpha \sigma_\alpha.$$

Any linear form $\sigma \in R^*$ is uniquely defined by its coefficients $\sigma_\alpha = \langle \sigma | \mathbf{x}^\alpha \rangle$ for $\alpha \in \mathbb{N}^n$, which are called the *moments* of σ .

From now on, we identify the dual $\text{Hom}_{\mathbb{K}}(\mathbb{K}[\mathbf{x}], \mathbb{K})$ with $\mathbb{K}[[\mathbf{y}]]$. Using this identification, the dual basis of the monomial basis $(\mathbf{x}^\alpha)_{\alpha \in \mathbb{N}^n}$ is $\left(\frac{\mathbf{y}^\alpha}{\alpha!} \right)_{\alpha \in \mathbb{N}^n}$.

If \mathbb{K} is a subfield of a field L , we have the embedding $\mathbb{K}[[\mathbf{y}]] \hookrightarrow L[[\mathbf{y}]]$, which allows to identify an element of $\mathbb{K}[\mathbf{x}]^*$ with an element of $L[\mathbf{x}]^*$.

The truncation of an element $\sigma(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{K}[[\mathbf{y}]]$ in degree d is $\sum_{|\alpha| \leq d} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!}$. It is denoted $\sigma(\mathbf{y}) + ((\mathbf{y}))^{d+1}$, that is, the class of σ modulo the ideal $(y_1, \dots, y_n)^{d+1} \subset \mathbb{K}[[\mathbf{y}]]$.

For an ideal $I \subset R = \mathbb{K}[\mathbf{x}]$, we denote by $I^\perp \subset \mathbb{K}[[\mathbf{y}]]$ the space of linear forms $\sigma \in \mathbb{K}[[\mathbf{y}]]$, such that $\forall p \in I, \langle \sigma | p \rangle = 0$. Similarly, for a vector space $D \subset \mathbb{K}[[\mathbf{y}]]$, we denote by $D^\perp \subset \mathbb{K}[\mathbf{x}]$ the space of polynomials $p \in \mathbb{K}[\mathbf{x}]$, such that $\forall \sigma \in D, \langle \sigma | p \rangle = 0$. If D is closed for the (\mathbf{y}) -adic topology, then $D^{\perp\perp} = D$ and if $I \subset \mathbb{K}[\mathbf{x}]$ is an ideal I^\perp , then $I^{\perp\perp} = I$.

The dual space $\text{Hom}(\mathbb{K}[\mathbf{x}], \mathbb{K}) \equiv \mathbb{K}[[\mathbf{y}]]$ has a natural structure of $\mathbb{K}[\mathbf{x}]$ -module, defined as follows: $\forall \sigma(\mathbf{y}) \in \mathbb{K}[[\mathbf{y}]], \forall p(\mathbf{x}), q(\mathbf{x}) \in \mathbb{K}[\mathbf{x}]$,

$$\langle p(\mathbf{x}) \star \sigma(\mathbf{y}) | q(\mathbf{x}) \rangle = \langle \sigma(\mathbf{y}) | p(\mathbf{x})q(\mathbf{x}) \rangle.$$

We check that $\forall \sigma \in \mathbb{K}[[\mathbf{y}]], \forall p, q \in \mathbb{K}[\mathbf{x}], (pq) \star \sigma = p \star (q \star \sigma)$. See e.g. [24], [45] for more details.

For $p = \sum_{\beta} p_\beta \mathbf{x}^\beta \in \mathbb{K}[\mathbf{x}]$ and $\sigma = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{K}[[\mathbf{y}]]$, the series expansion of $p \star \sigma$ is $p \star \sigma = \sum_{\alpha \in \mathbb{N}^n} \rho_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{K}[[\mathbf{y}]]$ with $\forall \alpha \in \mathbb{N}^n$,

$$\rho_\alpha = \sum_{\beta} p_\beta \sigma_{\alpha+\beta}.$$

Identifying $\mathbb{K}[\mathbf{x}]$ with the set $L_0(\mathbb{K}^{\mathbb{N}^n})$ of sequences $p = (p_\alpha)_{\alpha \in \mathbb{N}^n}$ of finite support (i.e. a finite number of non-zero terms), and $\mathbb{K}[[\mathbf{y}]]$ with the set of sequences $\sigma = (\sigma_\alpha)_{\alpha \in \mathbb{N}^n}$, $p \star \sigma$ is the cross-correlation sequence of p and σ .

For any $\sigma(\mathbf{y}) \in \mathbb{K}[[\mathbf{y}]]$, the inner product associated to $\sigma(\mathbf{y})$ on $\mathbb{K}[\mathbf{x}]$ is defined as follows:

$$\begin{aligned} \mathbb{K}[\mathbf{x}] \times \mathbb{K}[\mathbf{x}] &\rightarrow \mathbb{K} \\ (p(\mathbf{x}), q(\mathbf{x})) &\mapsto \langle p(\mathbf{x}), q(\mathbf{x}) \rangle_\sigma := \langle \sigma(\mathbf{y}) | p(\mathbf{x})q(\mathbf{x}) \rangle. \end{aligned}$$

2.1.1 Polynomial-Exponential series

Among the elements of $\text{Hom}(\mathbb{K}[\mathbf{x}], \mathbb{K}) \cong \mathbb{K}[[\mathbf{y}]]$, we have the evaluations at points of \mathbb{K}^n :

Definition 2.1 *The evaluation at a point $\xi = (\xi_1, \dots, \xi_n) \in \mathbb{K}^n$ is:*

$$\begin{aligned} e_\xi : \mathbb{K}[x_1, \dots, x_n] &\rightarrow \mathbb{K} \\ p(\mathbf{x}) &\mapsto p(\xi) \end{aligned}$$

It corresponds to the series:

$$e_\xi(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \xi^\alpha \frac{\mathbf{y}^\alpha}{\alpha!} = e^{\xi_1 y_1 + \dots + \xi_n y_n} = e^{\langle \xi, \mathbf{y} \rangle}.$$

Using this formalism, the series $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i e_{\xi_i}(\mathbf{y})$ with $\omega_i \in \mathbb{K}$ can be interpreted as a linear combination of evaluations at the points ξ_i with coefficients ω_i , for $i = 1, \dots, r$. These series belong to the more general family of polynomial-exponential series, that we define now.

Definition 2.2 *Let $\mathcal{POLYEXP}(y_1, \dots, y_n) = \{\sigma = \sum_{i=1}^r \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y}) \in \mathbb{K}[[\mathbf{y}]] \mid \xi_i \in \mathbb{K}^n, \omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]\}$ be the set of polynomial-exponential series. The polynomials $\omega_i(\mathbf{y})$ are called the weights of σ and ξ_i the frequencies.*

Notice that the product of $\mathbf{y}^\alpha e_\xi(\mathbf{y})$ with a monomial $\mathbf{x}^\beta \in \mathbb{C}[x_1, \dots, x_n]$ is given by

$$\begin{aligned} \langle \mathbf{y}^\alpha e_\xi(\mathbf{y}) | \mathbf{x}^\beta \rangle &= \frac{\beta!}{(\beta - \alpha)!} \xi^{\beta - \alpha} = \partial_{x_1}^{\alpha_1} \dots \partial_{x_n}^{\alpha_n} (\mathbf{x}^\beta)(\xi) \text{ if } \alpha_i \leq \beta_i \text{ for } i = 1, \dots, n \\ &= 0 \text{ otherwise.} \end{aligned} \quad (7)$$

Therefore an element $\sigma = \sum_{i=1}^r \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$ of $\mathcal{POLYEXP}(\mathbf{y})$ can also be seen as a sum of polynomial differential operators $\omega_i(\boldsymbol{\partial})$ ‘‘at’’ the points ξ_i , that we call *infinitesimal operators*: $\forall p \in \mathbb{K}[\mathbf{x}], \langle \sigma | p \rangle = \sum_{i=1}^r \omega_i(\boldsymbol{\partial})(p)(\xi)$.

2.1.2 Differential operators

An interesting property of the outer product defined on $\mathbb{K}[[\mathbf{y}]]$ is that polynomials act as differentials on the series:

Lemma 2.3 $\forall p \in \mathbb{K}[\mathbf{x}], \forall \sigma \in \mathbb{K}[[\mathbf{y}]], p(\mathbf{x}) \star \sigma(\mathbf{y}) = p(\boldsymbol{\partial})(\sigma)$.

Proof. We first prove the relation for $p = x_i$ ($i \in [1, n]$) and $\sigma = \mathbf{y}^\alpha$ ($\alpha \in \mathbb{N}^n$). Let $e_i = (0, \dots, 0, 1, 0, \dots, 0)$ be the exponent vector of x_i . $\forall \beta \in \mathbb{N}^n$ and $\forall i \in [1, n]$, we have

$$\begin{aligned} \langle x_i \star \mathbf{y}^\alpha | \mathbf{x}^\beta \rangle &= \langle \mathbf{y}^\alpha | x_i \mathbf{x}^\beta \rangle = \alpha! \text{ if } \alpha = \beta + e_i \text{ and } 0 \text{ otherwise} \\ &= \alpha_i \langle \mathbf{y}^{\alpha - e_i} | \mathbf{x}^\beta \rangle. \end{aligned}$$

with the convention that $\mathbf{y}^{\alpha - e_i} = 0$ if $\alpha_i = 0$. This shows that $x_i \star \mathbf{y}^\alpha = \alpha_i \mathbf{y}^{\alpha - e_i} = \partial_{y_i}(\mathbf{y}^\alpha)$. By transitivity and bilinearity of the product \star , we deduce that $\forall p \in \mathbb{K}[\mathbf{x}], \forall \sigma \in \mathbb{K}[[\mathbf{y}]], p(\mathbf{x}) \star \sigma(\mathbf{y}) = p(\boldsymbol{\partial})(\sigma)$. \square

This property can be useful to analyze the solution of partial differential equations. Let $p_1(\boldsymbol{\partial}), \dots, p_s(\boldsymbol{\partial}) \in \mathbb{K}[\partial_1, \dots, \partial_n] = \mathbb{K}[\boldsymbol{\partial}]$ be a set of partial differential polynomials with constant coefficients $\in \mathbb{K}$. The set of solutions $\sigma \in \mathbb{K}[[\mathbf{y}]]$ of the system

$$p_1(\boldsymbol{\partial})(\sigma) = 0, \dots, p_s(\boldsymbol{\partial})(\sigma) = 0$$

is in correspondence with the elements $\sigma \in (p_1, \dots, p_s)^\perp$, which satisfy $p_i \star \sigma = 0$ for $i = 1, \dots, s$ (see Theorem 2.18). The variety $\mathcal{V}(p_1, \dots, p_n) \subset \overline{\mathbb{K}}^n$ is called the *characteristic variety* and $I = (p_1, \dots, p_n)$ the *characteristic ideal* of the system of partial differential equations.

Lemma 2.4 $\forall p \in \mathbb{K}[\mathbf{x}], \forall \omega \in \mathbb{K}[[\mathbf{y}]], \xi \in \mathbb{K}^n, p(\mathbf{x}) \star (\omega(\mathbf{y})\mathbf{e}_\xi(\mathbf{y})) = p(\xi_1 + \partial_{y_1}, \dots, \xi_n + \partial_{y_n})(\omega(\mathbf{y}))\mathbf{e}_\xi(\mathbf{y})$.

Proof. By the previous lemma, $x_i \star (\omega(\mathbf{y})\mathbf{e}_\xi(\mathbf{y})) = \partial_{y_i}(\omega(\mathbf{y}))\mathbf{e}_\xi(\mathbf{y}) + \xi_i \omega(\mathbf{y})\mathbf{e}_\xi(\mathbf{y}) = (\xi_i + \partial_{y_i})(\omega(\mathbf{y}))\mathbf{e}_\xi(\mathbf{y})$ for $i = 1, \dots, n$. We deduce that the relation is true for any polynomial $p \in \mathbb{K}[\mathbf{x}]$ by repeated multiplications by the variables and linear combination. \square

Definition 2.5 For a subset $D \subset \mathbb{K}[[\mathbf{y}]]$, the inverse system generated by D is the vector space spanned by the elements $p(\mathbf{x}) \star \delta(\mathbf{y})$ for $\delta(\mathbf{y}) \in D, p(\mathbf{x}) \in \mathbb{K}[\mathbf{x}]$, that is, by the elements in D and all their derivatives.

For $\omega \in \mathbb{K}[[\mathbf{y}]]$, we denote by $\mu(\omega)$ the dimension of the inverse system of ω , generated by ω and all its derivatives $\partial^\alpha(\omega), \alpha \in \mathbb{N}^n$.

A simple way to compute this dimension is given in the next lemma:

Lemma 2.6 For $\omega \in \mathbb{K}[[\mathbf{y}]]$, $\mu(\omega)$ is the rank the matrix $\Theta = (\theta_{\alpha,\beta})_{\alpha \in A, \beta \in B}$ where

$$\omega(\mathbf{y} + \mathbf{t}) = \sum_{\alpha \in A \subset \mathbb{N}^n, \beta \in B \subset \mathbb{N}^n} \theta_{\alpha,\beta} \mathbf{y}^\alpha \mathbf{t}^\beta$$

for some finite subsets A, B of \mathbb{N}^n .

Proof. The Taylor expansion of $\omega(\mathbf{y} + \mathbf{t})$ at \mathbf{y} yields

$$\omega(\mathbf{y} + \mathbf{t}) = \sum_{\beta \in B \subset \mathbb{N}^n} \mathbf{t}^\beta \frac{1}{\beta!} \partial^\beta(\omega)(\mathbf{y}) = \sum_{\beta \in B \subset \mathbb{N}^n} \mathbf{t}^\beta \sum_{\alpha \in A \subset \mathbb{N}^n} \theta_{\alpha,\beta} \mathbf{y}^\alpha.$$

This shows that the rank of the matrix $\Theta = (\theta_{\alpha,\beta})_{\alpha \in A, \beta \in B}$, that is, the rank of the vector space spanned by $\sum_{\alpha \in A \subset \mathbb{N}^n} \theta_{\alpha,\beta} \mathbf{y}^\alpha$ for $\beta \in B$ is the rank $\mu(\omega)$ of the vector space spanned by all the derivatives $\partial^\beta(\omega)(\mathbf{y})$ of ω . \square

Lemma 2.7 The series $\mathbf{y}^{\alpha_{i,j}} \mathbf{e}_{\xi_i}(\mathbf{y})$ for $i = 1, \dots, r$ and $j = 1, \dots, \mu_i$ with $\alpha_{i,1}, \dots, \alpha_{i,\mu_i} \in \mathbb{N}^n$ and $\xi_i \in \mathbb{K}^n$ pairwise distinct are linearly independent.

Proof. Suppose that there exist $w_{i,j} \in \mathbb{K}$ such that $\sigma(\mathbf{y}) = \sum_{i=1}^r \sum_{j=1}^{\mu_i} w_{i,j} \mathbf{y}^{\alpha_{i,j}} \mathbf{e}_{\xi_i}(\mathbf{y}) = 0$ and let $\omega_i(\mathbf{y}) = \sum_{j=1}^{\mu_i} w_{i,j} \mathbf{y}^{\alpha_{i,j}}$. Then $\forall p \in \mathbb{K}[\mathbf{x}], p \star \sigma = 0 = \sum_{i=1}^r p(\xi_i + \partial)(\omega_i) \mathbf{e}_{\xi_i}(\mathbf{y})$. If the weights $\omega_i(\mathbf{y}) \in \mathbb{K}$ are of degree 0, by choosing for p an interpolation polynomial at one of the distinct points ξ_i , we deduce that $\omega_i = 0$ for $i = 1, \dots, r$. If the weights $\omega_i(\mathbf{y}) \in \mathbb{K}$ are degree ≥ 1 , by choosing $p = l(\mathbf{x}) - l(\xi_i) \in \mathbb{K}[\mathbf{x}]$ for a separating polynomial l of degree 1 ($l(\xi_i) \neq l(\xi_j)$ if $i \neq j$), we can reduce to a case where at least one of the non-zero weights has one degree less. By induction on the degree, we deduce that $\omega_i(\mathbf{y}) = 0$ for $i = 1, \dots, r$. This proves the linear independency of the series $\mathbf{y}^{\alpha_{i,j}} \mathbf{e}_{\xi_i}(\mathbf{y})$ for any $\alpha_{i,1}, \dots, \alpha_{i,\mu_i} \in \mathbb{N}^n$ and $\xi_i \in \mathbb{K}^n$ pairwise distinct. \square

2.1.3 Z-transform and positive characteristic

In the identification (6) of $\text{Hom}_{\mathbb{K}}(\mathbb{K}[\mathbf{x}], \mathbb{K})$ with the ring of power series in the variables \mathbf{y} , we can replace $\frac{\mathbf{y}^\alpha}{\alpha!}$ by \mathbf{z}^α where $\mathbf{z} = (z_1, \dots, z_n)$ is a set of new variables, so that $\text{Hom}_{\mathbb{K}}(\mathbb{K}[\mathbf{x}], \mathbb{K})$ is identified with $\mathbb{K}[[z_1, \dots, z_n]] = \mathbb{K}[[\mathbf{z}]]$. Any $\Lambda \in \text{Hom}_{\mathbb{K}}(\mathbb{K}[\mathbf{x}], \mathbb{K}) = R^*$ can be represented by the series:

$$\Lambda(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \Lambda(\mathbf{x}^\alpha) \mathbf{z}^\alpha \in \mathbb{K}[[\mathbf{z}]] \quad (8)$$

where $(\mathbf{z}^\alpha)_{\alpha \in \mathbb{N}^n}$ denotes the basis dual to the monomial basis $(\mathbf{x}^\alpha)_{\alpha \in \mathbb{N}^n}$ of $\mathbb{K}[\mathbf{x}]$. This corresponds to the *Z-transform* of the sequence $(\Lambda(\mathbf{x}^\alpha))_{\alpha \in \mathbb{N}^n}$ [1] or to the embedding in the ring of *divided powers* ($\mathbf{z}^\alpha = \frac{\mathbf{y}^\alpha}{\alpha!}$) [22][Sec. A 2.4], [34][Appendix A]. It allows to extend the duality properties to any field \mathbb{K} , which is not of characteristic 0.

The inverse transformation of the series $\sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \mathbf{z}^\alpha \in \mathbb{K}[[\mathbf{z}]]$ into the series $\sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{K}[[\mathbf{y}]]$ is known as the *Borel transform* [1].

For $\alpha, \beta \in \mathbb{N}^n$, we have $\mathbf{x}^\alpha \star \mathbf{z}^\beta = \begin{cases} \mathbf{z}^{\beta-\alpha} & \text{if } \beta - \alpha \in \mathbb{N}^n \\ 0 & \text{otherwise} \end{cases}$ so that z_i plays the role of the inverse of x_i . This explains the terminology of inverse system, introduced in [41]. With this formalism, the variables x_1, \dots, x_n act on the series in $\mathbb{K}[[\mathbf{z}]]$ as shift operators:

$$x_i \star \left(\sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \mathbf{z}^\alpha \right) = \sum_{\alpha \in \mathbb{N}^n} \sigma_{\alpha+e_i} \mathbf{z}^\alpha$$

where e_1, \dots, e_n is the canonical basis of \mathbb{N}^n . Therefore, for any $p_1, \dots, p_n \in \mathbb{K}[\mathbf{x}]$, the system of equations

$$p_1 \star \sigma = 0, \dots, p_n \star \sigma = 0$$

corresponds to a system of *difference equations* on $\sigma \in \mathbb{K}[[\mathbf{z}]]$.

In this setting, the evaluation e_ξ at a point $\xi \in \mathbb{K}^n$ is represented in $\mathbb{K}[[\mathbf{z}]]$ by the rational fraction $\frac{1}{\prod_{j=1}^n (1 - \xi_j z_j)}$. The series $\mathbf{y}^\beta e_\xi \in \mathbb{K}[[\mathbf{y}]]$ corresponds to the series of $\mathbb{K}[[\mathbf{z}]]$

$$\sum_{\alpha \in \mathbb{N}^n} \frac{(\alpha + \beta)!}{\alpha!} \xi^\alpha \mathbf{z}^{\alpha+\beta} = \beta! \mathbf{z}^\beta \sum_{\alpha \in \mathbb{N}^n} \binom{\alpha + \beta}{\beta} \xi^\alpha \mathbf{z}^\alpha = \frac{\beta! \mathbf{z}^\beta}{\prod_{j=1}^n (1 - \xi_j z_j)^{1+\beta_j}}.$$

The reconstruction of truncated series consists then in finding points $\xi_1, \dots, \xi_{r'} \in \mathbb{K}^n$ and finite sets A_i of coefficients $\omega_{i,\alpha} \in \mathbb{K}$ for $i = 1, \dots, r'$ and $\alpha \in A_i$ such that

$$\sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \mathbf{z}^\alpha = \sum_{i=1}^{r'} \sum_{\alpha \in A_i} \frac{\omega_{i,\alpha} \mathbf{z}^\alpha}{\prod_{j=1}^n (1 - \xi_{i,j} z_j)^{1+\alpha_j}} = \prod_{i=1}^{r'} \bar{z}_j \sum_{i=1}^{r'} \sum_{\alpha \in A_i} \frac{\omega_{i,\alpha}}{\prod_{j=1}^n (\bar{z}_j - \xi_{i,j})^{1+\alpha_j}} \quad (9)$$

where $\bar{z}_j = z_j^{-1}$.

In the univariate case, this reduces to computing polynomials $\omega(z), \delta(z) = \prod_{i=1}^{r'} (1 - \xi_i z)^{\mu_i} \in \mathbb{K}[z]$ with $\deg(\omega) < \deg(\delta) = \sum_i \mu_i = r$ such that

$$\sum_{k \in \mathbb{N}} \sigma_k z^k = \frac{\omega(z)}{\delta(z)}.$$

The decomposition can thus be computed from the *Padé approximant* of order $(r-1, r)$ of the sequence $(\sigma_k)_{k \in \mathbb{N}}$ (see e.g. [66][chap. 5]).

Unfortunately, this representation in terms of Padé approximant does not extend so nicely to the multivariate case. The series $\sigma = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \mathbf{z}^\alpha$ with a decomposition of the form (9) correspond to the series $\sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \mathbf{z}^{-\alpha}$, which is rational of the form $\frac{z^1 p(\mathbf{z})}{\prod q_i(z_i)}$ with a splittable denominator where $\deg(q_i) \geq 1$ are univariate polynomials (see e.g. [57], [7]). Though Padé approximants could be computed in this case by “separating” the variables (or by relaxing the constraints on the Padé approximants [20]), the rational fraction $\frac{z^1 p(\mathbf{z})}{\prod q_i(z_i)}$ is mixing the coordinates of the points $\xi_1, \dots, \xi_{r'} \in \mathbb{K}^n$ and the weights $\omega_{i,\alpha}$.

As the duality between multiplication and differential operators is less natural in $\mathbb{K}[[\mathbf{z}]]$, we will use hereafter the identification (6) of R^* with $\mathbb{K}[[\mathbf{y}]]$, when \mathbb{K} is of characteristic 0.

2.2 Hankel operators

The product \star allows us to define a Hankel operator as a multiplication operator by a dual element $\in \mathbb{K}[[\mathbf{y}]]$:

Definition 2.8 *The Hankel operator associated to an element $\sigma(\mathbf{y}) \in \mathbb{C}[[\mathbf{y}]]$ is*

$$\begin{aligned} H_\sigma : \mathbb{K}[\mathbf{x}] &\rightarrow \mathbb{K}[[\mathbf{y}]] \\ p(\mathbf{x}) &\mapsto p(\mathbf{x}) \star \sigma(\mathbf{y}). \end{aligned}$$

Its kernel is denoted $I_\sigma = \ker H_\sigma$. The series $\sigma = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} = H_\sigma(1) \in \mathbb{K}[[\mathbf{y}]]$ is called the symbol of H_σ .

Definition 2.9 *The rank of an element $\sigma \in \mathbb{K}[[\mathbf{y}]]$ is the rank of the Hankel operator $H_\sigma = r$.*

Definition 2.10 *The variety $\mathcal{V}_{\mathbb{K}}(I_\sigma)$ is called the characteristic variety of σ .*

The Hankel operator can also be interpreted as an operator on sequences:

$$\begin{aligned} H_\sigma : L_0(\mathbb{K}^{\mathbb{N}^n}) &\rightarrow \mathbb{K}^{\mathbb{N}^n} \\ p = (p_\beta)_{\beta \in B \subset \mathbb{N}^n} &\mapsto p \star \sigma = \left(\sum_{\beta \in B} p_\beta \sigma_{\alpha+\beta} \right)_{\alpha \in \mathbb{N}^n} \end{aligned}$$

where $L_0(\mathbb{K}^{\mathbb{N}^n})$ is the set of sequences $\in \mathbb{K}^{\mathbb{N}^n}$ with a finite support. This definition applies for a field \mathbb{K} of any characteristic. The operator H_σ can also be interpreted, via the Z-transform of the sequence $p \star \sigma$ (see Section 2.1.3), as the Hankel operator

$$\begin{aligned} H_\sigma : \mathbb{K}[\mathbf{x}] &\rightarrow \mathbb{K}[[\mathbf{z}]] \\ p = \sum_{\beta \in B} p_\beta \mathbf{x}^\beta &\mapsto p \star \sigma = \sum_{\alpha \in \mathbb{N}^n} \left(\sum_{\beta \in B} p_\beta \sigma_{\alpha+\beta} \right) \mathbf{z}^\alpha. \end{aligned}$$

As $\forall p, q \in \mathbb{K}[\mathbf{x}]$, $pq \star \sigma = p \star (q \star \sigma)$, we easily check that $I_\sigma = \ker H_\sigma$ is an ideal of $\mathbb{K}[\mathbf{x}]$ and that $\mathcal{A}_\sigma = \mathbb{K}[\mathbf{x}]/I_\sigma$ is an algebra.

Since $\forall p(\mathbf{x}), q(\mathbf{x}) \in \mathbb{K}[\mathbf{x}]$, $\langle p(\mathbf{x}) + I_\sigma, q(\mathbf{x}) + I_\sigma \rangle_\sigma = \langle p(\mathbf{x}), q(\mathbf{x}) \rangle_\sigma$, we see that $\langle \cdot, \cdot \rangle_\sigma$ induces an inner product on \mathcal{A}_σ .

Given a sequence $\sigma = (\sigma_\alpha)_{\alpha \in \mathbb{N}^n} \in \mathbb{K}^{\mathbb{N}^n}$, the kernel of H_σ is the set of polynomials $p = \sum_{\beta \in B} p_\beta \mathbf{x}^\beta$ such that $p = \sum_{\beta \in B} p_\beta \sigma_{\alpha+\beta}$ for all $\alpha \in \mathbb{N}^n$. This kernel is also called the set of *linear recurrence relations* of the sequence $\sigma = (\sigma_\alpha)_{\alpha \in \mathbb{N}^n}$.

Example 2.11 If $\sigma = e_\xi \in \mathbb{K}[[\mathbf{y}]]$ is the evaluation at a point $\xi \in \mathbb{K}^n$, then $H_{e_\xi} : p \in \mathbb{K}[\mathbf{x}] \mapsto p(\xi)e_\xi(\mathbf{y}) \in \mathbb{K}[[\mathbf{y}]]$. We easily check that $\text{rank } H_{e_\xi} = 1$ since the image of H_{e_ξ} is spanned by $e_\xi(\mathbf{y})$ and that $I_{e_\xi} = (x_1 - \xi_1, \dots, x_n - \xi_n)$.

If $\sigma = \sum_{i=1}^r \omega_i(\mathbf{y})e_{\xi_i}(\mathbf{y})$ then, by Lemma 2.3, the kernel I_σ is the set of polynomials $p \in \mathbb{K}[\mathbf{x}]$ such that $\forall q \in \mathbb{K}[\mathbf{x}]$, p is a solution of the following partial differential equation:

$$\sum_{i=1}^r \omega_i(\boldsymbol{\partial})(pq)(\xi_i) = 0.$$

Remark 2.12 The matrix of the operator H_σ in the bases $(\mathbf{x}^\alpha)_{\alpha \in \mathbb{N}^n}$ and its dual basis $\left(\frac{\mathbf{y}^\alpha}{\alpha!} \right)_{\alpha \in \mathbb{N}^n}$ is

$$[H_\sigma] = (\sigma_{\alpha+\beta})_{\alpha, \beta \in \mathbb{N}^n} = (\langle \sigma | \mathbf{x}^{\alpha+\beta} \rangle)_{\alpha, \beta \in \mathbb{N}^n}.$$

In the case $n = 1$, the coefficients of $[H_\sigma]$ depends only the sum of the indices indexing the rows and columns, which explains why it is are called an *Hankel* operator.

2.2.1 Truncated Hankel operators

In the sparse reconstruction problem, we are dealing with truncated series with known coefficients σ_α for α in a subset \mathbf{a} of \mathbb{N}^n . This leads to the definition of truncated Hankel operators.

Definition 2.13 *For two vector spaces $V, V' \subset \mathbb{K}[\mathbf{x}]$ and $\sigma \in \langle V \cdot V' \rangle^* = \langle v \cdot v' \mid v \in V, v' \in V' \rangle^* \subset \mathbb{K}[[\mathbf{y}]]$, we denote by $H_\sigma^{V, V'}$ the following map:*

$$\begin{aligned} H_\sigma^{V, V'} : V &\rightarrow V'^* = \text{hom}_{\mathbb{K}}(V', \mathbb{K}) \\ p(\mathbf{x}) &\mapsto p(\mathbf{x}) \star \sigma(\mathbf{y})|_{V'}. \end{aligned}$$

It is called the truncated Hankel operator on (V, V') .

When $V' = V$, the truncated Hankel operator is also denoted H_σ^V . When V (resp. V') is the vector space of polynomials of degree $\leq d \in \mathbb{N}$ (resp. $\leq d' \in \mathbb{N}$), the truncated operator is denoted $H_\sigma^{d, d'}$. If $B = \{b_1, \dots, b_r\}$ (resp. $B' = \{b'_1, \dots, b'_r\}$) is a basis of V (resp. V'), then the matrix of the operator $H_\sigma^{V, V'}$ in B and the dual basis of B' is

$$[H_\sigma^{B, B'}] = (\langle \sigma | b_j b'_i \rangle)_{1 \leq i, j \leq r}.$$

If $B = \mathbf{x}^{\mathbf{b}}$ and $B' = \mathbf{x}^{\mathbf{b}'}$ are monomial sets, we obtain the so-called *truncated moment matrix* of σ :

$$[H_\sigma^{B, B'}] = (\sigma_{\beta + \beta'})_{\beta' \in \mathbf{b}', \beta \in \mathbf{b}}.$$

When $n = 1$, this matrix is a classical Hankel matrix, which entries depend only of the sum of the indices of the rows and columns. When $n \geq 2$, we have a similar family of structured matrices, which rows and columns are indexed by exponents in \mathbb{N}^n and which entries depends on the sum of the row and column indices. These structured matrices called quasi-Hankel matrices have been studied for instance in [47].

2.3 Artinian algebra

In this section, we recall the properties of Artinian algebras. Let $I \subset \mathbb{K}[\mathbf{x}]$ be an ideal and let $\mathcal{A} = \mathbb{K}[\mathbf{x}]/I$ be the associated quotient algebra.

Definition 2.14 *The quotient algebra \mathcal{A} is artinian if $\dim_{\mathbb{K}}(\mathcal{A}) < \infty$.*

Notice that if \mathbb{K} is a subfield of a field \mathbb{L} , we denote by $\mathcal{A}_{\mathbb{L}} = \mathbb{L}[\mathbf{x}]/I_{\mathbb{L}} = \mathcal{A} \otimes \mathbb{L}$ where $I_{\mathbb{L}} = I \otimes \mathbb{L}$ is the ideal of $\mathbb{L}[\mathbf{x}]$ generated by the elements in I . As the dimension does not change by extension of the scalars, we have $\dim_{\mathbb{K}}(\mathbb{K}[\mathbf{x}]/I) = \dim_{\mathbb{L}}(\mathbb{L}[\mathbf{x}]/I_{\mathbb{L}}) = \dim_{\mathbb{L}}(\mathcal{A}_{\mathbb{L}})$. In particular, \mathcal{A} is artinian if and only if $\mathcal{A}_{\bar{\mathbb{K}}}$ is artinian, where $\bar{\mathbb{K}}$ is the algebraic closure. For the sake of simplicity, we are going to assume hereafter that \mathbb{K} is algebraically closed.

A classical result states that the quotient algebra $\mathcal{A} = \mathbb{K}[\mathbf{x}]/I$ is finite dimensional, i.e. artinian, if and only if, $\mathcal{V}_{\mathbb{K}}(I)$ is finite, that is, I defines a finite number of (isolated) points in $\bar{\mathbb{K}}^n$ (see e.g. [18][Theorem 6] or [23][Theorem 4.3]). Moreover, we have the following structure theorem (see [23][Theorem 4.9]):

Theorem 2.15 *Let $\mathcal{A} = \mathbb{K}[\mathbf{x}]/I$ be an artinian algebra of dimension r defined by an ideal I . Then we have a decomposition into a direct sum of subalgebras*

$$\mathcal{A} = \mathcal{A}_{\xi_1} \oplus \cdots \oplus \mathcal{A}_{\xi_{r'}} \quad (10)$$

where

- $\mathcal{V}(I) = \{\xi_1, \dots, \xi_{r'}\} \subset \bar{\mathbb{K}}^n$ with $r' \leq r$.
- $I = Q_1 \cap \cdots \cap Q_{r'}$ is a minimal primary decomposition of I where Q_i is \mathfrak{m}_{ξ_i} -primary with $\mathfrak{m}_{\xi_i} = (x_1 - \xi_{i,1}, \dots, x_n - \xi_{i,n})$.
- $\mathcal{A}_{\xi_i} \equiv \mathbb{K}[\mathbf{x}]/Q_i$ and $\mathcal{A}_{\xi_i} \cdot \mathcal{A}_{\xi_j} \equiv 0$ if $i \neq j$.

We check that \mathcal{A} localized at \mathfrak{m}_{ξ_i} is the local algebra \mathcal{A}_{ξ_i} . The dimension of \mathcal{A}_{ξ_i} is the multiplicity of the point ξ_i in $\mathcal{V}(I)$.

The projection of 1 on the sub-algebras \mathcal{A}_{ξ_i} as

$$1 \equiv \mathbf{u}_{\xi_1} + \cdots + \mathbf{u}_{\xi_{r'}}$$

with $\mathbf{u}_{\xi_i} \in \mathcal{A}_{\xi_i}$ yields the so-called *idempotents* \mathbf{u}_{ξ_i} associated to the roots ξ_i . By construction, they satisfy the following relations in \mathcal{A} , which characterize them:

- $1 \equiv \mathbf{u}_{\xi_1} + \cdots + \mathbf{u}_{\xi_{r'}}$,
- $\mathbf{u}_{\xi_i}^2 \equiv \mathbf{u}_{\xi_i}$ for $i = 1, \dots, r'$,
- $\mathbf{u}_{\xi_i} \mathbf{u}_{\xi_j} \equiv 0$ for $1 \leq i, j \leq r'$ and $i \neq j$.

The dual $\mathcal{A}^* = \text{Hom}_{\mathbb{K}}(\mathcal{A}, \mathbb{K})$ of $\mathcal{A} = \mathbb{K}[\mathbf{x}]/I$ is naturally identified with the sub-space

$$I^\perp = \{\Lambda \in \mathbb{K}[\mathbf{x}]^* = \mathbb{K}[[\mathbf{y}]] \mid \forall p \in I, \Lambda(p) = 0\}$$

of $\mathbb{K}[\mathbf{x}]^* = \mathbb{K}[[\mathbf{y}]]$. As I is stable by multiplication by the variables x_i , the orthogonal $I^\perp = \mathcal{A}^*$ is stable by the derivations $\frac{d}{dy_i}$. In the case of a primary ideal, the orthogonal has a simple form [41], [24], [45]:

Proposition 2.16 *Let Q be a primary ideal for the maximal ideal \mathfrak{m}_ξ of the point $\xi \in \mathbb{K}^n$ and let $\mathcal{A}_\xi = \mathbb{K}[\mathbf{x}]/Q$. Then*

$$Q^\perp = \mathcal{A}_\xi^* = D_\xi(Q) \cdot \mathbf{e}_\xi(\mathbf{y}),$$

where $D_\xi(Q) \subset \mathbb{K}[\mathbf{y}]$ is the set of polynomials $\omega(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$ such that $\forall q \in Q, \omega(\partial)(q)(\xi) = 0$.

The vector space $D_\xi(Q) \subset \mathbb{K}[\mathbf{y}]$ is called the *inverse system* of Q . As Q is an ideal, $Q^\perp = D_\xi(Q) \cdot \mathbf{e}_\xi(\mathbf{y})$ is stable by the derivations $\frac{d}{dy_i}$, and so is $D_\xi(Q)$.

If $I = Q_1 \cap \cdots \cap Q_{r'}$ is a minimal primary decomposition of the zero-dimensional ideal $I \subset \mathbb{K}[\mathbf{x}]$ with Q_i \mathfrak{m}_{ξ_i} -primary, then the decomposition (10) implies that

$$\mathcal{A}^* = I^\perp = Q_1^\perp \oplus \cdots \oplus Q_{r'}^\perp = \mathcal{A}_{\xi_1}^* \oplus \cdots \oplus \mathcal{A}_{\xi_{r'}}^*$$

since $Q_i^\perp \cap Q_j^\perp = (Q_i + Q_j)^\perp = (1)^\perp = \{0\}$ for $i \neq j$. The elements of $\mathcal{A}_{\xi_i}^*$ are the elements $\Lambda \in \mathcal{A}^* = I^\perp$ such that $\forall a_j \in \mathcal{A}_j, j \neq i, \lambda(a_j) = 0$. Any element $\Lambda \in \mathcal{A}^*$ decomposes as

$$\Lambda = \mathbf{u}_{\xi_1} \star \Lambda + \cdots + \mathbf{u}_{\xi_{r'}} \star \Lambda. \quad (11)$$

As we have $\mathbf{u}_{\xi_i} \star \Lambda(\mathcal{A}_{\xi_j}) = \Lambda(\mathbf{u}_{\xi_i} \mathcal{A}_{\xi_j}) = 0$ for $i \neq j$, we deduce that $\mathbf{u}_{\xi_i} \star \Lambda \in \mathcal{A}_{\xi_i}^* = Q_i^\perp$

By Proposition 2.16, $Q_i^\perp = D_i \mathbf{e}_\xi(\mathbf{y})$ where $D_i = D_{\xi_i}(Q_i)$ is the inverse system of Q_i . A basis of D_i can be computed (efficiently) from ξ_i and the generators of the ideal I (see e.g. [45] for more details).

From the decomposition (11) and Proposition 2.16, we deduce the following result:

Theorem 2.17 *Assume that K is algebraically closed. Let \mathcal{A} be an Artinian algebra of dimension r with $\mathcal{V}(I) = \{\xi_1, \dots, \xi_{r'}\} \subset K^n$. Let $D_i = D_{\xi_i}(I) \subset K[\mathbf{y}]$ be the vector space of differential polynomials $\omega(\mathbf{y}) \in K[\mathbf{y}]$ such that $\forall p \in I, \omega(\boldsymbol{\partial})(p)(\xi_i) = 0$. Then D_i is stable by the derivations $\frac{d}{dy_i}, i = 1, \dots, n$. It is of dimension μ_i with $\sum_{i=1}^{r'} \mu_i = r$. Any elements Λ of \mathcal{A}^* has a unique decomposition of the form*

$$\Lambda(\mathbf{y}) = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y}), \quad (12)$$

with $\omega_i(\mathbf{y}) \in D_i \subset K[\mathbf{y}]$, which is uniquely determined by values $\langle \Lambda | b_i \rangle$ for a basis $B = \{b_1, \dots, b_r\}$ of \mathcal{A} . Moreover, any element of this form is in \mathcal{A}^* .

Proof. For any polynomial $\omega(\mathbf{y}) \in K[\mathbf{y}]$, such that $\forall \xi \in \mathcal{V}(I), \forall p \in I, \omega(\boldsymbol{\partial})(p)(\xi) = 0$, the element $\omega(\mathbf{y}) e_{\xi}(\mathbf{y})$ is in I^\perp . Thus an element of the form (12) is in $I^\perp = \mathcal{A}^*$.

Let us prove that any element $\Lambda \in \mathcal{A}^*$ is of the form (12). By the relation (11), Λ decomposes as $\Lambda = \sum_{i=1}^{r'} \mathbf{u}_{\xi_i} \star \Lambda$ with $\mathbf{u}_{\xi_i} \star \Lambda \in \mathcal{A}_{\xi_i}^* = Q_i^\perp$. By Proposition 2.16, $Q_i^\perp = D_i e_{\xi_i}(\mathbf{y})$, where $D_i = D_{\xi_i}(Q_i)$ is the set of differential polynomials which vanish at ξ_i , on Q_i and thus on I . Thus $\mathbf{u}_{\xi_i} \star \Lambda$ is of the form $\mathbf{u}_{\xi_i} \star \Lambda = \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$ with $\omega_i(\mathbf{y}) \in D_i \subset K[\mathbf{y}]$. By Lemma 2.7, its decomposition as a sum of polynomial exponentials $\Lambda(\mathbf{y}) = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$ is unique. This concludes the proof. \square

Theorem 2.17 can be reformulated in terms of solutions of partial differential equations, using the relation between Artinian algebras and polynomial-exponentials $\mathcal{POLYEXP}$. This duality between polynomials equations and partial differential equations with constant coefficients goes back to [58] and has been further studied and extended for instance in [31], [24], [50], [49], [32]. In the case of a non-Artinian algebra, the solutions on an open convex domain are in the closure of the set of polynomial-exponential solutions (see e.g. [43][Théorème 2] or [33][Theorem 7.6.14]). The following result gives an explicit description of the solutions of partial differential equations associated to Artinian algebras, as special elements of $\mathcal{POLYEXP}$, with polynomial weights in the inverse systems of the points of the characteristic variety of the differential system:

Theorem 2.18 *Let $p_1, \dots, p_s \in C[x_1, \dots, x_n]$ be polynomials such that $C[\mathbf{x}]/(p_1, \dots, p_s)$ is finite dimensional over C . Let $\Omega \subset \mathbb{R}^n$ be a convex open domain of \mathbb{R}^n . A function $f \in C^\infty(\Omega)$ is a solution of the system of partial differential equations*

$$p_1(\boldsymbol{\partial})(f) = 0, \dots, p_s(\boldsymbol{\partial})(f) = 0 \quad (13)$$

if and only if it is of the form

$$f(\mathbf{y}) = \sum_{i=1}^r \omega_i(\mathbf{y}) e^{\xi_i \cdot \mathbf{y}}$$

with $\mathcal{VC}(p_1, \dots, p_s) = \{\xi_1, \dots, \xi_r\} \subset C^n$ and $\omega_i(\mathbf{y}) \in D_i \subset C[\mathbf{y}]$ where $D_i = D_{\xi_i}((p_1, \dots, p_s))$ is the space of differential polynomials, which vanish on the ideal (p_1, \dots, p_s) at ξ_i .

Proof. By a shift of the variables, we can assume that Ω contains 0. A solution of f of (13) in $C^\infty(\Omega)$ has a Taylor series expansion $f(\mathbf{y}) \in C[[\mathbf{y}]]$ at $0 \in \Omega$, which defines an element of $C[\mathbf{x}]^*$. By Lemma 2.3, f is a solution of the system (13) if and only if we have $p_1 \star f(\mathbf{y}) = 0, \dots, p_s \star f(\mathbf{y}) = 0$. Equivalently, $f(\mathbf{y}) \in I^\perp$ where $I = (p_1, \dots, p_s)$ is the ideal of $K[\mathbf{x}]$ generated by p_1, \dots, p_s . If $\mathcal{A} = C[\mathbf{x}]/I$ is finite dimensional, i.e. Artinian, Theorem 2.17 implies that the Taylor series $f(\mathbf{y})$ is in I^\perp , if and only if, it is of the form:

$$f(\mathbf{y}) = \sum_{i=1}^r \omega_i(\mathbf{y}) e^{\xi_i \cdot \mathbf{y}} \quad (14)$$

with $\mathcal{V}C(p_1, \dots, p_s) = \{\xi_1, \dots, \xi_r\} \subset \mathbb{C}^n$ and $\omega_i(\mathbf{y}) \in D_i = D_{\xi_i}(I) \subset C[\mathbf{y}]$ where D_i is the space of differential polynomials which vanish on $I = (p_1, \dots, p_s)$ at ξ_i . The polynomial-exponential function (14) is an analytic function with an infinite radius of convergence, which is a solution of the partial differential system (13) on Ω . By unicity of the solution with given derivatives at $0 \in \Omega$, $\sum_{i=1}^r \omega_i(\mathbf{y})e^{\xi_i \cdot \mathbf{y}}$ coincides with f on all the domain $\Omega \subset \mathbb{R}^n$. \square

Here is another reformulation of Theorem 2.17 in terms of *convolution* or *cross-correlation* of sequences:

Theorem 2.19 *Let $p_1, \dots, p_s \in \mathbb{C}[x_1, \dots, x_n]$ be polynomials such that $\mathbb{C}[\mathbf{x}]/(p_1, \dots, p_s)$ is finite dimensional over \mathbb{C} . The generating series of the sequences $\sigma = (\sigma_\alpha) \in \mathbb{C}^{\mathbb{N}^n}$ which satisfy the system of difference equations*

$$p_1 \star \sigma = 0, \dots, p_s \star \sigma = 0 \quad (15)$$

are of the form

$$\sigma(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} = \sum_{i=1}^r \omega_i(\mathbf{y})e^{\xi_i \cdot \mathbf{y}}$$

with $\mathcal{V}C(p_1, \dots, p_s) = \{\xi_1, \dots, \xi_r\} \subset \mathbb{C}^n$ and $\omega_i(\mathbf{y}) \in D_i \subset C[\mathbf{y}]$ such that $D_i = D_{\xi_i}((p_1, \dots, p_s))$ is the space of differential polynomials, which vanish on the ideal (p_1, \dots, p_s) at ξ_i .

Proof. The sequence σ is a solution of the system (15) if and only if $\sigma(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in I^\perp$ where $I = (p_1, \dots, p_s)$ is the ideal of $\mathbb{K}[\mathbf{x}]$ generated by p_1, \dots, p_s . We deduce the form of $\sigma(\mathbf{y}) \in \mathcal{POLYEXP}(\mathbf{y})$ from Theorem 2.17. \square

The solutions $\mathcal{V}(I) = \{\xi_1, \dots, \xi_r\}$ can be recovered by linear algebra, from the multiplicative structure of \mathcal{A} , using the properties of the following operators:

Definition 2.20 *Let g be a polynomial in \mathcal{A} . The g -multiplication operator \mathcal{M}_g is defined by*

$$\begin{aligned} \mathcal{M}_g : \mathcal{A} &\rightarrow \mathcal{A} \\ h &\mapsto \mathcal{M}_g(h) = gh. \end{aligned}$$

The transpose application \mathcal{M}_g^t of the g -multiplication operator \mathcal{M}_g is defined by

$$\begin{aligned} \mathcal{M}_g^t : \mathcal{A}^* &\rightarrow \mathcal{A}^* \\ \Lambda &\mapsto \mathcal{M}_g^t(\Lambda) = \Lambda \circ \mathcal{M}_g = g \star \Lambda. \end{aligned}$$

Let $B = \{b_1, \dots, b_r\}$ be a basis in \mathcal{A} and B^* its dual basis in \mathcal{A}^* . We denote by M_g^B (or simply M_g when there is no ambiguity on the basis) the matrix of \mathcal{M}_g in the basis B . As the matrix $(M_g^B)^t$ of the transpose application \mathcal{M}_g^t in the dual basis B^* in \mathcal{A}^* is the transpose of the matrix M_g^B of the application \mathcal{M}_g in the basis B in \mathcal{A} , the eigenvalues are the same for both matrices.

The main property we will use is the following (see e.g. [23]):

Proposition 2.21 *Let I be an ideal of $R = \mathbb{K}[\mathbf{x}]$ and suppose that $\mathcal{V}(I) = \{\xi_1, \xi_2, \dots, \xi_r\}$. Then*

- for all $g \in \mathcal{A}$, the eigenvalues of \mathcal{M}_g and \mathcal{M}_g^t are the values $g(\xi_1), \dots, g(\xi_r)$ of the polynomial g at the roots with multiplicities $\mu_i = \dim \mathcal{A}_{x_i}$.
- The eigenvectors common to all \mathcal{M}_g^t with $g \in \mathcal{A}$ are - up to a scalar - the evaluations $e_{\xi_1}, \dots, e_{\xi_r}$.

Remark 2.22 If $B = \{b_1, \dots, b_r\}$ is a basis of \mathcal{A} , then the coefficient vector of the evaluation

$$\mathbf{e}_{\xi_i} = \sum_{\beta \in \mathbb{N}^n} \xi_i^\beta \frac{\mathbf{y}^\beta}{\beta!} + \dots$$

in the dual basis of \mathcal{A}^* is $[(\mathbf{e}_{\xi_i} | b_j)]_{\beta \in B} = [b_j(\xi_i)]_{i=1 \dots r} = B(\xi_i)$. The previous proposition says that if M_g is the matrix of \mathcal{M}_g in the basis B of \mathcal{A} , then

$$M_g^t B(\xi_i) = g(\xi_i) B(\xi_i).$$

If moreover the basis B contains the monomials $1, x_1, x_2, \dots, x_n$, then the common eigenvectors of M_g^t are of the form $\mathbf{v}_i = c[1, \xi_{i,1}, \dots, \xi_{i,n}, \dots]$ and the root ξ_i can be computed from the coefficients of \mathbf{v}_i by taking the ratio of the coefficients of the monomials x_1, \dots, x_n by the coefficient of 1: $\xi_{i,k} = \frac{\mathbf{v}_{i,k+1}}{\mathbf{v}_{i,1}}$. Thus computing the common eigenvectors of all the matrices M_g^t for $g \in \mathcal{A}$ yield the roots ξ_i ($i = 1, \dots, r$). In practice, it is enough to compute the common eigenvectors of $M_{x_1}^t, \dots, M_{x_n}^t$, since $\forall g \in \mathbb{K}[\mathbf{x}], M_g^t = g(M_{x_1}^t, \dots, M_{x_n}^t)$.

We are going to consider special Artinian algebras, called *Gorenstein* algebras. They are defined as follows:

Definition 2.23 A \mathbb{K} -algebra \mathcal{A} is *Gorenstein* if $\exists \sigma \in \mathcal{A}^* = \text{Hom}_{\mathbb{K}}(\mathcal{A}, \mathbb{K})$ such that $\forall \Lambda \in \mathcal{A}^*, \exists a \in \mathcal{A}$ with $\Lambda = a \star \sigma$ and $a \star \sigma = 0$ implies $a = 0$.

In other words, \mathcal{A} is Gorenstein, if and only if, \mathcal{A}^* is a free \mathcal{A} -module of rank 1.

3 Correspondence between Artinian Gorenstein algebras and POLYEXP

In this section, we describe how polynomial-exponential functions are naturally associated to Artinian Gorenstein Algebras. As this property is preserved by tensorisation by $\bar{\mathbb{K}}$, we will also assume hereafter that $\mathbb{K} = \bar{\mathbb{K}}$ is *algebraically closed*.

Given $\sigma \in \mathbb{K}[[\mathbf{y}]]$, we consider its Hankel operator $H_\sigma : p \in \mathbb{K}[\mathbf{x}] \mapsto p \star \sigma \in \mathbb{K}[[\mathbf{y}]]$. The kernel I_σ of H_σ is an ideal and the elements $p \star \sigma$ of $\text{im } H_\sigma$ for $p \in \mathbb{K}[\mathbf{x}]$ are in $I_\sigma^\perp = \mathcal{A}_\sigma^*$ where $\mathcal{A}_\sigma = \mathbb{K}[\mathbf{x}]/I_\sigma : \forall q \in I_\sigma, \langle p \star \sigma | q \rangle = \langle q \star \sigma | p \rangle = 0$. If \mathcal{A}_σ is artinian of dimension r , then

$$\text{im } H_\sigma = \{p \star \sigma \mid p \in R\} \subset I_\sigma^\perp = \mathcal{A}_\sigma^*$$

is of dimension $\leq r$. Therefore, the injective map

$$\begin{aligned} \mathcal{H}_\sigma : \mathcal{A}_\sigma &\rightarrow \mathcal{A}_\sigma^* \\ p(\mathbf{x}) &\mapsto p(\mathbf{x}) \star \sigma(\mathbf{y}) \end{aligned}$$

induced by H_σ is an isomorphism, and we have the exact sequence:

$$0 \rightarrow I_\sigma \rightarrow \mathbb{K}[\mathbf{x}] \xrightarrow{H_\sigma} \mathcal{A}_\sigma^* \rightarrow 0. \quad (16)$$

Conversely, let \mathcal{A} be an Artinian Gorenstein Algebra of dimension r , generated by n elements a_1, \dots, a_n . It can be represented as the quotient algebra $\mathcal{A} = \mathbb{K}[\mathbf{x}]/I$ of $\mathbb{K}[\mathbf{x}]$ by an ideal I . As \mathcal{A} is Gorenstein, there exists $\sigma \in \mathcal{A}^*$ such that σ is a basis of the free \mathcal{A} -module \mathcal{A}^* . This implies that the kernel of the map

$$\begin{aligned} H_\sigma : \mathbb{K}[\mathbf{x}] &\rightarrow \mathcal{A}_\sigma^* \\ p &\mapsto p \star \sigma \end{aligned}$$

is the ideal I . Thus $\mathcal{A} = \mathcal{A}_\sigma$ and H_σ is of finite rank $r = \dim \mathcal{A}$.

This construction defines a correspondence between series $\sigma \in \mathbb{K}[[\mathbf{y}]]$ of finite rank or Hankel operators H_σ of finite rank and Artinian Gorenstein Algebras.

3.1 Hankel operators of finite rank

Hankel operators of finite rank play an important role in functional analysis. In one variable, they are characterized by Kronecker's theorem [35] as follows (see e.g. [51] for more details). Let $L_0(\mathbb{K}^{\mathbb{N}})$ be the vector space of sequences $\in \mathbb{K}^{\mathbb{N}}$ of finite support and let $\sigma = (\sigma_k)_{k \in \mathbb{N}} \in \mathbb{K}^{\mathbb{N}}$. The Hankel operator $H_\sigma : (p_l)_{l \in \mathbb{N}} \in L_0(\mathbb{K}^{\mathbb{N}}) \mapsto (\sum_l \sigma_{k+l} p_l)_{k \in \mathbb{N}} \in \mathbb{K}^{\mathbb{N}}$ is of finite rank r , if and only if, there exist polynomials $\omega_1(u), \dots, \omega_{r'}(u) \in \mathbb{K}[u]$ and $\xi_1, \dots, \xi_{r'} \in \mathbb{K}$ distinct such that

$$\sigma_k = \sum_{i=1}^{r'} \omega_i(k) \xi_i^k,$$

with $\sum_{i=1}^{r'} \deg(\omega_i) + 1 = \text{rank } H_\sigma$. Rewriting it in terms of generating series, we have $H_\sigma : p = \sum_l p_l x^l \in \mathbb{K}[x] \mapsto \sum_{k \in \mathbb{N}} (\sum_l \sigma_{k+l} p_l) \frac{y^k}{k!} = p \star \sigma$ is of finite rank, if and only if,

$$\sigma(y) = \sum_{k \in \mathbb{N}} \sigma_k \frac{y^k}{k!} = \sum_{i=1}^{r'} \omega_i(y) e^{\xi_i y}$$

with $\omega_1, \dots, \omega_{r'} \in \mathbb{K}[y]$ and $\xi_1, \dots, \xi_{r'} \in \mathbb{K}$ distinct such that $\sum_{i=1}^{r'} \deg(\omega_i) + 1 = \text{rank } H_\sigma$. Notice that $\deg(\omega_i) + 1$ is the dimension of the vector space spanned by $\omega_i(y)$ and all its derivatives.

The following result generalizes Kronecker's theorem, by establishing a correspondence between Hankel operators of finite rank and polynomial-exponential series and by connecting directly the rank of the Hankel operator with the decomposition of the associated polynomial-exponential series.

Theorem 3.1 *Let $\sigma(\mathbf{y}) \in \mathbb{K}[[\mathbf{y}]]$. Then $\text{rank } H_\sigma < \infty$, if and only if, $\sigma \in \text{POLYEXP}(\mathbf{y})$.*

If $\sigma(\mathbf{y}) = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$ with $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}] \setminus \{0\}$ and $\xi_i \in \mathbb{K}^n$ pairwise distinct, then the rank of H_σ is $r = \sum_{i=1}^{r'} \mu(\omega_i)$ where $\mu(\omega_i)$ is the dimension of the inverse system spanned by $\omega_i(\mathbf{y})$ and all its derivatives $\partial^\alpha \omega_i(\mathbf{y})$ for $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$.

Proof. If H_σ is of finite rank r , then $\mathcal{A}_\sigma = \mathbb{K}[\mathbf{x}]/I_\sigma = \mathbb{K}[\mathbf{x}]/\ker H_\sigma \sim \text{Im}(H_\sigma)$ is of dimension r and \mathcal{A}_σ is an artinian algebra. By Theorem 2.15, it can be decomposed as a direct sum of sub-algebras

$$\mathcal{A}_\sigma = \mathcal{A}_{\xi_1} \oplus \dots \oplus \mathcal{A}_{\xi_{r'}}$$

where $I_\sigma = Q_1 \cap \dots \cap Q_{r'}$ is a minimal primary decomposition, $\mathcal{V}(I_\sigma) = \{\xi_1, \dots, \xi_{r'}\}$ and \mathcal{A}_{ξ_i} is the local algebra for the maximal ideal \mathfrak{m}_{ξ_i} defining the root $\xi_i \in \mathbb{K}^n$, such that $\mathcal{A}_{\xi_i} \equiv \mathbb{K}[\mathbf{x}]/Q_i$ where Q_i is a \mathfrak{m}_{ξ_i} -primary component of I_σ .

By Theorem 2.17, the series $\sigma \in \mathcal{A}_\sigma^* = I_\sigma^\perp$ can be decomposed as

$$\sigma = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y}) \tag{17}$$

with $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$ and $\omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y}) \in \mathcal{A}_{\xi_i}^* = Q_i^\perp$, i.e. $\sigma \in \text{POLYEXP}(\mathbf{y})$.

Conversely, let us show that if $\sigma(\mathbf{y}) = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$ with $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}] \setminus \{0\}$ and $\xi_i \in \mathbb{K}^n$ pairwise distinct, the rank of H_σ is finite. Using Lemma 2.4, we check that $I_\sigma = \ker H_\sigma$ contains

$\cap_{i=1}^r \mathbf{m}_{\xi_i}^{d_i+1}$ where d_i is the degree of $\omega_i(\mathbf{y})$. Thus $\mathcal{V}(I_\sigma) \subset \{\xi_1, \dots, \xi_{r'}\}$, \mathcal{A}_σ is an artinian algebra and $\text{rank } H_\sigma = \dim(\text{Im}(H_\sigma)) = \dim(\mathbb{K}[\mathbf{x}]/I_\sigma) = \dim(\mathcal{A}_\sigma) < \infty$.

Let us show now that $\text{rank } H_\sigma = \sum_{i=1}^{r'} \mu(\omega_i)$. From the decomposition (11) and Proposition 2.16, we deduce that $\mathbf{u}_{\xi_i} \star \sigma = \omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})$. By the exact sequence (16), $\mathcal{A}_\sigma^* = \text{Im}(H_\sigma) = \{p \star \sigma \mid p \in \mathbb{K}[\mathbf{x}]\}$. Therefore, $\mathcal{A}_{\xi_i}^* = Q_i^\perp$ is spanned by the elements $\mathbf{u}_{\xi_i} \star (p \star \sigma) = p \star (\mathbf{u}_{\xi_i} \star \sigma) = p \star (\omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y}))$ for $p \in \mathbb{K}[\mathbf{x}]$, that is, by $\omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})$ and all its derivatives with respect to $\frac{d}{dy_i}$. This shows that $\mathcal{A}_{\xi_i}^* = D_i \mathbf{e}_{\xi_i}(\mathbf{y})$ where $D_i \subset \mathbb{K}[\mathbf{y}]$ is the inverse system spanned by $\omega_i(\mathbf{y})$. It implies that the multiplicity $\mu_i = \dim \mathcal{A}_{\xi_i}^* = \dim \mathcal{A}_{\xi_i}$ of ξ_i is the dimension $\mu(\omega_i)$ of the inverse system of $\omega_i(\mathbf{y})$. We deduce that $\dim \mathcal{A}_\sigma = \dim \mathcal{A}_\sigma^* = r = \sum_{i=1}^{r'} \mu(\omega_i)$. This concludes the proof of the theorem. \square

Let us give some direct consequences of this result.

Proposition 3.2 *If $\sigma(\mathbf{y}) = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})$ with $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}] \setminus \{0\}$ and $\xi_i \in \mathbb{K}^n$ pairwise distinct, then we have the following properties:*

- *The points $\xi_1, \xi_2, \dots, \xi_{r'} \in \mathbb{K}^n$ are the common roots of the polynomials in $I_\sigma = \ker H_\sigma = \{p \in \mathbb{K}[\mathbf{x}] \mid \forall q \in \mathbb{K}[\mathbf{x}], \langle \sigma | pq \rangle = 0\}$.*
- *The series $\omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}$ is a generator of the inverse system of Q_i^\perp , where Q_i is the primary component of I_σ associated to ξ_i .*
- *The inner product $\langle \cdot, \cdot \rangle_\sigma$ is non-degenerate on $\mathcal{A}_\sigma = \mathbb{K}[\mathbf{x}]/I_\sigma$.*

Proof. Suppose that $\sigma(\mathbf{y}) = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})$.

To prove the first point, we construct polynomials $\delta_i(\mathbf{x}) \in \mathbb{K}[\mathbf{x}]$ such that $\delta_i \star \sigma = \mathbf{e}_{\xi_i}(\mathbf{y})$. We chose a polynomial $\delta_i(\mathbf{x})$ such that $\delta_i(\xi_1 + \partial_{y_1}, \dots, \xi_n + \partial_{y_n})(\omega_i)(\mathbf{y}) = 1$. We can take for instance a term of the form $c \prod_{j=1}^n (x_j - \xi_{i,j})^{\alpha_j}$ where $c \in \mathbb{K}$ and $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$ is the exponent of a monomial of ω_i of highest degree. By Lemma 2.4, we have

$$\delta_i(\mathbf{x}) \star (\omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})) = \delta_i(\xi_i + \partial)(\omega_i)(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y}) = \mathbf{e}_{\xi_i}(\mathbf{y}).$$

Then $\forall p \in I_\sigma$, $\langle \delta_i \star (\mathbf{u}_{\xi_i} \star \sigma) | p \rangle = \langle \delta_i(\mathbf{x}) \star (\omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})) | p \rangle = \langle \mathbf{e}_{\xi_i}(\mathbf{y}) | p \rangle = p(\xi_i) = 0$ and $\mathcal{V}(I_\sigma) \supset \{\xi_1, \dots, \xi_{r'}\}$. As I_σ contains $\cap_{i=1}^r \mathbf{m}_{\xi_i}^{d_i+1}$ where d_i is the degree of $\omega_i(\mathbf{y})$, we also have $\mathcal{V}(I_\sigma) \subset \{\xi_1, \dots, \xi_{r'}\}$, which proves the first point.

The second point is a consequence of Theorem 3.1, since we have $\omega_i(\mathbf{y}) \mathbf{e}_{\xi_i} \in D_i = Q_i^\perp$ so that $\mu(\omega_i) = \mu(\omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}) \leq \dim(D_i) = \dim(Q_i^\perp)$ and

$$r = \sum_{i=1}^{r'} \mu(\omega_i) \leq \sum_{i=1}^{r'} \dim(Q_i^\perp) = \dim(I^\perp) = \dim(\mathcal{A}_\sigma) = r.$$

Therefore, the inverse system spanned by $\omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}$, of dimension $\mu(\omega_i) = \dim(Q_i^\perp) = \dim D_i$, is equal to D_i .

Finally, we prove the third point. By definition of I_σ , if $p \in \mathbb{K}[\mathbf{x}]$ is such that $\forall q \in \mathbb{K}[\mathbf{x}]$,

$$\langle p(\mathbf{x}), q(\mathbf{x}) \rangle_\sigma = \langle p \star \sigma(\mathbf{y}) | q(\mathbf{x}) \rangle = 0,$$

then $p \star \sigma(\mathbf{y}) = 0$ and $p \in I_\sigma$. We deduce that the inner product $\langle \cdot, \cdot \rangle_\sigma$ is non-generate on $\mathcal{A}_\sigma = \mathbb{K}[\mathbf{x}]/I_\sigma$, which proves the last point. \square

If $(b_i)_{1 \leq i \leq r}$ and $(b'_i)_{1 \leq i \leq r}$ are bases of \mathcal{A}_σ , then the matrix of \mathcal{H}_σ in the basis $(b_i)_{1 \leq i \leq \delta}$ and in the dual basis of $(b'_i)_{1 \leq i \leq r}$ is $[\mathcal{H}_\sigma] = (\langle \sigma | b_i(\mathbf{x}) b'_j(\mathbf{x}) \rangle)_{1 \leq i, j \leq r}$. In particular, if $(\mathbf{x}^\beta)_{\beta \in B}$ and $(\mathbf{x}^{\beta'})_{\beta' \in B'}$ are bases of \mathcal{A}_σ , its matrix in the corresponding bases is

$$[\mathcal{H}_\sigma] = (\langle \sigma | \mathbf{x}^{\beta+\beta'} \rangle)_{\beta \in B, \beta' \in B'} = (\sigma_{\beta+\beta'})_{\beta \in B, \beta' \in B'} = H_\sigma^{B, B'}.$$

It is a submatrix of the (infinite) matrix $[H_\sigma]$. Conversely, we have the following property:

Lemma 3.3 *Let $B = \{b_1, \dots, b_r\}$, $B' = \{b'_1, \dots, b'_r\} \subset \mathbf{K}[\mathbf{x}]$. If the matrix $H_\sigma^{B, B'} = (\langle \sigma | b_i b'_j \rangle)_{i \in B, j \in B'}$ is invertible, then B and B' are linearly independent in \mathcal{A}_σ .*

Proof. Suppose that $H_\sigma^{B, B'}$ is invertible. If there exist $p = \sum_i p_i b_i$ ($p_i \in \mathbf{K}$) such that $p \equiv 0$ in \mathcal{A}_σ . Then $p \star \sigma = 0$ and $\forall q \in R$, $\langle \sigma | pq \rangle = 0$. In particular, for $j = 1 \dots r$ we have

$$\sum_{i=1}^r \langle \sigma | b_i b'_j \rangle p_i = 0.$$

As $H_\sigma^{B, B'}$ is invertible, $p_i = 0$ for $i = 1, \dots, r$ and B is a family of linearly independent elements in \mathcal{A}_σ . Since we have $(H_\sigma^{B, B'})^t = H_\sigma^{B', B}$, we prove by a similar argument that $H_\sigma^{B, B'}$ invertible also implies that for B' is linearly independent in \mathcal{A}_σ . \square

Notice that the converse is not necessarily true, as shown by the following example in one variable: if $\sigma = y$, then $I_\sigma = (x^2)$, $\mathcal{A}_\sigma = \mathbf{K}[x]/(x^2)$ and $B = B' = \{1\}$ are linearly independent in \mathcal{A}_σ , but $H_\sigma^{B, B'} = (\langle \sigma | 1 \rangle) = (0)$ is not invertible.

This lemma implies that if $\dim \mathcal{A}_\sigma < +\infty$, $|B| = |B'| = \dim \mathcal{A}_\sigma$ and $H_\sigma^{B, B'}$ is invertible, then $(\mathbf{x}^\beta)_{\beta \in B}$ and $(\mathbf{x}^{\beta'})_{\beta' \in B'}$ are bases of \mathcal{A}_σ .

A special case of interest is when the roots are simple. We characterize it as follows:

Proposition 3.4 *Let $\sigma(\mathbf{y}) \in \mathbf{K}[[\mathbf{y}]]$. The following conditions are equivalent:*

1. $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}(\mathbf{y})$, with $\omega_i \in \mathbf{K} \setminus \{0\}$ and $\xi_i \in \mathbf{K}^n$ pairwise distinct.
2. The rank of H_σ is r and the multiplicity of the points ξ_1, \dots, ξ_r in $\mathcal{V}(I_\sigma)$ is 1.
3. A basis of \mathcal{A}_σ^* is $\mathbf{e}_{\xi_1}, \dots, \mathbf{e}_{\xi_r}$.

Proof. $1 \Rightarrow 2$. The dimension $\mu(\omega_i)$ of the inverse system spanned by $\omega_i \in \mathbf{K} \setminus \{0\}$ and its derivatives is 1. By Theorem 3.1, the rank \mathcal{A}_σ is $r = \sum_{i=1}^r \mu(\omega_i) = \sum_{i=1}^r 1$ and the multiplicity of the roots ξ_1, \dots, ξ_r in $\mathcal{V}(I_\sigma)$ is 1.

$2 \Rightarrow 3$. As the multiplicity of the roots is 1, by Theorem 3.1, $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}(\mathbf{y})$ with $\deg(\omega_i) = 0$. As \mathcal{A}_σ^* is spanned by the elements $p \star \sigma = \sum_{i=1}^r \omega_i p(\xi_i) \mathbf{e}_{\xi_i}$ for $p \in \mathbf{K}[\mathbf{x}]$, $\mathbf{e}_{\xi_1}, \dots, \mathbf{e}_{\xi_r}$ is a generating family of the vector space \mathcal{A}_σ^* . Thus $\mathbf{e}_{\xi_1}, \dots, \mathbf{e}_{\xi_r}$ is a basis of \mathcal{A}_σ^* .

$3 \Rightarrow 1$. As $\mathbf{e}_{\xi_1}, \dots, \mathbf{e}_{\xi_r}$ is a basis \mathcal{A}_σ^* , the points $\xi_i \in \mathbf{K}^n$ are pairwise distinct. As $\sigma \in \mathcal{A}_\sigma^*$, there exists $\omega_i \in \mathbf{K}$ such that $\sigma = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}$. If one of these coefficients ω_i vanishes then $\dim(\mathcal{A}_\sigma^*) < r$, which is contradicting point 3. Thus $\omega_i \in \mathbf{K} \setminus \{0\}$. \square

In the case where all the coefficients of σ are in \mathbf{R} , we can consider the following property of positivity:

Definition 3.5 *An element $\sigma \in \mathbf{R}[[\mathbf{y}]] = \mathbf{R}[\mathbf{x}]^*$ is semi-definite positive if $\forall p \in \mathbf{R}[\mathbf{x}]$, $\langle p, p \rangle_\sigma = \langle \sigma | p^2 \rangle \geq 0$. It is denoted $\sigma \succcurlyeq 0$.*

The positivity of σ induces a nice property of its decomposition, which is an important ingredient of polynomial optimisation. It is saying that a positive measure on \mathbf{R}^n with an Hankel operator of finite rank r is a convex combination of r distinct Dirac measures of \mathbf{R}^n . See e.g. [38] for more details. For the sake of completeness, we give here its simple proof (see also [37][prop. 3.14]).

Proposition 3.6 *Let $\sigma \in \mathbb{R}[[\mathbf{y}]]$ of finite rank. Then $\sigma \succcurlyeq 0$, if and only if,*

$$\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}(\mathbf{y})$$

with $\omega_i > 0$, $\xi_i \in \mathbb{R}^n$.

Proof. If $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}$ with $\omega_i > 0$, $\xi_i \in \mathbb{R}^n$, then clearly $\forall p \in \mathbb{R}[\mathbf{x}]$,

$$\langle \sigma | p^2 \rangle = \sum_{i=1}^r \omega_i p^2(\xi_i) \geq 0$$

and $\sigma \succcurlyeq 0$.

Conversely suppose that $\forall p \in \mathbb{R}[\mathbf{x}]$, $\langle \sigma | p^2 \rangle \geq 0$. Then $p \in I_\sigma$, if and only if, $\langle \sigma | p^2 \rangle = 0$. We check that I_σ is real radical: If $p^{2k} + \sum_j q_j^2 \in I_\sigma$ for some $k \in \mathbb{N}$, $p, q_j \in \mathbb{R}[\mathbf{x}]$ then

$$\left\langle \sigma | p^{2k} + \sum_j q_j^2 \right\rangle = \langle \sigma | p^{2k} \rangle + \sum_j \langle \sigma | q_j^2 \rangle = 0$$

which implies that $\langle \sigma | (p^k)^2 \rangle = 0$, $\langle \sigma | q_j^2 \rangle = 0$ and that $p^k, q_j \in I_\sigma$. Let $k' = \lceil \frac{k}{2} \rceil$. We have $\langle \sigma | (p^{k'})^2 \rangle = 0$, which implies that $p^{k'} \in I_\sigma$. Iterating this reduction, we deduce that $p \in I_\sigma$. This shows that I_σ is real radical and $\mathcal{V}(I_\sigma) \subset \mathbb{R}^n$. By Proposition 3.4, we deduce that $\sigma = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}$ with $\omega_i \in \mathbb{C} \setminus \{0\}$ and $\xi_i \in \mathbb{R}^n$. Let $\mathbf{u}_i \in \mathbb{R}[\mathbf{x}]$ be a family of interpolation polynomials at $\xi_i \in \mathbb{R}^n$: $\mathbf{u}_i(\xi_i) = 1$, $\mathbf{u}_i(\xi_j) = 0$ for $j \neq i$. Then $\langle \sigma | \mathbf{u}_i^2 \rangle = \omega_i \in \mathbb{R}_+$. This proves that $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}(\mathbf{y})$ with $\omega_i > 0$, $\xi_i \in \mathbb{R}^n$. \square

3.2 The decomposition of σ

The sparse decomposition problem of the series $\sigma \in \mathbb{K}[[\mathbf{y}]]$ consists in computing the support $\{\xi_1, \dots, \xi_r\}$ and the weights $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$ of so that $\sigma = \sum_{i=1}^r \omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})$. In this section, we describe how to compute it from the Hankel operator H_σ .

We recall classical results on the resolution of polynomial equations by eigenvalue and eigenvector computation, that we will use to compute the decomposition. Hereafter, $\mathcal{A} = \mathbb{K}[\mathbf{x}]/I$ is the quotient algebra of $\mathbb{K}[\mathbf{x}]$ by any ideal I and $\mathcal{A}^* = \text{Hom}_{\mathbb{K}}(\mathcal{A}, \mathbb{K})$ is the dual of \mathcal{A} . It is naturally identified with the orthogonal $I^\perp = \{\Lambda \in \mathbb{K}[[\mathbf{y}]] \mid \forall p \in I, \langle \Lambda, p \rangle = 0\}$. In the reconstruction problem, we will take $I = I_\sigma$.

By Proposition 3.2, H_σ induces the isomorphism

$$\begin{aligned} \mathcal{H}_\sigma : \mathcal{A}_\sigma &\rightarrow \mathcal{A}_\sigma^* \\ p(\mathbf{x}) &\mapsto p(\mathbf{x}) \star \sigma(\mathbf{y}). \end{aligned}$$

Lemma 3.7 *For any $g \in \mathbb{K}[\mathbf{x}]$, we have*

$$\mathcal{H}_{g \star \sigma} = \mathcal{M}_g^t \circ \mathcal{H}_\sigma = \mathcal{H}_\sigma \circ \mathcal{M}_g. \quad (18)$$

Proof. This is a direct consequence of the definitions of $\mathcal{H}_{g \star \sigma}$, \mathcal{H}_σ , \mathcal{M}_g^t and \mathcal{M}_g . \square

From Relation (18) and Proposition 2.21, we have the following property.

Proposition 3.8 *If $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})$ with $\omega_i \in \mathbb{K}[\mathbf{y}] \setminus \{0\}$ and $\xi_i \in \mathbb{K}^n$ distinct, then*

- for all $g \in \mathcal{A}$, the generalized eigenvalues of $(\mathcal{H}_{g\star\sigma}, \mathcal{H}_\sigma)$ are $g(\xi_i)$ with multiplicity $\mu_i = \mu(\omega_i)$, $i = 1 \dots r$,
- the generalized eigenvectors common to all $(\mathcal{H}_{g\star\sigma}, \mathcal{H}_\sigma)$ with $g \in \mathcal{A}$ are - up to a scalar - $\mathcal{H}_\sigma^{-1}(\mathbf{e}_{\xi_1}), \dots, \mathcal{H}_\sigma^{-1}(\mathbf{e}_{\xi_r})$.

Remark 3.9 If we take $g = x_i$, then the eigenvalues are the i -th coordinates of the points ξ_j .

3.2.1 The case of simple roots

In the case of simple roots, that is σ is of the form $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}(\mathbf{y})$ with $\omega_i \in \mathbb{K} \setminus \{0\}$ and $\xi_i \in \mathbb{K}^n$ distinct, computing the decomposition reduces to a simple eigenvector computation, as we will see.

By Proposition 3.4, $\{\mathbf{e}_{\xi_1}, \dots, \mathbf{e}_{\xi_r}\}$ is a basis of \mathcal{A}_σ^* . We denote by $\{\mathbf{u}_{\xi_1}, \dots, \mathbf{u}_{\xi_r}\}$ the basis of \mathcal{A}_σ , which is dual to $\{\mathbf{e}_{\xi_1}, \dots, \mathbf{e}_{\xi_r}\}$, so that $\forall a(\mathbf{x}) \in \mathcal{A}_\sigma$,

$$a(\mathbf{x}) \equiv \sum_{i=1}^r \langle \mathbf{e}_{\xi_i}(\mathbf{y}) | a(\mathbf{x}) \rangle \mathbf{u}_{\xi_i}(\mathbf{x}) \equiv \sum_{i=1}^r a(\xi_i) \mathbf{u}_{\xi_i}(\mathbf{x}). \quad (19)$$

From this formula, we easily verify that the polynomials $\mathbf{u}_{\xi_1}, \mathbf{u}_{\xi_2}, \dots, \mathbf{u}_{\xi_r}$ are the *interpolation polynomials* at the points $\xi_1, \xi_2, \dots, \xi_r$, and satisfy the following relations in \mathcal{A}_σ :

- $\mathbf{u}_{\xi_i}(\xi_j) = \begin{cases} 1 & \text{if } i = j, \\ 0 & \text{otherwise.} \end{cases}$
- $\mathbf{u}_{\xi_i}(\mathbf{x})^2 \equiv \mathbf{u}_{\xi_i}(\mathbf{x})$.
- $\sum_{i=1}^r \mathbf{u}_{\xi_i}(\mathbf{x}) \equiv 1$.

Proposition 3.10 Let $\sigma = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}(\mathbf{y})$ with ξ_i pairwise distinct and $\omega_i \in \mathbb{K} \setminus \{0\}$. The basis $\{\mathbf{u}_{\xi_1}, \dots, \mathbf{u}_{\xi_r}\}$ is an orthogonal basis of \mathcal{A}_σ for the inner product $\langle \cdot, \cdot \rangle_\sigma$ and satisfies $\langle \mathbf{u}_{\xi_i}, 1 \rangle_\sigma = \langle \sigma | \mathbf{u}_{\xi_i} \rangle = \omega_i$ for $i = 1 \dots r$.

Proof. For $i, j = 1 \dots r$, we have $\langle \mathbf{u}_{\xi_i}, \mathbf{u}_{\xi_j} \rangle_\sigma = \langle \sigma | \mathbf{u}_{\xi_i} \mathbf{u}_{\xi_j} \rangle = \sum_{k=1}^r \omega_k \mathbf{u}_{\xi_i}(\xi_k) \mathbf{u}_{\xi_j}(\xi_k)$. Thus

$$\langle \mathbf{u}_{\xi_i}, \mathbf{u}_{\xi_j} \rangle_\sigma = \begin{cases} \omega_i & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

and $\{\mathbf{u}_{\xi_1}, \dots, \mathbf{u}_{\xi_r}\}$ is an orthogonal basis of \mathcal{A}_σ . Moreover, $\langle \mathbf{u}_{\xi_i}, 1 \rangle_\sigma = \langle \sigma | \mathbf{u}_{\xi_i} \rangle = \sum_{k=1}^r \omega_k \mathbf{u}_{\xi_i}(\xi_k) = \omega_i$. \square

Proposition 2.21 implies the following result:

Corollary 3.11 If $g \in \mathbb{K}[\mathbf{x}]$ is separating the roots ξ_1, \dots, ξ_r (i.e. $g(\xi_i) \neq g(\xi_j)$ when $i \neq j$), then

- the operator \mathcal{M}_g is diagonalizable and its eigenvalues are $g(\xi_1), \dots, g(\xi_r)$,
- the corresponding eigenvectors of \mathcal{M}_g are, up to a non-zero scalar, the interpolation polynomials $\mathbf{u}_{\xi_1}, \dots, \mathbf{u}_{\xi_r}$.
- the corresponding eigenvectors of \mathcal{M}_g^\dagger are, up to a non-zero scalar, the evaluations $\mathbf{e}_{\xi_1}, \dots, \mathbf{e}_{\xi_r}$.

A simple computation shows that $H_\sigma(\mathbf{u}_{\xi_i}) = \omega_i \mathbf{e}_{\xi_i}(\mathbf{y})$ for $i = 1, \dots, r$. This leads to the following formula for the weights of the decomposition of σ :

Proposition 3.12 *If $\sigma = \sum_{i=1}^r \omega_i e_{\xi_i}(\mathbf{y})$ with ξ_i pairwise distinct and $\omega_i \in \mathbb{K} \setminus \{0\}$ and $g \in \mathbb{K}[\mathbf{x}]$ is separating the roots ξ_1, \dots, ξ_r , then there are r linearly independent generalized eigenvectors $\mathbf{v}_1(\mathbf{x}), \dots, \mathbf{v}_r(\mathbf{x})$ of $(\mathcal{H}_{g \star \sigma}, \mathcal{H}_\sigma)$, which satisfy the relations:*

$$\begin{aligned} \langle \sigma | x_j \mathbf{v}_i \rangle &= \xi_{i,j} \langle \sigma | \mathbf{v}_i \rangle \text{ for } j = 1, \dots, n, i = 1, \dots, r \\ \sigma(\mathbf{y}) &= \sum_{i=1}^r \frac{1}{\mathbf{v}_i(\xi_i)} \langle \sigma | \mathbf{v}_i \rangle e_{\xi_i}(\mathbf{y}) \end{aligned}$$

Proof. By the relations (18) and Corollary 3.11, the eigenvectors $\mathbf{u}_{\xi_1}, \dots, \mathbf{u}_{\xi_r}$ of \mathcal{M}_g are the generalized eigenvectors of $(\mathcal{H}_{g \star \sigma}, \mathcal{H}_\sigma)$. By Corollary 3.11, \mathbf{v}_i is a multiple of the interpolation polynomial \mathbf{u}_{ξ_i} , and thus of the form $\mathbf{v}_i(\mathbf{x}) = \mathbf{v}_i(\xi_i) \mathbf{u}_{\xi_i}(\mathbf{x})$ since $\mathbf{u}_{\xi_i}(\xi_i) = 1$. We deduce that $\mathbf{u}_{\xi_i}(\mathbf{x}) = \frac{1}{\mathbf{v}_i(\xi_i)} \mathbf{v}_i(\mathbf{x})$. By Proposition 3.10, we have

$$\omega_i = \langle \sigma | \mathbf{u}_{\xi_i} \rangle = \frac{1}{\mathbf{v}_i(\xi_i)} \langle \sigma | \mathbf{v}_i \rangle,$$

from which, we deduce the decomposition of $\sigma = \sum_{i=1}^r \frac{1}{\mathbf{v}_i(\xi_i)} \langle \sigma | \mathbf{v}_i \rangle e_{\xi_i}(\mathbf{y})$. It implies that

$$\langle \sigma | x_j \mathbf{u}_{\xi_i} \rangle = \sum_{k=1}^r \omega_k \xi_{k,j} \mathbf{u}_{\xi_i}(\xi_k) = \xi_{i,j} \omega_i = \xi_{i,j} \langle \sigma | \mathbf{u}_{\xi_i} \rangle.$$

Multiplying by $\mathbf{v}_i(\xi_i)$, we obtain the first relations. \square

This property shows that the decomposition of σ can be deduced directly from the generalized eigenvectors of $(\mathcal{H}_{g \star \sigma}, \mathcal{H}_\sigma)$. In particular, it is not necessary to solve a Vandermonde linear system to recover the weights ω_i as in the pencil method (see Section 1.1). We summarize it in the following algorithm, which computes the decomposition of σ , assuming a basis B of \mathcal{A}_σ is known.

Algorithm 3.1: Decomposition of polynomial-exponential series with constant weights

Input: the (first) coefficients σ_α of a series $\sigma \in \mathbb{K}[[\mathbf{y}]]$ for $\alpha \in \mathbf{a} \subset \mathbb{N}^n$ and bases $B = \{b_1, \dots, b_r\}$, $B = \{b'_1, \dots, b'_r\}$, of \mathcal{A}_σ such that $\langle B' \cdot B^+ \rangle \subset \langle \mathbf{x}^{\mathbf{a}} \rangle$.

- Construct the matrices $H_0 = (\langle \sigma | b'_i b_j \rangle)_{1 \leq i, j \leq r}$ (resp. $H_k = (\langle \sigma | x_k b'_i b_j \rangle)_{1 \leq i, j \leq r}$) of \mathcal{H}_σ (resp. $\mathcal{H}_{x_k \star \sigma}$) in the basis B of \mathcal{A}_σ ;
- Take a separating linear form $\mathbf{l}(\mathbf{x}) = l_1 x_1 + \dots + l_n x_n$ and construct $H_1 = \sum_{i=1}^n l_i H_i = (\langle \sigma | l'_i b'_j \rangle)_{1 \leq i, j \leq r}$;
- Compute the generalized eigenvectors $\mathbf{v}_1, \dots, \mathbf{v}_r$ of (H_1, H_0) where $r = |B|$;
- Compute $\xi_{i,j}$ such that $\langle \sigma | x_j \mathbf{v}_i \rangle = \xi_{i,j} \langle \sigma | \mathbf{v}_i \rangle$ for $j = 1, \dots, n, i = 1, \dots, r$;
- Compute $\mathbf{u}_i(\mathbf{x}) = \frac{1}{\mathbf{v}_i(\xi_i)} \mathbf{v}_i(\mathbf{x})$ where $\xi_i = (\xi_{i,1}, \dots, \xi_{i,n})$;
- Compute $\langle \sigma | \mathbf{u}_i \rangle = \omega_i$;

Output: the decomposition $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i e_{\xi_i}(\mathbf{y})$.

To apply this algorithm, one need to compute a basis B of \mathcal{A}_σ such that σ is defined on $B \cdot B^+$ where $B^+ = \cup_{i=1}^n x_i B \cup B$. In Section 4, we will detail an efficient method to compute such a basis B and a characterization of the sequences $(\sigma_\alpha)_{\alpha \in A}$, which admits a decomposition of rank r .

The second step of the algorithm consists in taking a linear form $\mathbf{l}(\mathbf{x}) = l_1 x_1 + \dots + l_n x_n$, which separates the roots in the decomposition ($\mathbf{l}(\xi_i) \neq \mathbf{l}(\xi_j)$ if $i \neq j$). A generic choice of

1 yields a separating linear form. This separating property can be verified a posteriori, by checking that there are r distinct generalized eigenvalues. Notice that we only need to compute the matrix H_1 of $\mathcal{H}_{1*\sigma}$ in the basis B of \mathcal{A}_σ and not necessarily all the matrices H_k .

The third step is the computation of generalized eigenvectors of a Hankel pencil. The other steps involve the application of σ on polynomials in B^+ .

We illustrate the method on a sequence σ_α obtained by evaluation of a sum of exponentials on a grid.

Example 3.13 We consider the function $h(u_1, u_2) = 2 + 3 \cdot 2^{u_1} 2^{u_2} - 3^{u_1}$. Its associated generating series is $\sigma = \sum_{\alpha \in \mathbb{N}^2} h(\alpha) \frac{\mathbf{y}^\alpha}{\alpha!}$. Its (truncated) moment matrix is

$$H_\sigma^{[1, x_1, x_2, x_1^2, x_1 x_2, x_2^2]} = \begin{bmatrix} h(0,0) & h(1,0) & h(0,1) & \cdots \\ h(1,0) & h(2,0) & h(1,1) & \cdots \\ h(0,1) & h(1,1) & h(0,2) & \cdots \\ \vdots & \vdots & \vdots & \\ \vdots & \vdots & \vdots & \end{bmatrix} = \begin{bmatrix} 4 & 5 & 7 & 5 & 11 & 13 \\ 5 & 5 & 11 & -1 & 17 & 23 \\ 7 & 11 & 13 & 17 & 23 & 25 \\ 5 & -1 & 17 & -31 & 23 & 41 \\ 11 & 17 & 23 & 23 & 41 & 47 \\ 13 & 23 & 25 & 41 & 47 & 49 \end{bmatrix}$$

We compute $B = \{1, x_1, x_2\}$. The generalized eigenvalues of $(H_{x_1*\sigma}, H_\sigma)$ are $[1, 2, 3]$ and corresponding eigenvectors are represented by the columns of

$$\mathbf{u} := \begin{bmatrix} 2 & -1 & 0 \\ -\frac{1}{2} & 0 & \frac{1}{2} \\ -\frac{1}{2} & 1 & -\frac{1}{2} \end{bmatrix},$$

associated to the polynomials $\mathbf{u}(x) = [2 - \frac{1}{2} x_1 - \frac{1}{2} x_2, -1 + x_2, \frac{1}{2} x_1 - \frac{1}{2} x_2]$. By computing the Hankel matrix

$$H_\sigma^{[1, x_1, x_2], \mathbf{u}} = \begin{bmatrix} \langle \sigma | \mathbf{u}_1 \rangle & \langle \sigma | \mathbf{u}_2 \rangle & \langle \sigma | \mathbf{u}_3 \rangle \\ \langle \sigma | x_1 \mathbf{u}_1 \rangle & \langle \sigma | x_1 \mathbf{u}_2 \rangle & \langle \sigma | x_1 \mathbf{u}_3 \rangle \\ \langle \sigma | x_2 \mathbf{u}_1 \rangle & \langle \sigma | x_2 \mathbf{u}_2 \rangle & \langle \sigma | x_2 \mathbf{u}_3 \rangle \end{bmatrix} = \begin{bmatrix} 2 & 3 & -1 \\ 2 \times 1 & 3 \times 2 & -1 \times 3 \\ 2 \times 1 & 3 \times 2 & -1 \times 1 \end{bmatrix}$$

we deduce the weights $2, 3, -1$ and the frequencies $(1, 1), (2, 2), (3, 1)$, which corresponds to the decomposition $\sigma = e^{y_1+y_2} + 3e^{2y_1+2y_2} - e^{2y_1+y_2}$ and $h(u_1, u_2) = 2 + 3 \cdot 2^{u_1+u_2} - 3^{u_1}$.

Let us recall other relations between the structured matrices involved in this eigenproblem, that are useful to analyse the numerical behavior of the method. For more details, see e.g. [47]. Such decompositions, referred as Carathéodory-Fejér-Pisarenko decompositions in [67], are induced by rank deficiency conditions or flat extension properties (see Section 4). They can be used to recover the decomposition of the series in Pencil-like methods.

Definition 3.14 Let $B = \{b_1, \dots, b_r\}$ be a family of polynomials. We define the B -Vandermonde matrix of the points $\xi_1, \dots, \xi_r \in \mathbb{C}^n$ as

$$V_{B, \xi} = ((\mathbf{e}_{\xi_j} | b_i))_{1 \leq i, j \leq r} = (b_i(\xi_j))_{1 \leq i, j \leq r}.$$

By remark 2.22, if $\{e_{\xi_1}, \dots, e_{\xi_r}\}$ is a basis of \mathcal{A}_σ^* and B is a basis of \mathcal{A}_σ , then $V_{B, \xi}$ is the matrix of coefficients of $e_{\xi_1}, \dots, e_{\xi_r}$ in the dual basis of B in \mathcal{A}_σ^* and it is invertible. Conversely, if $\{e_{\xi_1}, \dots, e_{\xi_r}\}$ is a basis of \mathcal{A}_σ^* , we check that $V_{B, \xi}$ is invertible implies that $B = \{b_1, \dots, b_r\}$ is a basis of \mathcal{A}_σ .

Proposition 3.15 *Suppose that $\sigma = \sum_{k=1}^r \omega_k e_{\xi_k}(\mathbf{y})$ with $\xi_1, \dots, \xi_r \in \mathbb{K}^n$ pairwise distinct and $\omega_1, \dots, \omega_r \in \mathbb{K} \setminus \{0\}$. Let $D_\omega = \text{diag}(\omega_1, \dots, \omega_r)$ be the diagonal matrix associated to the weights ω_i and let $D_g = \text{diag}(g(\xi_1), \dots, g(\xi_r))$ be the diagonal matrices associated to $g(\xi_1), \dots, g(\xi_r)$. For any family B, B' of $\mathbb{K}[\mathbf{x}]$, we have*

$$\begin{aligned} H_\sigma^{B, B'} &= V_{B', \xi} D_\omega V_{B, \xi}^t \\ H_{g \star \sigma}^{B, B'} &= V_{B', \xi} D_\omega D_g V_{B, \xi}^t = V_{B', \xi} D_g D_\omega V_{B, \xi}^t \end{aligned}$$

If moreover B is a basis of \mathcal{A}_σ , then $V_{B, \xi}$ is invertible and

$$(M_g^B)^t = V_{B, \xi} D_g V_{B, \xi}^{-1}$$

Proof. If $\sigma = \sum_{k=1}^r \omega_k e_{\xi_k}(\mathbf{y})$ and $B = \{b_1, \dots, b_r\}, B' = \{b'_1, \dots, b'_r\}$ are bases of \mathcal{A}_σ , then

$$H_\sigma^{B, B'} = \left[\sum_{k=1}^r \omega_k b'_i(\xi_k) b_j(\xi_k) \right]_{i, j=1, \dots, r} = V_{B', \xi} D_\omega V_{B, \xi}^t.$$

By a similar explicit computation, we check that $H_{g \star \sigma}^{B, B'} = V_{B', \xi} D_\omega D_g V_{B, \xi}^t$. Equation (18) implies that $(M_g^B)^t = H_{g \star \sigma}^{B, B} (H_\sigma^{B, B})^{-1} = V_{B, \xi} D_g V_{B, \xi}^{-1}$. \square

3.2.2 The case of multiple roots

We consider now the general case where σ is of the form $\sigma = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$ with $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$ and $\xi_i \in \mathbb{K}^n$ pairwise distinct. By Theorem 2.15, we have

$$\mathcal{A}_\sigma = \mathcal{A}_{\sigma, \xi_1} \oplus \dots \oplus \mathcal{A}_{\sigma, \xi_r'}$$

where $\mathcal{A}_{\sigma, \xi_i} \simeq \mathbb{K}[\mathbf{x}]/Q_i$ is the local algebra associated to the \mathfrak{m}_{ξ_i} -primary component Q_i of I_σ . The decomposition (11) and Proposition 2.16 imply that $\mathcal{A}_{\sigma, \xi_i}$ is a local Artinian Gorenstein Algebra such that $\mathbf{u}_{\xi_i} \star \sigma$ is a basis of $\mathcal{A}_{\sigma, \xi_i}^*$. The operators \mathcal{M}_{x_j} of multiplication by the variables x_j in \mathcal{A}_σ for $j = 1, \dots, n$ are commuting and have a block diagonal decomposition, corresponding to the decomposition of \mathcal{A}_σ .

It turns out that the operators \mathcal{M}_{x_j} have common eigenvectors $\mathbf{v}_i(\mathbf{x}) \in \mathcal{A}_{\sigma, \xi_i}$. Such an eigenvector is an element of the socle $(0 : \mathfrak{m}_{\xi_i}) = \{v \in \mathcal{A}_{\sigma, \xi_i} \mid (x_j - \xi_{i,j})v \equiv 0, j = 1, \dots, n\} = (Q_i : \mathfrak{m}_{\xi_i})/Q_i$.

In the case of an Artinian Gorenstein algebra $\mathcal{A}_{\sigma, \xi_i}$, the socle $(0 : \mathfrak{m}_{\xi_i})$ is a vector space of dimension 1 (see e.g. [23] [Sec. 7.1.5 and Sec. 9.5] for a simple proof). A basis element can be computed as a common eigenvector of the commuting operators \mathcal{M}_{x_j} . The corresponding eigenvalues are the coordinates $\xi_{i,1}, \dots, \xi_{i,n}$ of the roots $\xi_i, i = 1, \dots, r$.

For a separating linear form $\mathbf{l}(\mathbf{x}) = l_1 x_1 + \dots + l_n x_n$ (such that $\mathbf{l}(\xi_i) \neq \mathbf{l}(\xi_j)$ if $i \neq j$), the eigenspace of \mathcal{M}_1 for the eigenvalue $\mathbf{l}(\xi_i)$ is the local algebra \mathcal{A}_{ξ_i} associated to the root ξ_i . Let $B_i = \{b_{i,1}, \dots, b_{i,\mu_i}\}$ be a basis of this eigenspace. It spans the elements of \mathcal{A}_{ξ_i} , which are of the form $\mathbf{u}_{\xi_i} a$ for $a \in \mathcal{A}_\sigma$ where \mathbf{u}_{ξ_i} is the idempotent associated to ξ_i (see Theorem 2.15). In particular, the eigenspace of $\mathcal{M}_{\mathbf{l}(\mathbf{x})}$ associated to the eigenvalue $\mathbf{l}(\xi_i)$ contains the idempotent \mathbf{u}_{ξ_i} , which can be recovered as follows:

Lemma 3.16 *Let $B_i = \{b_{i,1}, \dots, b_{i,\mu_i}\}$ be a basis of \mathcal{A}_{ξ_i} and $\mathbf{U}_i = (\langle \sigma | b_{i,k} \rangle)_{k=1, \dots, \mu_i}$. Then $(H_\sigma^{B_i, B_i})^{-1} \mathbf{U}_i$ is the coefficient vector of the idempotent \mathbf{u}_{ξ_i} in the basis B_i of \mathcal{A}_{ξ_i} .*

Proof. As the idempotent \mathbf{u}_{ξ_i} satisfies the relation $\mathbf{u}_{\xi_i}^2 \equiv \mathbf{u}_{\xi_i}$ in \mathcal{A}_σ and $\mathcal{A}_{\xi_i} = \mathbf{u}_{\xi_i} \mathcal{A}_\sigma$, we have

$$\langle \mathbf{u}_{\xi_i} \star \sigma | b_{i,k} \rangle = \langle \sigma | \mathbf{u}_{\xi_i} b_{i,k} \rangle = \langle \sigma | b_{i,k} \rangle,$$

and $\mathbf{U}_i = (\langle \sigma | b_{i,k} \rangle)_{k=1, \dots, \mu_i}$ is the coefficient vector of $\mathbf{u}_{\xi_i} \star \sigma$ in the dual basis of B_i in $\mathcal{A}_{\xi_i}^*$. By Lemma 3.3, as B_i is a basis of \mathcal{A}_{ξ_i} , $H_{\sigma}^{B_i, B_i}$ is invertible and $(H_{\sigma}^{B_i, B_i})^{-1} \mathbf{U}_i$ is the coefficient vector of \mathbf{u}_{ξ_i} in the basis B_i of \mathcal{A}_{ξ_i} . \square

Using the idempotent \mathbf{u}_{ξ_i} , we have the following formula for the weights $\omega_i(\mathbf{y})$ in the decomposition of σ :

Proposition 3.17 *The polynomial coefficient of $\mathbf{e}_{\xi_i}(\mathbf{y})$ in the decomposition of σ is*

$$\omega_i(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \langle \mathbf{u}_{\xi_i} \star \sigma | (\mathbf{x} - \xi_i)^\alpha \rangle \frac{\mathbf{y}^\alpha}{\alpha!}. \quad (20)$$

Proof. By Theorem 3.1 and relation (11), we have

$$\mathbf{u}_{\xi_i} \star \sigma = \omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y}).$$

As $\langle \mathbf{y}^\beta \mathbf{e}_{\xi_i}(\mathbf{y}) | (\mathbf{x} - \xi_i)^\alpha \rangle = \begin{cases} \alpha! & \text{if } \alpha = \beta \\ 0 & \text{otherwise} \end{cases}$, we deduce the decomposition (20), which is a finite sum since $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$. \square

This leads to the following decomposition algorithm in the case of multiple roots.

Algorithm 3.2: Decomposition of polynomial-exponential series with polynomial weights

Input: the coefficients σ_α of a series $\sigma \in \mathbb{K}[[\mathbf{y}]]$ for $\alpha \in \mathbf{a} \subset \mathbb{N}^n$ and bases $B = \{b_1, \dots, b_r\}$, $B = \{b'_1, \dots, b'_r\}$, of \mathcal{A}_σ such that $\langle B' \cdot B^+ \rangle \subset \langle \mathbf{x}^\mathbf{a} \rangle$.

- Construct the matrices $H_0 = (\langle \sigma | b'_i b_j \rangle)_{1 \leq i, j \leq r}$ (resp. $H_k = (\langle \sigma | x_k b'_i b_j \rangle)_{1 \leq i, j \leq r}$) of \mathcal{H}_σ (resp. $\mathcal{H}_{x_k \star \sigma}$) in a basis B of \mathcal{A}_σ ;
- Compute common eigenvectors $\mathbf{v}_1, \dots, \mathbf{v}_r$ of all the pencils (H_k, H_0) , $k = 1, \dots, n$ and $\xi_i = (\xi_{i,1}, \dots, \xi_{i,n})$ such that $(H_k - \xi_{i,k} H_0) \mathbf{v}_i = 0$;
- Take a separating linear form $\mathbf{l}(\mathbf{x}) = l_1 x_1 + \dots + l_n x_n$;
- Compute bases $B_i, i = 1, \dots, r'$ of the generalized eigenspaces of (H_1, H_0) ;
- For each basis $B_i = \{b_{i,1}, \dots, b_{i,\mu_i}\}$, compute $\mathbf{U}_i = (\langle \sigma | b_{i,k} \rangle)_{k=1, \dots, \mu_i}$ and $\mathbf{u}_i = (H_{\sigma}^{B_i, B_i})^{-1} \mathbf{U}_i$;
- Compute $\omega_i(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \langle \mathbf{u}_i \star \sigma | (\mathbf{x} - \xi_i)^\alpha \rangle \frac{\mathbf{y}^\alpha}{\alpha!}$;

Output: the decomposition $\sigma(\mathbf{y}) = \sum_{i=1}^r \omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})$.

Here also, we need to know a basis B of \mathcal{A}_σ such that σ is known on $B' \cdot B^+$. The second step is the computation of common eigenvectors of pencil of matrices. Efficient methods as in [30] can be used to computed them. The other steps generalize the computation of the simple root case. The solution of a Hankel system is required to compute the coefficient vector of the idempotent \mathbf{u}_i in the basis B_i of \mathcal{A}_{ξ_i} .

The relations between Vandermonde matrices and Hankel matrices (Proposition 3.15) can be generalized to the case of multiple roots. Let $\sigma = \sum_{k=1}^{r'} \omega_k(\mathbf{y}) \mathbf{e}_{\xi_k}(\mathbf{y})$ with $\xi_1, \dots, \xi_{r'} \in \mathbb{K}^n$ pairwise distinct, $\omega_1(\mathbf{y}), \dots, \omega_{r'}(\mathbf{y}) \in \mathbb{K}[\mathbf{y}] \setminus \{0\}$. To deduce a decomposition of $H_{\sigma}^{B, B'}$ similar to the decomposition of Proposition 3.15 for multiple roots, we introduce the Wronskian of a set $B = \{b_1, \dots, b_l\} \subset \mathbb{K}[\mathbf{x}]$ and a set of exponents $\Gamma = \{\gamma_1, \dots, \gamma_s\} \subset \mathbb{N}^n$ at a point $\xi \in \mathbb{K}^n$:

$$W_{B, \Gamma, \xi} = \left[\frac{1}{\gamma_j!} \partial^{\gamma_j} (b_i)(\xi) \right]_{1 \leq i \leq r, 1 \leq j \leq s}.$$

For a collection $\Gamma = \{\Gamma_1, \dots, \Gamma_{r'}\}$ with $\Gamma_1, \dots, \Gamma_{r'} \subset \mathbb{N}^n$ and points $\xi = \{\xi_1, \dots, \xi_{r'}\} \subset \mathbb{K}^n$ let

$$W_{B, \Gamma, \xi} = [W_{B, \Gamma_1, \xi_1}, \dots, W_{B, \Gamma_{r'}, \xi_{r'}}]$$

be the matrix obtained by concatenation of the columns of W_{B, Γ_k, ξ_k} , $k = 1, \dots, r'$.

We consider the monomial decomposition $\omega_k(\mathbf{y}) = \sum_{\alpha \in A_k} \omega_{k, \alpha}(\mathbf{x} - \xi_k)^\alpha$ with $\omega_{k, \alpha} \neq 0$. We denote by Γ_k the set of all the exponents $\alpha \in A_k$ in this decomposition and all their divisors $\beta = (\beta_1, \dots, \beta_n)$ with $\beta \ll \alpha$. Let us denote by $\gamma_1, \dots, \gamma_{s_k}$ the elements of Γ_k .

Let $\Delta_{\omega_k}^{\Gamma_k} = [(\gamma_i + \gamma_j)! \omega_{k, \gamma_i + \gamma_j}]_{1 \leq i, j \leq s_k}$ with the convention that $\omega_{k, \gamma_i + \gamma_j} = 0$ if $\gamma_i + \gamma_j \notin A_k$ is not a monomial exponent of $\omega_k(\mathbf{y})$. Let Δ_{ω}^{Γ} be the block diagonal matrix, which diagonal blocks are $\Delta_{\omega_k}^{\Gamma_k}$, $k = 1, \dots, r'$.

The following decomposition generalizes the Carathéodory-Fejér decomposition in the case of multiple roots (it is also implied by rank deficiency conditions, see Section 4.1):

Proposition 3.18 *Suppose that $\sigma = \sum_{k=1}^{r'} \omega_k(\mathbf{y}) e_{\xi_k}(\mathbf{y})$ with $\xi_1, \dots, \xi_{r'} \in \mathbb{K}^n$ pairwise distinct, $\omega_1(\mathbf{y}), \dots, \omega_{r'}(\mathbf{y}) \in \mathbb{K}[\mathbf{y}] \setminus \{0\}$. For $g \in \mathbb{K}[\mathbf{x}]$, $g \otimes \omega = [g(\xi_1 + \boldsymbol{\theta})(\omega_1), \dots, g(\xi_{r'} + \boldsymbol{\theta})(\omega_{r'})]$. For any set $B, B' \subset \mathbb{K}[\mathbf{x}]$ of size l , we have*

$$\begin{aligned} H_{\sigma}^{B, B'} &= W_{B', \Gamma, \xi} \Delta_{\omega}^{\Gamma} W_{B, \Gamma, \xi}^t \\ H_{g \star \sigma}^{B, B'} &= W_{B', \Gamma, \xi} \Delta_{g \otimes \omega}^{\Gamma} W_{B, \Gamma, \xi}^t \end{aligned}$$

If moreover B is a basis of \mathcal{A}_{σ} , then $W_{B', \Gamma, \xi}$ and Δ_{ω}^{Γ} are invertible and the matrix of multiplication by g in the basis B of \mathcal{A}_{σ} is

$$M_g^B = W_{B, \Gamma, \xi}^{-t} (\Delta_{\omega}^{\Gamma})^{-1} \Delta_{g \otimes \omega} W_{B, \Gamma, \xi}^{-t}.$$

Proof. By the relation (7), we have

$$H_{\sigma}^{B, B'} = \left[\sum_{k=1}^{r'} \omega_k(\boldsymbol{\theta})(b'_i b_j)(\xi_k) \right]_{1 \leq i, j \leq l}.$$

By expansion, we obtain

$$\omega_k(\boldsymbol{\theta})(b'_i b_j)(\xi_k) = \sum_{\alpha \in A_k} \omega_{k, \alpha} \partial_{\mathbf{x}}^{\alpha}(b'_i b_j)(\xi_k).$$

By Leibniz rule, we have

$$\partial_{\mathbf{x}}^{\alpha}(b'_i b_j) = \sum_{\beta \ll \alpha} \frac{\alpha!}{\beta!(\alpha - \beta)!} \partial_{\mathbf{x}}^{\beta}(b'_i) \partial_{\mathbf{x}}^{\alpha - \beta}(b_j) = \alpha! \sum_{\beta \ll \alpha} \frac{\partial_{\mathbf{x}}^{\beta}(b'_i)}{\beta!} \frac{\partial_{\mathbf{x}}^{\alpha - \beta}(b_j)}{(\alpha - \beta)!}.$$

We deduce that

$$\begin{aligned} \omega_k(\boldsymbol{\theta})(b'_i b_j)(\xi_k) &= \sum_{\alpha \in A_k} \omega_{k, \alpha} \partial_{\mathbf{x}}^{\alpha}(b'_i b_j)(\xi_k) \\ &= \sum_{\alpha \in A_k} \alpha! \omega_{k, \alpha} \sum_{\beta \ll \alpha} \frac{\partial_{\mathbf{x}}^{\beta}(b'_i)}{\beta!}(\xi_k) \frac{\partial_{\mathbf{x}}^{\alpha - \beta}(b_j)}{(\alpha - \beta)!}(\xi_k) \\ &= W_{B', \Gamma_k, \xi_k} \Delta_{\omega_k}^{\Gamma_k} W_{B, \Gamma_k, \xi_k}^t. \end{aligned}$$

By concatenation of the columns of W_{B, Γ_k, ξ_k} and W_{B', Γ_k, ξ_k} , using the block diagonal matrix Δ_{ω}^{Γ} , we obtain the decomposition of $H_{\sigma}^{B, B'} = W_{B', \Gamma, \xi} \Delta_{\omega}^{\Gamma} W_{B, \Gamma, \xi}^t$.

By Lemma 2.4, we have

$$g \star \sigma = \sum_{k=1}^{r'} g(\xi_k + \boldsymbol{\vartheta})(\omega_k) e_{\xi_k} = \sum_{k=1}^{r'} (g \otimes \boldsymbol{\omega})_k e_{\xi_k}.$$

Thus, a similar computation yields the decomposition: $H_{g \star \sigma}^{B, B'} = W_{B', \Gamma, \xi} \Delta_{g \otimes \boldsymbol{\omega}}^{\Gamma} W_{B, \Gamma, \xi}^t$.

If B is a basis of \mathcal{A}_σ , then by Proposition 3.2, $H_\sigma^{B, B}$ is invertible, which implies that $W_{B', \Gamma, \xi}$ and $\Delta_{\boldsymbol{\omega}}^{\Gamma}$ are invertible. By Relation (18), we have

$$M_g^B = (H_\sigma^{B, B})^{-1} H_{g \star \sigma}^{B, B} = W_{B, \Gamma, \xi}^{-t} (\Delta_{\boldsymbol{\omega}}^{\Gamma})^{-1} \Delta_{g \otimes \boldsymbol{\omega}} W_{B, \Gamma, \xi}^{-t}.$$

□

4 Reconstruction from truncated Hankel operators

Given the first terms $\sigma_\alpha, \alpha \in \mathbf{a}$ of a series $\sigma = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{K}[[\mathbf{y}]]$, where $\mathbf{a} \subset \mathbb{N}^n$ is a finite set of exponents, the reconstruction problem consists in finding points $\xi_1, \dots, \xi_r \in \mathbb{K}^n$ and polynomial $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$ such that the coefficient of $\frac{\mathbf{y}^\alpha}{\alpha!}$, in the series

$$\sum_{i=1}^r \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y}) \tag{21}$$

coincides with σ_α , for all $\alpha \in \mathbf{a}$.

It is natural to ask when this extension problem has a solution. This problem has been studied for the reconstruction of measures from moments. The first answer is probably due to [25] in the case of positive sequences indexed by \mathbb{N} (see [2][Theorem 5]). The extension to several variables involves the notion of flat extension, which corresponds to rank conditions on submatrices of the truncated Hankel matrix. See [19] for semi-definite positive Hankel matrices and its generalisation in [39].

This result is closely connected to the factorisation of positive semidefinite (PSD) Toeplitz matrices as the product of Vandermonde matrices with a diagonal matrix [17], which has been recently generalized to positive semidefinite multi-level block Toeplitz matrices in [67] and [4]. Theorem 4.2 gives a condition under which a truncated series can be extended in low rank. In view of Proposition 3.15 and 3.18, it also provides a rank condition for a generalized Carathéodory-Fejér decomposition of general multivariate Hankel matrices. Its specialization to multivariate positive semidefinite Hankel matrices is given in Theorem 4.4.

We are going to use this flat extension property to determine when σ has an extension of the form (21) and to compute a basis B of \mathcal{A}_σ . The decomposition of σ will be deduced from eigenvector computation of submatrices of H_σ , using the algorithms described in Section 3.2.

In this section, we also analyze the problem of finding a (monomial) basis B of \mathcal{A}_σ from the coefficients $\sigma_\alpha, \alpha \in \mathbf{a}$. We first characterize the series σ , which admit a decomposition of the form (21) such that B is a basis of \mathcal{A}_σ .

4.1 Flat extension

The flat extension property is defined as follows for general matrices:

Definition 4.1 *For any matrix H which is a submatrix of another matrix H' , we say that H' is a flat extension of H if $\text{rank } H = \text{rank } H'$.*

Before applying it to Hankel matrices, we need to introduce the following constructions. For a vector space $V \subset \mathbb{K}[\mathbf{x}]$, we denote by V^+ the vector space $V^+ = V + x_1V + \dots + x_nV$. We say that V is *connected to 1*, if there exists an increasing sequence of vector spaces $V_0 \subset V_1 \subset \dots \subset V_s = V$ such that $V_0 = \langle 1 \rangle$ and $V_{l+1} \subset V_l^+$. The *index* of an element $v \in V$ is the smallest l such that $v \in V_l$.

We say that a set of polynomials $B \subset \mathbb{K}[\mathbf{x}]$ is connected to 1 if the vector space $\langle B \rangle$ spanned by B is connected to 1. In particular, a monomial set $B = \{\mathbf{x}^{\beta_1}, \dots, \mathbf{x}^{\beta_r}\}$ is connected to 1 if for all $m \in B$, either $m = 1$ or there exists $m' \in B$ and $i_0 \in [1, \dots, n]$ such that $m = x_{i_0}m'$.

The following result generalizes the sparse flat extension results of [39] to distinct vector spaces connected to 1. We give its proof for the sake of completeness, since the hypotheses are slightly different.

Theorem 4.2 *Let $V, V' \subset \mathbb{K}[\mathbf{x}]$ vector spaces connected to 1 and let $\sigma \in \langle V \cdot V' \rangle^*$. Let $U \subset V$, $U' \subset V'$ be vector spaces such that $1 \in U$, $U^+ \subset V$, $U'^+ \subset V'$. If $\text{rank } H_\sigma^{V, V'} = \text{rank } H_\sigma^{U, U'} = r$, then there is a unique extension $\tilde{\sigma} \in \mathbb{K}[[\mathbf{y}]]$ such that $\tilde{\sigma}$ coincides with σ on $\langle V \cdot V' \rangle$ and $\text{rank } H_{\tilde{\sigma}} = r$. In this case, $\tilde{\sigma} = \sum_{i=1}^{r'} \omega_i(\mathbf{y})e_{\xi_i}(\mathbf{y})$ with $\omega_i(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$, $\xi_i \in \mathbb{K}^n$, $r = \sum_{i=1}^{r'} \mu(\omega_i)$ and $I_{\tilde{\sigma}} = (\ker H_\sigma^{U^+, U'})$.*

Proof. Let $K = \ker H_\sigma^{V, V'}$. The condition $\text{rank } H_\sigma^{U, U'} = \text{rank } H_\sigma^{V, V'}$ implies that

$$\kappa \in K \Leftrightarrow \forall v' \in V', \langle \sigma \mid kv' \rangle = 0 \quad (22)$$

$$\Leftrightarrow \forall u' \in U', \langle \sigma \mid ku' \rangle = 0. \quad (23)$$

In particular,

$$\kappa \in K \text{ and } x_i\kappa \in V \text{ implies } x_i\kappa \in K, \quad (24)$$

since $U'^+ \subset V'$, $\forall u' \in U'$, $\langle \sigma \mid \kappa x_i u' \rangle = \langle \sigma \mid x_i \kappa u' \rangle = 0$, which implies by the relation (23) that $x_i\kappa \in K$.

Suppose first that $1 \in K$. Then as V is connected to 1, using Relation (24) we prove by induction on the index l that every element of V of index > 0 , which is a sum of terms of V of the form $x_i\kappa$ with $\kappa \in K$, is in K . Then $\sigma = 0$ and the result is obviously true for $\tilde{\sigma} = 0$.

Assume now that $1 \notin K$. The condition $\text{rank } H_\sigma^{U, U'} = \text{rank } H_\sigma^{V, V'}$ implies that $V = K + U$ and we can assume that $U \cap K = \{0\}$ and $\dim(U) = \dim(U') = \text{rank } H_\sigma^{U, U'} = \text{rank } H_\sigma^{V, V'} = r$ with $1 \in U$. In this case, $H_\sigma^{U, U'}$ is invertible.

Let $M_i := (H_\sigma^{U, U'})^{-1} H_{x_i \star \sigma}^{U, U'}$. It is a linear operator of U . As $H_{x_i \star \sigma}^{U, U'} = H_\sigma^{U, U'} \circ M_i$, we have $\forall u \in U, u' \in U'$

$$\langle \sigma \mid x_i u u' \rangle = \langle \sigma \mid M_i(u) u' \rangle$$

As $\text{rank } H_\sigma^{V, V'} = \text{rank } H_\sigma^{U, U'} = r$ and $U^+ \subset V, U'^+ \subset V'$, we also have $\forall j = 1, \dots, n, \forall u \in U, \forall u' \in U'$

$$\langle \sigma \mid x_i x_j u u' \rangle = \langle \sigma \mid x_i u x_j u' \rangle = \langle \sigma \mid M_i(u) x_j u' \rangle = \langle \sigma \mid M_j \circ M_i(u) u' \rangle.$$

We deduce that $\langle \sigma \mid M_j \circ M_i(u) u' \rangle = \langle \sigma \mid M_i \circ M_j(u) u' \rangle$ and the operators M_i, M_j commute: $M_j \circ M_i = M_i \circ M_j$.

Let us define the operator

$$\begin{aligned} \phi : \mathbb{K}[\mathbf{x}] &\rightarrow U \\ p &\mapsto p(M)(1) \end{aligned}$$

and the linear form

$$\begin{aligned}\tilde{\sigma} : \mathbf{K}[\mathbf{x}] &\rightarrow \mathbf{K} \\ p &\mapsto \langle \sigma \mid p(M)(1) \rangle\end{aligned}$$

We are going to show that $\tilde{\sigma}$ extends σ and that $I_{\tilde{\sigma}} = (\ker H_{\tilde{\sigma}}^{U, U'})$. As the operators M_i commute, the operator $p(M)$ obtained by substituting the variable x_i by M_i in the polynomial $p \in \mathbf{K}[\mathbf{x}]$ is well-defined and the kernel J of ϕ is an ideal of $\mathbf{K}[\mathbf{x}]$.

We first prove that $\tilde{\sigma}$ coincides with σ on $\langle V \cdot V' \rangle$. We prove by induction on the index that $\forall v \in V, \forall u' \in U', \langle \sigma \mid vu' \rangle = \langle \sigma \mid \phi(v)u' \rangle$. If v is of index 0, then $v = 1$ (up to a scalar) and $\phi(1) = 1$ so that the property is true.

Let us assume that the property is true for the elements of V of index $l-1 \geq 0$ and let $v \in V$ of index l : there exists $v_i \in V$ of index $l-1$ such that $v = \sum_i x_i v_i$. By induction hypothesis and the relations (22) and (23), we have $\forall u' \in U'$,

$$\begin{aligned}\langle \sigma \mid vu' \rangle &= \sum_i \langle \sigma \mid v_i x_i u' \rangle = \sum_i \langle \sigma \mid \phi(v_i) x_i u' \rangle = \sum_i \langle \sigma \mid M_i \circ \phi(v_i) u' \rangle \\ &= \left\langle \sigma \mid \left(\sum_i \phi(x_i v_i) \right) u' \right\rangle = \langle \sigma \mid \phi(v) u' \rangle.\end{aligned}$$

Using relations (22) and (23), we also have

$$\forall v \in V, \forall v' \in V', \langle \sigma \mid vv' \rangle = \langle \sigma \mid \phi(v)v' \rangle. \quad (25)$$

In a similar way, we prove that

$$\forall u \in U, \forall v' \in V', \langle \sigma \mid uv' \rangle = \langle \sigma \mid v'(M)(u) \rangle. \quad (26)$$

The property is true for $v' = 1$. Let us assume that it is true for the elements of V' of index $l-1 > 0$ and let $v' \in V'$ be an element of index l . There exist $v'_i \in V'$ of index $l-1$ such that $v' = \sum_i x_i v'_i$. By induction hypothesis and the relations (22) and (23), we have $\forall v \in V$,

$$\begin{aligned}\langle \sigma \mid uv' \rangle &= \sum_i \langle \sigma \mid v'_i x_i u \rangle = \sum_i \langle \sigma \mid v'_i M_i(u) \rangle = \sum_i \langle \sigma \mid v'_i(M) M_i(u) \rangle \\ &= \left\langle \sigma \mid \left(\sum_i M_i \circ v'_i(M) \right) (u) \right\rangle = \langle \sigma \mid v'(M)(u) \rangle.\end{aligned}$$

By the relations (25) and (26), we have $\forall v \in V, \forall v' \in V'$,

$$\langle \sigma \mid vv' \rangle = \langle \sigma \mid v'v(M)(1) \rangle = \langle \sigma \mid v'(M) \circ v(M)(1) \rangle = \langle \sigma \mid \phi(vv') \rangle = \langle \tilde{\sigma} \mid vv' \rangle.$$

This shows that $\tilde{\sigma}$ coincides with σ on $\langle V \cdot V' \rangle$.

We deduce from relation (25) that $\forall u \in U, \forall u' \in U', \langle \sigma \mid (u - \phi(u))u' \rangle = 0$ and $\phi(u) = u$ since $H_{\tilde{\sigma}}^{U, U'}$ is invertible. Therefore ϕ is the projection of $\mathbf{K}[\mathbf{x}]$ on U along its kernel J and we have the exact sequence

$$0 \rightarrow J \rightarrow \mathbf{K}[\mathbf{x}] \xrightarrow{\phi} U \rightarrow 0.$$

Let $I_{\sigma} = \ker H_{\tilde{\sigma}}$ and $\mathcal{A}_{\sigma} = \mathbf{K}[\mathbf{x}]/I_{\sigma}$. As $J \subset I_{\sigma}$, we have $\dim_{\mathbf{K}} \mathcal{A}_{\sigma} \leq \dim_{\mathbf{K}} \mathbf{K}[\mathbf{x}]/J = \dim U = r$ and U is generating \mathcal{A}_{σ} . Since $\tilde{\sigma}$ coincides with σ on $\langle U \cdot U' \rangle$ and $H_{\tilde{\sigma}}^{U, U'}$ is invertible, by Lemma 3.3 a basis of the vector space $U \subset \mathbf{K}[\mathbf{x}]$ is linearly independent in \mathcal{A}_{σ} . This shows that $\dim_{\mathbf{K}} \mathcal{A}_{\sigma} = r$ and that $J = I_{\sigma}$.

Since U contains 1 and ϕ is the projection of $\mathbf{K}[\mathbf{x}]$ on U along $I_\sigma = J$, we check that I_σ is generated by the element $x_i u - \phi(x_i u)$ for $u \in U$, $i = 1, \dots, n$, that is by the elements of $\ker H_\sigma^{U^+, U'} \subset K$.

If there is another $\tilde{\sigma}' \in \mathbf{K}[[\mathbf{y}]]$ which coincides with σ on $\langle V \cdot V' \rangle$ and such that $\text{rank } H_{\tilde{\sigma}'} = r$, then $\ker H_\sigma^{U^+, U'} \subset \ker H_{\tilde{\sigma}'} = I_{\tilde{\sigma}'}$ and $J = (\ker H_\sigma^{U^+, U'}) \subset I_{\tilde{\sigma}'}$. Therefore, we have $\forall p \in \mathbf{K}[\mathbf{x}]$, $\langle \tilde{\sigma}' | p \rangle = \langle \tilde{\sigma}' | \phi(p) \rangle = \langle \sigma | \phi(p) \rangle = \langle \tilde{\sigma} | p \rangle$, so that $\tilde{\sigma}' = \tilde{\sigma}$, which conclude the proof of the theorem. \square

Remark 4.3 Let B be a monomial set. If $H_\sigma^{B^+, B'}$ is a flat extension of $H_\sigma^{B, B'}$ and $H_\sigma^{B, B'}$ is invertible, then a basis of the kernel of $H_\sigma^{B^+, B'}$ is given by the columns of $\begin{pmatrix} -P \\ I \end{pmatrix}$, where $H_\sigma^{B, B'} P = H_\sigma^{\partial B, B'}$. The columns of this matrix represent polynomials of the form

$$\mathbf{x}^\alpha - \sum_{\beta \in B} p_{\alpha, \beta} \mathbf{x}^\beta$$

for $\alpha \in \partial B$. These polynomials are the border relations which project monomials of ∂B on the vector space spanned by B , modulo $\ker H_\sigma^{B^+}$. Using Theorem 4.2 and the characterization of border bases in terms of commutation relations [46], [48], we prove that they form a border basis of the ideal generated by $\ker H_\sigma^{B^+}$, if and only if, $\text{rank } H_\sigma^B = \text{rank } H_\sigma^{B^+} = |B|$, or in other words, if and only if, $H_\sigma^{B^+}$ has a flat extension. As shown in [15] (see also [12]), the flat extension condition is equivalent to the commutation property of formal multiplication operators.

Let us consider the case where $\mathbf{K} = \mathbf{R}$, $V = V'$. We say that $H_\sigma^{V, V}$ is semi-definite positive or simply that σ is semi-definite positive on V , if $\forall p \in V$, $\langle H_\sigma^{V, V}(p) | p \rangle = \langle \sigma | p^2 \rangle \geq 0$.

We have the following flat extension version:

Theorem 4.4 *Let $V \subset \mathbf{R}[\mathbf{x}]$ be a vector space connected to 1 and $\sigma \in \langle V \cdot V \rangle^*$. Let $U \subset V$ such that $1 \in U$, $U^+ \subset V$, $\text{rank } H_\sigma^{V, V} = \text{rank } H_\sigma^{U, U}$ and $H_\sigma^{V, V} \succcurlyeq 0$. Then there is a unique extension $\tilde{\sigma} \in \mathbf{R}[[\mathbf{y}]]$ which coincides with σ on $\langle V \cdot V' \rangle$ and such that $r = \text{rank } H_{\tilde{\sigma}}$, which is of the form*

$$\tilde{\sigma} = \sum_{i=1}^r \omega_i \mathbf{e}_{\xi_i}(\mathbf{y})$$

with $\omega_i > 0$ and $\xi_i \in \mathbf{R}^n$.

Proof. By Theorem 4.2, there is a unique extension $\tilde{\sigma} \in \mathbf{R}[[\mathbf{y}]]$ which coincides with σ on $\langle V \cdot V' \rangle$ and such that $r = \text{rank } H_{\tilde{\sigma}}$. As $H_\sigma^{V, V} \succcurlyeq 0$, for any $p \in \mathbf{R}[\mathbf{x}]$ $\langle \tilde{\sigma} | p^2 \rangle = \langle \sigma | \phi(p)^2 \rangle \geq 0$ and $\tilde{\sigma}$ is semi-definite positive (on $\mathbf{R}[\mathbf{x}]$). The real decomposition of $\tilde{\sigma}$ with positive weights is then a consequence of Proposition 3.6. \square

4.2 Orthogonal bases of \mathcal{A}_σ

An important step in the decomposition method consists in computing a basis B of \mathcal{A}_σ . In this section, we describe how to compute a monomial basis $B = \{\mathbf{x}^\beta\}$ and two other bases $\mathbf{p} = (p_\beta)$ and $\mathbf{q} = (q_\beta)$, which are pairwise orthogonal for the inner product $\langle \cdot, \cdot \rangle_\sigma$:

$$\langle p_\beta, q_{\beta'} \rangle_\sigma = \begin{cases} 1 & \text{if } \beta = \beta' \\ 0 & \text{otherwise.} \end{cases}$$

Such pairwise orthogonal bases of \mathcal{A}_σ exist, since \mathcal{A}_σ is an Artinian Gorenstein algebra and $\langle \cdot, \cdot \rangle_\sigma$ is non-degenerate (Proposition 3.2).

To compute these pairwise orthogonal bases, we will use a projection process, similar to Gram-Schmidt orthogonalization process. The main difference is that we compute pairs p_β, q_β of orthogonal polynomials. As the inner product $\langle \cdot, \cdot \rangle_\sigma$ may be isotropic, the two polynomials p_β, q_β may not be equal, up to a scalar.

The method proceeds inductively starting from $\mathbf{b} = []$, extending the monomials basis \mathbf{b} with new monomials \mathbf{x}^α , projecting them onto the space spanned by \mathbf{b} :

$$p_\alpha = \mathbf{x}^\alpha - \sum_{\beta \in \mathbf{b}} \langle \mathbf{x}^\alpha, q_\beta \rangle_\sigma p_\beta$$

and computing q_α , if it exists, such that $\langle p_\alpha, q_\alpha \rangle_\sigma = 1$ and $\langle \mathbf{x}^\beta, q_\alpha \rangle_\sigma = 0$ for $\beta \in \mathbf{b}$. Here is a more detailed description of the algorithm:

Algorithm 4.1: Orthogonal bases

Input: the coefficients σ_α of a series $\sigma \in \mathbb{K}[[\mathbf{y}]]$ for $\alpha \in \mathbf{a} \subset \mathbb{N}^n$.

Let $\mathbf{b} := []$; $\mathbf{b}' := []$; $\mathbf{d} := []$; $\mathbf{n} := [\mathbf{0}]$; $\mathbf{s} := \mathbf{a}$; $\mathbf{s}' := \mathbf{a}$; $l := 0$;

while $\mathbf{n} \neq \emptyset$ **do**

$l := l + 1$;

for each $\alpha \in \mathbf{n}$ **do**

 a) compute $p_\alpha = \mathbf{x}^\alpha - \sum_{\beta \in \mathbf{b}} \langle \mathbf{x}^\alpha, q_\beta \rangle_\sigma p_\beta$;

 b) find the first $\alpha' \in \mathbf{s}'$ such that $\mathbf{x}^{\alpha'} p_\alpha \in \langle \mathbf{a} \rangle$ and $\langle \mathbf{x}^{\alpha'}, p_\alpha \rangle_\sigma \neq 0$;

 c) **if** such an α' exists **then**

 let $q_\alpha := \frac{1}{\langle \mathbf{x}^{\alpha'}, p_\alpha \rangle_\sigma} \left(\mathbf{x}^{\alpha'} - \sum_{\beta \in \mathbf{b}} \langle \mathbf{x}^{\alpha'}, p_\beta \rangle_\sigma q_\beta \right)$;

 add α to \mathbf{b} ; remove α from \mathbf{s} ;

 add α' to \mathbf{b}' ; remove α' from \mathbf{s}' ;

else

 add α to \mathbf{d} ;

end

$\mathbf{n} := \text{next}(\mathbf{b}, \mathbf{d}, \mathbf{s})$;

end

Output:

– monomial sets $\mathbf{b} = [\beta_1, \dots, \beta_r] \subset \mathbf{a}$, $\mathbf{b}' = [\beta'_1, \dots, \beta'_r] \subset \mathbf{a}$.

– pairwise orthogonal bases $\mathbf{p} = (p_{\beta_i})$, $\mathbf{q} = (q_{\beta_i})$ for $\langle \cdot, \cdot \rangle_\sigma$.

– the relations $p_\alpha := \mathbf{x}^\alpha - \sum_{i=1}^r \langle \mathbf{x}^\alpha, q_{\beta_i} \rangle_\sigma p_{\beta_i}$ for $\alpha \in \mathbf{d}$.

The algorithm manipulates the ordered lists $\mathbf{b}, \mathbf{d}, \mathbf{s}, \mathbf{s}'$ of exponents, identified with monomials. The monomials are ordered according to a total order denoted \prec . The index l is the loop index.

The algorithm uses the function $\text{next}(\mathbf{b}, \mathbf{d}, \mathbf{s})$, which computes the set of monomials α in $\partial \mathbf{b} \cap \mathbf{s}$, which are not in \mathbf{d} and such that $\alpha + \mathbf{b}' \subset \mathbf{a}$.

We verify that at each loop of the algorithm, the lists \mathbf{b} and \mathbf{s} (resp. \mathbf{b}' and \mathbf{s}') are disjoint and $\mathbf{b} \cup \mathbf{s} = \mathbf{a}$ (resp. $\mathbf{b}' \cup \mathbf{s}' = \mathbf{a}$).

We also verify by induction that at each loop, $\langle \mathbf{x}^{\mathbf{b}} \rangle = \langle p_\beta \mid \beta \in \mathbf{b} \rangle$ and $\langle \mathbf{x}^{\mathbf{b}'} \rangle = \langle q_\beta \mid \beta \in \mathbf{b}' \rangle$. The following properties are also satisfied at the end of the algorithm:

Theorem 4.5 *Let $\mathbf{b} = [\beta_1, \dots, \beta_r]$, $\mathbf{b}' = [\beta'_1, \dots, \beta'_r]$, $\mathbf{p} = [p_{\beta_1}, \dots, p_{\beta_r}]$, $\mathbf{q} = [q_{\beta_1}, \dots, q_{\beta_r}]$ be the output of Algorithm 4.1. Let $V = \langle \mathbf{x}^{\mathbf{b}^+} \rangle$. If there exists a vector space V' connected to 1 such that $\mathbf{x}^{(\mathbf{b}')^+} \subset V'$ and $V \cdot V' = \langle \mathbf{x}^{\mathbf{a}} \rangle$. Then σ coincides on $\langle \mathbf{x}^{\mathbf{a}} \rangle$ with the unique series $\tilde{\sigma} \in \mathbb{K}[[\mathbf{y}]]$ such that $\text{rank } H_{\tilde{\sigma}} = r$, and we have the following properties:*

- (\mathbf{p}, \mathbf{q}) are pairwise orthogonal bases of $\mathcal{A}_{\tilde{\sigma}}$ for the inner product $\langle \cdot, \cdot \rangle_{\tilde{\sigma}}$.
- The family $\{p_\alpha = \mathbf{x}^\alpha - \sum_{i=1}^r \langle \mathbf{x}^\alpha, q_{\beta_i} \rangle_{\sigma} p_{\beta_i}, \alpha \in \mathbf{d}\}$ is a border basis of the ideal $I_{\tilde{\sigma}}$, with respect to $\mathbf{x}^{\mathbf{b}}$.
- The matrix of multiplication by x_k in the basis \mathbf{p} (resp. \mathbf{q}) of $\mathcal{A}_{\tilde{\sigma}}$ is $M_k := (\langle \sigma | x_k p_{\beta_j} q_{\beta_i} \rangle)_{1 \leq i, j \leq r}$ (resp. M_k^t).

Proof. By construction, $V = \langle \mathbf{x}^{\mathbf{b}^+} \rangle$ is connected to 1 and $\mathbf{x}^{\mathbf{b}}$ contains 1, otherwise $\sigma = 0$. As V' contains $\mathbf{x}^{\mathbf{b}'}$ and $V \cdot V' = \langle \mathbf{x}^{\mathbf{a}} \rangle$, we have $\forall \alpha \in \partial \mathbf{b}, \mathbf{x}^\alpha \cdot \mathbf{x}^{\mathbf{b}'} \subset \mathbf{x}^{\mathbf{a}}$. Thus when the algorithm stops, we have $\mathbf{n} = \emptyset$ and $\partial \mathbf{b} = \mathbf{d}$. By construction, for $\alpha \in \mathbf{d}$ the polynomials $p_\alpha = \mathbf{x}^\alpha - \sum_{\beta \in \mathbf{b}} \langle \mathbf{x}^\alpha, q_\beta \rangle_{\sigma} p_\beta$ are orthogonal to $\langle q_\beta \mid \beta \in \mathbf{b} \rangle = \langle \mathbf{x}^{\mathbf{b}'} \rangle$. As $\alpha \in \mathbf{d}$, for each $v' \in V'$, we have moreover $\langle p_\alpha, v' \rangle_{\sigma} = 0$.

A basis of V is formed by the polynomials p_α for $\alpha \in \mathbf{b}^+$ since $\langle p_\beta \mid \beta \in \mathbf{b} \rangle = \langle \mathbf{x}^{\mathbf{b}} \rangle$ and $p_\alpha = \mathbf{x}^\alpha + b_\alpha$ with $b_\alpha \in \langle \mathbf{x}^{\mathbf{b}} \rangle$ for $\alpha \in \mathbf{d} = \partial \mathbf{b}$. The matrix of $H_{\sigma}^{V, V'}$ in this basis of V and in a basis of V' , which first elements are $q_{\beta_1}, \dots, q_{\beta_r}$, is of the form

$$H_{\sigma}^{V, V'} = \begin{pmatrix} I_r & 0 \\ * & 0 \end{pmatrix}$$

where I_r is the identity matrix of size r . The kernel of $H_{\sigma}^{V, V'}$ is generated by the polynomials p_α for $\alpha \in \mathbf{d}$.

By Theorem 4.2, σ coincides on $V \cdot V' = \langle \mathbf{x}^{\mathbf{a}} \rangle$ with a series $\tilde{\sigma}$ such that $\mathbf{x}^{\mathbf{b}}$ is a basis of $\mathcal{A}_{\tilde{\sigma}} = \mathbb{K}[\mathbf{x}]/I_{\tilde{\sigma}}$ and $I_{\tilde{\sigma}} = (\ker H_{\tilde{\sigma}}^{V, V'}) = (p_\alpha)_{\alpha \in \mathbf{d}}$.

As $p_\alpha = \mathbf{x}^\alpha + b_\alpha$ with $\alpha \in \partial \mathbf{b}$ and $b_\alpha \in \langle \mathbf{x}^{\mathbf{b}} \rangle$, $(p_\alpha)_{\alpha \in \partial \mathbf{b}}$ is a border basis with respect to $\mathbf{x}^{\mathbf{b}}$ for the ideal $I_{\tilde{\sigma}}$, since $\mathbf{x}^{\mathbf{b}}$ is a basis of $\mathcal{A}_{\tilde{\sigma}}$.

This shows that $\text{rank } H_{\tilde{\sigma}} = \dim \mathcal{A}_{\tilde{\sigma}} = |\mathbf{b}| = r$. By construction, (\mathbf{p}, \mathbf{q}) are pairwise orthogonal for the inner product $\langle \cdot, \cdot \rangle_{\sigma}$, which coincides with $\langle \cdot, \cdot \rangle_{\tilde{\sigma}}$ on $\langle \mathbf{x}^{\mathbf{a}} \rangle$. Thus they are pairwise orthogonal bases of $\mathcal{A}_{\tilde{\sigma}}$ for the inner product $\langle \cdot, \cdot \rangle_{\tilde{\sigma}}$.

As we have $x_k p_{\beta_j} \equiv \sum_{i=1}^r \langle x_k p_{\beta_j}, q_{\beta_i} \rangle_{\sigma} p_{\beta_i}$, the matrix of multiplication by x_k in the basis \mathbf{p} of $\mathcal{A}_{\tilde{\sigma}}$ is $M_k := (\langle x_k p_{\beta_j}, q_{\beta_i} \rangle_{\sigma})_{1 \leq i, j \leq r} = (\langle \sigma | x_k p_{\beta_j} q_{\beta_i} \rangle)_{1 \leq i, j \leq r}$. Exchanging the role of \mathbf{p} and \mathbf{q} , we obtain M_k^t for the matrix of multiplication by x_k in the basis \mathbf{q} . \square

Remark 4.6 If the polynomials p_α, q_α are at most of degree d , then only the coefficients of σ of degree $\leq 2d + 1$ are involved in this computation. In this case, the border basis and the decomposition of the series σ as a sum of exponential polynomials can be computed from these first coefficients.

Remark 4.7 When the monomials in \mathbf{s} are chosen according to a monomial ordering \prec , the polynomials $p_\alpha = \mathbf{x}^\alpha + b_\alpha$, $\alpha \in \mathbf{d}$ are constructed in such a way that their leading term is \mathbf{x}^α . They form a Gröbner basis of the ideal $I_{\tilde{\sigma}}$. To construct a minimal Gröbner basis of $I_{\tilde{\sigma}}$ for the monomial ordering \prec , it suffices to keep the elements p_α with $\alpha \in \mathbf{d}$ minimal for the division.

Remark 4.8 The computation can be simplified, when $\langle \cdot, \cdot \rangle_\sigma$ is semi-definite, that is, when for all $p \in \langle \mathbf{x}^\alpha \rangle$ such that $p^2 \in \langle \mathbf{x}^\alpha \rangle$, we have $\langle p, p \rangle_\sigma = 0$ implies that $\forall \alpha \in \mathbf{a}$ with $\mathbf{x}^\alpha p \in \langle \mathbf{x}^\alpha \rangle$, $\langle p, \mathbf{x}^\alpha \rangle_\sigma = 0$. In this case, the algorithm constructs a family of orthogonal polynomials $\mathbf{p} = [p_{\beta_1}, \dots, p_{\beta_r}]$ and $\mathbf{q} = [q_{\beta_1}, \dots, q_{\beta_r}]$ with $q_{\beta_i} = \frac{1}{\langle p_{\beta_i}, p_{\beta_i} \rangle_\sigma} p_{\beta_i}$ and we have $\mathbf{b} = \mathbf{b}'$. Indeed, in the while loop for each $\alpha \in \mathbf{n}$, either $\langle p_\alpha, p_\alpha \rangle_\sigma = 0$, which implies that $\forall \alpha' \in \mathbf{t}$ with $\mathbf{x}^{\alpha'} p_\alpha \in \langle \mathbf{x}^\alpha \rangle$, $\langle \mathbf{x}^{\alpha'}, p_\alpha \rangle_\sigma = 0$, so that $\alpha \in \mathbf{d}$, or $\langle p_\alpha, p_\alpha \rangle_\sigma = \langle \mathbf{x}^\alpha, p_\alpha \rangle_\sigma \neq 0$ and the first $\alpha' \in \mathbf{t}$ such that $\langle \mathbf{x}^{\alpha'}, p_\alpha \rangle_\sigma$ is $\alpha' = \alpha \in \mathbf{b}$.

If $\mathbf{K} = \mathbf{R}$ and σ is semi-definite positive, then the polynomials $\frac{1}{\sqrt{\langle p_{\beta_i}, p_{\beta_i} \rangle_\sigma}} p_{\beta_i}$ are classical orthogonal polynomials for $\langle \cdot, \cdot \rangle_\sigma$.

We can now describe the decomposition algorithm of polynomial-exponential series, obtained by combining the algorithm for computing bases of \mathcal{A}_σ and the algorithm for computing the frequency points and the weights:

Algorithm 4.2: Polynomial-Exponential decomposition

Input: the coefficients σ_α of a series $\sigma \in \mathbf{K}[[\mathbf{y}]]$ for $\alpha \in \mathbf{a} \subset \mathbf{N}^n$.

- Apply Algorithm 4.1 to compute bases $B = \mathbf{x}^{\mathbf{b}}$, $B' = \mathbf{x}^{\mathbf{b}'}$ of \mathcal{A}_σ ;
- **if** $\exists V' \supset B'$ s.t. $\langle V' \cdot B^+ \rangle = \langle \mathbf{x}^\alpha \rangle$ **then**
Apply Algorithm 3.2 (or Algorithm 3.1 if the weights are constant);

Output: the polynomial-exponential series $\sum_{i=1}^r \omega_i(\mathbf{y}) \mathbf{e}_{\xi_i}(\mathbf{y})$ with $\omega_i(\mathbf{y}) \in \mathbf{K}[\mathbf{y}]$, $\xi_i \in \mathbf{K}^n$ with the same Taylor coefficients σ_α as σ for $\alpha \in \mathbf{a} \subset \mathbf{N}^n$.

4.3 Examples

Example 4.9 Let $n = 1$ and $\sigma(y) = \frac{y^d}{d!} \in \mathbf{K}[[y]]$ with $0 < d$ and $a \neq 0 \in \mathbf{K}$.

In the first step of the algorithm, we take $p_1 = 1$ and compute the first i such that $\langle x^i, p_1 \rangle_\sigma$ is not zero. This yields $\mathbf{b} = [1]$, $\mathbf{b}' = [x^d]$ and $q_1 = x^d$.

In a second step, we have $p_x = x - \langle x, q_1 \rangle_\sigma p_1 = x$. The first i such that $\langle x^i, p_x \rangle_\sigma$ is not zero yields $\mathbf{b} = [1, x]$, $\mathbf{b}' = [x^d, x^{d-1}]$ and $q_x = x^{d-1} - \langle x^{d-1}, p_1 \rangle_\sigma q_1 = x^{d-1}$.

We repeat this computation until $\mathbf{b} = [1, \dots, x^d]$, $\mathbf{b}' = [x^d, x^{d-1}, \dots, 1]$ with $p_{x^i} = x^i$, $q_{x^i} = x^{d-i}$ for $i = 0, \dots, d$.

In the following step, we have $p_{x^{d+1}} = x^{d+1} - \langle x^{d+1}, q_1 \rangle_\sigma p_1 - \dots - \langle x^{d+1}, q_{x^d} \rangle_\sigma p_{x^d} = x^{d+1}$. The algorithm stops and outputs $\mathbf{b} = [1, \dots, x^d]$, $\mathbf{b}' = [x^d, x^{d-1}, \dots, 1]$, $p_{x^{d+1}} = x^{d+1}$.

Example 4.10 We consider the function $h(u_1, u_2) = 2 + 3 \cdot 2^{u_1} 2^{u_2} - 3^{u_1}$. Its associated generating series is $\sigma = \sum_{\alpha \in \mathbf{N}_2} h(\alpha) \frac{\mathbf{y}^\alpha}{\alpha!}$. Its (truncated) moment matrix is

$$H_\sigma^{[1, x_1, x_2, x_1^2, x_1 x_2, x_2^2]} = \begin{bmatrix} h(0, 0) & h(1, 0) & h(0, 1) & \cdots \\ h(1, 0) & h(2, 0) & h(1, 1) & \cdots \\ h(0, 1) & h(1, 1) & h(0, 2) & \cdots \\ \vdots & \vdots & \vdots & \ddots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix} = \begin{bmatrix} 4 & 5 & 7 & 5 & 11 & 13 \\ 5 & 5 & 11 & -1 & 17 & 23 \\ 7 & 11 & 13 & 17 & 23 & 25 \\ 5 & -1 & 17 & -31 & 23 & 41 \\ 11 & 17 & 23 & 23 & 41 & 47 \\ 13 & 23 & 25 & 41 & 47 & 49 \end{bmatrix}.$$

At the first step, we have $\mathbf{b} = [1]$, $\mathbf{p} = [1]$, $\mathbf{q} = [\frac{1}{4}]$. At the second step, we compute $\mathbf{b} = [1, x_1, x_2]$, $\mathbf{p} = [1, x_1 - \frac{5}{4}, x_2 + \frac{9}{5}x_1 - 4] = [p_1, p_{x_1}, p_{x_2}]$ and $\mathbf{q} = [\frac{1}{4}p_1, -\frac{4}{5}p_{x_1}, \frac{5}{24}p_{x_2}]$. At the third step, $\mathbf{d} = [x_1^2, x_1 x_2, x_2^2]$ and the algorithm stops. We obtain the following generators of

$\ker H_\sigma$:

$$\begin{aligned} p_{x_1^2} &= x_1^2 + x_2 - 4x_1 + 2 \\ p_{x_1 x_2} &= x_1 x_2 - 2x_2 - x_1 + 2 \\ p_{x_2^2} &= x_2^2 - 3x_2 + 2 \end{aligned}$$

We have modulo $\ker H_\sigma$:

$$\begin{aligned} x_1 p_1 &\equiv \frac{5}{4} p_1 + p_{x_1} \\ x_1 p_{x_1} &\equiv -\frac{5}{16} p_1 + \frac{91}{20} p_{x_1} - p_{x_2} \\ x_1 p_{x_2} &\equiv \sum_i \frac{\langle x_1 p_i, p_i \rangle_\sigma}{\langle p_i, p_i \rangle_\sigma} b_i = \frac{96}{25} p_{x_1} + \frac{1}{5} p_{x_2} \end{aligned}$$

The matrix of multiplication by x_1 in the basis \mathbf{p} is

$$M_1 = \begin{bmatrix} \frac{5}{4} & -\frac{5}{16} & 0 \\ 1 & \frac{91}{20} & \frac{96}{25} \\ 0 & -1 & \frac{1}{5} \end{bmatrix}$$

Its eigenvalues are [\[1, 2, 3\]](#) and the corresponding matrix of eigenvectors is

$$U := \begin{bmatrix} \frac{1}{2} & \frac{3}{4} & -\frac{1}{4} \\ \frac{2}{5} & -\frac{9}{5} & \frac{7}{5} \\ -\frac{1}{2} & 1 & -\frac{1}{2} \end{bmatrix},$$

that is, the polynomials $U(x) = [2 - \frac{1}{2} x_1 - \frac{1}{2} x_2, -1 + x_2, \frac{1}{2} x_1 - \frac{1}{2} x_2]$. By computing the Hankel matrix

$$H_\sigma^{U, [1, x_1, x_2]} = \begin{bmatrix} 2 & 3 & -1 \\ 2 \times 1 & 3 \times 2 & -1 \times 3 \\ 2 \times 1 & 3 \times 2 & -1 \times 1 \end{bmatrix}$$

we deduce the weights [2, 3, -1](#) and the frequencies [\(1, 1\), \(2, 2\), \(3, 1\)](#), which corresponds to the decomposition $\sigma = e^{y_1+y_2} + 3e^{2y_1+2y_2} - e^{2y_1+y_2}$ associated to $h(u_1, u_2) = 2 + 3 \cdot 2^{u_1+u_2} - 3^{u_1}$.

5 Sparse decomposition from generating series

To exploit the previous results in the context of functional analysis or signal processing, we need to transform functions into series or sequences in $\mathbb{K}^{\mathbb{N}^n}$. Here is the general context that we consider, which extends the approach of [\[53\]](#) to multi-index sequences. We assume that \mathbb{K} is algebraically close.

- Let \mathcal{F} be a functional space (in which “leaves the functions, distributions or signals”).
- Let $S_1, \dots, S_n : \mathcal{F} \rightarrow \mathcal{F}$ be linear operators of \mathcal{F} , which are commuting: $S_i \circ S_j = S_j \circ S_i$.
- Let $\Delta : h \in \mathcal{F} \mapsto \Delta[h] \in \mathbb{K}$ be a linear functional on \mathcal{F} .

We associate to an element $h \in \mathcal{F}$, its generating series:

Definition 5.1 For $h \in \mathcal{F}$, the generating series associated to h is

$$\sigma_h(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \frac{1}{\alpha!} \Delta[S^\alpha(h)] \mathbf{y}^\alpha \tag{27}$$

where $S^\alpha = S_1^{\alpha_1} \circ \dots \circ S_n^{\alpha_n}$ for $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$.

Definition 5.2 We say that the regularity condition is satisfied if the map $h \in \mathcal{F} \mapsto \sigma_h(\mathbf{y}) \in \mathbb{K}[[\mathbf{y}]]$ is injective.

We are interested in the decomposition of a function $h \in \mathcal{F}$ in terms of (generalized) eigenfunctions of the operators S_i . An eigenfunction of the operators S_i is a function $E \in \mathcal{F}$ such that $S_j(E) = \xi_j E$ for $j = 1, \dots, n$ with $\xi = (\xi_1, \dots, \xi_n) \in \mathbb{K}^n$. Generalized eigenfunctions of the operators S_i are functions $E_1, \dots, E_\mu \in \mathcal{F}$ such that $S_j(E_k) = \xi_j E_k + \sum_{k' < k} m_{k',k}^{j,k} E_{k'}$ for $k = 1, \dots, \mu$ and $\xi_1, \dots, \xi_n \in \mathbb{K}$.

The following proposition shows that if a function is a linear combination of generalized eigenfunctions, then its generating series is a sum of polynomial-exponential series.

Theorem 5.3 Let S_1, \dots, S_n be commuting operators of \mathcal{F} . Let $E_{1,1}, \dots, E_{1,\mu_1}, \dots, E_{r,1}, \dots, E_{r,\mu_r} \in \mathcal{F}$ be generalized eigenfunctions of S_1, \dots, S_n such that for $i = 1, \dots, r$, $j = 1, \dots, n$, $k = 1, \dots, \mu_i$,

$$S_j(E_{i,k}) = \xi_{i,j} E_{i,k} + \sum_{k' < k} m_{k',k}^{i,j} E_{i,k'}$$

with $\xi_i = (\xi_{i,1}, \dots, \xi_{i,n}) \in \mathbb{K}^n$ pairwise distinct. If $h = \sum_{i=1}^r \sum_{k=1}^{\mu_i} h_{i,k} E_{i,k}$, then the generating series σ_h has a unique decomposition as:

$$\sigma_h(\mathbf{y}) = \sum_{i=1}^r \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$$

where $\omega_i(\mathbf{y}) \in \mathbb{K}[[\mathbf{y}]]$. If the regularity condition is satisfied, the decomposition uniquely determines the coefficients $h_{i,k}$ of the decomposition of $h \in \mathcal{F}$.

Proof. By Lemma 2.7, in a decomposition of series as a polynomial-exponential function $\sum_{i=1}^r \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$, the polynomials $\omega_i(\mathbf{y}) \in \mathbb{K}[[\mathbf{y}]]$ and the support $\{\xi_1, \dots, \xi_r\}$ are unique. Let $N_{i,j} = S_j - \xi_{i,j} \text{Id}$ be the linear operator of $\mathbf{E}_i = \langle E_{i,1}, \dots, E_{i,\mu_i} \rangle$ such that $N_{i,j}(E_{j,k}) = \sum_{k' < k} m_{j,k'}^{i,j} E_{j,k'}$. By construction, $N_{i,j}$ is nilpotent of order $\leq \mu_i + 1$ and its matrix in the basis $\{E_{i,1}, \dots, E_{i,\mu_i}\}$ of \mathbf{E}_i is $(m_{k,k'}^{i,j})_{k,k'}$ (with $m_{k,k'}^{i,j} = 0$ if $k \geq k'$). As the operators S_j restricted to \mathbf{E}_i are $\xi_{i,j} \text{Id} + N_{i,j}$ and commute, we deduce that the operators $N_{i,j}$ commute for $j = 1, \dots, n$. By the binomial expansion of $S^\alpha = S_1^{\alpha_1} \dots S_n^{\alpha_n}$ for $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$ and the commutation of the matrices $N_{i,j}$, we have

$$S^\alpha(E_{i,k}) = \sum_{\beta \ll \alpha, \beta_j \leq \mu_j} \binom{\alpha}{\beta} \xi_i^{\alpha-\beta} N_i^\beta(E_{i,k}),$$

where $\binom{\alpha}{\beta} = \binom{\alpha_1}{\beta_1} \dots \binom{\alpha_n}{\beta_n}$ and $N_i^\beta = N_{i,1}^{\beta_1} \dots N_{i,n}^{\beta_n}$. As $N_{i,j}$ is nilpotent of order $\mu_i + 1$, this sum involves at most $(\mu_i + 1)^n$ terms such that $\beta_j \leq \mu_j$, $j = 1, \dots, n$.

The generating series of $E_{i,k}$ is then

$$\begin{aligned} \sigma_{E_{i,k}}(\mathbf{y}) &= \sum_{\alpha \in \mathbb{N}^n} \sum_{\beta \ll \alpha, \beta_j \leq \mu_j} \Delta[N_i^\beta(E_{i,k})] \binom{\alpha}{\beta} \xi_i^{\alpha-\beta} \frac{\mathbf{y}^\alpha}{\alpha!} \\ &= \sum_{\beta_i \leq \mu_i} \Delta[N_i^\beta(E_{i,k})] \frac{\mathbf{y}^\beta}{\beta!} \sum_{\alpha' \in \mathbb{N}^n} \xi_i^{\alpha'} \frac{\mathbf{y}^{\alpha'}}{\alpha'!} \\ &= \sum_{\beta_i \leq \mu_i} \Delta[N_i^\beta(E_{i,k})] \frac{\mathbf{y}^\beta}{\beta!} e_{\xi_i}(\mathbf{y}) = \omega_{i,k}(\mathbf{y}) e_{\xi_i}(\mathbf{y}), \end{aligned}$$

using the relation $\frac{1}{\alpha!} \binom{\alpha}{\beta} = \frac{1}{\beta!} \frac{1}{(\alpha-\beta)!}$, exchanging the summation order and setting $\alpha' = \alpha - \beta$. We deduce that if $h = \sum_{i=1}^r \sum_{k=1}^{\mu_i} h_{i,k} E_{i,k}$, then $\sigma_h(\mathbf{y}) = \sum_{i=1}^r \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$ with $\omega_i(\mathbf{y}) = \sum_k h_{i,k} \omega_{i,k}(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$. If the regularity condition is satisfied, the map $h \in \mathcal{F} \mapsto \sigma_h(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$ is injective and the polynomials $\omega_{i,k}(\mathbf{y})$ $k = 1, \dots, \mu_i$ are linearly independent. Therefore, the coefficients $h_{i,k}$, $k = 1, \dots, \mu_i$ are uniquely determined by the polynomial $\omega_i(\mathbf{y}) = \sum_k h_{i,k} \omega_{i,k}(\mathbf{y})$. \square

Definition 5.4 *We say that the completeness condition is satisfied if for any polynomial-exponential series $\omega(\mathbf{y}) e_{\xi}(\mathbf{y})$ with $\omega(\mathbf{y}) \in \mathbb{K}[\mathbf{y}]$ and $\xi \in \mathbb{K}^n$, there exists a linear combination $h \in \mathcal{F}$ of generalized eigenfunctions of the operators S_i , such that its generating function is $\omega(\mathbf{y}) e_{\xi}(\mathbf{y})$.*

Under the completeness condition and the regularity condition, any function $h \in \mathcal{F}$ with a generating series of finite rank can be decomposed into a linear combination of eigenfunctions. We analyse several cases, for which this framework applies.

5.1 Reconstruction from moments

Let $\mathcal{E} = C^\infty(\mathbb{R}^n)$, \mathcal{S} be the set of functions in \mathcal{E} with fast decrease at infinity ($\forall f \in \mathcal{S}, \forall p \in \mathbb{C}[\mathbf{x}], |pf|$ is bounded on \mathbb{R}^n), \mathcal{O}_M be the set of functions in \mathcal{E} with slow increase at infinity ($\forall f \in \mathcal{O}_M, |f(\mathbf{x})| < C(1 + |\mathbf{x}|)^N$ for some $C \in \mathbb{R}, N \in \mathbb{N}$), \mathcal{E}' be the set of distributions with compact support (dual to \mathcal{E}), \mathcal{S}' be the set of tempered distribution (dual to \mathcal{S}) and \mathcal{O}'_C be the space of distributions with rapid decrease at infinity (see [63]).

In this problem, we consider the following space and operators:

- $\mathcal{F} = \mathcal{O}'_C$ is the space of distributions with rapid decrease at infinity;
- $S_i : h(\mathbf{x}) \in \mathcal{O}'_C \mapsto x_i h(\mathbf{x}) \in \mathcal{O}'_C$ is the multiplication by x_j ;
- $\Delta : h(\mathbf{x}) \in \mathcal{O}'_C \mapsto \int h(\mathbf{x}) d\mathbf{x} \in \mathbb{C}$.

For any $h \in \mathcal{O}'_C$, for any $\alpha \in \mathbb{N}^n$,

$$\Delta[S^\alpha(h)] = \int \mathbf{x}^\alpha h(\mathbf{x}) d\mathbf{x}$$

is the α^{th} moment of h . For $h \in \mathcal{O}'_C$ and $\sigma_h = \sum_{\alpha \in \mathbb{N}^n} \int h(\mathbf{x}) \mathbf{x}^\alpha \frac{\mathbf{y}^\alpha}{\alpha!} d\mathbf{x}$ its generating series, we verify that $\forall p \in \mathbb{C}[\mathbf{x}], \langle \sigma_h | p \rangle = \int h(\mathbf{x}) p(\mathbf{x}) d\mathbf{x}$ (i.e. the distribution h applied to p). We check that

- the operators S_j are well defined and commute
- a Dirac measure δ_ξ with $\xi = (\xi_1, \dots, \xi_n) \in \mathbb{C}^n$ is an eigenfunction of S_j : $S_j(\delta_\xi) = \xi_j \delta_\xi$. Similarly for $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$ and
- the Dirac derivation $\delta_\xi^{(\alpha)}$ ($\forall f \in C^\infty(\Omega), \langle \delta_\xi^{(\alpha)}, f \rangle = (-1)^{|\alpha|} \partial_{x_1}^{\alpha_1} \dots \partial_{x_n}^{\alpha_n} (f)(\xi)$) satisfies

$$S_i(\delta_\xi^{(\alpha)}) = x_i \delta_\xi^{(\alpha)} = \xi_i \delta_\xi^{(\alpha)} + \delta_\xi^{(\alpha - e_i)}$$

with the convention that $\delta_\xi^{(\alpha - e_i)} = 0$ if $\alpha_i = 0$. It is a generalized eigenfunction of the operators S_j .

By the relation (28), the generating series of $\delta_\xi^{(\alpha)}$ is

$$\sigma_{\delta_\xi^{(\alpha)}} = \langle \delta_\xi^{(\alpha)}, \mathbf{e}^{\mathbf{x} \cdot \mathbf{y}} \rangle = \mathbf{y}^\alpha e_\xi(\mathbf{y}).$$

This shows that the completeness condition is satisfied.

To check the regularity condition, we use the *Fourier transform* $\mathcal{F} : f \in \mathcal{O}_M \mapsto \int f(\mathbf{x}) e^{-i\mathbf{x} \cdot \mathbf{z}} d\mathbf{x} \in \mathcal{O}'_C$. It is a bijection between \mathcal{O}_M and \mathcal{O}'_C (see [63][Théorème XV]). Its inverse is $\mathcal{F}^{-1} : f \in \mathcal{O}'_C \mapsto (2\pi)^n \int f(\mathbf{x}) e^{i\mathbf{x} \cdot \mathbf{z}} d\mathbf{x} \in \mathcal{O}_M$. Let $\iota : f(\mathbf{y}) \in \mathcal{C}[[\mathbf{y}]] \mapsto f(i\mathbf{y}) \in \mathcal{C}[[\mathbf{y}]]$.

The generating series of $f \in \mathcal{O}'_C$ is

$$\sigma_f(i\mathbf{y}) = \iota \circ \sigma_f(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \int f(\mathbf{x}) \mathbf{x}^\alpha \frac{i^{|\alpha|} \mathbf{y}^\alpha}{\alpha!} d\mathbf{x} = \int f(\mathbf{x}) \mathbf{e}^{i\mathbf{x} \cdot \mathbf{y}} d\mathbf{x} = (2\pi)^n \mathcal{F}^{-1}(f). \quad (28)$$

This shows that the map $f \in \mathcal{O}'_C \mapsto \sigma_f \in \mathcal{C}[[\mathbf{y}]]$ is injective and the regularity condition is satisfied.

For $f \in \mathcal{O}'_C$, the Hankel operator H_{σ_f} is such that $\forall g \in \mathcal{C}[\mathbf{x}]$,

$$\begin{aligned} H_{\iota \circ \sigma_f}(g) &= \sum_{\alpha \in \mathbb{N}^n} \int f(\mathbf{x}) g(\mathbf{x}) \mathbf{x}^\alpha \frac{i^{|\alpha|} \mathbf{y}^\alpha}{\alpha!} d\mathbf{x} \\ &= \int f(\mathbf{x}) g(\mathbf{x}) \mathbf{e}^{i\mathbf{x} \cdot \mathbf{y}} d\mathbf{x} = (2\pi)^n \mathcal{F}^{-1}(fg). \end{aligned}$$

Using Relation (28), we rewrite it as $\forall g \in \mathcal{C}[\mathbf{x}]$,

$$H_{\mathcal{F}^{-1}(f)}(g) = \mathcal{F}^{-1}(fg) \quad (29)$$

with $\varphi = \mathcal{F}^{-1}(f) \in \mathcal{O}_M$.

From this relation, we see that the operator $H_{\mathcal{F}^{-1}(f)}$ can be extended by continuity to an operator $H_{\mathcal{F}^{-1}(f)} : \mathcal{O}_M \mapsto \mathcal{O}_M$.

The Hankel operator $H_{\iota \circ \sigma}$ (or $H_{\mathcal{F}^{-1}(f)}$) can be related to integral operators on functions defined in terms of convolution products or cross-correlation. For $\varphi \in \mathcal{S}'$, the convolution with a distribution $\psi \in \mathcal{O}'_C$ is well-defined [63]. The convolution operator associated to φ on \mathcal{O}'_C is:

$$\mathfrak{H}_\varphi : \psi \in \mathcal{O}'_C \mapsto \varphi \star \psi = \int \varphi(\mathbf{x} - \mathbf{t}) \psi(\mathbf{t}) d\mathbf{t} \in \mathcal{S}'.$$

The image of an element $\psi \in \mathcal{O}'_C$ is a tempered distribution in \mathcal{S}' . The distribution φ is the *symbol* of the operator \mathfrak{H}_φ .

Using the property that $\forall \varphi \in \mathcal{S}', \forall \psi \in \mathcal{O}'_C, \mathcal{F}(\varphi \star \psi) = \mathcal{F}(\varphi) \mathcal{F}(\psi) \in \mathcal{S}'$ and the relation (29), we have for any $\psi \in \mathcal{O}'_C$,

$$H_{\mathcal{F}^{-1}(f)}(g) = \mathcal{F}^{-1}(fg) = \varphi \star \psi = \mathfrak{H}_\varphi(\psi),$$

with $f = \mathcal{F}(\varphi) \in \mathcal{S}', g = \mathcal{F}(\psi) \in \mathcal{O}_M$. We deduce that

$$\mathfrak{H}_\varphi = H_\varphi \circ \mathcal{F} \quad (30)$$

with $H_\varphi : g \in \mathcal{O}_M \mapsto \mathcal{F}^{-1}(\mathcal{F}(\varphi)g) \in \mathcal{S}'$.

In the case where $\varphi \in \mathcal{POLYEX} \cap \mathcal{O}_M$, the operator is of finite rank:

Proposition 5.5 *Let $\varphi = \omega(\mathbf{y}) e_{i\xi}(\mathbf{y})$ with $\omega \in \mathcal{C}[\mathbf{y}]$ and $\xi \in \mathbb{R}^n$. Then $\text{rank } \mathfrak{H}_\varphi \leq \mu(\omega)$.*

Proof. By Taylor expansion of the polynomial ω at \mathbf{x} , we have $\forall \psi \in \mathcal{O}'_C$

$$\begin{aligned}\mathfrak{H}_\varphi(\psi) &= \int \omega(\mathbf{x} - \mathbf{t}) e^{i\xi \cdot (\mathbf{x} - \mathbf{t})} \psi(\mathbf{t}) d\mathbf{t} \\ &= \sum_{\alpha \in \mathbb{N}^n} \partial^\alpha(\omega)(\mathbf{x}) e^{i\xi \cdot \mathbf{x}} \int (-1)^\alpha \frac{\mathbf{t}^\alpha}{\alpha!} \psi(\mathbf{t}) e^{-i\xi \cdot \mathbf{t}} d\mathbf{t}.\end{aligned}$$

This shows that $\mathfrak{H}_\varphi(\psi)$ belongs to the space spanned by $\partial^\alpha(\omega)(\mathbf{x}) e^{i\xi \cdot \mathbf{x}}$ for $\alpha \in \mathbb{N}^n$, which is of dimension $\mu(\omega)$ and thus $\text{rank } \mathfrak{H}_\varphi \leq \mu(\omega)$. \square

The converse is also true:

Theorem 5.6 *Suppose that $\varphi \in \mathcal{S}'$ is such that the convolution operator \mathfrak{H}_φ is of finite rank r . Then its symbol φ is of the form*

$$\varphi = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{i\xi_i}(\mathbf{y}).$$

with $\xi_i = (\xi_{i,1}, \dots, \xi_{i,n}) \in \mathbb{R}^n$, $\omega_i(\mathbf{y}) \in \mathcal{C}[\mathbf{y}]$. The rank r of \mathfrak{H}_φ is the sum of the dimension of the vector spaces spanned by $\omega_i(\mathbf{y})$ and all its derivatives $\partial^\gamma \omega_i(\mathbf{y})$, $\gamma \in \mathbb{N}^n$.

Proof. Since \mathcal{F} is a bijection between \mathcal{O}'_C and \mathcal{O}_M , the relation (30) implies that \mathfrak{H}_φ is of finite rank r , if and only if, $H_\varphi : \mathcal{O}_M \mapsto \mathcal{O}_M$ is of rank r . As the restriction of H_φ to the set of polynomials $\mathcal{C}[\mathbf{x}] \subset \mathcal{O}_M$ is of rank $\tilde{r} \leq r = \text{rank } \mathfrak{H}_\varphi$, Theorem 3.1 implies that

$$\varphi = \sum_{i=1}^{r'} \sum_{\alpha \in A_i} \omega_{i,\alpha} \mathbf{y}^\alpha e_{\xi'_i}(\mathbf{y})$$

with $\xi'_i \in \mathbb{C}^n$ distincts, $A_i \subset \mathbb{N}^n$ finite and $\tilde{r} = \sum_{i=1}^{r'} \mu(\omega_i)$ where $\mu(\omega_i)$ is the dimension of the inverse system of $\omega_i = \sum_{\alpha \in A_i} \omega_{i,\alpha} \mathbf{y}^\alpha$, spanned by $\omega_i(\mathbf{y})$ and all its derivatives. As $\varphi \in \mathcal{S}'$ is a distribution with slow increase at infinity, we have $\xi'_i = i\xi_i$ with $\xi_i \in \mathbb{R}^n$.

By Proposition 5.5, we have $r = \text{rank } \mathfrak{H}_\varphi \leq \sum_{i=1}^{r'} \mu(\omega_i) = \tilde{r}$. This shows that $\text{rank } \mathfrak{H}_\varphi = \sum_{i=1}^{r'} \mu(\omega_i)$ and concludes the proof of the theorem. \square

We can derive a similar result for the convolution by functions or distributions with support in a bounded domain Ω of \mathbb{R}^n . The main ingredient is the decomposition $\mathfrak{H}_\varphi = H_\varphi \circ \mathcal{F}$, which extends the construction used in [59] for Hankel and Toeplitz operators on $L^2(I)$ where I is a bounded interval in \mathbb{R} .

By the generalized Paley-Wiener theorem (see [63][Théorème XVI]), the Fourier transform \mathcal{F} is a bijection between the set \mathcal{E}' of distributions with a compact support and the set of continuous functions $f \in C(\mathbb{R}^n)$ with an analytic extension of exponential type (there exists $A \in \mathbb{R}, C \in \mathbb{R}_+$ such that $\forall \mathbf{z} \in \mathbb{C}^n, |f(\mathbf{z})| \leq C e^{A(|z_1| + \dots + |z_n|)}$). Let us denote by $\mathcal{E}'(\Omega)$ the set of distributions with a support in Ω , and by $\mathcal{PW}(\Omega) = \{\mathcal{F}(\varphi) \mid \varphi \in \mathcal{E}'(\Omega)\}$ the set of their Fourier transforms.

Theorem 5.7 *Let Ω, Ξ be open bounded domains of \mathbb{R}^n with $\Upsilon = \Xi + \Omega \subset \mathbb{R}^n$ and $\varphi \in \mathcal{E}'(\Omega)$. The convolution operator*

$$\mathfrak{H}_\varphi : \psi \in \mathcal{E}'(\Xi) \mapsto \int \varphi(x - t) \psi(t) dt \in \mathcal{E}'(\Upsilon)$$

is of finite rank r , if and only if, the symbol φ is of the form

$$\varphi = 1_\Omega \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$$

where $\xi_i = (\xi_{i,1}, \dots, \xi_{i,n}) \in \mathbb{C}^n$, $\omega_i(\mathbf{y}) \in \mathbb{C}[\mathbf{y}]$. The rank r of \mathfrak{H}_φ is the sum of the dimensions $\mu(\omega_i)$ of the vector spaces spanned by $\omega_i(\mathbf{y})$ and all the derivatives $\partial_\gamma^\gamma \omega_i(\mathbf{y})$, $\gamma \in \mathbb{N}^n$.

Proof. Using the relations $\forall \varphi \in \mathcal{E}'(\Omega), \psi \in \mathcal{E}'(\Xi)$,

$$\mathcal{F}(\varphi \star \psi) = \mathcal{F}(\varphi) \mathcal{F}(\psi),$$

and (29), we still have the decomposition

$$\mathfrak{H}_\varphi = H_\varphi \circ \mathcal{F}.$$

with $H_\varphi : g \in \mathcal{PW}(\Xi) \rightarrow \mathcal{F}^{-1}(\mathcal{F}(\varphi)g) \in \mathcal{E}'(\Upsilon)$. Thus \mathfrak{H}_φ is of finite rank r , if and only if, H_φ is of finite rank r . As the rank of the restriction of H_φ to $\mathbb{C}[\mathbf{x}] \subset \mathcal{PW}(\Xi)$ is at most r , we conclude by using Theorem 3.1, a result similar to Proposition 5.5 for elements $\psi \in \mathcal{E}'(\Xi)$ and the relation $\mathcal{F}^{-1}(\mathcal{F}(\varphi)) = \varphi$ on Ω . \square

Similar results also apply for the cross-correlation operator defined as

$$\tilde{\mathfrak{H}}_\varphi : \psi \in \mathcal{E}' \mapsto \varphi \star \psi = \int \varphi(x+t) \bar{\psi}(t) dt \in \mathcal{S}'.$$

Using the relation $\mathcal{F}(\varphi \star \psi) = \mathcal{F}(\varphi) \bar{\mathcal{F}}(\psi)$ (with $\bar{\mathcal{F}} = \varsigma \circ \mathcal{F}$ where $\varsigma : z \in \mathbb{C} \mapsto \bar{z} \in \mathbb{C}$ is the complex conjugation), we have $\tilde{\mathfrak{H}}_\varphi = H_\varphi \circ \bar{\mathcal{F}}$. As $\bar{\mathcal{F}}^{-1} = \mathcal{F}^{-1} \circ \varsigma$, we deduce that $\tilde{\mathfrak{H}}_\varphi$ and H_φ have the same rank and the same type of decomposition of the symbol φ holds when $\tilde{\mathfrak{H}}_\varphi$ is of finite rank.

Remark 5.8 To compute the decomposition of $\varphi \in \mathcal{S}'$ (resp. $\varphi \in \mathcal{E}'(\Omega)$) as a polynomial exponential function, we first compute the Taylor coefficients of $\sigma_{\mathcal{F}(\varphi)} = \mathfrak{H}_\varphi(1)$, that is, the values $\sigma_\alpha = (-i)^{|\alpha|} \mathcal{F}(\mathbf{x}^\alpha \varphi)(\mathbf{0})$ for some $\alpha \in \mathbf{a} \subset \mathbb{N}^n$ and apply the decomposition algorithm 4.2 to the (truncated) sequence $(\sigma_\alpha)_{\alpha \in \mathbf{a}}$.

5.2 Reconstruction from Fourier coefficients

We consider here the problem of reconstruction of functions or distributions from Fourier coefficients. Let $T = (T_1, \dots, T_n) \in \mathbb{R}_+^n$ and $\Omega = \prod_{i=1}^n [-\frac{2\pi T_i}{2}, \frac{2\pi T_i}{2}] \subset \mathbb{R}^n$. We take:

- $\mathcal{F} = L^2(\Omega)$;
- $S_i : h(\mathbf{x}) \in L^2(\Omega) \mapsto e^{2\pi \frac{x_i}{T_i}} h(\mathbf{x}) \in L^2(\Omega)$ is the multiplication by $e^{2\pi \frac{x_i}{T_i}}$;
- $\Delta : h(\mathbf{x}) \in \mathcal{O}'_C \mapsto \int h(\mathbf{x}) d\mathbf{x} \in \mathbb{C}$.

For $f \in \mathcal{E}'(\Omega)$ with a support in Ω and $\gamma = (\gamma_1, \dots, \gamma_n) \in \mathbb{Z}^n$, the γ -th Fourier coefficient of f is

$$\sigma_\gamma = \frac{1}{\prod_{j=1}^n T_j} \mathcal{F}(f) \left(2\pi \frac{\gamma_1}{T_1}, \dots, 2\pi \frac{\gamma_n}{T_n} \right) = \frac{1}{\prod_{j=1}^n T_j} \int f(\mathbf{x}) e^{-2\pi i \sum_{j=1}^n \frac{\gamma_j x_j}{T_j}} d\mathbf{x}$$

Let $\sigma = (\sigma_\gamma)_{\gamma \in \mathbb{Z}^n}$ be the sequence of the Fourier coefficients. The discrete convolution operator associated to σ is $\Phi_\sigma : (\rho_\beta)_{\beta \in \mathbb{Z}^n} \in L^2(\mathbb{Z}^n) \mapsto \left(\sum_{\beta} \sigma_{\alpha-\beta} \rho_\beta \right)_{\alpha \in \mathbb{Z}^n} \in L^2(\mathbb{Z}^n)$. The discrete

cross-correlation operator of σ is $\Gamma_\sigma : (\rho_\beta)_{\beta \in \mathbb{Z}^n} \in L^2(\mathbb{Z}^n) \mapsto \left(\sum_\beta \sigma_{\alpha+\beta} \rho_\beta \right)_{\alpha \in \mathbb{Z}^n} \in L^2(\mathbb{Z}^n)$. It is obtained from Γ_σ by composition by $\mathcal{R} : (r_\beta)_{\beta \in \mathbb{Z}^n} \in L^2(\mathbb{Z}^n) \mapsto (\rho_{-\beta})_{\beta \in \mathbb{Z}^n} \in L^2(\mathbb{Z}^n)$: $\Gamma_\sigma = \Phi_\sigma \circ \mathcal{R}$.

A decomposition similar to the previous section also holds:

Theorem 5.9 *Let $f \in L^2(\Omega)$ and let $\sigma = (\sigma_\gamma)_{\gamma \in \mathbb{Z}^n}$ be its sequence of Fourier coefficients. The discrete convolution (resp. cross-correlation) operator Φ_σ (resp. Γ_σ) is of finite rank if and only if*

$$f = \sum_{i=1}^{r'} \sum_{\alpha \in A_i \subset \mathbb{N}^n} \omega_{i,\alpha} \delta_{\xi_i}^{(\alpha)}$$

where

- $\xi_i = (\xi_{i,1}, \dots, \xi_{i,n}) \in \Omega$, $\omega_{i,\alpha} \in \mathbb{C}$, $A_i \subset \mathbb{N}^n$ is finite,
- the rank of Γ_σ is the sum of the dimensions $\mu(\omega_i)$ of the vector spaces spanned by $\omega_i(\mathbf{y}) = \sum_{\alpha \in A_i} \omega_{i,\alpha} \mathbf{y}^\alpha$ and all the derivatives $\partial_{\mathbf{y}}^\gamma(\omega_i)$, $\gamma \in \mathbb{N}^n$.

Proof. Let $S : f \in L^2(\Omega) \mapsto (\sigma_\gamma)_{\gamma \in \mathbb{Z}^n} \in L^2(\mathbb{Z}^n)$ be the discrete Fourier transform where $\sigma_\gamma = \frac{1}{\prod_{j=1}^n T_j} \mathcal{F}(f) \left(2\pi \frac{\gamma_1}{T_1}, \dots, 2\pi \frac{\gamma_n}{T_n} \right)$. Its inverse is $S^{-1} : \sigma = (\sigma_\gamma)_{\gamma \in \mathbb{Z}^n} \in L^2(\mathbb{Z}^n) \mapsto \sum_{\alpha \in \mathbb{Z}^n} \sigma_\alpha 1_\Omega e^{2\pi i \sum_{j=1}^n \frac{\gamma_j x_j}{T_j}} \in L^2(\Omega)$. As the discrete Fourier transform exchanges the convolution and the product, using Relation (29), we have $\forall \sigma, \rho \in L^2(\mathbb{Z}^n)$,

$$\Phi_\sigma(\rho) = S(S^{-1}(\sigma)S^{-1}(\rho)) = S(fg) = S \circ \mathcal{F} \circ \mathcal{F}^{-1}(fg) = S \circ \mathcal{F} \circ H_{\mathcal{F}^{-1}(f)}(g)$$

where $f = S^{-1}(\sigma)$, $g = S^{-1}(\rho) \in L^2(\Omega)$ and $H_{\mathcal{F}^{-1}(f)} : g \in L^2(\Omega) \mapsto \mathcal{F}^{-1}(fg) \in \mathcal{PW}(\Omega)$. We deduce that

$$\Phi_\sigma = S \circ \mathcal{F} \circ H_{\mathcal{F}^{-1} \circ S^{-1}(\sigma)} \circ S^{-1}.$$

As S is an isometry between $L^2(\mathbb{Z}^n)$ and $L^2(\Omega)$ and \mathcal{F} is an isomorphism between $L^2(\Omega)$ and $\mathcal{PW}(\Omega)$, $\Phi_\sigma = S \circ \mathcal{F} \circ H_{\mathcal{F}^{-1} \circ S^{-1}(\sigma)} \circ S^{-1}$ and $H_{\mathcal{F}^{-1} \circ S^{-1}(\sigma)}$ have the same rank.

As $\mathbb{C}[\mathbf{x}] \subset \mathcal{PW}(\Omega)$, we deduce from Theorem 3.1 that

$$\mathcal{F}^{-1} \circ S^{-1}(\sigma) = \sum_{i=1}^{r'} \tilde{\omega}_i(\mathbf{y}) \mathbf{e}_{\tilde{\xi}_i}(\mathbf{y})$$

where $\tilde{\xi}_i = (\tilde{\xi}_{i,1}, \dots, \tilde{\xi}_{i,n}) \in \mathbb{C}^n$, $\tilde{\omega}_i(\mathbf{y}) = \sum_{\alpha \in A_i} \tilde{\omega}_{i,\alpha} \mathbf{y}^\alpha \in \mathbb{C}[\mathbf{z}]$. Using a result similar to Proposition 5.5 for the elements $\psi \in L^2(\Omega)$, we deduce that the rank r of Φ_σ is $r = \sum_{i=1}^{r'} \mu(\tilde{\omega}_i)$. Consequently,

$$f = S^{-1}(\sigma) = \mathcal{F} \left(\sum_{i=1}^{r'} \sum_{\alpha \in A_i} \tilde{\omega}_{i,\alpha} \mathbf{y}^\alpha \mathbf{e}_{\tilde{\xi}_i}(\mathbf{y}) \right) = (2\pi)^n \sum_{i=1}^{r'} \sum_{\alpha \in A_i \subset \mathbb{N}^n} \mathbf{i}^{|\alpha|} \tilde{\omega}_{i,\alpha} \delta_{\mathbf{i}\tilde{\xi}_i}^{(\alpha)}.$$

As the support of f is in Ω , we have $\xi_i = \mathbf{i}\tilde{\xi}_i \in \Omega$. We deduce the decomposition of f with $\omega_i = (2\pi)^n \sum_{i=1}^{r'} \sum_{\alpha \in A_i \subset \mathbb{N}^n} \mathbf{i}^{|\alpha|} \tilde{\omega}_{i,\alpha} \mathbf{y}^\alpha$.

The dimension $\mu(\tilde{\omega}_i)$ of the vector space spanned by $\tilde{\omega}_i(\mathbf{y}) = \sum_{\alpha \in A_i} \tilde{\omega}_{i,\alpha} \mathbf{y}^\alpha$ and all its derivatives is the same as the dimension $\mu(\omega_i)$ of the space spanned by $\omega_i(\mathbf{y}) = (2\pi)^n \sum_{\alpha \in A_i} \tilde{\omega}_{i,\alpha} \mathbf{i}^{|\alpha|} \mathbf{y}^\alpha$ and all its derivatives, since $\omega_i(\mathbf{y}) = (2\pi)^n \tilde{\omega}_i(\mathbf{i}\mathbf{y})$. Therefore, $\text{rank } \Phi_\sigma = r = \sum_{i=1}^{r'} \mu(\tilde{\omega}_i) = \sum_{i=1}^{r'} \mu(\omega_i)$. This concludes the proof of the theorem. \square

Remark 5.10 To compute the decomposition of $f \in L^2(\Omega)$ as a weighted sum of Dirac measures and derivatives, we apply the decomposition algorithm 4.2 to the (truncated) sequence of Fourier coefficients $(\sigma_\alpha)_{\alpha \in \mathbf{a}}$ for some subset $\mathbf{a} \subset \mathbb{N}^n$. The polynomial-exponential decomposition $\varphi = \sum_{i=1}^{r'} \sum_{\alpha \in A_i} \tilde{\omega}_{i,\alpha} \mathbf{y}^\alpha e_{\tilde{\xi}_i}(\mathbf{y})$, from which we deduce the decomposition $f = (2\pi)^n \sum_{i=1}^{r'} \sum_{\alpha \in A_i \subset \mathbb{N}^n} \mathbf{i}^{|\alpha|} \tilde{\omega}_{i,\alpha} \delta_{\tilde{\xi}_i}^{(\alpha)}$.

5.3 Reconstruction from values

In this problem, we are interested in reconstructing a function in $C^\infty(\mathbb{R}^n)$ from sampled values. We take

- $\mathcal{F} = C^\infty(\mathbb{R}^n)$,
- $S_j : h(x) \mapsto h(x_1, \dots, x_{j-1}, x_j + 1, x_{j+1}, \dots, x_n)$ the shift operator of x_j by 1,
- $\Delta : h(x) \mapsto \Delta[h] = h(0)$ the evaluation at 0.

The generating series of h is

$$\sigma_h(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} h(\alpha_1, \dots, \alpha_n) \frac{\mathbf{y}^\alpha}{\alpha!} = \sum_{\alpha \in \mathbb{N}^n} h(\alpha) \frac{\mathbf{y}^\alpha}{\alpha!}.$$

The operators S_j are commuting and we have $S_j(e^{\mathbf{f} \cdot \mathbf{x}}) = \xi_j e^{\mathbf{f} \cdot \mathbf{x}}$ where $\mathbf{f} = (f_1, \dots, f_n) \in \mathbb{C}^n$ and $\xi_j = e^{f_j}$. The generating series associated to $e^{\mathbf{f} \cdot \mathbf{x}}$ is $e_\xi(\mathbf{y})$ where $\xi = (\xi_1, \dots, \xi_n) = (e^{f_1}, \dots, e^{f_n})$.

Similarly for any $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$, $S_j(\mathbf{x}^\alpha e^{\mathbf{f} \cdot \mathbf{x}}) = \xi_j \sum_{i=0}^{\alpha_j} \binom{\alpha_j}{i} x_j^i \prod_{i \neq j} x_i^{\alpha_i} e^{\mathbf{f} \cdot \mathbf{x}}$, which shows that the function $\mathbf{x}^\alpha e^{\mathbf{f} \cdot \mathbf{x}}$ is a generalized eigenfunction of the operators S_j . Its generating series is

$$\sigma_{\mathbf{x}^\alpha e^{\mathbf{f} \cdot \mathbf{x}}}(\mathbf{y}) = \sum_{\beta \in \mathbb{N}^n} \beta^\alpha \xi^\beta \frac{\mathbf{y}^\beta}{\beta!}. \quad (31)$$

Let $b_\alpha(\mathbf{y}) = \binom{y_1}{\alpha_1} \dots \binom{y_n}{\alpha_n}$ be the Macaulay binomial polynomial with $\binom{y_i}{\alpha_i} = \frac{1}{\alpha_i!} y_i (y_i - 1) \dots (y_i - \alpha_i + 1)$, which roots are $0, \dots, \alpha_i - 1$. It satisfies the following relations:

$$\sum_{\beta \in \mathbb{N}^n} b_\alpha(\beta) \xi^\beta \frac{\mathbf{y}^\beta}{\beta!} = \sum_{\beta \gg \alpha} b_\alpha(\beta) \xi^\beta \frac{\mathbf{y}^\beta}{\beta!} = \sum_{\beta \gg \alpha} \frac{1}{\alpha!} \xi^\beta \frac{\mathbf{y}^\beta}{(\beta - \alpha)!} = \frac{1}{\alpha!} \xi^\alpha \mathbf{y}^\alpha e_\xi(\mathbf{y}).$$

As $\mathbf{y}^\alpha = \sum_{\alpha' \ll \alpha} m_{\alpha', \alpha} \mathbf{y}^{\alpha'}$ for some coefficients $m_{\alpha', \alpha} \in \mathbb{Q}$ such that $m_{\alpha, \alpha} = 1$, we have

$$\sigma_{\mathbf{x}^\alpha e^{\mathbf{f} \cdot \mathbf{x}}}(\mathbf{y}) = \left(\sum_{\alpha' \ll \alpha} m_{\alpha', \alpha} \xi^{\alpha'} \frac{\mathbf{y}^{\alpha'}}{\alpha'!} \right) e_\xi(\mathbf{y}) = \omega_\alpha(\mathbf{y}) e_\xi(\mathbf{y}). \quad (32)$$

The monomials of $\omega_\alpha(\mathbf{y})$ are among the monomials $\mathbf{y}^{\alpha'} = y_1^{\alpha'_1} \dots y_n^{\alpha'_n}$ such that $0 \leq \alpha'_i \leq \alpha_i$, which divide \mathbf{y}^α . As the coefficient of \mathbf{y}^α in $\omega_\alpha(\mathbf{y})$ is 1, we deduce that $(\omega_\alpha)_{\alpha \in \mathbb{N}^n}$ is a basis of $\mathbb{C}[\mathbf{y}]$ and the completeness property is satisfied.

Let $h = (h(\alpha))_{\alpha \in \mathbb{N}^n}$. The Hankel operator H_h is such that $\forall p = \sum_\beta p_\beta \mathbf{x}^\beta \in \mathbb{C}[\mathbf{x}]$,

$$H_h(p) = \sum_{\alpha \in \mathbb{N}^n} \left(\sum_{\beta} h(\alpha + \beta) p_\beta \right) \frac{\mathbf{y}^\alpha}{\alpha!}$$

Identifying the series $\sigma(\mathbf{y}) = \sum_{\alpha \in \mathbb{N}^n} \sigma_\alpha \frac{\mathbf{y}^\alpha}{\alpha!} \in \mathbb{C}[[\mathbf{y}]]$ with the multi-index sequence $(\sigma_\alpha)_{\alpha \in \mathbb{N}^n}$ and a polynomial $p = \sum_{\alpha \in A} p_\alpha \mathbf{x}^\alpha$ with the sequence $(p_\alpha)_{\alpha \in \mathbb{N}^n} \in L_0(\mathbb{N}^n)$ of finite support, the operator H_h corresponds to the discrete cross-correlation operator by the sequence h . This operator can be extended to sequences h, p are in $L^2(\mathbb{N}^n)$.

Theorem 5.11 Let $h \in C^\infty(\mathbb{R}^n)$. The discrete cross-correlation operator $\Gamma_h : p \in L^2(\mathbb{N}^n) \mapsto h \star p = \left(\sum_{\beta} h(\alpha + \beta) p_\beta \right)_{\alpha \in \mathbb{N}^n} \in L^2(\mathbb{N}^n)$ is of finite rank, if and only if,

$$h(\mathbf{x}) = \sum_{i=1}^{r'} g_i(\mathbf{x}) e^{f_i \cdot \mathbf{x}} + r(\mathbf{x})$$

where

- $f_i = (f_{i,1}, \dots, f_{i,n}) \in \mathbb{C}^n$, $g_i(\mathbf{x}) \in \mathbb{C}[\mathbf{x}]$,
- $r(\mathbf{x}) \in C^\infty(\mathbb{R}^n)$ such that $r(\alpha) = 0$, $\forall \alpha \in \mathbb{N}^n$,
- The rank of Γ_h is the sum of the dimension $\mu(g_i)$ of the vector space spanned by $g_i(\mathbf{x})$ and all its derivatives $\partial_{\mathbf{x}}^\alpha g_i$, $\alpha \in \mathbb{N}^n$.

Proof. Since H_h is of finite rank, Theorem 3.1 implies that

$$\sigma_h = \sum_{\alpha \in \mathbb{N}^n} h(\alpha) \frac{\mathbf{y}^\alpha}{\alpha!} = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$$

where $\xi_i \in \mathbb{C}^n$, $\omega_i(\mathbf{x}) \in \mathbb{C}[\mathbf{x}]$ and $\text{rank } H_{\sigma_h} = \sum_{i=1}^{r'} \mu(\omega_i)$. Let $\mathbf{f}_i = (f_{i,1}, \dots, f_{i,n}) \in \mathbb{C}^n$ such that $\xi_i = (e^{f_{i,1}}, \dots, e^{f_{i,n}})$ and $g_{i,\alpha} \in \mathbb{C}$ for $\alpha \in A_i \subset \mathbb{N}^n$ such that

$$\omega_i(\mathbf{y}) = \sum_{\alpha \in A_i} g_{i,\alpha} \omega_\alpha(\mathbf{y}).$$

By the relation (32), the generating series of $r(\mathbf{x}) = h - \sum_{i=1}^{r'} \sum_{\alpha \in A_i} g_{i,\alpha} \mathbf{x}^\alpha e^{f_i \cdot \mathbf{x}}$ is 0, which implies that r is a function in $C^\infty(\mathbb{R}^n)$ such that $r(\alpha) = 0$, $\forall \alpha \in \mathbb{N}^n$.

It remains to prove that the inverse systems spanned by $\omega_i(\mathbf{y}) = \sum_{\alpha \in A_i} g_{i,\alpha} \omega_\alpha(\mathbf{y})$ and by $g_i(\mathbf{x}) = \sum_{\alpha \in A_i} g_{i,\alpha} \mathbf{x}^\alpha$ have the same dimension. The polynomials ω_α are of the form

$$\omega_\alpha(\mathbf{y}) = \mathbf{y}^\alpha + \sum_{\alpha' \neq \alpha, \alpha' \ll \alpha} \omega_{\alpha,\alpha'} \mathbf{y}^{\alpha'},$$

with $\omega_{\alpha,\alpha'} \in \mathbb{Q}$. Let ρ denotes the linear map of $\mathbb{C}[\mathbf{y}]$ such that $\rho(\mathbf{y}^\alpha) = \omega_\alpha(\mathbf{y}) - \mathbf{y}^\alpha$. We choose a monomial ordering \succ , which is a total ordering on the monomials compatible with the multiplication. Then, the initial $\text{in}(\omega_\alpha)$ of ω_α , that is the maximal monomial of the support of ω_α , is \mathbf{y}^α since $\mathbf{y}^\alpha \succ \text{in}(\rho(\mathbf{y}^\alpha))$. As the support of ω_α is in $\{\alpha', \alpha' \ll \alpha\}$, the support of $\partial^\beta \omega_\alpha$ ($\beta \in \mathbb{N}^n$) is $\{\alpha', \alpha' \ll \alpha - \beta\}$ and the initial of $\partial^\beta \omega_\alpha$ is $\partial^\beta(\mathbf{x}^\alpha)$. By linearity, for any $g \in \mathbb{C}[\mathbf{y}]$, we have $\text{in}(g) \succ \text{in}(\rho(g))$. We deduce that

$$\omega_i(\mathbf{y}) = \sum_{\alpha \in A_i} g_{i,\alpha} \omega_\alpha(\mathbf{y}) = \sum_{\alpha \in A_i} g_{i,\alpha} (\mathbf{y}^\alpha + \rho(\mathbf{y}^\alpha)) = g_i(\mathbf{y}) + \rho(g_i)$$

and the initial $\text{in}(\partial^\beta \omega_i)$ is also the initial of $\partial^\beta g_i$ ($\beta \in \mathbb{N}^n$). Therefore the initial of the vector space spanned by $\omega_i(\mathbf{y}) = g_i(\mathbf{y}) + \rho(g_i)$ and all its derivatives coincides with the vector space spanned by the initial of $\omega_i(\mathbf{y}) = g_i(\mathbf{y})$ and all its derivatives. Therefore, the two vector spaces have the same dimension. This concludes the proof. \square

Remark 5.12 Instead of a shift by 1 and the generating series of h computed on the unitary grid \mathbb{N}^n , one can consider the shift $S_j(h) = h\left(x_1, \dots, x_{j-1}, x_j + \frac{1}{T_j}, x_{j+1}, \dots, x_n\right)$ for $T_j \in \mathbb{R}_+$ and the generating series of the sequence $\left(h\left(\frac{\alpha_1}{T_1}, \dots, \frac{\alpha_n}{T_n}\right)\right)_{\alpha \in \mathbb{N}^n}$. The previous results apply directly, replacing the function h by $h_T : (x_1, \dots, x_n) \mapsto h\left(\frac{x_1}{T_1}, \dots, \frac{x_n}{T_n}\right)$ where $T = (T_1, \dots, T_n)$.

Remark 5.13 Using Lemma 2.7, we check that the map $h \in \mathcal{POLYEXP} \mapsto \sigma_h \in \mathbb{C}[[\mathbf{y}]]$ is injective and the regularity condition is satisfied on $\mathcal{POLYEXP}$. Thus, in Theorem 5.11 if $h \in \mathcal{POLYEXP}$ then we must have $r(\mathbf{x}) = 0$.

Remark 5.14 By applying Algorithm 4.2 to the sequence of evaluations of a function $h \in \mathcal{POLYEXP}$ on the (first) points of a regular grid in \mathbb{R}^n , we obtain a method to decompose functions in $\mathcal{POLYEXP}$ as a sum of products of polynomials by exponentials.

5.4 Sparse interpolation

For $\beta = (\beta_1, \dots, \beta_n) \in \mathbb{N}^n$ and $\mathbf{x} \in \mathbb{C}^n$, we denote $\log^\beta \mathbf{x} = \prod_{i=1}^n (\log(x_i))^{\beta_i}$ where $\log(x)$ is the principal value of the complex logarithm $\mathbb{C} \setminus \{0\}$. Let

$$\mathcal{POLYLOG}(x_1, \dots, x_n) = \left\{ \sum_{\alpha, \beta} p_{\alpha, \beta} \mathbf{x}^\alpha \log^\beta(\mathbf{x}), p_{\alpha, \beta} \in \mathbb{C} \right\}$$

be the set of functions, which are the sum of products of polynomials in \mathbf{x} and polynomials in $\log(\mathbf{x})$.

For $h = \sum_{\alpha, \beta} h_{\alpha, \beta} \mathbf{x}^\alpha \log^\beta(\mathbf{x}) \in \mathcal{POLYLOG}(\mathbf{x})$, we denote by $\varepsilon(h)$ the set of exponents $\alpha \in \mathbb{N}^n$ such that $h_{\alpha, \beta} \neq 0$.

The sparse interpolation problem consists in computing the decomposition of a function p of $\mathcal{POLYLOG}(\mathbf{x})$ as a sum of terms of the form $p_{\alpha, \beta} \mathbf{x}^\alpha \log^\beta(\mathbf{x})$ from the values of p . We apply the construction introduced in Section 5 with

- $\mathcal{F} = \mathcal{POLYLOG}(\mathbf{x})$,
- $S_j : h(x_1, \dots, x_n) \mapsto h(x_1, \dots, x_{j-1}, \lambda_j x_j, x_{j+1}, \dots, x_n)$ the scaling operator of x_j by $\lambda_j \in \mathbb{C}$,
- $\Delta : h(x_1, \dots, x_n) \mapsto \Delta[h] = h(1, \dots, 1)$ the evaluation at $\mathbf{1} = (1, \dots, 1)$.

We easily check that

- the operators S_j are commuting,
- for $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$, the monomial \mathbf{x}^α is an eigenfunction of S_j : $S_j(\mathbf{x}^\alpha) = \lambda_j^{\alpha_j} \mathbf{x}^\alpha$.
- for $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$, $\beta = (\beta_1, \dots, \beta_n) \in \mathbb{N}^n$, $\mathbf{x}^\alpha \log^\beta(\mathbf{x})$ is a generalized eigenfunction of S_j :

$$S_j(\mathbf{x}^\alpha \log^\beta(\mathbf{x})) = \sum_{0 \leq \beta' \leq \beta_j} \lambda_j^{\alpha_j} \binom{\beta_j}{\beta'} \log^{\beta_j - \beta'} \lambda_j \log^{\beta'}(x_j) \mathbf{x}^\alpha \prod_{k \neq j} \log^{\beta_k}(x_k).$$

More generally, for $\gamma \in \mathbb{N}^n$, we have

$$\begin{aligned} S^\gamma(\mathbf{x}^\alpha \log^\beta(\mathbf{x})) &= \left(\prod_{i=1}^n (\lambda_i^{\gamma_i} x_i)^{\alpha_i} \right) \left(\prod_{i=1}^n (\gamma_i \log(\lambda_i) + \log(x_i))^{\beta_i} \right) \\ &= \xi^\gamma \mathbf{x}^\alpha \left(\sum_{\beta' \ll \beta} \binom{\beta}{\beta'} \gamma^{\beta'} \log^{\beta'}(\boldsymbol{\lambda}) \log^{\beta - \beta'}(\mathbf{x}) \right) \end{aligned}$$

where $\xi = (\lambda_1^{\alpha_1}, \dots, \lambda_n^{\alpha_n})$. We deduce that,

$$\Delta[S^\gamma(\mathbf{x}^\alpha \log^\beta(\mathbf{x}))] = \xi^\gamma \gamma^\beta \log^\beta(\boldsymbol{\lambda}). \quad (33)$$

Theorem 5.15 Let $h \in \mathcal{POLYLOG}(\mathbf{x})$. For $\lambda_1, \dots, \lambda_n \in \mathbb{C}$, the generating series $\sigma_h = \sum_{\gamma \in \mathbb{N}^n} h(\lambda_1^{\gamma_1}, \dots, \lambda_n^{\gamma_n}) \frac{\mathbf{y}^\gamma}{\gamma!}$ of h is of the form

$$\sigma_h(\mathbf{y}) = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$$

with

- $\varepsilon(h) = \{\alpha_1, \dots, \alpha_{r'}\}$,
- $\xi_i = (\lambda_1^{\alpha_{i,1}}, \dots, \lambda_n^{\alpha_{i,n}}) \in \mathbb{C}^n$,
- $\omega_i(\mathbf{y}) = \sum_{\beta \in B_i} \omega_{i,\beta} \mathbf{y}^\beta \in \mathbb{C}[\mathbf{y}]$.

If moreover $\lambda_i \neq 1$ and the points $\xi_i = (\lambda_1^{\alpha_{i,1}}, \dots, \lambda_n^{\alpha_{i,n}})$, $\alpha_i \in \varepsilon(h)$ are distinct, then $h = \sum_{i=1}^{r'} \sum_{\beta \in B_i} \omega_{i,\beta} \mathbf{x}^{\alpha_i} \log^\beta(\mathbf{x})$.

Proof. Let $\alpha, \beta \in \mathbb{N}^n$. As \mathbf{x}^α is an eigenfunction of the operators S_j , its generating series associated to \mathbf{x}^α is $e_\xi(\mathbf{y})$ where $\xi = (\lambda_1^{\alpha_1}, \dots, \lambda_n^{\alpha_n})$. From the relations (31) and (32), we deduce that the generating series of $\mathbf{x}^\alpha \log^\beta(\mathbf{x})$ is

$$\sigma_{\mathbf{x}^\alpha \log^\beta(\mathbf{x})} = \log^\beta(\boldsymbol{\lambda}) \sum_{\gamma \in \mathbb{N}^n} \gamma^\beta \xi^\gamma \frac{\mathbf{y}^\gamma}{\gamma!} = \log^\beta(\boldsymbol{\lambda}) \omega_\beta(\mathbf{y}) e_\xi(\mathbf{y})$$

where $\omega_\beta(\mathbf{y})$ is the polynomial obtained from the expansion of \mathbf{y}^β in terms of the Macaulay binomial polynomials $b_\alpha(\mathbf{y})$. As in Section 5.3, this shows that the completeness property is satisfied.

If $h = \sum_{i=1}^{r'} \sum_{\beta \in B_i} h_{i,\beta} \mathbf{x}^{\alpha_i} \log^\beta(\mathbf{x})$, $\lambda_i \neq 1$ and the points $\xi_i = (\lambda_1^{\alpha_{i,1}}, \dots, \lambda_n^{\alpha_{i,n}})$ are distinct, then

$$\sigma_h = \sum_{i=1}^{r'} \left(\sum_{\beta \in B_i} h_{i,\beta} \log^\beta(\boldsymbol{\lambda}) \omega_\beta(\mathbf{y}) \right) e_{\xi_i}(\mathbf{y}) = \sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$$

with $\xi_i = (\lambda_1^{\alpha_{i,1}}, \dots, \lambda_n^{\alpha_{i,n}})$ and $\omega_i(\mathbf{y}) \in \mathbb{C}[\mathbf{x}]$. By Lemma 2.7 and the linear independency of the polynomials ω_β , we deduce that the coefficients $h_{i,\beta}$ are uniquely determined from the coefficients of the decomposition of $\omega_i(\mathbf{y})$ in terms of the Macaulay binomial polynomials ω_β , since $\log^\beta(\boldsymbol{\lambda}) \neq 0$. \square

This result leads to a new method to decompose an element $h \in \mathcal{POLYLOG}(\mathbf{x})$ with an exponent set $\varepsilon(h) \subset A \subset \mathbb{N}^n$. By choosing $\lambda_1, \dots, \lambda_n \in \mathbb{C} \setminus \{1\}$ such that the points $(\lambda_1^{\alpha_1}, \dots, \lambda_n^{\alpha_n})$ for $\alpha \in A$ are distinct and by computing the decomposition of the generating series as a polynomial-exponential series $\sum_{i=1}^{r'} \omega_i(\mathbf{y}) e_{\xi_i}(\mathbf{y})$ (Algorithm 4.2), we deduce the exponents $\alpha_i = (\log_{\lambda_1}(\xi_{i,1}), \dots, \log_{\lambda_n}(\xi_{i,n}))$ and the coefficients $h_{i,\beta}$ in the decomposition $h = \sum_{i=1}^{r'} \sum_{\beta \in B_i} h_{i,\beta} \mathbf{x}^{\alpha_i} \log^\beta(\mathbf{x})$ from the weight polynomials $\omega_i(\mathbf{y})$.

This method generalizes the sparse interpolation methods of [10], [68], [28], where a single operator $S : h(x_1, \dots, x_n) \mapsto h(\lambda_1 x_1, \dots, \lambda_n x_n)$ is used for some $\lambda_1, \dots, \lambda_n \in \mathbb{C}$ and where only polynomial functions are considered. The monomials \mathbf{x}^α ($\alpha \in \mathbb{N}^n$) are eigenfunctions of S for the eigenvalue $\boldsymbol{\lambda}^\alpha = \prod_{i=1}^n \lambda_i^{\alpha_i}$. For $h = \sum_{i=1}^r \omega_i \mathbf{x}^{\alpha_i}$, the corresponding univariate generating series σ_h defines an Hankel operator, whose kernel is generated by the polynomial $p(x) = \prod_{i=1}^r (x - \boldsymbol{\lambda}^{\alpha_i})$ when $\boldsymbol{\lambda}^{\alpha_1}, \dots, \boldsymbol{\lambda}^{\alpha_r}$ are distinct. If $\lambda_1, \dots, \lambda_n \in \mathbb{C}$ are chosen adequately (for instance distinct prime integers [10], [68] or roots of unity of different orders [28]), the roots of p yield the exponents of $h \in \mathbb{C}[\mathbf{x}]$.

The multivariate approach allows to use moments $h(\lambda_1^{\alpha_1}, \dots, \lambda_n^{\alpha_n})$ with $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$ of degree $|\alpha| = \alpha_1 + \dots + \alpha_n$ less than the degree $2r - 1$ needed in the previous sparse interpolation methods. Sums of products of polynomials and logarithm functions can also be recovered by this method, the logarithm terms corresponding to multiple roots.

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