



**HAL**  
open science

# Touchless intra-operative display for interventional radiologist

A Iannessi, P.-y Marcy, O Clatz, P Fillard, N Ayache

► **To cite this version:**

A Iannessi, P.-y Marcy, O Clatz, P Fillard, N Ayache. Touchless intra-operative display for interventional radiologist. *Diagnostic and Interventional Imaging*, 2014, 10.1016/j.diii.2013.09.007 . hal-01364021

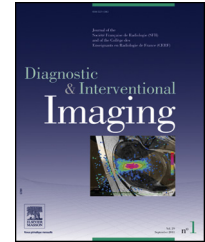
**HAL Id: hal-01364021**

**<https://inria.hal.science/hal-01364021v1>**

Submitted on 12 Sep 2016

**HAL** is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.



TECHNICAL NOTE / *Technical*

# Touchless intra-operative display for interventional radiologist



A. Iannessi<sup>a,\*</sup>, P.-Y. Marcy<sup>a</sup>, O. Clatz<sup>b</sup>, P. Fillard<sup>c</sup>,  
N. Ayache<sup>b</sup>

<sup>a</sup> *Department of Diagnostic Imaging and Interventional Radiology, Cancer Centre, Antoine Lacassagne Centre, 33, avenue de Valombrose, 06189 Nice cedex 2, France*

<sup>b</sup> *INRIA Sophia-Antipolis Méditerranée, Asclepios Groups, 2004, route des Lucioles, 06560 Sophia-Antipolis, France*

<sup>c</sup> *INRIA Saclay, Île-de-France, Équipe pariétal, Alan Turing Building, Polytechnic School Campus, 1, rue Honoré-d'Estienne-d'Orves, 91120 Palaiseau, France*

## KEYWORDS

User-computer interface;  
Gesture;  
CT-scan;  
Interventional radiology;  
Sterility

Imaging records are an essential part of the overall management of patients due to undergo invasive interventional radiology (IR) or surgery. Imaging is needed for diagnosis, to confirm operability, plan the procedure, and as a per-operative guide [1]. In both IR and surgery, it is essential to be able to visualise and manipulate images from the workstation [2,3]. Current solutions, including the use of the PACS in operating theatres, are completely inadequate. The practice has become routine in interventional CT and the main manufacturers offer dedicated equipment to work with the imaging instrument and images [4]. The interface which offers the most is the use of a joystick to move the cursor on the screen in the same way as the conventional mouse. Manipulation, however, is imprecise and makes it slow and frustrating to use. Telecommand is easier to use but does not allow complex interactions.

In reality, once the operator is under sterile conditions, working with pre- and per-operative imaging becomes extremely limited. In complex situations, it requires a third party (loading previous imaging, MR or PET-CT displays, multi-planar reformatting, zooming in onto an area of interest, etc.) sometimes leading to loss of concentration and loss of time [5].

\* Corresponding author.

E-mail address: [antoineiannessi@gmail.com](mailto:antoineiannessi@gmail.com) (A. Iannessi).

Ideally, we believe that the operator in theatre should have sterile access to the image visualisation and manipulation functionalities similar to those on his/her usual image processing console. In order to meet this need, control technologies inspired from video games (kinect<sup>®</sup>, Microsoft) now appear to be mature and suitable for sterile interventional medical use [6].

To confirm this hypothesis, we have developed a hand-recognition software, linked to an interventional CT, to manipulate images from the operator's sterile workstation.

The system includes a planning interface in the CT command workstation and an additional recall screen fitted with a movement sensor in the operating theatre (Fig. 1).

Feasibility tested on ten IR procedures was 100%, each enabling the imaging findings to be displayed and manipulated in the operating theatre. The system also allowed the desired information to be obtained without using the CT system interface or a third party, and without the loss of operator sterility.

## Discussion

The robustness of movement recognition systems now enables solutions with appropriate functionality for sterile IR settings. Technically, we experienced operator detection problems due to movements of the CT table and staff present in the intervention room. In order to minimise these, a sensor activation lock-out enables the operator to identify him/herself with a hand gesture to "unlock" the system. In addition, understanding feedback enables the operator to determine whether he/she has been correctly detected, by superimposing a green or red avatar on the screen as well as his/her hands on the image (Fig. 2). In addition, a few fine hand movement detection difficulties are directly due to the resolution limitations of the sensors, which we applaud but will need technical advances to bring in future solutions soon [7–9].

As there is a single system operator for all procedures, it was not possible to assess the learning curve and the extent to which a radiologist who has not previously used the interface adopts the system. "Operational" feasibility is therefore probably overestimated. During the laboratory design phase, however, we found that the system was very intuitive, mostly as a result of the choice of gestures derived from smartphones and explicit hand posture icons displayed on the screen (Fig. 1).

Overall compatibility with the situation in an IR room is good, as none of the procedures resulted in loss of operator sterility. Initially, the version designed in the laboratory responded to gestures on the operator's sides. Restricting the interaction area to the area in front of the user was probably a key factor in its feasibility.

Use of the system was compelling and there was no need to return to the previous system used. This included more complex procedures than biopsies (cementoplasty and alcoholisation) (Fig. 2). System control was robust and is therefore consistent with its use in more stressful and higher risk procedures.

The hand-recognition interface close to the patient in a sterile environment offers the operator the following advantages:

- increased independent, removing the "pollution" due to the third party (occasionally not of the same skill level);
- preservation of concentration (no orders to give and operator attention focused on the procedure) with no interference from a third party. Reduction of unnecessary stress;
- a gain in ergonomics, allowing the operator to move more quickly through images than with a joystick or telecommand;
- maintaining optimal sterility conditions, reducing the procedure time and risk of complications. The operator no longer needs to leave the sterile area for fine manipulation of the image, as he/she may have been used to doing [3,5,10];
- access to new functionalities: zooming in onto an area of interest, multi-planar reformatting, manual fenestration, navigating through the patient's past records with a simple searcher connected to the PACS enabling all modalities to be displayed.

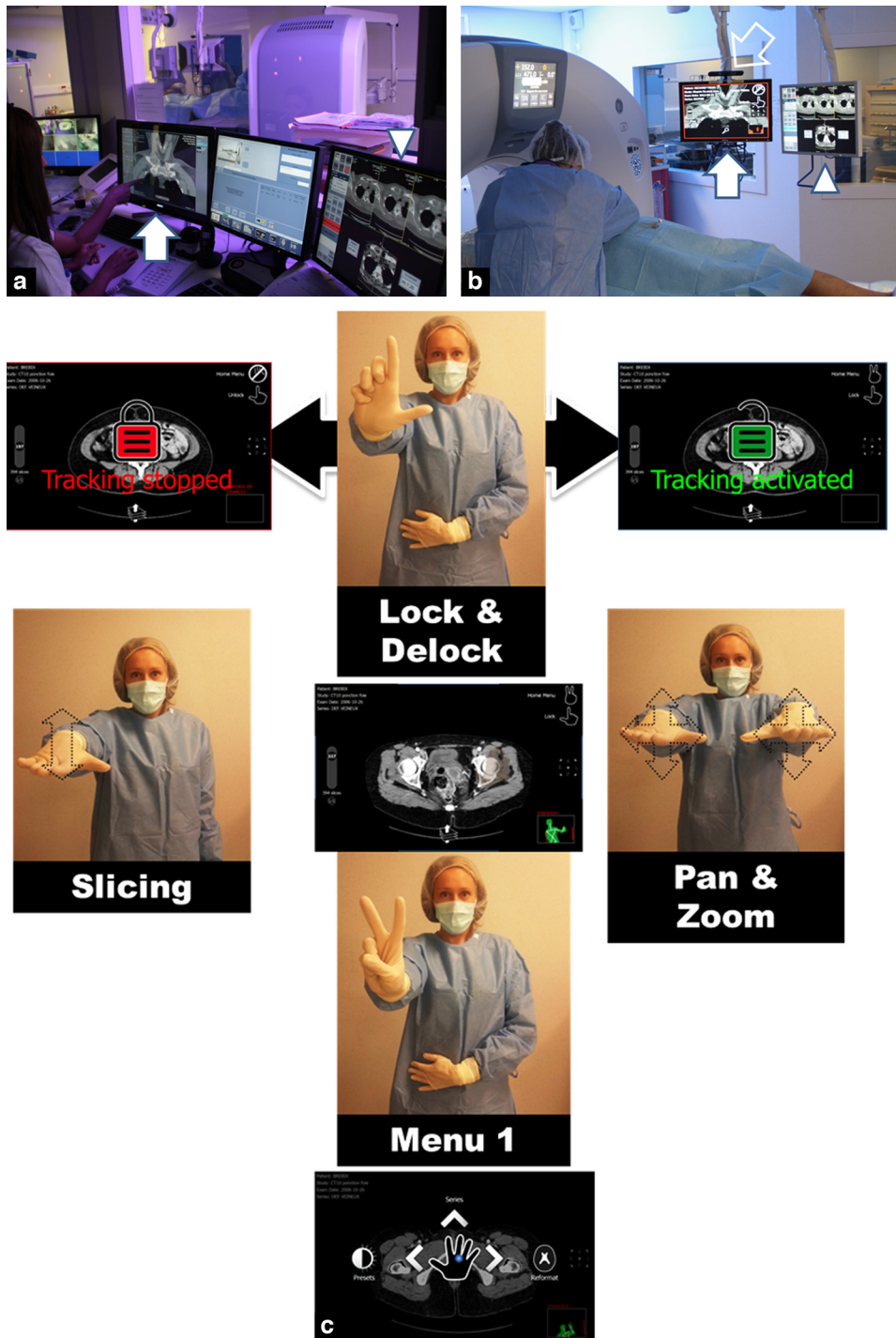
Overall, the system offers greater ergonomics, greater independent, improved concentration, better sterile conditions, reduced operating time, and new functionalities.

At the time of our assessment, a literature review only found two medical publications using a contactless interface to navigate through medical images. A "plug-in" developed for the OsiriX open-source software, has been tested in the laboratory to assess the effectiveness of manipulating using this device [10]. The authors showed that the manipulation time was 1.5 times greater than for the touchscreen interface (mouse) in order to carry out the same procedures and that the system requires a learning time.

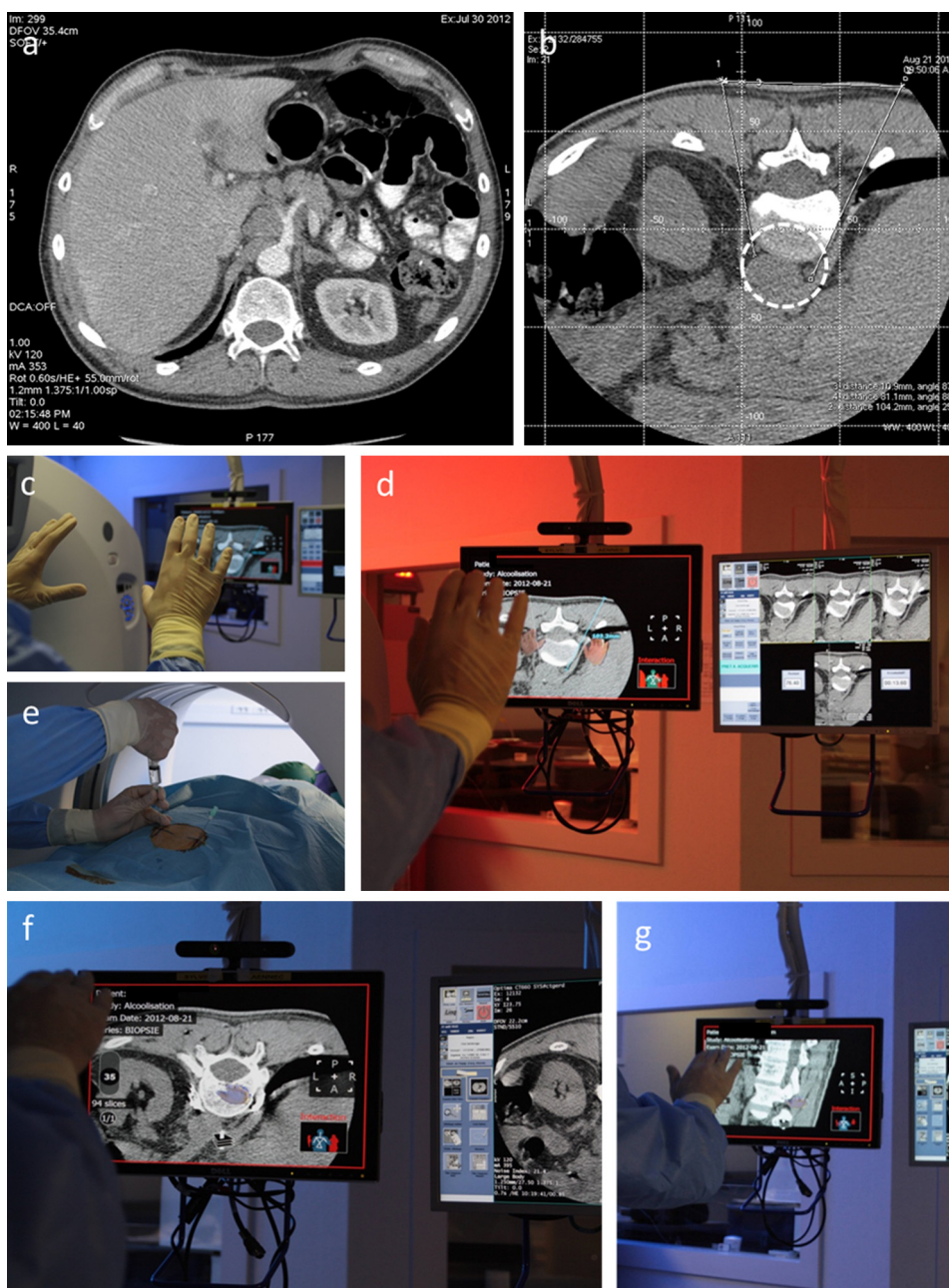
One surgical group has recently demonstrated the feasibility and medical utility of a contactless solution for partial kidney surgery and that the procedure time was reduced [11]. The same positive conclusions were also found mapping the mouse cursor to body movements, although this does not in our view seem to be the best solution to facilitate the interaction process.

As this is a new and as yet little used display, it does require a learning time. A hand or arm movement, however, is a more natural action than working with a mouse or keyboard. In order to become completely incorporated the display must become seamless in the environment of the operator, who is already concentrating fully on his/her hands. Gesture semantics is the key for adopting this system. The functionalities we are waiting for in software development which would enable further independence are distance measurement on an image and predicting volumes for heat ablation.

New technologies are continuing to revolutionise health. Camera and instrument miniaturisation has completely changed open surgery towards less invasive procedures such as laparoscopy. Procedures can be carried out with greater precision through robotisation [12]. Similarly, medical imaging is becoming a requirement to plan all invasive procedures in order to predict the risks of the procedure in advance. It can also be used to guide positioning of instruments



**Figure 1.** Installation of the system in an interventional CT room and operation. a: CT command room with manipulators; b: intervention room, arrowheads = display of images produced during the procedure by the CT duplicated in the intervention room, solid arrows = contactless interface with computer in the command room and full screen duplicated display in the intervention room, hollow arrow = gesture sensor; c: interface gesture semantics.



**Figure 2.** A case of splanchnic nerve alcoholisation using the gesture recognition system. Previous contrast enhanced-CT scan accessible in the room, allowing the vessels (a) to be seen unlike the planning CT with the patient lying on his/her front and without enhancement, target shown in dots (b). Zoom in into the area of interest in the intervention room (c-d). The operator works when he/she is recognised (green avatar at the bottom on the right) and when his/her hands are visible on the screen. Iodine injection through the needle to identify the track for the alcohol (e). Confirmation of repeat view in the intervention room with sagittal reformatting which is usually not accessible without a third party (f-g).

through ‘navigation’ in surgery or IR using imaging. In parallel with this, contactless displays offer the most natural and appropriate way for the user to work with the image under sterile conditions. It is already possible to install this type of system in an IR environment, and it provides a clear advantage over the existing offering. In more general terms, we expect to see this type of contactless solution increase in sterile situations as the precision of gesture detection increases. The gain in time, sterility, working

comfort and safety of the procedure which provides accessible, manipulable imaging independently and contactlessly, will undoubtedly be the driver for this increasing use.

### Disclosure of interest

The authors declare that they have no conflicts of interest concerning this article.

## References

- [1] Ratib O. Imaging informatics: from image management to image navigation. Yearbook of medical informatics; 2009. p. 167–72 [<http://www.ncbi.nlm.nih.gov/pubmed/19855892>].
- [2] Rosset A, Spadola L, Pysher L, Ratib O. Informatics in radiology (infoRAD): navigating the fifth dimension: innovative interface for multidimensional multimodality image navigation. *RadioGraphics* 2006;26(1):299–308.
- [3] Mentis HM, O'Hara K, Sellen A, Trivedi RL. Interaction proxemics and image use in neurosurgery. Austin, Texas, USA: Proceedings of the SIGCHI Conference on human factors in computing systems; 2012. p. 927–36, 2208536.
- [4] Haaga JR, Interventional CT: 30 years' experience. *Eur Radiol* 2005;15(Suppl. 4):D116–20.
- [5] Grätzel C, Fong T, Grange S, Baur C. A non-contact mouse for surgeon-computer interaction. *Technol Health Care* 2004;12(3):245–57.
- [6] Lange B, Chang CY, Suma E, Newman B, Rizzo AS, Bolas M. Development and evaluation of low cost game-based balance rehabilitation tool using the Microsoft Kinect sensor. Conference proceedings: Annual International Conference of the IEEE Engineering in Medicine and Biology Society IEEE Engineering in Medicine and Biology Society Conference, 2011; 2011. p. 1831–4 [<http://www.ncbi.nlm.nih.gov/pubmed/22254685>].
- [7] Watanabe M, Nayar SK. Rational filters for passive depth from defocus. *Int J Comput Vision* 1998;27(3):203–25.
- [8] Li Z, Curless B, Seitz SM. Rapid shape acquisition using color structured light and multi-pass dynamic programming. Proceedings of the First International Symposium on 3D Data Processing Visualization and Transmission; 2002. p. 24–36 [<http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.116.1059>].
- [9] Isard M, MacCormick J. Dense motion and disparity estimation via loopy belief propagation. Proceedings of the 7th Asian conference on Computer Vision-Volume Part II. Hyderabad, India: Springer-Verlag; 2006. p. 32–41, 2114657.
- [10] Ebert LC, Hatch G, Ampanozi G, Thali MJ, Ross S. You can't touch this: touch-free navigation through radiological images. *Surg Innov* 2012;19(3):301–7.
- [11] Ruppert GC, Reis LO, Amorim PH, de Moraes TF, da Silva JV. Touchless gesture user interface for interactive image visualization in urological surgery. *World J Urol* 2012;30(5):687–91.
- [12] Volonté F, Pugin F, Buchs NC, Spaltenstein J, Hagen M, Ratib O, et al. Console-integrated stereoscopic OsiriX 3D volume-rendered images for da Vinci colorectal robotic surgery. *Surg Innov* 2013;20(2):158–63.