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## Cuboid Partitioning for Parallel Matrix Multiplication on Heterogeneous Platforms

Olivier Beaumont, Lionel Eyraud-Dubois, and Thomas Lambert

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Abstract The problem of partitioning a square into zones of prescribed areas arises when partitioning matrices for dense linear algebra kernels onto a set of heterogeneous processors, and several approximation algorithms have been proposed for that problem. In this paper, we address the natural generalization of this problem in dimension 3: partition a cuboid in a set of zones of prescribed volumes (which represent the amount of computations to perform), while minimizing the surface of the boundaries between zones (which represent the data transfers involved). This problem naturally arises in the context of matrix multiplication, and can be seen as a heterogeneous generalization of 2.5D approaches that have been proposed in this context. The contributions of this paper are twofold. We prove the NP-completeness of the general problem, and we propose a  $\frac{5}{6^{2/3}} \simeq 1.51$ -approximation algorithm for cube-partitioning. This is the first known approximation result for this 3D partitioning problem.

#### 1 Introduction

In the context of Linear Algebra kernels and in the case of homogeneous processing resources, the way to partition data in order to both balance the load throughout the computation and to minimize communications is well understood. 2D block-cyclic distributions, for instance, have been introduced in Scalapack [11] in order to achieve this goal. More recently, the problem has received a lot of attention for Communication Avoiding algorithms design (see [15,1] and [21,3] for Matrix Multiplication specifically). In this context, the goal is to partition the set of computations to be performed into a minimal number of zones, each zone being able to be stored (both input and output data) in the memory. This corresponds to maximize the volume of computations that can be processed with a given amount of memory.

In this paper, we concentrate on Matrix Multiplication algorithm and more specifically on Matrix Multiplication algorithms that involve  $N^3$  elementary operations of type  $C_{i,j} \leftarrow C_{i,j} + A_{i,k}B_{k,j}$ , *i.e.* we ignore variants such as Strassen or Coppersmith-Winograd. Note that throughout the paper, we will assume that the matrices are partitioned into blocks, whose size is chosen so as to be well adapted to all types of resources (typically CPUs and GPUs). On the other hand, we consider a fully heterogeneous platform, where all nodes may have different processing capacities and we address the most general problem, where several partially aggregated copies of C can be used simultaneously in memory, such as in 2.5D algorithms [21]. In this context, the problem consists in partitioning the computational domain (the cube of  $N^3$  points) into sub-domains allocated to the different resources. In order to balance the load between the processing units, each unit should receive a volume of computations proportional to its processing speed and the overall amount of communications corresponds to the overall boundary area between the zones allocated to the resources.

Many algorithms [16,6,9,13,18,14] have been proposed in the context of dense matrix multiplication based on Canon's-like algorithm, that corresponds to the 2D version of the problem, *i.e.* how to partition a matrix into zones of fixed area while minimizing the overall length of the boundaries. On the other hand, to our best knowledge, this paper is the first to consider the complexity of the 3D version of the algorithm.

#### **Related Works**

The 2D version of this optimization problem has been first introduced by Lastovetsky and Kalinov in [16]. In [6], it has been proven that the problem is NP-Complete, and a first approximation algorithm with bounded ratio (1.75)has been proposed. This algorithm has been improved along two directions. On the one hand, Lastovetsky et al. have proposed to relax the assumption stating that the zones allocated to the processors should consist in a single rectangle and have proposed optimal algorithms, but limited to 2 processors [9] and more recently to 3 processors [13]. On the other hand, recursive partitioning algorithms have recently been proposed, in which at each step, the set of processors is split into two parts. Sophisticated proof techniques enabled Nagamochi and Abe [18] to improve the approximation ratio down to 1.25. Recently, Fügenschuh et al. [14] improved this result to 1.15, but under the assumption that if we consider processors in decreasing order of their processing speeds, there is no abrupt change in the performance between 2 successive processors. Unfortunately, such an abrupt decrease typically happens when considering nodes consisting of CPUs and GPUs, such that Fügenschuh's algorithm is limited to the case of relatively homogeneous platforms. In [8], an algorithm based on the idea of non rectangular partitioning proposed by Lastovetsky and extended to any number of processors by adapting the recursive partitioning algorithm proposed by Nagamochi has been proposed. It achieves an approximation ratio of  $\frac{2}{\sqrt{3}} \simeq 1.15$ , that does not require any specific assumption on the relative speed of resources and is therefore applicable to nodes consisting of both regular cores and accelerators.

This partitioning problem has been adapted to distributed hierarchical and highly heterogeneous platforms in [12], where the partitioning is applied at two levels (intra-node and inter-node), based on sophisticated performance models. The same partitioning has also been extended to finite-difference time-domain (FDTD) method to obtain numerical solutions of Maxwell's equations in [20]. The extension to more dynamic settings has also been considered in [17]. Recently, in order to cope with resource heterogeneity and the difficulty to build optimal schedules, the use of dynamic runtime schedulers have been proposed, such as StarPU [2], StarSs [19], or PaRSEC [10]. At runtime, the scheduler takes the scheduling and allocation decisions based on the set of ready tasks (tasks whose all data and control dependencies have been resolved), on the availability of the resources (estimated using expecting processing and communication times), and on the actual location of input data. The comparison between static scheduling strategies and runtime scheduling strategies has been considered in [7], where the analysis of the behavior of static, dynamic, and hybrid strategies highlights the benefits of introducing more static knowledge and allocation decisions in runtime libraries.

#### Paper Outline

The paper is organized as follows. In Section 2, we formally present the partitioning problem and the notations that will be used throughout the paper. In Section 3, the complexity of the associated decision problem in the 3D case is established and a  $\frac{5}{6^{2/3}} \simeq 1.51$ -approximation algorithm for cube-partitioning is proposed in Section 4. Conclusions and perspectives are given in Section 5.

### 2 General Context

**Definition 1.** Let P be a connected polyhedron of  $[0, x] \times [0, y] \times [0, z]$ . We define its covering cuboid as the smallest cuboid  $Cu(P) = [x_1, x_2] \times [y_1, y_2] \times [z_1, z_2]$  that includes P. We define also its width w(P) as  $x_2 - x_1$ , its height h(P) as  $y_2 - y_1$ and its length l(P) as  $z_2 - z_1$ . We also define Hs(P) = h(P)l(P) + w(P)l(P) +h(P)w(P),  $\rho(p) = \frac{max(h(P),w(P),l(P))}{min(h(P),w(P),l(P))}$  and  $\rho'(P) = \frac{max(h(P),w(P),l(P))}{med(h(P),w(P),l(P))}$ . Finally we define V(P) as the volume of P.

Problem 1 (Minimizing-Surface-Cuboid-Partition (MSCuboidP)). Given a set of n given numbers  $\{v_1, \ldots, v_n\}$  such that  $\sum v_k = xyz$ , and the cuboid  $Cu = [0, x] \times [0, y] \times [0, z]$ , find for each  $v_k$  a polyhedron  $P_k$  of Cu such that  $V(P_k) = v_k$ and  $\bigcup P_k = Cu$  minimizing  $\sum Hs(P_k)$ .

A general lower bound for this problem has been proposed by Ballard et al. [4] and comes from Loomis-Whitney inequality. It simply states that a polyhedron P of volume V(P) minimize the surface of its covering cuboid if and only if shape as a cube.

$$Hs(P) \ge 3V(P)^{\frac{2}{3}} \tag{1}$$

#### 3 NP-Completeness

We prove here the NP-completeness of the decision problem associated to MSCuboidP, MSCuboidP-DEC.

Problem 2 (MSCuboidP-DEC). Given a set of n given numbers  $\{v_1, \ldots, v_n\}$  such that  $\sum v_k = xyz$ , a cuboid  $Cu = [0, x] \times [0, y] \times [0, z]$  and a number K, is there a set of k polyhedra  $P_k$  of Cu such that  $V(P_k) = v_k$ ,  $\bigcup P_k = Cu$  and  $\sum Hs(P_k) \leq K$ .

We start by reducing this problem to a more constrained variant named ACCuboidP, in which the goal is to partition the cuboid in cubes of specified side lengths.

Problem 3 (All-Cube-Cuboid-Partition (ACCuboidP)). Given a set of p given lengths  $\{l_1, \ldots, l_p\}$  such that  $\sum l_k^3 = xyz$ , and a cuboid  $Cu = [0, x] \times [0, y] \times [0, z]$ , is there a set of k cubes  $C_k \in Cu$  such that  $V(C_k) = l_k^3$  and  $\bigcup C_k = Cu$ ?

Lemma 1. ACCuboidP is NP-Complete.

#### Proof of Lemma 1

It is easy to see that ACCuboidP belongs to NP.

We prove NP-hardess of ACCuboidP with a method inspired from the hardness proof of the equivalent 2D problem [5], by using a reduction from 2-PART-EQUAL, a variant of the well-known 2-PART problem. Our proof consists in two steps: from an instance of 2-PART-EQUAL, we first derive another set of numbers  $b_i$  and prove that they can be partitioned in two equal sets if and only if the 2-PART-EQUAL instance has a solution. Then, we use these  $b_i$  numbers to build an instance of ACCuboidP for which the existence of a packing is equivalent to partitioning the  $b_i$  in two equal sets.

Problem 4 (2-PART-EQUAL). Given a set of 2n integers  $\{a_1, \ldots, a_{2n}\}$  does there exist  $I \subseteq [1, n]$  such that |I| = n and

$$\sum_{i \in I} a_i = \sum_{i \notin I} a_i$$

**First Reduction** Let us now consider a instance of 2-PART-EQUAL,  $\{a_1, \ldots, a_{2n}\}$  and let us denote  $2A = \sum_{1 \le i \le 2n} a_i$  and  $M = 6n \times \max_i a_i$ . We suppose, without loss of generality, that n is a multiple of 120. Let us define a new set  $\{b_1, \ldots, b_{2n}\}$  as:

$$\forall i, \ b_i = a_i + 3n \times \max a_i + D$$

where

$$D = \frac{60M - (A \mod 60M)}{n}$$

In addition, we let us set  $k = \frac{n}{120} + \frac{A+nD}{60M}$  and  $S = \frac{1}{2} \sum_{1 \le i \le 2n} b_i$ . One can prove that k is an integer (since n is a multiple of 120) and that  $S = 60k \times M$ . In

addition, let us notice that for all  $i, \frac{M}{2} < b_i$  (because  $D \ge 0$  and  $a_i > 0$ ) and  $b_i \le M$ . Indeed  $D \le \frac{60M}{n} \le \frac{M}{4}$  and  $a_i + 3n \times \max_i a_i \le M(\frac{1}{2} + \frac{1}{6n}) \le \frac{4M}{6}$ . Therefore  $b_i \le \frac{11M}{12} \le M$ .

Let us prove now that there is a solution to our instance of 2-PART-EQUAL if and only if there exist a set  $I \subset [1, n]$  such that  $\sum_{i \in I} b_i = \sum_{i \notin I} b_i$ . If there exists Isuch that |I| = n and  $\sum_{i \in I} a_i = \sum_{i \notin I} a_i$ , then (with  $a_{max} = \max_i a_i$ )

$$\sum_{i \in I} b_i = \sum_{i \in I} a_i + \frac{n}{2} (3n \times a_{max} + D)$$
$$= \sum_{i \notin I} a_i + \frac{n}{2} (3n \times a_{max} + D)$$
$$= \sum_{i \notin I} b_i$$

We suppose now that there is I such that  $\sum_{i\in I} b_i = \sum_{i\notin I} b_i.$  Then:

$$\sum_{i \in I} b_i - \sum_{i \notin I} b_i = \sum_{i \in I} a_i - \sum_{i \notin I} a_i + (|I| - |\overline{I}|)(3n \times a_{max} + D)$$
$$\sum_{i \notin I} a_i - \sum_{i \in I} a_i = (|I| - |\overline{I}|)(3n \times a_{max} + D)$$

Yet,  $\sum_{i \notin I} a_i - \sum_{i \in I} a_i \le 2n \times a_{max}$  and  $3n \times a_{max} \le 3n \times a_{max} + D$ . Therefore:

$$\begin{aligned} (|I| - |\overline{I}|) & 3n \times a_{max} \le 2n \times a_{max} \\ (|I| - |\overline{I}|) \le \frac{2}{3} < 1. \end{aligned}$$

And thus  $|I| = |\overline{I}|$  and I is a solution to 2-PART-EQUAL.

**Second Reduction** In order to construct the ACCuboidP instance that we use for the reduction, we use the result from a work of Walters [22] which proves that it is possible to tile any cuboid with a number of cubes which is poly-logarithmic in the side lengths of the cuboid. We call the cubes in such tilings Walters' cubes, and we denote by WS(X, Y, Z) a set of cubes that can tile a cuboid  $X \times Y \times Z$ .

We now propose the following instance of ACCuboidP:

- A cuboid of size  $11M \times 45M \times S$  (with  $S = 60k \times M$ ).
- -20k cubes of length 6M.
- -24k cubes of length 5M.
- -30k cubes of length 4M.
- -20k cubes of length 3M.
- $\forall i, a cube of length b_i.$

 $- \forall i, WS(M - b_i, b_i, b_i) \text{ and } WS(M, M - b_i, b_i).$ 

One can see that the reduction is polynomial, since the sizes of the Walters' cubes sets are poly-logarithmic functions of the  $b_i$ s.

In the first part of the proof, let us show that if we can split the  $b_i$  items in two equal sets, then these cubes can be packed in the cuboid.



Figure 1: Tiling of a  $b_i \times M \times M$  cuboid.

We first consider, for each *i*, the cube of length  $b_i$  and the three corresponding Walters' cubes sets. Figure 1 shows that they can be packed in a cuboid of size  $M \times M \times b_i$ , where the cuboid of size  $(M - b_i) \times b_i \times b_i$  and the cuboid of size  $(M - b_i) \times b_i \times M$  are tiled with the cubes from  $WS(M - b_i, b_i, b_i)$  and  $WS(M, M - b_i, b_i)$ . By piling such cuboids on top of one another, we can build two  $M \times M \times S$  cuboids from the two sets I and  $\overline{I}$ , see Figure 2.



Figure 2

Figure 3 shows how to tile a  $11M \times 15M$  rectangle with the corresponding squares, where the two  $M \times M$  squares represent a slice of the two  $M \times M \times S$ 



Figure 3: Tiling of a  $11M \times 15M$  rectangle.

cuboids presented above. This disposition can be repeated for a total length of S, since

$$10k \times 6M = 12k \times 5M = 15k \times 4M = 20k \times 3M = 60K \times M = S.$$

Hence, this provides a tiling of the whole  $11M \times 15M \times S$  cuboid.

For the second part of the proof, we want to prove if the cuboid can be tiled with the given cubes, then a partition of the  $b_i$  values in two equal sets exists. We start by proving that in any valid tiling of the cuboid, the  $11M \times 15M$  rectangle can only be tiled as shown on Figure 3 (or under the same pattern but with an horizontal symmetry).

Let us note that, except the  $b_i$ -cubes and the Walters' cubes, all cubes have length that are multiple of M. Therefore one can see that the resulting projections of the  $b_i$ -cubes and the Walters' cubes on the  $11M \times 15M$  rectangle can be seen as several  $M \times M$  squares.

Let us consider any valid tiling of the cuboid, and analyze the disposition of the 3M-cubes,  $b_i$ -cubes and Walters' cubes. Their total volume is  $27M^3 \times 20k + 120M^3 \times k = 660M^3 \times k$ . On average over all the S slices of the cuboid, this represents a surface of  $\frac{660M^3 \times k}{S} = 11M^2$ . We now prove that it is actually impossible to tile this  $11M \times 15M$  face with less than  $11M^2$  surface coming from these cubes.

Let s be the surface coming from these cubes divided by  $M^2$ ,  $s \in [0, 10]$ . Let  $p_6$ , respectively  $p_5$  and  $p_4$ , the number or 6M-cubes, respectively 5M-cubes and 4M-cubes, used to tile the  $11M \times 15M$ -face. We have computed the possible values such that  $(15 \times 11 - s)M^2 = (36p_6 + 25p_5 + 16p_4)M^2$ , they can be found in Table 1. We now consider each case one by one.

**Case (1)** s = 0,  $p_6 = 3$ ,  $p_5 = 1$ ,  $p_4 = 2$ : 11 and 15 are odd, therefore there must be a least one fraction of an odd square in every line or column (we can see

Case	s	$p_6$	$p_5$	$p_4$	Case	s	$p_6$	$p_5$	$p_4$
(1)	0	3	1	2		5			
(2)	1	0	4	4	(8)	6	1	3	3
(3)		1	0	8	(9)	7	3	2	0
(4)	2	2	3	1	(10)	8	0	5	2
(5)	3	0	2	7	(11)		1	1	6
(6)	4	1	5	0	(12)	9	3	0	3
(7)		2	1	4	(13)	10	0	3	5

Table 1: Possible values of  $p_6$ ,  $p_5$  and  $p_4$  as a function of s.

the rectangle as a grid  $11 \times 15$ ). The odd cubes are the 5*M*-cubes, the 3*M*-cubes and the ones we can produces with  $b_i$ -cubes and Walters' cubes. Since we have only one 5*M*-cube, the total length of odd squares is less than 15, so we cannot have one fraction of an odd square in every column. Therefore the tiling in this case is not possible.

**Case (2)** s = 1,  $p_6 = 0$ ,  $p_5 = 4$ ,  $p_4 = 4$ : As  $5 \times 4 > 15$ , we cannot have more than three 5-squares in a line and therefore, with four 5-squares, we have to be in one of the dispositions shown in Figure 4(a) and Figure 4(b). In both cases, there exist at least two columns where two 5-squares are superposed (denoted  $d_i$  in the figures). However, the only way to complete these columns to a height of 11 is to use a square of size 1, and we have only one *M*-square since s = 1. Therefore the tiling in this case is not possible.



Figure 4: Tiling in cases (2), (4) and (9).

**Case (3)** s = 1,  $p_6 = 2$ ,  $p_5 = 0$ ,  $p_4 = 8$ : By a parity argument similar to the one used in Case (1), we can prove the impossibility of the tiling.

**Case (4)** s = 2,  $p_6 = 2$ ,  $p_5 = 3$ ,  $p_4 = 1$ : It is easy to see that the 6-squares and the 5-squares can only be tiled in a way similar to Figure 4(c). Therefore there is no room to place the 4-square and the tiling is impossible in this case.

**Case (5)** s = 3,  $p_6 = 0$ ,  $p_5 = 2$ ,  $p_4 = 7$ : By a parity argument similar to the one used in Case (1), we can prove the impossibility of the tiling.

**Case (6)** s = 4,  $p_6 = 1$ ,  $p_5 = 5$ ,  $p_4 = 0$ : By reasoning on the number of 5-squares in a similar fashion than in Case (2), we can prove the impossibility of the tiling.

**Case (7)** s = 4,  $p_6 = 2$ ,  $p_5 = 1$ ,  $p_4 = 4$ : By a parity argument similar to the one used in Case (1), we can prove the impossibility of the tiling.

**Case (8)** s = 6,  $p_6 = 1$ ,  $p_5 = 3$ ,  $p_4 = 3$ : Since 5 + 5 + 6 > 15, we cannot have two 5-squares and one 6-square appearing on the same line. Then we have only two choices to tiles these squares. The first is shown on Figure 5(a). In this case there is a rectangle of size  $9M \times 6M$  that can be proved impossible to tile with six *M*-square and three 4M-squares. Therefore we have to be in the case of Figure 5(c), where the dashed zone does not intersect the last 5M-square (otherwise we are in the case in Figure 5(b) that is strictly harder to tile than the case of Figure 5(a)). Therefore the dashed zone, a square of size  $5M \times 5M$ has to be tiled with only fractions of 4M-squares and *M*-squares. In order to fill the gap of size 5M the only way to begin is the one shown in Figure 5(d). To complete the last column, we have to fill the 7M-gap, and  $7 = 5 + 2 \times 1$  is the only possibility (there are only two *M*-squares remaining). This yields the situation shown in Figure 5(e), and one can see that the tiling can not be finished with the remaining 4M-squares: the tiling is impossible in this case.



Figure 5: Tiling in case (8).

**Case (9)** s = 7,  $p_6 = 3$ ,  $p_5 = 2$ ,  $p_4 = 0$ : It is impossible to have three 6M-squares. Indeed  $2 \times 6 > 11$  and then we cannot have two 6M-squares appearing on the same column. In the same time,  $3 \times 6 > 15$  and then we cannot have three 6M-squares appearing on the same line (see Figure 4(d) to have a better visualization). Hence there is no room to store three 6M-squares, and the tiling in this case is not possible.

**Case (10)** s = 8,  $p_6 = 0$ ,  $p_5 = 5$ ,  $p_4 = 2$ : By reasoning on the number of 5-squares in a similar fashion than in Case (2), we can prove the impossibility of the tiling.

**Case (11)** s = 8,  $p_6 = 1$ ,  $p_5 = 1$ ,  $p_4 = 2$ : By a parity argument similar to the one used in Case (1), we can prove the impossibility of the tiling.

**Case (12)** s = 9,  $p_6 = 3$ ,  $p_5 = 0$ ,  $p_4 = 3$ : By a parity argument similar to the one used in Case (1), we can prove the impossibility of the tiling.

**Case (13)**  $s = 10, p_6 = 0, p_5 = 3, p_4 = 5$ : We consider two sub-cases: either we have one 3M-rectangle and one M-rectangle, or we have ten M-rectangles. In the first case we notice that with the available rectangles there are only two ways to achieve a exact length of 11M: 1M + 5M + 5M and 3M + 4M + 4M. Both options create gaps that cannot be filled with the remaining rectangles, see Figure 6(a). In the second case (ten M square and no 3M-square), there are more options to achieve a length of 11M. The first one is to use two 4M-square and three M-square. This creates a  $3M \times 4M$  gap, and there are too few M-squares to fill it, see Figure 6(b), therefore we cannot tile this way. The second option is to use two 5M-squares and one M-square. In this case we have to use four more M-squares to complete and then we have again a length 11M to achieve, that, with the remaining resources, can only be done either with two 4M-squares and three M-squares, and we have proven above that it is not feasible, or with a 4M-square, a 5M-square and two M-squares, but in this case we cannot tile the resulting  $2M \times 3M$  rectangle because we have too few *M*-squares, see Figure 6(c). Another option is to use a 4M-square and seven M-squares, but this results in a gap of length 7M to fill and one can see that is not possible, see Figure 6(d) (replacing the 5M-square of the figure by a 4M-square yields the same problem). Another possibility is to use a 5M-square and six M-squares, for which the only reasonable continuation is the case shown on Figure 6(e) and this creates a gap of length 6M which cannot be tiled with the remaining squares. The last option is to use a 5*M*-square, a 4*M*-square and two *M*-squares but the tiling is still impossible, as it is shown on Figure 6(f). Therefore, in any sub-case, the tiling is impossible in this case.



Figure 6: Tiling in case (13).

This proves that at every slice of the main cuboid, the surface coming from the 3M-cubes, the  $b_i$ -cubes and the Walters' cubes is at least  $11M^2$ . Since this is

exactly the average value, this implies that this surface is exactly  $11M^2$  at each slice. We can now observe that this requires at least two *M*-squares in any slice and once again this is exactly the average value of *M*-squares. Therefore, in any slice, there are exactly two *M*-squares and one 3M-square. The argument used to create Table 1 now shows that the slice necessarily includes two 6M-squares, two 5M-squares and two 4M-squares, and one can prove that the only way to tile the  $11M \times 15M$  rectangle with these squares is as shown on Figure 3.

We now have a pattern that has to be present on each slice of the cuboid, in which the  $b_i$  cubes have to be included in two separate parts of the tiling. Denote by I the indices of the  $b_i$  cubes which appear in the leftmost  $M \times M \times S$ cuboid. Since by construction,  $b_i > \frac{M}{2}$  for all i, these cubes have to be stored as on Figure 2. This shows that  $\sum_{i \in I} b_i \leq S$  and  $\sum_{i \notin I} b_i \leq S$ . Since the total sum is 2S, this implies that both sums are equal to S, and thus that there exists a solution to the original 2-PART-EQUAL instance.

Note that the pattern in Figure 3 can be horizontally reversed. Furthermore, both possibles patterns can be present on the final tiling. However, even in this case, consider the  $b_i$ -cubes on the left side still yields a set I such that  $\sum_{i \in I} b_i = \sum_{i \notin I} b_i = S$ .

#### **Theorem 1.** MSCuboidP-DEC is NP-complete.

*Proof.* There is a reduction from ACCuboidP to MSCuboidP-DEC. Indeed,  $ACCuboidP(\{l_1, \ldots, l_p\}, [0, x] \times [0, y] \times [0, z])$  is true is equivalent to  $MSCuboidP-DEC(\{l_1^3, \ldots, l_p^3\}, [0, x] \times [0, y] \times [0, z], 3 \sum v_k^{2/3})$  is true (the bound in (1) is reach if and only if there exist a partitioning where only cubes are used). Yet, thank to Lemma 1, we know that ACCuboidP is NP-complete. Therefore MSCuboidP-DEC is NP-complete.

#### 4 Approximation Algorithm

In this Section, we present 3D-NRRP, an approximation algorithm for the case where the cuboid to partition is cubic (this corresponds to the multiplication of square matrices). It is inspired by the NRRP algorithm proposed in [8] for the 2D-case, itself inspired by the one proposed by Nagamochi et al. [18].

#### 4.1 Presentation and correctness of 3D-NRRP

The basic principle of 3D-NRRP (see Algorithm 1) is divide and conquer, and the analysis relies on the following invariant: at each step, the aspect ratio of the current cuboid to be partitioned is below 3. In all what follows, we define the aspect ratio  $\rho$  of a cuboid as the ratio of the greatest length to the smallest length. We also define the second aspect ratio  $\rho'$  as the ratio of the greatest length to the median length.

#### Algorithm 1: 3D-NRRP

**Input**: A set of given volume  $\{v_1, \ldots, v_n\}$  sorted in non-decreasing order, a cuboid  $Cu = [a, b] \times [c, d] \times [e, f]$  with  $(b - a) \times (d - c) \times (f - e) = \sum_{i=1}^{n} v_i$ **Output**: For each  $1 \leq i \leq n$  a polyhedron  $P_i$  such that  $\bigcup P_i = Cu$  and  $V(P_i) = v_i$ 1 if n = 1 then  $\mathbf{2}$ return Cu3 else  $v = \sum_{i=1}^{n} v_i ;$  w = b - a ; h = d - c ; l = f - e ;  $\rho_1 = \frac{max(w,h,l)}{min(w,h,l)} ; \rho_2 = \frac{max(w,h,l)}{med(w,h,l)} ;$ if there exists k such that  $\sum_{i=1}^{k-1} v_i \ge \frac{v}{3\rho_2} \text{ then}$  $\mathbf{4}$  $\mathbf{5}$ 6 7  $k={\rm the}\ {\rm smallest}\ {\rm such}\ k$  ; 8  $v' = \sum_{i=1}^{k-1} v_i$ ; if w = max(w, h, l) then 9 10  $Cu_1 = [a, a + v'/(h * l)] \times [c, d] \times [e, f];$ 11  $Cu_2 = [a + v'/(h * l), b] \times [c, d] \times [e, f]$ 12else 13 if h = max(w, h, l) then 14  $Cu_1 = [a, b] \times [c, c + s'/(w * l)] \times [e, f];$   $Cu_2 = [a, b] \times [c + s'/(w * l), d] \times [e, f]$ 15else 16  $Cu_1 = [a, n] \times [c, d] \times [e, e + v'/(w * h)];$   $Cu_2 = [a, b] \times [c, d] \times [e + v'/(w * h), f]$  $\mathbf{17}$ return 3D-NRRP( $\{v_1, ..., v_{k-1}\}, Cu_1$ ) + 3D-NRRP( $\{v_k, ..., v_n\}, Cu_2$ );  $\mathbf{18}$ 19 else  $v' = \sum_{i=1}^{n-1} v_i \; ; \qquad$  $\mathbf{20}$  $Cu_1 = [a, a + \sqrt[3]{v'}] \times [c, c + \sqrt[3]{v'}] \times [e, e + \sqrt[3]{v'}];$ 21 **return 3D-NRRP** $(\{v_1, ..., v_{k-1}\}, Cu_1) + (Cu \setminus Cu_1)$ 22

At each step of the algorithm, the current cuboid (whose aspect ratio is below 3) is split in two parts, then the same routine is recursively applied to each part. To ensure that the resulting parts have an aspect ratio below 3, the splitting has two modes. The first mode is the general case, in which the cuboid is partitioned in two disjoint cuboids by cutting along the greatest length (Lines 7 to 18 in Algorithm 1, and Figure 7(a)). This is possible if there exists k such that  $\sum_{i=1}^{k-1} v_i \geq \frac{v}{3\rho_2}$ . Indeed, Lemmas 2 and 3 show that this condition is sufficient to prove the invariant for both parts. More specifically, Lemma 2 states that in that case, both resulting cuboids have a total volume greater than a third of the

total volume, and Lemma 3 states that the aspect ratio of both cuboids is below 3, under the assumption that the previous one had also a ratio less than 3. and then ensure the correctness of the algorithm.

In the second mode, one of the  $v_i$ s is significantly larger than the other ones. Splitting in two cuboids would result in the smallest cuboid having an aspect ratio below 3. Therefore it is shaped as a cube, included in the covering cuboid of the other part, which only contains one element (Lines 20 to 22 of Algorithm 1, and Figure 7(b)).



Figure 7: The two splitting modes of 3D-NRRP.

**Lemma 2.** Let  $\{v_1, \ldots, v_n\}$  be a set of positive values sorted in non-decreasing order,  $\rho \ge 1$ , and  $v = \sum_i v_i$ . Assume that there exists k such that  $\sum_{i=1}^{k-1} v_i \ge v/3\rho$ , and consider the smallest such integer. Then  $\sum_{i=k}^n v_i \ge v/3\rho$ .

*Proof.* By definition of k,  $\sum_{i=1}^{k-2} v_i < v/3\rho$ . Therefore, if we suppose that  $\sum_{i=k}^n v_i < v/3\rho$ , we obtain  $v_{k-1} = v - \sum_{i=1}^{k-2} v_i - \sum_{i=k}^n v_i \ge v/3\rho$  (because  $\rho \ge 1$ ). Since  $v_k \le \sum_{i=k}^n v_i < v/3\rho$ , we have  $v_{k-1} > v_k$  which is a contradiction with the fact that the  $v_i$ s are sorted in non-decreasing order.

**Lemma 3.** Let Cu be a cuboid of dimension  $w \times h \times l$ , with volume V = hwl, aspect ratio  $\rho$ , and second aspect ratio  $\rho'$ . Assume we obtain  $Cu_1$  and  $Cu_2$  by within Cu along the gradient length with V(Cu) and V(Cu) not employed then

cutting Cu along the greatest length, with  $V(Cu_1)$  and  $V(Cu_2)$  not smaller than  $\frac{V}{3\rho'}$ . Then  $\rho(Cu_1) \leq max(3,\rho)$  and  $\rho(Cu_2) \leq max(3,\rho)$ .

*Proof.* We suppose that  $w \leq h \leq l$  without loss of generality. In this case,  $w = w(Cu_1) = w(Cu_2)$ ,  $h = h(Cu_1) = h(Cu_2)$ ,  $\rho = l/w$  and  $\rho' = l/h$ . We denote  $l_1 = l(Cu_1)$  and  $l_2 = l(Cu_2)$ . We consider cuboid  $Cu_1$ , and distinguish three cases:

- If  $h \leq l_1$ , then  $\rho(Cu_1) = l_1/w \leq l/w = \rho$ .
- If  $w \leq l_1 \leq h$ , then  $\rho(Cu_1) = h/w \leq l/w \leq \rho$ . If  $l_1 \leq w \leq h$ , by assumption  $w \times h \times l_1 = V(Cu_1) \geq \frac{V}{3\rho'} = \frac{w \times h \times l}{3\rho'}$ . Therefore  $l_1 \ge l/3\rho'$ . Then,  $\rho(Cu_1) = h/l_1 \le \frac{3h\rho'}{l} = 3$ .

So in any case  $\rho(Cu_1) \leq max(3,\rho)$ . By symmetry, the same proof applies to  $Cu_2$ .

#### 4.2**Approximation Ratio**

This Section is devoted to proving Theorem 2, which states the  $\frac{5}{6^{2/3}}$  approximation factor of 3D-NRRP  $\left(\frac{5}{6^{2/3}} \simeq 1.51\right)$ .

**Theorem 2.** 3D-NRRP is a  $\frac{5}{6^{2/3}}$ -approximation of our problem.

This proof relies extensively on the following lemmas.

**Lemma 4.** Let  $(\{v_1, \ldots, v_n\}, Cu)$  be a instance of MSCuboidP. Then for any valid solution  $\{P_1, \ldots, P_n\}$  of this instance,

$$\sum_{i=1}^{n} Hs(P_i) \ge 3\sum_{i=1}^{n} v_i^{\frac{2}{3}}.$$

*Proof.* This result is a direct consequence of Equation (1), which states that the property is valid term by term. This lower bound is used to prove the approximation ratio in Theorem 2

**Lemma 5.** Let A, B, C and D denote 4 real numbers such that  $\frac{A}{B} \leq \alpha$  and  $\frac{C}{D} \leq \alpha$ , then  $\frac{A+C}{B+D} \leq \alpha$ .

We omit the proof of this textbook lemma. It plays a crucial role in the following proof.

The sketch of the proof is the following: if  $\{P_1, \ldots, P_n\}$  is an output of 3D-NRRP, we prove for all  $P_i$  that  $\frac{H_s(P_i)}{3V(P_i)^{\frac{2}{3}}} \leq \frac{5}{6^{\frac{2}{3}}}$  and then, Lemmas 4 and 5 complete the proof of Theorem 2.

One can see that there are only two situations in which 3D-NRRP returns a singleton: Line 2 and Line 22. In the first case, the returned zone is a cuboid with aspect ratio less than 3. In this case Lemma 7 provides the desired result, since  $\frac{5}{3\sqrt[3]{3}} \leq \frac{5}{c^2}$ . We first start with a technical result in Lemma 6.

**Lemma 6.** Let  $f(x, y) = \frac{y + x(1+y)}{3(xy)^{2/3}}$ . Then, with  $x \in [1, y]$  and  $y \in [1, 3]$ ,  $f(x, y) \leq 1$  $\frac{5}{3\sqrt[3]{3}}$ .

Proof. One can show that  $\frac{\partial f}{\partial x}(x,y) = \frac{2x-1-y}{9y^{1/3}x^{4/3}}$ . Since  $x \ge 0$  and  $y \ge 0$ ,  $\frac{\partial f}{\partial x}(x,y) \ge 0$  if and only if  $x \le \frac{1+y}{2}$ . Hence,  $x \mapsto f(x,y)$  is decreasing on  $[1, \frac{1+y}{2}]$  and increasing in  $[\frac{1+y}{2}, y]$ , which implies  $f(x,y) \le \max(f(1,y), f(y,y))$ .  $f(1,y) = \frac{y+2}{3\frac{\sqrt{y}}{\sqrt{y}}}$  and  $f(y,y) = \frac{2y+1}{3y^{2/3}}$ . From  $y \ge 1$ , one can obtain  $(y+2)\sqrt[3]{y} \ge \frac{y+2}{\sqrt{y}}$ .

 $f(1,y) = \frac{y+2}{3\sqrt[3]{y}}$  and  $f(y,y) = \frac{2y+1}{3y^{2/3}}$ . From  $y \ge 1$ , one can obtain  $(y+2)\sqrt[3]{y} \ge 2y+1$ , and this implies  $\frac{y+2}{3\sqrt[3]{y}} \ge \frac{2y+1}{3y^{2/3}}$ . Let us denote  $g(y) = \frac{y+2}{3\sqrt[3]{y}}$ : the previous statements show that  $f(x,y) \le g(y)$ . One can prove that  $g'(y) = \frac{2(y-1)}{9y^{4/3}}$ . Therefore g is increasing on  $[1,\infty]$  and, in the considered case,  $g(y) \le g(3) = \frac{5}{3\sqrt[3]{y}}$ , which proves the desired result.

**Lemma 7.** If P is a cuboid with  $\rho(P) \leq 3$ , then  $\frac{Hs(P)}{3V(P)^{2/3}} \leq \frac{5}{3\sqrt[3]{3/3}}$ .

*Proof.* We denote  $\rho(P) = \rho$  and V(P) = V. We suppose that  $w = w(P) \le h = h(P) \le l(P) = l$  without loss of generality. We denote x = h/w. In this case  $l = \rho w$  and  $V = whl = \rho xh^3$ . Therefore

$$\frac{Hs(P)}{3V^{2/3}} = \frac{(x+\rho+x\rho)w^2}{3(\rho x w^3)^{2/3}} = \frac{\rho+x(1+\rho)}{3(\rho x)^{2/3}} = f(x,\rho)$$

where f is as defined in Lemma 6, which provides the conclusion.

In the other case, 3D-NRRP returns a cuboid minus a cube (Line 22 of Algorithm 1, as described on Figure 7(b)). The bound on the volume of the cube allows to satisfy the conditions of Lemma 9. As before, we start with proving the more technical Lemma 8.

**Lemma 8.** Let  $f(x,y) = \frac{y+x(1+y)}{3(xy-\frac{x^2}{3})^{2/3}}$ . Then, with  $x \in [1,y]$  and  $y \in [1,3]$ ,  $f(x,y) \leq \frac{5}{6^{2/3}}$ .

*Proof.* One can prove that  $\frac{\partial f}{\partial x}(x,y) = \frac{\frac{1+y}{3}x^2 + (\frac{7}{3}+y)yx - 2y^2}{9(yx - \frac{x^2}{3})^{5/3}}$ . Then  $\frac{\partial f}{\partial x}$  has the same sign than  $P_y(x) = \frac{1+y}{3}x^2 + (\frac{7}{3}+y)yx - 2y^2$ . Since  $P_y$  is a second order polynomial with  $P_y(0) = -2y^2 < 0$  and  $\lim_{x \to +\infty} p_y(x) = +\infty$ ,  $P_y$  is either positive on [1, y], negative on [1, y], or negative and then positive. Therefore  $x \mapsto f(x, y)$  on [1, y] is either increasing, decreasing or decreasing and then increasing. In any case,  $f(x, y) \leq max(f(1, y), f(y, y))$ .

Let  $g(y) = f(1, y) = \frac{1+2y}{3(y-1/3)^{2/3}}$ . One can show that  $g'(y) = \frac{2(y-2)}{9(y-1/3)^{5/3}}$ , hence g is decreasing on [1, 2] and increasing on [2, 3]. Therefore  $g(y) \le max(g(1), g(3)) = max((\frac{3}{2})^{2/3}, \frac{7}{4\sqrt[3]{3}}) = (\frac{3}{2})^{2/3}$ .

Let  $h(y) = f(y, y) = \frac{2+y}{\sqrt[3]{12y^2}}$ . One can show that  $h'(y) = \frac{2(y-1)}{\sqrt[3]{12y^2}}$ , hence h is

increasing on [1,3]. Therefore  $h(y) \le h(3) = \frac{5}{6^{2/3}}$ . Putting it all together, we get  $f(x,y) \le max((\frac{3}{2})^{2/3}, \frac{5}{6^{2/3}}) = \frac{5}{6^{2/3}}$ .

**Lemma 9.** If  $V(P) \ge (1 - \frac{1}{3\rho'(P)})V(Cu(P))$  and  $\rho(P) \le 3$ , then  $\frac{Hs(S)}{3V(S)^{2/3}} \le \frac{5}{6^{2/3}}$ .

*Proof.* We denote  $\rho = \rho(P)$ ,  $\rho' = \rho'(P)$ , V = V(P), and we use w, g, l for the dimensions of Cu(P). We suppose that  $w \leq h \leq l$  without loss of generality. Then  $l = \rho w$  and  $l = \rho' h$ , and we also denote  $x = h/w = \rho/\rho'$ . With such notations, we get  $V(Cu(P)) = \rho x w^3$  and  $Hs(P) = (\rho x (1 + \rho)) w^2$ . We can then write the condition on V(P) as

$$V(P) \ge (1 - \frac{1}{3\rho'(P)})Cu(P) = (1 - \frac{h}{x\rho})\rho x w^3 = (\rho x - \frac{x^2}{3})w^3.$$

This yields

$$\frac{Hs(P)}{3V(P)^{2/3}} \le \frac{(\rho x(1+\rho))w^2}{3(\rho x - \frac{x^2}{3})^{2/3}w^2} = \frac{\rho + x(1+\rho)}{3(\rho x - \frac{x^2}{3})^{2/3}} = f(x,\rho),$$

where f is as defined in Lemma 8, which provides the conclusion.

#### 5 Conclusion

In this paper we introduce a modeling of the 2.5D matrix multiplication algorithm on heterogeneous processors, a problem of crucial importance in high performance computing. We propose here to see this operation as the splitting of a cuboid in several polyhedra, each representing the set of computations that are attributed to a processor. We provide two theoretical results: a proof of the NPcompleteness of this problem, and an approximation result for 3D-NRRP, which generalizes the 2D case. This is the first known approximation result for this problem, and provides a strong guarantee  $(\frac{5}{6^{2/3}} \simeq 1.51)$ . In addition, the computation time of the algorithm is quite low,  $O(n \log n)$ , where *n* is the number of processors. This work opens some interesting questions: on the theoretical side, one might wonder if this approximation result can be generalized to the *n* dimension case (which would represent tensor multiplication); on the practical side, this work also calls for the implementation and evaluation of the partitionings provided by 3D-NRRP on a real CPU and GPU system.

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