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Variational problems on product spaces Different obstacle constraints

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Abstract

We study two principle minimizing problems, subject of different constraints. Our open sets are assumed bounded, except mentioning otherwise; precisely $\Omega =]0,1[^n \in \mathbb{R}^n, n=1 \text{ or } n=2.$

Keywords: Variational problem, Optimization, Convexity, Euler Lagrange, Sobolev spaces, Weak topology.

1 Introduction

Theorem 1.1 (Rellich-Kondrachov theorem). Suppose Ω is bounded and of class C^1 then, $W^{1,p} \subset L^p$ with compact injection for all p (and all n).

Let $p \ge 2$ and $W^{1,p}(]0,1[;\mathbb{R}^2) = \{u = (u_1,u_2); u_1 \in W^{1,p}(]0,1[;\mathbb{R}), u_2 \in W^{1,p}(]0,1[;\mathbb{R})\}$

Define the functionals

1.
$$W^{1,p}(]0,1[;\mathbb{R}^2) \to \mathbb{R}_+$$

 $u \to F(u) = \int_0^1 |u'(x)|_2^p = \int_0^1 \left(|u_1'(x)|^2 + |u_2'(x)|^2 \right)^{\frac{p}{2}}$

2.
$$W_0^{1,p}(\Omega; \mathbb{R}^2) \to \mathbb{R}_+$$

 $u \to K(u) = \int_{\Omega} |\nabla u(x)|_2^p = \int_{\Omega} (|\nabla u_1(x)|_2^2 + |\nabla u_2(x)|_2^2)^{\frac{p}{2}}$

Mainly, our goals are:

- show if that there exists $u_0 \in A_i$ unique such that, $G(u_0) = \inf\{G(u); u \in A_i\}$
- write the Euler-Lagrange equation satisfied by a 'smooth' u_0 Let us define the constraint sets:

1.
$$A_1 = \{u \in W^{1,p}(]0,1[;\mathbb{R}^2): |u|_2^2 = (|u_1|^2 + |u_2|^2) = 1 \text{ a.e. so } |u_i|_{\infty} \leq 1, u_1^2 = 1 - u_2^2; u(0) = (0,1), u(1) = (1,0)\}$$

2.
$$A_2 = \{u \in W^{1,p}(\Omega; \mathbb{R}^2); u_1 = 0 \& u_2 = 1 \text{ on } \partial\Omega; u_1 \in W_0^{1,p}(\Omega), |u|_2^2 = (|u_1|^2 + |u_2|^2) = 1 \text{ a.e. so } |u_i|_{\infty} \le 1, u_1^2 = 1 - u_2^2 \}$$

Note that the condition **a.e.** is implicitly important. One can notice that it could be written directly into equation $u_2 = \sqrt{1 - (u_1)^2}$; without loss of generality we didn't do so. Clearly, boundary condition does not define a vector space, if $u_1(0) = 0$, $u_1(1) = 1$, we write $u_1 = g$ and $u_2 = 1 - g$ on $\partial\Omega$ and g may be a function defined on the open set Ω as well.

2 Solutions

Lemma 2.1. $A_i \neq \phi$ for all i.

Proof. For i = 1 consider the bounded smooth functionals

$$x \to u_1 = \begin{cases} \exp\left(\frac{x}{x^p - 1}\right) & \text{for any p } > 0 \text{ if } x \in [0.1[\\ 0 & \text{if not} \end{cases}$$

For i = 2, similarly but more explicitly we use the following proposition about partition of unity which lead to the result after a regularization process.

Proposition 2.1. let Ω be an open set of \mathbb{R}^d and K a compact $\subset \Omega$. Then $\exists \Phi \in C_c(\mathbb{R}^d)$, such that

$$0 \le \Phi \le 1, \quad supp(\Phi) \subset \Omega.$$

Definition 2.1. The p-norm on \mathbb{R}^n is defined as:

$$x = (x_1, \dots, x_n) \in \mathbb{R}^n, p \in]0; +\infty[: x \to |x|_p = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}}$$

and it is denoted by $|.|_p$.

Lemma 2.2. If $u_1 \in L^p(\Omega)$, and $u_2 \in L^p(\Omega)$ then $(|u_1(x)|^2 + |u_2(x)|^2)^{\frac{p}{2}} \in L^1(\Omega)$

Proof. Write
$$|u|_2 \leq C|u|_p$$
 for some $C > 0$.

2.1 Existence and uniqueness

Note that product spaces such $V \times V$ are equipped with the sum norm that is ||u|| + ||v||.

Usually we will study $K(u)^{\frac{1}{p}}$, and $F(u)^{\frac{1}{p}}$ as the norm L^p will appear explicitly. Before we state the main theorem, we have:

Proposition 2.2.
$$|v(\partial\Omega)| \leq C||v||_{W^{1,p}} \quad \forall v \in W^{1,p}]0,1[$$
 where $\partial\Omega := \{0,1\}$

Remark 2.1. A minimizer of a positive valued function f is also a minimizer of f^p and conversely, $\forall p > 0$.

Theorem 2.1.

- There exists at least one function $u = (u_1, u_2) \in A_1$ solving $F(u) = \min_{w \in A_1} F(w)$.
- There exists at least one function $u = (u_1, u_2) \in A_2$ solving $K(u) = \min_{w \in A_2} K(w)$.

Proof. First $F(u)^{\frac{1}{p}}$ and $K(u)^{\frac{1}{p}}$ are both continuous convex functions thus weakly lower semi continuous. Also the constraints sets are weakly closed, in the sense that, if $u_n \to u$, and u_n is satisfying any of the constraint, u will be as well. For the boundary condition that is u = g on the boundary, choose any h satisfying same constraints, $u_n - h$ is a sequence $\in W_0^{1,p} \times W_0^{1,p}$, a convex closed subspace of $W^{1,p} \times W^{1,p}$, hence weakly closed.

For the condition of $|u_i|_{\infty} \leq 1$ a.e. it suffices to show that $|u_1|_{\infty} \leq 1$ a.e. Take a sequence weakly convergent to u in $W^{1,p}$ by Rellich-K. Theorem we have a strong convergence at least in one of the L^p 's. Thus we can extract

a subsequence that converges a.e. to u. Giving that $|\Omega| < \infty$, by Egoroff theorem the a.e convergence is equivalent to uniform convergence, up to arbitrarily negligible sets. Since the set is closed for the uniform convergence, we conclude that $|u_i|_{\infty} \leq 1$, i = 1, 2 a.e

It could be said directly after the extraction of a subsequence a.e. convergent, that we have

$$|u_{k_{j1}}|^2 + |u_{k_{j2}}|^2 \to |u_1|^2 + |u_2|^2 = 1$$
 a.e

Remaining to show that the functionals verify a coercivity condition over the product space.

1. Set $f := \inf_{u \in A_1} F(u)$. If $f = +\infty$ we are done, suppose f is finite. Select a minimizing sequence $\{u_k\}$, then $F(u_k) \to f$ cause we are in \mathbb{R}

$$F(u) \ge C. \left(\|u_1\|_{W_0^{1,p}}^p + \|u_2\|_{W_0^{1,p}}^p \right) \ge CC' \left(\|u_1\|_{W_0^{1,p}} + \|u_2\|_{W_0^{1,p}} \right)^p$$

One can verify because of boundary conditions (on A_1) that we have equivalence between the two norms $\|.\|_{W_0^{1,p}}$ and $\|.\|_{W^{1,p}}$ i.e.

$$F(u_k) \ge \alpha ||u_k|| := \alpha \left(||u_{k_1}||_{W^{1,p}} + ||u_{k_2}||_{W^{1,p}} \right)^p.$$

This estimate implies that $\{u_k\}$ is bounded in $W^{1,p} \times W^{1,p}$. Consequently there exist a subsequence $\{u_{k_j}\}$ and a function $u \in W^{1,p} \times W^{1,p}$ such that; $u_{k_j} \to u$ weakly in $W^{1,p} \times W^{1,p}$, thus F(u) is weakly lower semi continuous. $F(u) \leq \liminf_{j \to \infty} F(u_{k_j}) = f$, since $u \in A_1$ it follows that

$$F(u) = f = \min_{u \in A_1} F(u).$$

2. Similarly, set $m := \inf_{u \in A_2} K(u)$. If $m = +\infty$ we are done, suppose m is finite, select a minimizing sequence $\{u_k\}$, then $K(u_k) \to m$ because we are in \mathbb{R} .

$$K(u) = \int_{\Omega} |\nabla u(x)|_{2}^{p} = \int_{\Omega} \left(|\nabla u_{1}(x)|_{2}^{2} + |\nabla u_{2}(x)|_{2}^{2} \right)^{\frac{p}{2}}$$

$$\int_{\Omega} \left(|\nabla u_{1}(x)|_{2}^{2} + |\nabla u_{2}(x)|_{2}^{2} \right)^{\frac{p}{2}} = \int_{\Omega} \left(\left(\frac{\partial u_{1}}{\partial x_{1}} \right)^{2} + \left(\frac{\partial u_{1}}{\partial x_{2}} \right)^{2} + \left(\frac{\partial u_{2}}{\partial x_{1}} \right)^{2} + \left(\frac{\partial u_{2}}{\partial x_{2}} \right)^{2} \right)^{\frac{p}{2}}$$

$$\geq C \int_{\Omega} \left(\left(\frac{\partial u_{1}}{\partial x_{1}} \right)^{p} + \left(\frac{\partial u_{1}}{\partial x_{2}} \right)^{p} + \left(\frac{\partial u_{2}}{\partial x_{1}} \right)^{p} + \left(\frac{\partial u_{2}}{\partial x_{2}} \right)^{p} \right)$$

Consequently

$$K(u_k) \ge \min(C, 1)(\|u_{k_1}\|_{W^{1,p}}^p + \|\nabla\sqrt{1 - u_{k_1}^2}\|_{L^p}^p)$$
 (1)

since $u_1 \in W_0^{1,p}$, if u_1 is bounded so is u_2 and conversely for:

$$|1 - ||u_1||^2| \le ||1 - u_1||^2| \le ||u_2||^2$$

we conclude that the sequence $\{u_k\}$ is bounded in $W^{1,p} \times W^{1,p}$ and the proof is similar to that of F(u).

Theorem 2.2. The minimizing problem: $F(u) = \min_{w \in A_1} F(w)$ has a <u>unique</u> solution

Proof. Suppose not, if another distinct minimizer exists $v:=(v_1,v_2)$ write $w=(w_1,w_2)=\left(\frac{u_1+v_1}{2},\frac{u_2+v_2}{2}\right)$ now recall that L^p is strictly convex for $p\geq 2$, that's means as long as

$$v' \neq \alpha . u' \text{ a.e.}$$
 (2)

we have the strict inequality:

$$G(u)^{\frac{1}{p}} = \left[\int_0^1 |w'(x)|_2^p \right]^{\frac{1}{p}} = \left[\int_0^1 \left(\left(\frac{u_1' + v_1'}{2} \right)^2 + \left(\frac{u_2' + v_2'}{2} \right)^2 \right)^{\frac{p}{2}} \right]^{\frac{1}{p}}$$

$$< \frac{1}{2} G(u)^{\frac{1}{p}} + \frac{1}{2} G(v)^{\frac{1}{p}}$$

which is of course a contradiction. That completes the proof if we showed that $v' \neq \alpha.u'$ a.e. Suppose the converse so $u = \beta v + cte$ say $u_1 = \beta_1 v_1 + cte_1$ applying boundary constraints and using Proposition 2.2 we conclude that $u_1 \neq \beta_1 v_1 + cte_1$ a.e. for any β_1 and any cte_1

3 Euler-Lagrange

Lemma 3.1. F(u) and K(u) are both differentiable (C^1) on the product space except at (0,0)

Proof. This follows by the regularity of the $|.|_2$ norm and derivation under integral sign.

From this, we can compute the Euler-Lagrange equations giving the existence of a minimizer $(u_{0_1},u_{0_2})\neq 0$. Bearing in mind that C^1 Gateaux differentiable is the same as C^1 Frechet -differentiable. We will give the 'equation' satisfied by the 'minimizer' of K(u) as it is the most general case. Fix $v\in W_0^{1,p}(\Omega,\mathbb{R}^2)\cap L^\infty(\Omega,\mathbb{R}^2)$. Since $|u|_2=1$ a.e, we have

$$|u + \tau v|_2 \neq 0$$
 a.e.

for each sufficiently small τ by continuity. Consequently

$$v(\tau) := \frac{u + \tau v}{|u + \tau v|_2} \in A_2$$

Thus

$$k(\tau) := K(v(\tau))$$

has a minimum at $\tau = 0$, and so

$$k'(0) = 0.$$

Norms on product spaces are of course Euclidien norms, that is $|.|_2$. Matrices such the gradient matrix (here it's a 2×2 matrix) can be identified to a vector $\in \mathbb{R}^4$, and let (.) denotes the usual scalar product on \mathbb{R}^n , by a direct computation we have:

Proposition 3.1.
$$v'(\tau) = \frac{v}{|u + \tau v|} - \frac{[(u + \tau v).v](u + \tau v)}{|u + \tau v|^3}$$

Theorem 3.1. Let $u \in A_2$ satisfy

$$K(u) = \min_{w \in A_2} K(w).$$

Then

$$\int_{\Omega} p|Du|^{\frac{p}{2}-1}[(Du.Dv) - |Du|^2(u.v)] \tag{3}$$

for each $v \in W_0^{1,p}(\Omega, \mathbb{R}^2) \cap L^{\infty}(\Omega, \mathbb{R}^2)$.

Proof. In fact

$$K(u) = \int_{\Omega} |Du|^p$$

where Du is the gradient matrix associated to u and the norm as said is the one associated to the scalar product: $\langle A, B \rangle = Tr(B^t.A)$.

$$k'(0) = 0 = \int_{\Omega} p|Du|^{\frac{p}{2}-1} Du.Dv'(0)$$

$$= \int_{\Omega} p|Du|^{\frac{p}{2}-1}Du.D(v - (u.v)u)$$
(4)

Upon differentiating $|u|^2 = 1$ a.e., we have

$$(Du)^T u = 0$$

Using this fact, we then verify

$$Du.(D(u.v)u) = |Du|^2(u.v)$$
 a.e. in Ω

This identity employed in (4) gives (3). We leave details to the interested reader. [2]

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