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Simply Typed Lambda-Calculus Modulo Type Isomorphisms[☆]

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Abstract

We define a simply typed, non-deterministic lambda-calculus where isomorphic types are equated. To this end, an equivalence relation is settled at the term level. We then provide a proof of strong normalisation modulo equivalence. Such a proof is a non-trivial adaptation of the reducibility method.

Keywords: typed lambda calculus, normalisation, type isomorphisms, deduction modulo

1. Introduction

The starting point of this work was to understand and formalize the non-determinism of quantum programming languages [3, 4]. Unlike other calculi, that contain a non deterministic operator $|$, such that $\mathbf{r} | \mathbf{t}$ reduces both to \mathbf{r} and to \mathbf{t} , possibly with some probabilities, the non-determinism of quantum programming languages comes from the interaction of two operators. The first allows to build a superposition, that is a linear combination, of two terms $\alpha.\mathbf{r} + \beta.\mathbf{t}$, reflecting that a system may be in more than one state at a time. The second is a measurement operator π , reflecting that, during measurement, the state of such a system is reduced.

The non-determinism arises from the combination of these two constructions as the term $\pi(\alpha.\mathbf{r} + \beta.\mathbf{t})$ reduces to \mathbf{r} and to \mathbf{t} with probabilities $|\alpha|^2$ and $|\beta|^2$. Leaving probabilities aside, the non-determinism, in quantum programming languages, comes from the combination of the operators $+$ and π , as the term $\pi(\mathbf{r} + \mathbf{t})$ reduces to \mathbf{r} and to \mathbf{t} . In other words, the primitive operator $|$ of

[☆]A preliminary version of this work, including also polymorphism, was published as [14]. Such a version presents some of the ideas in this paper, but it does not deal with all the isomorphisms nor include a normalisation proof, the main result on the present work.

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non-deterministic languages is decomposed into two operators, and $\mathbf{r} \mid \mathbf{t}$ can be seen as an abbreviation for $\pi(\mathbf{r} + \mathbf{t})$.

The rules

$$\pi(\mathbf{r} + \mathbf{t}) \rightarrow \mathbf{r}$$

$$\pi(\mathbf{r} + \mathbf{t}) \rightarrow \mathbf{t}$$

are reminiscent of the rules for pairing constructs

$$\pi_1\langle \mathbf{r}, \mathbf{t} \rangle \rightarrow \mathbf{r}$$

$$\pi_2\langle \mathbf{r}, \mathbf{t} \rangle \rightarrow \mathbf{t}$$

and it is therefore tempting to consider the term $\mathbf{r} + \mathbf{t}$ as the pair $\langle \mathbf{r}, \mathbf{t} \rangle$ and π as a projection, that projects the pair $\langle \mathbf{r}, \mathbf{t} \rangle$ to \mathbf{r} and to \mathbf{t} .

As, in quantum programming languages, unlike with the usual pairing construct, the places in the pair are immaterial, and the superposed states $\mathbf{r} + \mathbf{t}$ and $\mathbf{t} + \mathbf{r}$ are identical, it is compelling to consider the pairs $\mathbf{r} + \mathbf{t}$ and $\mathbf{t} + \mathbf{r}$ as identical and therefore the type $A \wedge B$ and $B \wedge A$ as identical.

In typed λ -calculus, the types $A \wedge B$ and $B \wedge A$ are known to be isomorphic, thus our goal to understand the non-determinism of quantum programming languages, led us to consider quantum programming languages as typed lambda-calculi where isomorphic types were identified, thus pairs unordered, hence projection non-deterministic.

In typed λ -calculus, in programming languages, and in proof theory, two types A and B are said to be isomorphic, when there exists two functions ϕ from A to B and ψ from B to A such that $\psi\phi\mathbf{r} = \mathbf{r}$ for all terms \mathbf{r} of type A and $\phi\psi\mathbf{s} = \mathbf{s}$ for all terms \mathbf{s} of type B .

Isomorphic types are often identified in informal mathematics. For instance, the natural numbers and non negative integers are never distinguished, although they formally are different structures. In Martin-Löf's type theory [23], in the Calculus of Constructions [9], and in Deduction modulo [17, 19], some isomorphic types, called definitionally equivalent types, for instance $x \subset y$, $x \in P(y)$, and $\forall z (z \in x \Rightarrow z \in y)$ are identified, but definitional equality does not handle all the isomorphisms and, for example, $A \wedge B$ and $B \wedge A$ are not identified: a term of type $A \wedge B$ does not have type $B \wedge A$.

It has already been noticed that not identifying such types has many drawbacks. For instance, if a library contains a proof of $B \wedge A$, a request on a proof of $A \wedge B$ fails to find it [26], if \mathbf{r} and \mathbf{s} are proofs of $(A \wedge B) \Rightarrow C$ and $B \wedge A$ respectively, it is not possible to apply \mathbf{r} to \mathbf{s} to get a proof of C , but we need to explicitly apply a function of type $(B \wedge A) \Rightarrow (A \wedge B)$ to \mathbf{s} before we can apply \mathbf{r} to this term. If A and B are isomorphic types and a library contains a proof of a properties on A , we cannot use this property on B without any extra transformation, etc. This has lead to several projects aiming at identifying in one way or another isomorphic types in type theory, for instance with the univalence axiom [27].

In [7], Bruce, Di Cosmo and Longo have provided a characterisation of isomorphic types in the simply typed λ -calculus extended with products and a unit

type (see [13] for a concise overview on type isomorphisms, or [12] for a more comprehensive reference). In this work, we define a simply typed λ -calculus extended with products, where all the isomorphic types are identified, and we prove strong normalisation for this calculus. All the isomorphisms in such a setting, are consequences of the following four:

$$A \wedge B \equiv B \wedge A \quad (1)$$

$$A \wedge (B \wedge C) \equiv (A \wedge B) \wedge C \quad (2)$$

$$A \Rightarrow (B \wedge C) \equiv (A \Rightarrow B) \wedge (A \Rightarrow C) \quad (3)$$

$$(A \wedge B) \Rightarrow C \equiv A \Rightarrow B \Rightarrow C \quad (4)$$

For example, $A \Rightarrow B \Rightarrow C \equiv B \Rightarrow A \Rightarrow C$ is a consequence of (4) and (1).

Identifying types requires to also identify terms. For instance, if \mathbf{r} is a closed term of type A , then $\lambda x^A.x$ is a term of type $A \Rightarrow A$, and $\langle \lambda x^A.x, \lambda x^A.x \rangle$ is a term of type $(A \Rightarrow A) \wedge (A \Rightarrow A)$, hence, by isomorphism (3), also a term of type $A \Rightarrow (A \wedge A)$. Thus the term $\langle \lambda x^A.x, \lambda x^A.x \rangle \mathbf{r}$ is a term of type $A \wedge A$. Although this term contains no redex, we do not want to consider it as normal, in particular because it is not an introduction. So we shall distribute the application over the pair, yielding the term $\langle (\lambda x^A.x) \mathbf{r}, (\lambda x^A.x) \mathbf{r} \rangle$ that finally reduces to $\langle \mathbf{r}, \mathbf{r} \rangle$. Similar considerations lead to the introduction of several equivalence rules on terms, one related to the isomorphism (1), the commutativity of the conjunction, $\langle \mathbf{r}, \mathbf{s} \rangle \rightleftharpoons \langle \mathbf{s}, \mathbf{r} \rangle$; one related to the isomorphism (2), the associativity of the conjunction, $\langle \langle \mathbf{r}, \mathbf{s} \rangle, \mathbf{t} \rangle \rightleftharpoons \langle \mathbf{r}, \langle \mathbf{s}, \mathbf{t} \rangle \rangle$; four to the isomorphism (3), the distributivity of implication with respect to conjunction, e.g. $\langle \mathbf{r}, \mathbf{s} \rangle \mathbf{t} \rightleftharpoons \langle \mathbf{r}\mathbf{t}, \mathbf{s}\mathbf{t} \rangle$; and one related to the isomorphisms (4), the currying, $\mathbf{r}\mathbf{s}\mathbf{t} \rightleftharpoons \mathbf{r}\langle \mathbf{s}, \mathbf{t} \rangle$. As our comma is associative and commutative, and because it can be identified with a non-deterministic operator, we will write it $+$. For instance, the equivalence due to the associativity of conjunction is rewritten $(\mathbf{r} + \mathbf{s}) + \mathbf{t} \rightleftharpoons \mathbf{r} + (\mathbf{s} + \mathbf{t})$.

One of the main difficulties in the design of this calculus is the design of the elimination rule for the conjunction. A rule like “if $\mathbf{r} : A \wedge B$ then $\pi_1(\mathbf{r}) : A$ ”, would not be consistent. Indeed, if A and B are two arbitrary types, \mathbf{s} a term of type A and \mathbf{t} a term of type B , then $\mathbf{s} + \mathbf{t}$ has both types $A \wedge B$ and $B \wedge A$, thus $\pi_1(\mathbf{s} + \mathbf{t})$ would have both type A and type B . The approach we have followed is to consider explicitly typed (Church style) terms, and parametrise the projection by the type: if $\mathbf{r} : A \wedge B$ then $\pi_A(\mathbf{r}) : A$ and the reduction rule is then that $\pi_A(\mathbf{s} + \mathbf{t})$ reduces to \mathbf{s} if \mathbf{s} has type A .

Hence, this rule introduces the expected non-determinism. Indeed, in the particular case where A happens to be equal to B , then both \mathbf{s} and \mathbf{t} have type A and $\pi_A(\mathbf{s} + \mathbf{t})$ reduces both to \mathbf{s} and to \mathbf{t} . Notice that although this reduction rule is non-deterministic, it preserves typing. This can be summarised by the slogan “*the subject reduction property is more important than the uniqueness of results*” [18].

Thus, our calculus is one of the many non-deterministic calculi in the sense of [6, 8, 10, 11, 24] and our pair-construction operator $+$ is also the parallel composition operator of a non deterministic calculus.

In non-deterministic calculi, the parallel composition is such that if \mathbf{r} and \mathbf{s} are two λ -terms, the term $\mathbf{r} + \mathbf{s}$ represents the computation that runs either \mathbf{r} or \mathbf{s} non-deterministically, that is such that $(\mathbf{r} + \mathbf{s})\mathbf{t}$ reduces either to $\mathbf{r}\mathbf{t}$ or $\mathbf{s}\mathbf{t}$. In our case, $\pi_B((\mathbf{r} + \mathbf{s})\mathbf{t})$ is equivalent to $\pi_B(\mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t})$, which reduces to $\mathbf{r}\mathbf{t}$ or $\mathbf{s}\mathbf{t}$.

The calculus developed in this paper is also related to the algebraic calculi [1, 2], some of which have been designed to express quantum algorithms. In this case, the pair $\mathbf{s} + \mathbf{t}$ is not interpreted as a non-deterministic choice but as a superposition of two processes running \mathbf{s} and \mathbf{t} . In this case the projection π is the projection related to the projective measurement, that is the only non deterministic operation. In such calculi, the distributivity rule $(\mathbf{r} + \mathbf{s})\mathbf{t} \rightleftharpoons \mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t}$ is seen as the pointwise definition of the sum of two functions.

The main difficulty in the normalisation proof seems to be related to the fact that our equivalence relation is “confusing”, that is, it equates types with different main connectives such as the isomorphism (3). In [19], for instance, only the case of “non confusing” equivalence relations is considered: if two non atomic types are equivalent, they have the same head symbol and their arguments are equivalent. It is clear however that this restriction needs to be dropped if we want to identify, for instance, $A \Rightarrow (B \wedge C)$ and $(A \Rightarrow B) \wedge (A \Rightarrow C)$.

Summarising, this paper is the result of three motivations relatively independent: to formalise non-deterministic calculi, to integrate the type isomorphisms to the language, and to understand how much we can extend the deduction modulo techniques.

2. The Calculus

2.1. Formal Definition

In this section we present the calculus. We consider the following grammar of types, with one atomic type τ ,

$$A, B, C, \dots ::= \tau \mid A \Rightarrow B \mid A \wedge B .$$

The Isomorphisms (1), (2), (3) and (4) are made explicit by a congruent equivalence relation between types:

$$\begin{aligned} A \wedge B &\equiv B \wedge A, & A \Rightarrow (B \wedge C) &\equiv (A \Rightarrow B) \wedge (A \Rightarrow C), \\ (A \wedge B) \wedge C &\equiv A \wedge (B \wedge C), & (A \wedge B) \Rightarrow C &\equiv A \Rightarrow B \Rightarrow C. \end{aligned}$$

The set of terms is defined inductively by the grammar

$$\mathbf{r}, \mathbf{s}, \mathbf{t} ::= x^A \mid \lambda x^A. \mathbf{r} \mid \mathbf{r}\mathbf{s} \mid \mathbf{r} + \mathbf{s} \mid \pi_A(\mathbf{r})$$

The set of contexts is defined inductively by the grammar

$$C[\cdot] ::= [\cdot] \mid \lambda x^A. C[\cdot] \mid C[\cdot]\mathbf{r} \mid \mathbf{r}C[\cdot] \mid C[\cdot] + \mathbf{r} \mid \mathbf{r} + C[\cdot] \mid \pi_A(C[\cdot])$$

The type system is given in Table 1. Typing judgements are of the form $\mathbf{r} : A$. A term \mathbf{r} is typable if there exists a type A such that $\mathbf{r} : A$.

| | |
|--|---|
| $\frac{}{x^A : A} \text{ (ax)}$ | $[A \equiv B] \frac{\mathbf{r} : A}{\mathbf{r} : B} \text{ (}\equiv\text{)}$ |
| $[(V(\mathbf{r}) \cup \{x^A\})^f] \frac{\mathbf{r} : B}{\lambda x^A. \mathbf{r} : A \Rightarrow B} \text{ (}\Rightarrow_i\text{)}$ | $[V(\mathbf{rs})^f] \frac{\mathbf{r} : A \Rightarrow B \quad \mathbf{s} : A}{\mathbf{rs} : B} \text{ (}\Rightarrow_e\text{)}$ |
| $[V(\mathbf{r+s})^f] \frac{\mathbf{r} : A \quad \mathbf{s} : B}{\mathbf{r+s} : A \wedge B} \text{ (}\wedge_i\text{)}$ | $\frac{\mathbf{r} : A \wedge B}{\pi_A(\mathbf{r}) : A} \text{ (}\wedge_{e_n}\text{)}$ |
| $\frac{\mathbf{r} : A}{\pi_A(\mathbf{r}) : A} \text{ (}\wedge_{e_1}\text{)}$ | |

Table 1: The type system

Because of the associativity property of $+$, the term $\mathbf{r} + (\mathbf{s} + \mathbf{t})$ is the same as the term $(\mathbf{r} + \mathbf{s}) + \mathbf{t}$, so we can just express it as $\mathbf{r} + \mathbf{s} + \mathbf{t}$, that is, the parenthesis are meaningless, and pairs become lists. In particular, we can project with respect to the type of $\mathbf{s} + \mathbf{t}$ in the previous example. Hence, for completeness, we also allow to project a term with respect to its full type, that is, if $\mathbf{r} : A$, then $\pi_A(\mathbf{r})$ reduces to \mathbf{r} .

Since our reduction relation is oriented by the types, we follow [21, 25], and use a presentation of typed lambda-calculus without contexts, which makes the reduction rules clearer. To this end each variable occurrence is labelled by its type, such as $\lambda x^A. x^A$ or $\lambda x^A. y^B$. We sometimes omit the labels and write, for example, $\lambda x^A. x$ for $\lambda x^A. x^A$. As usual, we consider implicit α -equivalence on syntactical terms. The type system forbids terms such as $\lambda x^A. x^B$ when A and B are different types, by imposing preconditions to the applicability of the typing rules. Let $S = \{x_1^{A_1}, \dots, x_n^{A_n}\}$ be a set of variables, we write S^f to express that this set is functional, that is when $x_i = x_j$ implies $A_i = A_j$. For example $\{x^A, y^{A \Rightarrow B}\}^f$, but not $\{x^A, x^{A \Rightarrow B}\}^f$. We write the preconditions of a typing rule, at its left.

The sets $FV(\mathbf{r})$ of free variables of \mathbf{r} , $BV(\mathbf{r})$ of bounded variables of \mathbf{r} and $V(\mathbf{r}) = FV(\mathbf{r}) \cup BV(\mathbf{r})$ are defined as usual in the λ -calculus (cf. [5, §2.1]). For example $V(\lambda x^{A \Rightarrow B \Rightarrow C}. x y^A z^B) = \{x^{A \Rightarrow B \Rightarrow C}, y^A, z^B\}$. We say that a term \mathbf{r} is closed whenever $FV(\mathbf{r}) = \emptyset$.

Given two terms \mathbf{r} and \mathbf{s} we denote by $\mathbf{r}[\mathbf{s}/x]$ the term obtained by simultaneously substituting the term \mathbf{s} for all the free occurrences of x in \mathbf{r} , subject to the usual proviso about renaming bound variables in \mathbf{r} to avoid capture of the free variables of \mathbf{s} .

Lemma 2.1. *If $\mathbf{r} : A$ and $\mathbf{r} : B$, then $A \equiv B$.*

Proof. Straightforward structural induction on the typing derivation of \mathbf{r} . \square

The operational semantics of the calculus is given in Table 2, where there are two distinct relations between terms: a symmetric relation $\overset{\delta}{\rightleftharpoons}$ and a reduction relation \hookrightarrow , which include a labelling $\neg\delta$ or δ . Such a labelling is omitted when it is not necessary to distinguish the rule. Moreover, relation \hookrightarrow is $\overset{\neg\delta}{\hookrightarrow} \cup \overset{\delta}{\hookrightarrow}$.

| | | |
|--|--|---|
| Symmetric relation: | | |
| $\mathbf{r} + \mathbf{s}$ | \rightleftharpoons | $\mathbf{s} + \mathbf{r}$ (COMM) |
| $(\mathbf{r} + \mathbf{s}) + \mathbf{t}$ | \rightleftharpoons | $\mathbf{r} + (\mathbf{s} + \mathbf{t})$ (ASSO) |
| $\lambda x^A.(\mathbf{r} + \mathbf{s})$ | \rightleftharpoons | $\lambda x^A.\mathbf{r} + \lambda x^A.\mathbf{s}$ (DIST _{ii}) |
| $(\mathbf{r} + \mathbf{s})\mathbf{t}$ | \rightleftharpoons | $\mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t}$ (DIST _{ie}) |
| $\pi_{A \Rightarrow B}(\lambda x^A.\mathbf{r})$ | \rightleftharpoons | $\lambda x^A.\pi_B(\mathbf{r})$ (DIST _{ei}) |
| If $\mathbf{r} : A \Rightarrow (B \wedge C)$, $\pi_{A \Rightarrow B}(\mathbf{r})\mathbf{s}$ | \rightleftharpoons | $\pi_B(\mathbf{r}\mathbf{s})$ (DIST _{ee}) |
| $\mathbf{r}\mathbf{s}\mathbf{t}$ | \rightleftharpoons | $\mathbf{r}(\mathbf{s} + \mathbf{t})$ (CURRY) |
| If $A \equiv B$, \mathbf{r} | \rightleftharpoons | $\mathbf{r}[A/B]$ (SUBST) |
| If $\left\{ \begin{array}{l} \mathbf{r} : A \wedge B \\ \mathbf{s} : C \wedge D \end{array} \right\}$, $\pi_{A \wedge C}(\mathbf{r} + \mathbf{s})$ | \rightleftharpoons | $\pi_A(\mathbf{r}) + \pi_C(\mathbf{s})$ (SPLIT) |
| Reductions: | | |
| If $\mathbf{s} : A$, $(\lambda x^A.\mathbf{r})\mathbf{s}$ | $\xrightarrow{\neg\delta}$ | $\mathbf{r}[\mathbf{s}/x]$ (β) |
| If $\mathbf{r} : A$, $\pi_A(\mathbf{r} + \mathbf{s})$ | $\xrightarrow{\neg\delta}$ | \mathbf{r} (π_n) |
| If $\mathbf{r} : A$, $\pi_A(\mathbf{r})$ | $\xrightarrow{\neg\delta}$ | \mathbf{r} (π_1) |
| If $\left\{ \begin{array}{l} \mathbf{r} : A \wedge B \\ \mathbf{r} \not\rightleftharpoons^* \mathbf{s} + \mathbf{t} \end{array} \right\}$, \mathbf{r} | $\xrightarrow{\delta}$ | $\pi_A(\mathbf{r}) + \pi_B(\mathbf{r})$ (δ) |
| $\frac{\mathbf{r} \rightleftharpoons \mathbf{s}}{C[\mathbf{r}] \rightleftharpoons C[\mathbf{s}]} \text{ (C}\rightleftharpoons\text{)}$ | $\frac{\mathbf{r} \xrightarrow{\neg\delta} \mathbf{s}}{C[\mathbf{r}] \xrightarrow{\neg\delta} C[\mathbf{s}]} \text{ (C}\xrightarrow{\neg\delta}\text{)}$ | $\frac{\mathbf{r} \xrightarrow{\delta} \mathbf{s} \quad C[\cdot] \not\rightleftharpoons^* C'[\pi_A(\cdot)]}{C[\mathbf{r}] \xrightarrow{\delta} C[\mathbf{s}]} \text{ (C}\xrightarrow{\delta}\text{)}$ |

Table 2: Operational semantics

Type substitution on a term \mathbf{r} , written $\mathbf{r}[A/B]$, is defined by the syntactic substitution of all occurrences of B in \mathbf{r} by A . We write \hookrightarrow^* and \rightleftharpoons^* for the transitive and reflexive closure of \hookrightarrow and \rightleftharpoons respectively. Note that \rightleftharpoons^* is an equivalence relation. We write \rightsquigarrow for the relation \hookrightarrow modulo \rightleftharpoons^* (i.e. $\mathbf{r} \rightsquigarrow \mathbf{s}$ iff $\mathbf{r} \rightleftharpoons^* \mathbf{r}' \hookrightarrow \mathbf{s}' \rightleftharpoons^* \mathbf{s}$), and \rightsquigarrow^* for its reflexive and transitive closure.

Each isomorphism taken as equivalence between types induces an equivalence between terms, given by relation \rightleftharpoons . Four possible rules exist however for the isomorphism (3), depending of which distribution is taken into account: elimination or introduction of conjunction, and elimination or introduction of implication.

Only two rules in the symmetric relation \rightleftharpoons are not a direct consequence of an isomorphism: rules (SUBST) and (SPLIT). The former allows to update the types signature of the Church-style terms. The latter is needed to be used in combination to rule (DIST_{ei}) when the argument in the projection is not a λ -abstraction, but a λ -abstraction plus something else (cf. Example 2.10).

Rule (δ) has been added to deal with curryfication, (cf. Example 2.9). Notice that the condition in this rule not only asks for the term to not be a sum, but to not be equivalent to a sum. Lemma 2.4 ensures that the equivalent classes defined by relation \rightleftharpoons^* , $\{\mathbf{s} \mid \mathbf{s} \rightleftharpoons^* \mathbf{r}\}$, are finite, and since the relation is

computable, the side condition of (δ) is decidable.

In addition, Lemma 2.4 also implies that every reduction tree is finitely branching.

To prove that for any term \mathbf{r} , the set $\{\mathbf{s} \mid \mathbf{s} \rightleftharpoons^* \mathbf{r}\}$ is finite, one possible way would be to prove that if $\mathbf{r} \rightleftharpoons \mathbf{s}$ then $S(\mathbf{r}) = S(\mathbf{s})$ where the size $S(\mathbf{r})$ of a term \mathbf{r} is defined as the number of variables and symbols λ and π

- $S(x^A) = 1$,
- $S(\lambda x^A.\mathbf{r}) = 1 + S(\mathbf{r})$,
- $S(\mathbf{rs}) = S(\mathbf{r}) + S(\mathbf{s})$,
- $S(\mathbf{r} + \mathbf{s}) = S(\mathbf{r}) + S(\mathbf{s})$,
- $S(\pi_A(\mathbf{r})) = 1 + S(\mathbf{r})$.

Indeed, the set $\{\mathbf{s} \mid \mathbf{s} \rightleftharpoons^* \mathbf{r}\}$ would then be a subset of the set $\{\mathbf{s} \mid FV(\mathbf{s}) \subseteq FV(\mathbf{r}) \text{ and } S(\mathbf{s}) = S(\mathbf{r})\}$ which is finite.

Unfortunately, it is not the case that the size S is an invariant for the relation \rightleftharpoons as the rule (DIST_{ii})

$$\lambda x^A.(\mathbf{r} + \mathbf{s}) \rightleftharpoons \lambda x^A.\mathbf{r} + \lambda x^A.\mathbf{s}$$

for instance duplicates the symbol λ and the term $\lambda x^A.(x + x)$ is equivalent to $\lambda x^A.x + \lambda x^A.x$, while $S(\lambda x^A.(x + x)) = 3$ and $S(\lambda x^A.x + \lambda x^A.x) = 4$. In the same way, the rule (DIST_{ie})

$$(\mathbf{r} + \mathbf{s})\mathbf{t} \rightleftharpoons \mathbf{rt} + \mathbf{st}$$

duplicates the term \mathbf{t} .

However, the number of times the symbol λ can be duplicated in the term $\lambda x^A.\mathbf{t}$, is bounded by the number of symbols $+$ that the term \mathbf{t} may generate. A bound $P(\mathbf{t})$ on this number is easy to define

- $P(x^A) = 0$,
- $P(\lambda x^A.\mathbf{r}) = P(\mathbf{r})$,
- $P(\mathbf{rs}) = P(\mathbf{r})$,
- $P(\mathbf{r} + \mathbf{s}) = 1 + P(\mathbf{r}) + P(\mathbf{s})$,
- $P(\pi_A(\mathbf{r})) = P(\mathbf{r})$.

and we can define a size-like measure on terms M , such that $M(\mathbf{r})$ is a bound on the size of \mathbf{s} for $\mathbf{s} \rightleftharpoons \mathbf{r}$. For instance $M(\lambda x^A.\mathbf{r})$ is not $1 + M(\mathbf{r})$ but $1 + M(\mathbf{r}) + P(\mathbf{r})$, to express that the size of \mathbf{s} may be bigger than that of \mathbf{r} , because a symbol λ may be duplicated in \mathbf{s} , but not much bigger, as it can be duplicated at most $P(\mathbf{r})$ times.

- $M(x^A) = 1$,

- $M(\lambda x^A.\mathbf{r}) = 1 + M(\mathbf{r}) + P(\mathbf{r})$,
- $M(\mathbf{rs}) = M(\mathbf{r}) + M(\mathbf{s}) + P(\mathbf{r})M(\mathbf{s})$,
- $M(\mathbf{r} + \mathbf{s}) = M(\mathbf{r}) + M(\mathbf{s})$,
- $M(\pi_A(\mathbf{r})) = 1 + M(\mathbf{r}) + P(\mathbf{r})$.

Prior to state and prove Lemma 2.4, we need the following two auxiliary lemmas, showing that $P(\mathbf{t})$ and $M(\mathbf{t})$ are invariant with respect to \rightleftharpoons (Lemmas 2.2 and 2.3 respectively).

Lemma 2.2. *If $\mathbf{r} \rightleftharpoons \mathbf{s}$ then $P(\mathbf{r}) = P(\mathbf{s})$.*

Proof. $\mathbf{r} + \mathbf{s} \rightleftharpoons \mathbf{s} + \mathbf{r}$: $P(\mathbf{r} + \mathbf{s}) = 1 + P(\mathbf{r}) + P(\mathbf{s}) = P(\mathbf{s} + \mathbf{r})$.

$$\begin{aligned} (\mathbf{r} + \mathbf{s}) + \mathbf{t} \rightleftharpoons \mathbf{r} + (\mathbf{s} + \mathbf{t}): & P((\mathbf{r} + \mathbf{s}) + \mathbf{t}) = 1 + P(\mathbf{r} + \mathbf{s}) + P(\mathbf{t}) \\ & = 2 + P(\mathbf{r}) + P(\mathbf{s}) + P(\mathbf{t}) = 1 + P(\mathbf{r}) + P(\mathbf{s} + \mathbf{t}) \\ & = P(\mathbf{r} + (\mathbf{s} + \mathbf{t})) \end{aligned}$$

$$\begin{aligned} \lambda x^A.(\mathbf{r} + \mathbf{s}) \rightleftharpoons \lambda x^A.\mathbf{r} + \lambda x^A.\mathbf{s}: & P(\lambda x^A.(\mathbf{r} + \mathbf{s})) = P(\mathbf{r} + \mathbf{s}) \\ & = 1 + P(\mathbf{r}) + P(\mathbf{s}) = 1 + P(\lambda x^A.\mathbf{r}) + P(\lambda x^A.\mathbf{s}) \\ & = P(\lambda x^A.\mathbf{r} + \lambda x^A.\mathbf{s}) \end{aligned}$$

$$\begin{aligned} (\mathbf{r} + \mathbf{s})\mathbf{t} \rightleftharpoons \mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t}: & P((\mathbf{r} + \mathbf{s})\mathbf{t}) = P(\mathbf{r} + \mathbf{s}) \\ & = 1 + P(\mathbf{r}) + P(\mathbf{s}) = 1 + P(\mathbf{r}\mathbf{t}) + P(\mathbf{s}\mathbf{t}) \\ & = P(\mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t}) \end{aligned}$$

$$\begin{aligned} \pi_{A \Rightarrow B}(\lambda x^A.\mathbf{r}) \rightleftharpoons \lambda x^A.\pi_B(\mathbf{r}): & P(\pi_{A \Rightarrow B}(\lambda x^A.\mathbf{r})) = P(\lambda x^A.\mathbf{r}) \\ & = P(\mathbf{r}) = P(\pi_B(\mathbf{r})) \\ & = P(\lambda x^A.\pi_B(\mathbf{r})) \end{aligned}$$

$$\begin{aligned} \pi_{A \Rightarrow B}(\mathbf{r})\mathbf{s} \rightleftharpoons \pi_B(\mathbf{rs}): & P(\pi_{A \Rightarrow B}(\mathbf{r})\mathbf{s}) = P(\pi_{A \Rightarrow B}(\mathbf{r})) \\ & = P(\mathbf{r}) = P(\mathbf{rs}) \\ & = P(\pi_B(\mathbf{rs})) \end{aligned}$$

$$(\mathbf{rs})\mathbf{t} \rightleftharpoons \mathbf{r}(\mathbf{s} + \mathbf{t}): P((\mathbf{rs})\mathbf{t}) = P(\mathbf{rs}) = P(\mathbf{r}) = P(\mathbf{r}(\mathbf{s} + \mathbf{t})).$$

$$\mathbf{r} \rightleftharpoons \mathbf{r}[A/B]: P(\mathbf{r}) = P(\mathbf{r}[A/B]).$$

$$\begin{aligned} \pi_{A \wedge C}(\mathbf{r} + \mathbf{s}) \rightleftharpoons \pi_A(\mathbf{r}) + \pi_C(\mathbf{s}): & P(\pi_{A \wedge C}(\mathbf{r} + \mathbf{s})) = P(\mathbf{r} + \mathbf{s}) \\ & = 1 + P(\mathbf{r}) + P(\mathbf{s}) = 1 + P(\pi_A(\mathbf{r})) + P(\pi_C(\mathbf{s})) \\ & = P(\pi_A(\mathbf{r}) + \pi_C(\mathbf{s})) \end{aligned}$$

$C[\mathbf{r}] \rightleftharpoons C[\mathbf{s}]$ **with $\mathbf{r} \rightleftharpoons \mathbf{s}$** : Straightforward case by case on the structure of $C[\cdot]$. For example, let $C[\cdot] = C'[\cdot] + \mathbf{t}$, then $P(C[\mathbf{r}]) = 1 + P(C'[\mathbf{r}]) + P(\mathbf{t})$, which, by the induction hypothesis, is equal to $1 + P(C'[\mathbf{s}]) + P(\mathbf{t}) = P(C[\mathbf{s}])$. \square

Lemma 2.3. *If $\mathbf{r} \rightleftharpoons \mathbf{s}$ then $M(\mathbf{r}) = M(\mathbf{s})$.*

Proof. We proceed by structural induction on relation \rightleftharpoons .

$$\mathbf{r} + \mathbf{s} \rightleftharpoons \mathbf{s} + \mathbf{r}: M(\mathbf{r} + \mathbf{s}) = M(\mathbf{r}) + M(\mathbf{s}) = M(\mathbf{s} + \mathbf{r}).$$

$$(\mathbf{r} + \mathbf{s}) + \mathbf{t} \rightleftharpoons \mathbf{r} + (\mathbf{s} + \mathbf{t}): M((\mathbf{r} + \mathbf{s}) + \mathbf{t}) = M(\mathbf{r}) + M(\mathbf{s}) + M(\mathbf{t}) = M(\mathbf{r} + (\mathbf{s} + \mathbf{t})).$$

$$\begin{aligned} \lambda x^A.(\mathbf{r} + \mathbf{s}) \rightleftharpoons \lambda x^A.\mathbf{r} + \lambda x^A.\mathbf{s}: & M(\lambda x^A.(\mathbf{r} + \mathbf{s})) \\ &= 2 + M(\mathbf{r}) + M(\mathbf{s}) + P(\mathbf{r}) + P(\mathbf{s}) \\ &= M(\lambda x^A.\mathbf{r} + \lambda x^A.\mathbf{s}) \end{aligned}$$

$$\begin{aligned} (\mathbf{r} + \mathbf{s})\mathbf{t} \rightleftharpoons \mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t}: & M((\mathbf{r} + \mathbf{s})\mathbf{t}) \\ &= M(\mathbf{r} + \mathbf{s}) + M(\mathbf{t}) + P(\mathbf{r} + \mathbf{s})M(\mathbf{t}) \\ &= M(\mathbf{r}) + M(\mathbf{s}) + 2M(\mathbf{t}) + P(\mathbf{r})M(\mathbf{t}) + P(\mathbf{s})M(\mathbf{t}) \\ &= M(\mathbf{r}\mathbf{t}) + M(\mathbf{s}\mathbf{t}) \\ &= M(\mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t}) \end{aligned}$$

$$\begin{aligned} \pi_{A \Rightarrow B}(\lambda x^A.\mathbf{r}) \rightleftharpoons \lambda x^A.\pi_B(\mathbf{r}): & M(\pi_{A \Rightarrow B}(\lambda x^A.\mathbf{r})) \\ &= 1 + M(\lambda x^A.\mathbf{r}) + P(\lambda x^A.\mathbf{r}) \\ &= 2 + M(\mathbf{r}) + 2P(\mathbf{r}) \\ &= M(\lambda x^A.\pi_B(\mathbf{r})) \end{aligned}$$

$$\begin{aligned} \pi_{A \Rightarrow B}(\mathbf{r})\mathbf{s} \rightleftharpoons \pi_B(\mathbf{r}\mathbf{s}): & M(\pi_{A \Rightarrow B}(\mathbf{r})\mathbf{s}) \\ &= M(\pi_{A \Rightarrow B}(\mathbf{r})) + M(\mathbf{s}) + P(\pi_{A \Rightarrow B}(\mathbf{r}))M(\mathbf{s}) \\ &= 1 + M(\mathbf{r}) + P(\mathbf{r}) + M(\mathbf{s}) + P(\mathbf{r})M(\mathbf{s}) \\ &= 1 + M(\mathbf{r}\mathbf{s}) + P(\mathbf{r}\mathbf{s}) \\ &= M(\pi(\mathbf{r}\mathbf{s})) \end{aligned}$$

$$\begin{aligned} (\mathbf{r}\mathbf{s})\mathbf{t} \rightleftharpoons \mathbf{r}(\mathbf{s} + \mathbf{t}): & M((\mathbf{r}\mathbf{s})\mathbf{t}) \\ &= M(\mathbf{r}\mathbf{s}) + M(\mathbf{t}) + P(\mathbf{r}\mathbf{s})M(\mathbf{t}) \\ &= M(\mathbf{r}) + M(\mathbf{s}) + P(\mathbf{r})M(\mathbf{s}) + M(\mathbf{t}) + P(\mathbf{r})M(\mathbf{t}) \\ &= M(\mathbf{r}) + M(\mathbf{s} + \mathbf{t}) + P(\mathbf{r})M(\mathbf{s} + \mathbf{t}) \\ &= M(\mathbf{r}(\mathbf{s} + \mathbf{t})) \end{aligned}$$

$$\mathbf{r} \rightleftharpoons \mathbf{r}[A/B]: M(\mathbf{r}) = M(\mathbf{r}[A/B]).$$

$$\begin{aligned} \pi_{A \wedge C}(\mathbf{r} + \mathbf{s}) \rightleftharpoons \pi_A(\mathbf{r}) + \pi_C(\mathbf{s}): & M(\pi_{A \wedge C}(\mathbf{r} + \mathbf{s})) \\ &= 1 + M(\mathbf{r} + \mathbf{s}) + P(\mathbf{r} + \mathbf{s}) \\ &= 1 + M(\mathbf{r}) + M(\mathbf{s}) + 1 + P(\mathbf{r}) + P(\mathbf{s}) \\ &= M(\pi_A(\mathbf{r})) + M(\pi_C(\mathbf{s})) \\ &= M(\pi_A(\mathbf{r}) + \pi_C(\mathbf{s})) \end{aligned}$$

$C[\mathbf{r}] \rightleftharpoons C[\mathbf{s}]$ **with** $\mathbf{r} \rightleftharpoons^* \mathbf{s}$: Straightforward case by case on the structure of $C[\cdot]$.
 For example, let $C[\cdot] = \lambda x^A.C'[\cdot]$, then $M(C[\mathbf{r}]) = 1 + M(C'[\mathbf{r}]) + P(C'[\mathbf{r}])$, which, by the induction hypothesis, is equal to $1 + M(C'[\mathbf{s}]) + P(C'[\mathbf{r}])$, and this, by Lemma 2.2, is equal to $1 + M(C'[\mathbf{s}]) + P(C'[\mathbf{s}]) = M(C[\mathbf{s}])$. \square

Lemma 2.4. *For any term \mathbf{r} , the set $\{\mathbf{s} \mid \mathbf{s} \rightleftharpoons^* \mathbf{r}\}$ is finite (modulo α -equivalence).*

Proof. As $\{\mathbf{s} \mid \mathbf{s} \rightleftharpoons^* \mathbf{r}\} \subseteq \{\mathbf{s} \mid FV(\mathbf{s}) = FV(\mathbf{r}) \text{ and } M(\mathbf{s}) = M(\mathbf{r})\} \subseteq \{\mathbf{s} \mid FV(\mathbf{s}) \subseteq FV(\mathbf{r}) \text{ and } M(\mathbf{s}) \leq M(\mathbf{r})\}$ all we need to prove is that for all natural numbers n , for all finite sets of variables F , the set $H(n, F) = \{\mathbf{s} \mid FV(\mathbf{s}) \subseteq F \text{ and } M(\mathbf{s}) \leq n\}$ is finite.

We first prove by induction on \mathbf{s} that $M(\mathbf{s}) \geq 1$ and then the property by induction on n . For $n = 1$ the set $\{\mathbf{s} \mid FV(\mathbf{s}) \subseteq F \text{ and } M(\mathbf{s}) \leq 1\}$ contains only the variables of F . Assume the property is proved for n then $H(n + 1, F)$ is a subset of the finite set containing the variables of F , the abstractions $(\lambda x^A.\mathbf{r})$ for \mathbf{r} in $H(n, F \cup \{x^A\})$, the applications (\mathbf{rs}) for \mathbf{r} and \mathbf{s} in $H(n, F)$, the sums $\mathbf{r} + \mathbf{s}$ for \mathbf{r} and \mathbf{s} in $H(n, F)$, the projections $\pi_A(\mathbf{r})$ for in $H(n, F)$. \square

2.2. Examples

Example 2.5. Let $\mathbf{s} : A$ and $\mathbf{t} : B$. Then $\pi_{B \Rightarrow A}((\lambda x^{A \wedge B}.x)\mathbf{s})\mathbf{t} : A$,

$$\frac{\frac{\frac{\lambda x^{A \wedge B}.x : (A \wedge B) \Rightarrow (A \wedge B)}{\lambda x^{A \wedge B}.x : A \Rightarrow B \Rightarrow (A \wedge B)} \quad (\equiv)}{(\lambda x^{A \wedge B}.x)\mathbf{s} : B \Rightarrow (A \wedge B)} \quad (\Rightarrow_e)}{\frac{(\lambda x^{A \wedge B}.x)\mathbf{s} : (B \Rightarrow A) \wedge (B \Rightarrow B)}{\pi_{B \Rightarrow A}((\lambda x^{A \wedge B}.x)\mathbf{s}) : B \Rightarrow A} \quad (\wedge_{en})} \quad \mathbf{t} : B \quad (\Rightarrow_e)}{\pi_{B \Rightarrow A}((\lambda x^{A \wedge B}.x)\mathbf{s})\mathbf{t} : A} \quad (\Rightarrow_e)$$

The reduction is as follows:

$$\begin{aligned} \pi_{B \Rightarrow A}((\lambda x^{A \wedge B}.x)\mathbf{s})\mathbf{t} &\rightleftharpoons \pi_A((\lambda x^{A \wedge B}.x)\mathbf{st}) \rightleftharpoons \pi_A((\lambda x^{A \wedge B}.x)(\mathbf{s} + \mathbf{t})) \\ &\hookrightarrow \pi_A(\mathbf{s} + \mathbf{t}) \hookrightarrow \mathbf{s} \end{aligned}$$

Example 2.6. Let $\mathbf{r} : A$, $\mathbf{s} : B$. Then $(\lambda x^A.\lambda y^B.x)(\mathbf{r} + \mathbf{s}) \rightleftharpoons (\lambda x^A.\lambda y^B.x)\mathbf{rs} \hookrightarrow^* \mathbf{r}$. However, if $A \equiv B$, it is also possible to reduce in the following way

$$\begin{aligned} (\lambda x^A.\lambda y^B.x)(\mathbf{r} + \mathbf{s}) &\rightleftharpoons (\lambda x^A.\lambda y^A.x)(\mathbf{r} + \mathbf{s}) \\ &\rightleftharpoons (\lambda x^A.\lambda y^A.x)(\mathbf{s} + \mathbf{r}) \\ &\rightleftharpoons (\lambda x^A.\lambda y^A.x)\mathbf{sr} \\ &\hookrightarrow^* \mathbf{s} \end{aligned}$$

Hence, the encoding of the projector also behaves non-deterministically.

Example 2.7. Let $\mathbf{TF} = \lambda x^A.\lambda y^B.(x + y)$. Then

$$\frac{\frac{\frac{}{x^A : A} \text{ (ax)}}{\frac{}{y^B : B} \text{ (ax)}} \text{ (}\wedge_i\text{)}}{x^A + y^B : A \wedge B} \text{ (}\Rightarrow_i\text{)}}{\frac{\lambda y^B.(x + y) : B \Rightarrow (A \wedge B)}{\mathbf{TF} : A \Rightarrow B \Rightarrow (A \wedge B)} \text{ (}\Rightarrow_i\text{)}} \text{ (}\equiv\text{)}}{\frac{\mathbf{TF} : (A \Rightarrow B \Rightarrow A) \wedge (A \Rightarrow B \Rightarrow B)}{\pi_{A \Rightarrow B \Rightarrow A}(\mathbf{TF}) : A \Rightarrow B \Rightarrow A} \text{ (}\wedge_e\text{)}}$$

Then, if $\mathbf{r} : A$ and $\mathbf{s} : B$, we have $\pi_{A \Rightarrow B \Rightarrow A}(\mathbf{TF})\mathbf{rs} : A$. Notice that

$$\pi_{A \Rightarrow B \Rightarrow A}(\mathbf{TF})\mathbf{rs} \stackrel{\rhd}{\Leftarrow} \pi_{B \Rightarrow A}(\mathbf{TFr})\mathbf{s} \stackrel{\rhd}{\Leftarrow} \pi_A(\mathbf{TFrs}) \hookrightarrow^* \pi_A(\mathbf{r} + \mathbf{s}) \hookrightarrow \mathbf{r}$$

Example 2.8. Let $\mathbf{T} = \lambda x^A.\lambda y^B.x$ and $\mathbf{F} = \lambda x^A.\lambda y^B.y$. Then

$$\frac{\frac{\mathbf{T} : A \Rightarrow B \Rightarrow A \quad \mathbf{F} : A \Rightarrow B \Rightarrow B}{\mathbf{T} + \mathbf{F} : (A \Rightarrow B \Rightarrow A) \wedge (A \Rightarrow B \Rightarrow B)} \text{ (}\wedge_i\text{)}}{\mathbf{T} + \mathbf{F} + \mathbf{TF} : ((A \Rightarrow B \Rightarrow A) \wedge (A \Rightarrow B \Rightarrow B)) \wedge ((A \Rightarrow B \Rightarrow A) \wedge (A \Rightarrow B \Rightarrow B))} \text{ (}\wedge_i\text{)}$$

Hence $\pi_{(A \Rightarrow B \Rightarrow A) \wedge (A \Rightarrow B \Rightarrow B)}(\mathbf{T} + \mathbf{F} + \mathbf{TF})$ is well typed and reduces non-deterministically either to $\mathbf{T} + \mathbf{F}$ or to \mathbf{TF} . Moreover, notice that $\mathbf{T} + \mathbf{F}$ and \mathbf{TF} are observationally equivalent, that is, $(\mathbf{T} + \mathbf{F})\mathbf{rs}$ and \mathbf{TFrs} both reduce to the same term $(\mathbf{r} + \mathbf{s})$. Hence in this very particular case, the non-deterministic choice does not play any role. We will come back to the encoding of booleans on this calculus on Section 4.3.

Example 2.9. Let $\mathbf{r} : C$. Then

$$\lambda x^{(A \wedge B) \Rightarrow A}.\lambda y^{(A \wedge B) \Rightarrow B}.\mathbf{r} : ((A \wedge B) \Rightarrow A) \Rightarrow ((A \wedge B) \Rightarrow B) \Rightarrow C$$

and since $((A \wedge B) \Rightarrow A) \Rightarrow ((A \wedge B) \Rightarrow B) \Rightarrow C \equiv ((A \wedge B) \Rightarrow (A \wedge B)) \Rightarrow C$, we also can derive

$$\lambda x^{(A \wedge B) \Rightarrow A}.\lambda y^{(A \wedge B) \Rightarrow B}.\mathbf{r} : ((A \wedge B) \Rightarrow (A \wedge B)) \Rightarrow C$$

Hence,

$$(\lambda x^{(A \wedge B) \Rightarrow A}.\lambda y^{(A \wedge B) \Rightarrow B}.\mathbf{r})(\lambda z^{A \wedge B}.z) : C$$

The reduction is as follows:

$$\begin{aligned} & (\lambda x^{(A \wedge B) \Rightarrow A}.\lambda y^{(A \wedge B) \Rightarrow B}.\mathbf{t})(\lambda z^{A \wedge B}) \\ & \hookrightarrow (\lambda x^{(A \wedge B) \Rightarrow A}.\lambda y^{(A \wedge B) \Rightarrow B}.\mathbf{t}) (\pi_{(A \wedge B) \Rightarrow A}(\lambda z^{A \wedge B}) + \pi_{(A \wedge B) \Rightarrow B}(\lambda z^{A \wedge B})) \\ & \stackrel{\rhd}{\Leftarrow} \left((\lambda x^{(A \wedge B) \Rightarrow A}.\lambda y^{(A \wedge B) \Rightarrow B}.\mathbf{t})\pi_{(A \wedge B) \Rightarrow A}(\lambda z^{A \wedge B}) \right) \pi_{(A \wedge B) \Rightarrow B}(\lambda z^{A \wedge B}) \\ & \hookrightarrow^* \mathbf{t}[\pi_{(A \wedge B) \Rightarrow A}(\lambda z^{A \wedge B})/x][\pi_{(A \wedge B) \Rightarrow B}(\lambda z^{A \wedge B})/y] \end{aligned}$$

Example 2.10. Let $\mathbf{r} : C$. Then

$$\frac{\frac{\frac{x^{A \wedge B} : A \wedge B}{\lambda x^{A \wedge B}.x : (A \wedge B) \Rightarrow (A \wedge B)}^{(ax)} \quad \mathbf{r} : C}{(\lambda x^{A \wedge B}.x) + \mathbf{r} : (A \wedge B) \Rightarrow (A \wedge B) \wedge C}^{(\Rightarrow_i)} \quad (\wedge_i)}{\frac{(\lambda x^{A \wedge B}.x) + \mathbf{r} : ((A \wedge B) \Rightarrow A) \wedge C \wedge (A \wedge B) \Rightarrow B}{\pi_{((A \wedge B) \Rightarrow A) \wedge C}((\lambda x^{A \wedge B}.x) + \mathbf{r}) : ((A \wedge B) \Rightarrow A) \wedge C}}^{(\equiv)} \quad (\wedge_e)}$$

The reduction is as follows:

$$\begin{aligned} \pi_{((A \wedge B) \Rightarrow A) \wedge C}((\lambda x^{A \wedge B}.x) + \mathbf{r}) &\stackrel{\rightrightarrows}{=} \pi_{(A \wedge B) \Rightarrow A}(\lambda x^{A \wedge B}.x) + \pi_C(\mathbf{r}) \\ &\hookrightarrow \pi_{(A \wedge B) \Rightarrow A}(\lambda x^{A \wedge B}.x) + \mathbf{r} \\ &\stackrel{\rightrightarrows}{=} (\lambda x^{A \wedge B}.\pi_A(x)) + \mathbf{r} \end{aligned}$$

2.3. Subject Reduction

Our system has the subject reduction property, that is, the set of types assigned to a term is invariant under $\stackrel{\rightrightarrows}{=}$ and \hookrightarrow . Before proving subject reduction, we need the following results.

Lemma 2.11 (Generation Lemmas).

1. If $x^A : B$, then $A \equiv B$.
2. If $\lambda x^A.\mathbf{r} : B$, then $B \equiv A \Rightarrow C$, $\mathbf{r} : C$ and $(V(\mathbf{r}) \cup \{x^A\})^f$.
3. If $\mathbf{r}\mathbf{s} : B$, then $\mathbf{r} : A \Rightarrow B$ and $\mathbf{s} : A$.
4. If $\mathbf{r} + \mathbf{s} : A$, then $A \equiv B \wedge C$ with $\mathbf{r} : B$ and $\mathbf{s} : C$.
5. If $\pi_A(\mathbf{r}) : B$, then $A \equiv B$ and $(\mathbf{r} : B \text{ or } \mathbf{r} : B \wedge C)$.

Proof. The proof follows by a straightforward induction on the typing derivation. To notice that such an induction is straightforward, it suffices to realize that the only typing rule not changing the term, is (\equiv) . For example, if $\lambda x^A.\mathbf{r} : B$, then the only way to type this term is either by rule (\Rightarrow_i) , and so $B = A \Rightarrow C$ for some, C , $\mathbf{r} : C$ and $(V(\mathbf{r}) \cup \{x^A\})^f$, or by rule (\equiv) , and so the induction hypothesis applies and $B \equiv A \Rightarrow C$. \square

In the remaining of this paper, we may use Lemma 2.11 implicitly.

Lemma 2.12 (Substitution Lemma). *If $\mathbf{r} : A$, $\mathbf{s} : B$ and $(V(\mathbf{r}) \cup \{x^B\})^f$, then $\mathbf{r}[s/x^B] : A$*

Proof. We proceed by structural induction on \mathbf{r} .

- Let $\mathbf{r} = x^A$. Since $(V(x^A) \cup \{x^B\})^f$ implies $A = B$, we have $\mathbf{s} : A$. Notice that $x^A[s/x^A] = \mathbf{s}$, so $x^A[s/x^B] : A$.
- Let $\mathbf{r} = y^A$, with $y \neq x$. Notice that $y^A[s/x^B] = y^A$, so $y^A[s/x^B] : A$.

- Let $\mathbf{r} = \lambda y^C . \mathbf{r}'$. Then $A \equiv C \Rightarrow D$, with $\mathbf{r}' : D$. By the induction hypothesis $\mathbf{r}'[\mathbf{s}/x^B] : D$, and so, by rule (\Rightarrow_i) , $\lambda y^C . \mathbf{r}'[\mathbf{s}/x^B] : C \Rightarrow D$. Since $\lambda y^C . \mathbf{r}'[\mathbf{s}/x^B] = (\lambda y^A . \mathbf{r}')[\mathbf{s}/x^B]$, using rule (\equiv) , $(\lambda y^C . \mathbf{r}')[\mathbf{s}/x^B] : A$.
- Let $\mathbf{r} = \mathbf{r}_1 \mathbf{r}_2$. Then $\mathbf{r}_1 : C \Rightarrow A$ and $\mathbf{r}_2 : C$. By the induction hypothesis $\mathbf{r}_1[\mathbf{s}/x^B] : C \Rightarrow A$ and $\mathbf{r}_2[\mathbf{s}/x^B] : C$, and so, by rule (\Rightarrow_e) , $(\mathbf{r}_1[\mathbf{s}/x^B])(\mathbf{r}_2[\mathbf{s}/x^B]) : A$. Since $(\mathbf{r}_1[\mathbf{s}/x^B])(\mathbf{r}_2[\mathbf{s}/x^B]) = (\mathbf{r}_1 \mathbf{r}_2)[\mathbf{s}/x^B]$, we have $(\mathbf{r}_1 \mathbf{r}_2)[\mathbf{s}/x^B] : A$.
- Let $\mathbf{r} = \mathbf{r}_1 + \mathbf{r}_2$. Then $\mathbf{r}_1 : A_1$ and $\mathbf{r}_2 : A_2$, with $A \equiv A_1 \wedge A_2$. By the induction hypothesis $\mathbf{r}_1[\mathbf{s}/x^B] : A_1$ and $\mathbf{r}_2[\mathbf{s}/x^B] : A_2$, and so, by rule (\wedge_i) , $(\mathbf{r}_1[\mathbf{s}/x^B]) + (\mathbf{r}_2[\mathbf{s}/x^B]) : A_1 \wedge A_2$. Since $(\mathbf{r}_1[\mathbf{s}/x^B]) + (\mathbf{r}_2[\mathbf{s}/x^B]) = (\mathbf{r}_1 + \mathbf{r}_2)[\mathbf{s}/x^B]$, using rule (\equiv) , we have $(\mathbf{r}_1 + \mathbf{r}_2)[\mathbf{s}/x^B] : A$.
- Let $\mathbf{r} = \pi_A(\mathbf{r}')$. Then either $\mathbf{r}' : A$, or $\mathbf{r}' : A \wedge C$. By the induction hypothesis, either $\mathbf{r}'[\mathbf{s}/x^B] : A$ or $\mathbf{r}'[\mathbf{s}/x^B] : A \wedge C$. In any case, either by rule \wedge_{e_1} or \wedge_{e_n} , $\pi_A(\mathbf{r}'[\mathbf{s}/x^B]) : A$. Since $\pi_A(\mathbf{r}'[\mathbf{s}/x^B]) = \pi_A(\mathbf{r}')[\mathbf{s}/x^B]$, we have $\pi_A(\mathbf{r}')[\mathbf{s}/x^B] : A$. \square

Theorem 2.13 (Subject reduction). *If $\mathbf{r} : A$ and $\mathbf{r} \hookrightarrow \mathbf{s}$ or $\mathbf{r} \rightleftharpoons \mathbf{s}$ then $\mathbf{s} : A$.*

Proof. We proceed by induction on the rewrite relation.

$\mathbf{r} + \mathbf{s} \rightleftharpoons \mathbf{s} + \mathbf{r}$: If $\mathbf{r} + \mathbf{s} : A$, then $A \equiv A_1 \wedge A_2 \equiv A_2 \wedge A_1$, with $\mathbf{r} : A_1$ and $\mathbf{s} : A_2$.

Then,

$$\frac{\frac{\mathbf{s} : A_2 \quad \mathbf{r} : A_1}{\mathbf{s} + \mathbf{r} : A_2 \wedge A_1} (\wedge_i)}{\mathbf{s} + \mathbf{r} : A} (\equiv)$$

$(\mathbf{r} + \mathbf{s}) + \mathbf{t} \rightleftharpoons \mathbf{r} + (\mathbf{s} + \mathbf{t})$:

(\rightarrow) If $(\mathbf{r} + \mathbf{s}) + \mathbf{t} : A$, then $A \equiv (A_1 \wedge A_2) \wedge A_3 \equiv A_1 \wedge (A_2 \wedge A_3)$, with $\mathbf{r} : A_1$, $\mathbf{s} : A_2$ and $\mathbf{t} : A_3$. Then,

$$\frac{\frac{\frac{\mathbf{s} : A_2 \quad \mathbf{t} : A_3}{\mathbf{s} + \mathbf{t} : A_2 \wedge A_3} (\wedge_i)}{\mathbf{r} : A_1 \quad \mathbf{s} + \mathbf{t} : A_2 \wedge A_3} (\wedge_i)}{\mathbf{r} + (\mathbf{s} + \mathbf{t}) : A_1 \wedge (A_2 \wedge A_3)} (\wedge_i)}{\mathbf{r} + (\mathbf{s} + \mathbf{t}) : A} (\equiv)$$

(\leftarrow) Analogous to (\rightarrow) .

$\lambda x^B . (\mathbf{r} + \mathbf{s}) \rightleftharpoons \lambda x^B . \mathbf{r} + \lambda x^B . \mathbf{s}$:

(\rightarrow) If $\lambda x^B . (\mathbf{r} + \mathbf{s}) : A$, then $A \equiv B \Rightarrow (C_1 \wedge C_2) \equiv (B \Rightarrow C_1) \wedge (B \Rightarrow C_2)$, with $\mathbf{r} : C_1$ and $\mathbf{s} : C_2$. Then,

$$\frac{\frac{\frac{\mathbf{r} : C_1}{\lambda x^B . \mathbf{r} : B \Rightarrow C_1} (\Rightarrow_i) \quad \frac{\mathbf{s} : C_2}{\lambda x^B . \mathbf{s} : B \Rightarrow C_2} (\Rightarrow_i)}{\lambda x^B . \mathbf{r} + \lambda x^B . \mathbf{s} : (B \Rightarrow C_1) \wedge (B \Rightarrow C_2)} (\wedge_i)}{\lambda x^B . \mathbf{r} + \lambda x^B . \mathbf{s} : A} (\equiv)$$

(\leftarrow) If $\lambda x^B.\mathbf{r} + \lambda x^B.\mathbf{s} : A$, then $A \equiv (B \Rightarrow C_1) \wedge (B \Rightarrow C_2) \equiv B \Rightarrow (C_1 \wedge C_2)$, with $\mathbf{r} : C_1$ and $\mathbf{s} : C_2$. Then,

$$\frac{\frac{\mathbf{r} : C_1 \quad \mathbf{s} : C_2}{\mathbf{r} + \mathbf{s} : C_1 \wedge C_2} \wedge_i}{\frac{\lambda x^B.(\mathbf{r} + \mathbf{s}) : B \Rightarrow (C_1 \wedge C_2)}{\lambda x^B.(\mathbf{r} + \mathbf{s}) : A} \begin{matrix} (\Rightarrow_i) \\ (\equiv) \end{matrix}}$$

$(\mathbf{r} + \mathbf{s})\mathbf{t} \rightleftharpoons \mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t}$:

(\rightarrow) If $(\mathbf{r} + \mathbf{s})\mathbf{t} : A$, then $\mathbf{r} + \mathbf{s} : B \Rightarrow A$, and $\mathbf{t} : B$. Hence $A \equiv A_1 \wedge A_2$, with $\mathbf{r} : B \Rightarrow A_1$ and $\mathbf{s} : B \Rightarrow A_2$. Then,

$$\frac{\frac{\mathbf{r} : B \Rightarrow A_1 \quad \mathbf{t} : B}{\mathbf{r}\mathbf{t} : A_1} \begin{matrix} (\Rightarrow_e) \\ (\equiv) \end{matrix} \quad \frac{\mathbf{s} : B \Rightarrow A_2 \quad \mathbf{t} : B}{\mathbf{s}\mathbf{t} : A_2} \begin{matrix} (\Rightarrow_e) \\ (\equiv) \end{matrix}}{\frac{\mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t} : A_1 \wedge A_2}{\mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t} : A} \begin{matrix} (\wedge_i) \\ (\equiv) \end{matrix}}$$

(\leftarrow) If $\mathbf{r}\mathbf{t} + \mathbf{s}\mathbf{t} : A$, then $A \equiv A_1 \wedge A_2$ with $\mathbf{r} : B \Rightarrow A_1$, $\mathbf{s} : B' \Rightarrow A_2$, $\mathbf{t} : B$ and $\mathbf{t} : B'$. By Lemma 2.1, $B \equiv B'$. Then

$$\frac{\frac{\frac{\mathbf{r} : B \Rightarrow A_1 \quad \mathbf{s} : B' \Rightarrow A_2}{\mathbf{r} + \mathbf{s} : (B \Rightarrow A_1) \wedge (B \Rightarrow A_2)} \begin{matrix} (\wedge_i) \\ (\equiv) \end{matrix}}{\mathbf{r} + \mathbf{s} : B \Rightarrow (A_1 \wedge A_2)} \begin{matrix} (\equiv) \\ (\equiv) \end{matrix} \quad \mathbf{t} : B}{\frac{(\mathbf{r} + \mathbf{s})\mathbf{t} : A_1 \wedge A_2}{(\mathbf{r} + \mathbf{s})\mathbf{t} : A} \begin{matrix} (\Rightarrow_e) \\ (\equiv) \end{matrix}}$$

$\pi_{B \Rightarrow C}(\lambda x^B.\mathbf{r}) \rightleftharpoons \lambda x^B.\pi_C(\mathbf{r})$:

(\rightarrow) If $\pi_{B \Rightarrow C}(\lambda x^B.\mathbf{r}) : A$, then $A \equiv B \Rightarrow C$ and either $\lambda x^B.\mathbf{r} : B \Rightarrow (C \wedge D)$ or $\lambda x^B.\mathbf{r} : C \Rightarrow D$. Hence either $\mathbf{r} : C \wedge D$, or $\mathbf{r} : C$. In any case, either by rule (\wedge_{e1}) or (\wedge_{e_n}) , $\pi_C(\mathbf{r}) : C$, so

$$\frac{\pi_C(\mathbf{r}) : C}{\frac{\lambda x^B.\pi_C(\mathbf{r}) : B \Rightarrow C}{\lambda x^B.\pi_C(\mathbf{r}) : A} \begin{matrix} (\Rightarrow_i) \\ (\equiv) \end{matrix}}$$

(\leftarrow) If $\lambda x^B.\pi_C(\mathbf{r}) : A$, then $A \equiv B \Rightarrow C$ and $\pi_C(\mathbf{r}) : C$, so either $\mathbf{r} : C \wedge D$ or $\mathbf{r} : C$. Hence, either

$$\frac{\frac{\frac{\mathbf{r} : C \wedge D}{\lambda x^B.\mathbf{r} : B \Rightarrow (C \wedge D)}{\lambda x^B.\mathbf{r} : (B \Rightarrow C) \wedge (B \Rightarrow D)} \begin{matrix} (\equiv) \\ (\Rightarrow_i) \\ (\wedge_e) \end{matrix}}{\pi_{B \Rightarrow C}(\lambda x^B.\mathbf{r}) : B \Rightarrow C} \begin{matrix} (\equiv) \\ (\equiv) \end{matrix}}{\pi_{B \Rightarrow C}(\lambda x^B.\mathbf{r}) : A} \begin{matrix} (\equiv) \\ (\equiv) \end{matrix} \quad \text{or} \quad \frac{\frac{\mathbf{r} : C}{\lambda x^B.\mathbf{r} : B \Rightarrow C} \begin{matrix} (\Rightarrow_i) \\ (\wedge_e) \end{matrix}}{\pi_{B \Rightarrow C}(\lambda x^B.\mathbf{r}) : B \Rightarrow C} \begin{matrix} (\equiv) \\ (\equiv) \end{matrix}}$$

$\pi_{B \Rightarrow C}(\mathbf{r})\mathbf{s} \Leftrightarrow \pi_C(\mathbf{r}\mathbf{s})$ **with** $\mathbf{r} : B \Rightarrow (C \wedge D)$: Then $\mathbf{s} : B$.

(\rightarrow) If $\pi_{B \Rightarrow C}(\mathbf{r})\mathbf{s} : A$, then $A \equiv C$.

$$\frac{\frac{\mathbf{r} : B \Rightarrow (C \wedge D) \quad \mathbf{s} : B}{\mathbf{r}\mathbf{s} : C \wedge D} (\Rightarrow_e)}{\frac{\pi_C(\mathbf{r}\mathbf{s}) : C}{\pi_C(\mathbf{r}\mathbf{s}) : A} (\equiv)} (\wedge_{en})$$

(\leftarrow) If $\pi_C(\mathbf{r}\mathbf{s}) : A$, then $A \equiv C$.

$$\frac{\frac{\frac{\mathbf{r} : B \Rightarrow (C \wedge D)}{\mathbf{r} : (B \Rightarrow C) \wedge (B \Rightarrow D)} (\equiv)}{\pi_{B \Rightarrow C}(\mathbf{r}) : B \Rightarrow C} (\wedge_e)}{\frac{\pi_{B \Rightarrow C}(\mathbf{r})\mathbf{s} : C}{\pi_{B \Rightarrow C}(\mathbf{r})\mathbf{s} : A} (\equiv)} (\Rightarrow_e) \quad \mathbf{s} : B$$

$\mathbf{r}\mathbf{s}\mathbf{t} \Leftrightarrow \mathbf{r}(\mathbf{s} + \mathbf{t})$:

(\rightarrow) If $\mathbf{r}\mathbf{s}\mathbf{t} : A$, then $\mathbf{r} : B \Rightarrow C \Rightarrow A \equiv (B \wedge C) \Rightarrow A$, $\mathbf{s} : B$ and $\mathbf{t} : C$.

Then,

$$\frac{\frac{\mathbf{r} : B \Rightarrow C \Rightarrow A}{\mathbf{r} : (B \wedge C) \Rightarrow A} (\equiv) \quad \frac{\mathbf{s} : B \quad \mathbf{t} : C}{\mathbf{s} + \mathbf{t} : B \wedge C} (\wedge_i)}{\mathbf{r}(\mathbf{s} + \mathbf{t}) : A} (\Rightarrow_e)$$

(\leftarrow) If $\mathbf{r}(\mathbf{s} + \mathbf{t}) : A$, then $\mathbf{r} : (B \wedge C) \Rightarrow A \equiv B \Rightarrow C \Rightarrow A$, $\mathbf{s} : B$ and $\mathbf{t} : C$.

Then

$$\frac{\frac{\mathbf{r} : (B \wedge C) \Rightarrow A}{\mathbf{r} : B \Rightarrow C \Rightarrow A} (\equiv)}{\frac{\mathbf{r}\mathbf{s} : C \Rightarrow A}{\mathbf{r}\mathbf{s}\mathbf{t} : A} (\Rightarrow_e)} (\Rightarrow_e) \quad \mathbf{s} : B \quad \mathbf{t} : C$$

$\mathbf{r} \Leftrightarrow \mathbf{r}[B/C]$ **with** $B \equiv C$: If $\mathbf{r} : A$, since $A \equiv A[B/C]$, a straightforward induction on \mathbf{r} allows to prove $\mathbf{r}[B/C] : A$.

$\pi_{B \wedge D}(\mathbf{r} + \mathbf{s}) \Leftrightarrow \pi_B(\mathbf{r}) + \pi_D(\mathbf{s})$ **with** $\mathbf{r} : B \wedge C$ **and** $\mathbf{s} : D \wedge E$:

(\rightarrow) If $\pi_{B \wedge D}(\mathbf{r} + \mathbf{s}) : A$ then $A \equiv B \wedge D$. Then

$$\frac{\frac{\frac{\mathbf{r} : B \wedge C}{\pi_B(\mathbf{r}) : B} (\wedge_e) \quad \frac{\mathbf{s} : D \wedge E}{\pi_D(\mathbf{s}) : D} (\wedge_e)}{\pi_B(\mathbf{r}) + \pi_D(\mathbf{s}) : B \wedge D} (\wedge_i)}{\pi_B(\mathbf{r}) + \pi_D(\mathbf{s}) : A} (\equiv)$$

(\leftarrow) If $\pi_B(\mathbf{r}) + \pi_D(\mathbf{s}) : A$, then $A \equiv B \wedge D$. Then

$$\frac{\frac{\frac{\mathbf{r} : B \wedge C \quad \mathbf{s} : D \wedge E}{\mathbf{r} + \mathbf{s} : (B \wedge C) \wedge (D \wedge E)} (\wedge_i)}{\mathbf{r} + \mathbf{s} : (B \wedge D) \wedge (C \wedge E)} (\equiv)}{\pi_{B \wedge D}(\mathbf{r} + \mathbf{s}) : B \wedge D} (\wedge_e)}{\pi_{B \wedge D}(\mathbf{r} + \mathbf{s}) : A} (\equiv)$$

$(\lambda x^B.\mathbf{r})\mathbf{s} \hookrightarrow \mathbf{r}[\mathbf{s}/x]$ **with** $\mathbf{s} : B$: If $(\lambda x^B.\mathbf{r})\mathbf{s} : A$, then $\lambda x^B.\mathbf{r} : B \Rightarrow A$ and $\mathbf{s} : B$, and so $\mathbf{r} : A$ and $(V(\mathbf{r}) \cup \{x^B\})^f$. Then by Lemma 2.12, $\mathbf{r}[\mathbf{s}/x^B] : A$.

$\pi_B(\mathbf{r} + \mathbf{s}) \hookrightarrow \mathbf{r}$ **with** $\mathbf{r} : B$: If $\pi_B(\mathbf{r} + \mathbf{s}) : A$, then $A \equiv B$, and so, by rule (\equiv) , $\mathbf{r} : A$.

$\pi_B(\mathbf{r}) \hookrightarrow \mathbf{r}$ **with** $\mathbf{r} : B$: If $\pi_B(\mathbf{r}) : A$, then $A \equiv B$, and so, by rule (\equiv) , $\mathbf{r} : A$.

$\mathbf{r} \hookrightarrow \pi_B(\mathbf{r}) + \pi_C(\mathbf{r})$ **with** $\mathbf{r} \not\equiv^* \mathbf{r}_1 + \mathbf{r}_2$ **and** $\mathbf{r} : B \wedge C$: If $\mathbf{r} : A$ then $A \equiv B \wedge C$.

Then

$$\frac{\frac{\frac{\mathbf{r} : B \wedge C}{\pi_B(\mathbf{r}) : B} (\wedge_e) \quad \frac{\mathbf{r} : B \wedge C}{\pi_B(\mathbf{r}) : B} (\wedge_e)}{\pi_B(\mathbf{r}) + \pi_C(\mathbf{r}) : B \wedge C} (\wedge_i)}{\pi_B(\mathbf{r}) + \pi_C(\mathbf{r}) : A} (\equiv)$$

Contextual cases Let $\mathbf{t} \rightarrow \mathbf{r}$, where \rightarrow is either \rightleftharpoons or \hookrightarrow .

$\lambda x^B.\mathbf{t} \rightarrow \lambda x^B.\mathbf{r}$ If $\lambda x^B.\mathbf{t} : A$, then $A \equiv B \Rightarrow C$ and $\mathbf{t} : C$, hence by the induction hypothesis, $\mathbf{r} : C$ and so $\lambda x^B.\mathbf{r} : B \Rightarrow C \equiv A$.

$\mathbf{t}\mathbf{s} \rightarrow \mathbf{r}\mathbf{s}$ If $\mathbf{t}\mathbf{s} : A$ then $\mathbf{t} : B \Rightarrow A$ and $\mathbf{s} : B$, hence by the induction hypothesis, $\mathbf{r} : B \Rightarrow A$ and so $\mathbf{r}\mathbf{s} : A$.

$\mathbf{st} \rightarrow \mathbf{st}$ If $\mathbf{st} : A$ then $\mathbf{s} : B \Rightarrow A$ and $\mathbf{t} : B$, hence by the induction hypothesis $\mathbf{r} : B$ and so $\mathbf{sr} : A$.

$\mathbf{t} + \mathbf{s} \rightarrow \mathbf{r} + \mathbf{s}$ If $\mathbf{t} + \mathbf{s} : A$ then $A \equiv A_1 \wedge A_2$ where $\mathbf{t} : A_1$ and $\mathbf{s} : A_2$, hence by the induction hypothesis, $\mathbf{r} : A_1$ and so $\mathbf{r} + \mathbf{s} : A_1 \wedge A_2 \equiv A$.

$\mathbf{s} + \mathbf{t} \rightarrow \mathbf{s} + \mathbf{r}$ Analogous to previous case.

$\pi_B(\mathbf{t}) \rightarrow \pi_B(\mathbf{r})$ If $\pi_B(\mathbf{t}) : A$ then $A \equiv B$ and $\mathbf{t} : B \wedge C$ or $\mathbf{t} : B$, hence by the induction hypothesis $\mathbf{r} : B \wedge C$ or $\mathbf{r} : B$, in any case, $\pi_B(\mathbf{r}) : B \equiv A$. \square

3. Strong Normalisation and Normal Forms

3.1. Strong Normalisation

Now we prove the strong normalisation property. In our setting, strong normalisation means that every reduction sequence fired from a typed term eventually terminates in a term in *normal form* modulo \rightleftharpoons^* . In other words, no \hookrightarrow reduction can be fired from it, even after \rightleftharpoons steps. Formally, we define $\text{Red}(\mathbf{r}) = \{\mathbf{s} \mid \mathbf{r} \rightsquigarrow \mathbf{s}\}$. Hence, a term \mathbf{r} is in normal form if $\text{Red}(\mathbf{r}) = \emptyset$. When \mathbf{r} is strongly normalising, we write $(\mathbf{r})\zeta$ for the maximum number of \rightsquigarrow -steps needed to get a normal form of \mathbf{r} . We denote by SN the set of strongly normalising terms.

We use the notation $\overline{(A_i)_{i=1}^n} \Rightarrow B$ for $A_1 \Rightarrow \dots \Rightarrow A_n \Rightarrow B$, with the convention that $\overline{(A_i)_{i=1}^0} \Rightarrow B = B$. In addition, we write $\vec{\mathbf{s}}$ for $\mathbf{s}_1 \dots \mathbf{s}_n$.

The normalisation proof is based in the representation lemma for types (Lemma 3.4), for which we define conjunction-free types as follows.

Definition 3.1. A conjunction-free type is a type without conjunctions, which can be produced by the following grammar:

$$S, R, T ::= \tau \mid S \Rightarrow R$$

The canonical form of a type, written $\text{can}(A)$, is a conjunction of conjunction-free types, and it is defined inductively by

$$\begin{aligned} \text{can}(\tau) &= \tau & \text{can}(A \Rightarrow B) &= \text{let } \bigwedge_{i=1}^n S_i = \text{can}(A) \text{ in} \\ & & & \text{let } \bigwedge_{j=1}^m R_j = \text{can}(B) \text{ in} \\ \text{can}(A \wedge B) &= \text{can}(A) \wedge \text{can}(B) & & \bigwedge_{j=1}^m \left(\overline{(S_i)_{i=1}^n} \Rightarrow R_j \right) \end{aligned}$$

Example 3.2. $\text{can}((S_1 \wedge S_2) \Rightarrow (R_1 \wedge R_2)) = (S_1 \Rightarrow S_2 \Rightarrow R_1) \wedge (S_1 \Rightarrow S_2 \Rightarrow R_2)$

Lemma 3.3. For any A , $A \equiv \text{can}(A)$.

Proof. We proceed by structural induction on A .

- Let $A = \tau$. Then $A = \text{can}(A)$.
- Let $A = B \wedge C$. By the induction hypothesis $B \equiv \text{can}(B)$ and $C \equiv \text{can}(C)$, hence $A \equiv \text{can}(B) \wedge \text{can}(C) = \text{can}(B \wedge C) = \text{can}(A)$.
- Let $A = B \Rightarrow C$. By the induction hypothesis $B \equiv \bigwedge_{i=1}^n S_i$ and $C \equiv \bigwedge_{j=1}^m R_j$, so $A \equiv (\bigwedge_{i=1}^n S_i) \Rightarrow (\bigwedge_{j=1}^m R_j) \equiv \bigwedge_{j=1}^m (\bigwedge_{i=1}^n S_i) \Rightarrow R_j$ which is finally equivalent to $\bigwedge_{j=1}^m \overline{(S_i)_{i=1}^n} \Rightarrow R_j$. \square

Lemma 3.4. For any A , $\text{can}(A) = \bigwedge_{i=1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$, with $n \geq 1$ and $\forall i, m_i \geq 0$.

Proof. We proceed by structural induction on A .

- $A = \tau$. Then take $n = 1$ and $m_1 = 0$.
- $A = B \wedge C$. By the induction hypothesis $\text{can}(B) = \bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$ and $\text{can}(C) = \bigwedge_{i=k+1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$, so $\text{can}(B \wedge C) = \text{can}(B) \wedge \text{can}(C) = \bigwedge_{i=1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$.
- $A = B \Rightarrow C$. By the induction hypothesis $\text{can}(B) = \bigwedge_{i=1}^n \overline{(S_{ik})_{k=1}^{m_i}} \Rightarrow \tau$ and $\text{can}(C) = \bigwedge_{j=1}^o \overline{(R_{ji})_{i=1}^{p_j}} \Rightarrow \tau$. Then we have that $\text{can}(B \Rightarrow C) = \bigwedge_{j=1}^o \overline{(\overline{(S_{ik})_{k=1}^{m_i}} \Rightarrow \tau)_{i=1}^n} \Rightarrow \overline{(R_{ji})_{i=1}^{p_j}} \Rightarrow \tau = \bigwedge_{j=1}^o \overline{(T_{ji})_{i=1}^{n+p_j}} \Rightarrow \tau$, with $T_{ji} = \overline{(S_{ik})_{k=1}^{m_i}} \Rightarrow \tau$ if $i \leq n$, and $T_{ji} = R_{j(i-n)}$ if $i > n$. \square

Definition 3.5. The interpretation of canonical types is given by

$$\left[\left[\bigwedge_{i=1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau \right] \right] = \left\{ \mathbf{r} \mid \forall i, \left[\begin{array}{l} \mathbf{s}_{ij} \in \llbracket S_{ij} \rrbracket \\ j = 1, \dots, m_i \end{array} \right] \text{ implies } \pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\mathbf{r}) \vec{s}_i \in \text{SN} \right\}$$

where $n \geq 1$, and $m \geq 0$.

The interpretation of a general type A is defined by $\llbracket \text{can}(A) \rrbracket$.

In order to prove that equivalent types have the same interpretation (Corollary 3.10), we need first the following intermediate results.

Definition 3.6. Let $\text{can}^{lo}(A)$ be defined in a similar way than $\text{can}(A)$ but where each time there is a conjunction, it is taken in quasi-lexicographic order (that is, strings are ordered firstly by length, and then lexicographically), and with the parenthesis associated to the right.

Example 3.7. Let $S_1 \leq S_2 \leq S_3$ and $R_1 \leq R_2$.

- $\text{can}^{lo}((\tau \Rightarrow \tau) \wedge \tau) = \tau \wedge (\tau \Rightarrow \tau)$.
- $\text{can}^{lo}(\bigwedge_{i=1}^3 S_i) = S_1 \wedge (S_2 \wedge S_3)$.
- $\text{can}^{lo}((S_2 \wedge S_3) \wedge S_1) = S_1 \wedge (S_2 \wedge S_3)$.
- $\text{can}^{lo}((S_2 \wedge S_1) \Rightarrow R) = S_1 \Rightarrow S_2 \Rightarrow R$.
- $\text{can}^{lo}((S_2 \wedge S_1) \Rightarrow (R_1 \wedge R_2)) = (S_1 \Rightarrow S_2 \Rightarrow R_1) \wedge (S_1 \Rightarrow S_2 \Rightarrow R_2)$.

Lemma 3.8. *If $A \equiv B$, then $\text{can}^{lo}(A) = \text{can}^{lo}(B)$.*

Proof. By induction on the equivalence relation.

- $A \wedge B \equiv B \wedge A$. Let $\text{can}^{lo}(A)$ be equal to $\text{can}^{lo}(\bigwedge_{i=1}^n S_i)$ and $\text{can}^{lo}(B)$ equal to $\text{can}^{lo}(\bigwedge_{j=1}^m R_j)$. Then $\text{can}^{lo}(A \wedge B) = \text{can}^{lo}((\bigwedge_{i=1}^n S_i) \wedge (\bigwedge_{j=1}^m R_j)) = \text{can}^{lo}(B \wedge A)$.
- $(A \wedge B) \wedge C \equiv A \wedge (B \wedge C)$. Analogous to the previous case.
- $A \Rightarrow (B \wedge C) \equiv (A \Rightarrow B) \wedge (A \Rightarrow C)$. Let $\text{can}^{lo}(A) = \text{can}^{lo}(\bigwedge_{i=1}^n S_i)$, $\text{can}^{lo}(B) = \text{can}^{lo}(\bigwedge_{j=1}^k R_j)$ and $\text{can}^{lo}(C) = \text{can}^{lo}(\bigwedge_{j=k+1}^m R_j)$, so $\text{can}^{lo}(B \wedge C) = \text{can}^{lo}(\bigwedge_{j=1}^m R_j)$. Hence, $\text{can}^{lo}(A \Rightarrow (B \wedge C)) = \text{can}^{lo}(\bigwedge_{j=1}^m \overline{(S_i)}_{i=1}^n \Rightarrow R_j) = \text{can}^{lo}(\text{can}^{lo}(A \Rightarrow B) \wedge \text{can}^{lo}(A \Rightarrow C)) = \text{can}^{lo}((A \Rightarrow B) \wedge (A \Rightarrow C))$.
- $(A \wedge B) \Rightarrow C \equiv A \Rightarrow B \Rightarrow C$. Let $\text{can}^{lo}(A) = \text{can}^{lo}(\bigwedge_{i=1}^k S_i)$, $\text{can}^{lo}(B) = \text{can}^{lo}(\bigwedge_{i=k+1}^n S_i)$ and $\text{can}^{lo}(C) = \text{can}^{lo}(\bigwedge_{j=1}^m R_j)$. Hence, $\text{can}^{lo}((A \wedge B) \Rightarrow C) = \text{can}^{lo}(\bigwedge_{j=1}^m \overline{(S_i)}_{i=1}^n \Rightarrow R_j)$.

On the other hand, $\text{can}^{lo}(B \Rightarrow C) = \text{can}^{lo}(\bigwedge_{j=1}^m \overline{(S_i)}_{i=k+1}^n \Rightarrow R_j)$, so $\text{can}^{lo}(A \Rightarrow B \Rightarrow C) = \text{can}^{lo}(\bigwedge_{j=1}^m \overline{(S_i)}_{i=1}^k \Rightarrow \overline{(S_i)}_{i=k+1}^n \Rightarrow R_j)$, and notice that this is equal to $\text{can}^{lo}(\bigwedge_{j=1}^m \overline{(S_i)}_{i=1}^n \Rightarrow R_j) = \text{can}^{lo}((A \wedge B) \Rightarrow C)$.

- Congruence:
 - Let $A \equiv B$ be a consequence of $A = B$. Trivial case.
 - Let $A \equiv C$ be a consequence of $A \equiv B$ and $B \equiv C$. By the induction hypothesis $\text{can}^{lo}(A) = \text{can}^{lo}(B)$ and $\text{can}^{lo}(B) = \text{can}^{lo}(C)$, hence $\text{can}^{lo}(A) = \text{can}^{lo}(C)$.

- Let $A \Rightarrow C \equiv B \Rightarrow C$ be a consequence of $A \equiv B$. Let $\text{can}^{lo}(A) = \text{can}^{lo}(\bigwedge_{i=1}^n S_i)$, and $\text{can}^{lo}(C) = \text{can}^{lo}(\bigwedge_{j=1}^m R_j)$. Then $\text{can}^{lo}(A \Rightarrow C) = \text{can}^{lo}(\bigwedge_{j=1}^m \overline{(S_i)_{i=1}^n} \Rightarrow R_j)$. By the induction hypothesis, we have that $\text{can}^{lo}(B) = \text{can}^{lo}(\bigwedge_{i=1}^n S_i)$, and hence $\text{can}^{lo}(B \Rightarrow C) = \text{can}^{lo}(\bigwedge_{j=1}^m \overline{(S_i)_{i=1}^n} \Rightarrow R_j) = \text{can}^{lo}(A \Rightarrow C)$.
- Let $A \wedge C \equiv B \wedge C$ be a consequence of $A \equiv B$. $\text{can}^{lo}(A \wedge C) = \text{can}^{lo}(\text{can}^{lo}(A) \wedge \text{can}^{lo}(C))$, which by the induction hypothesis, is equal to $\text{can}^{lo}(\text{can}^{lo}(B) \wedge \text{can}^{lo}(C)) = \text{can}^{lo}(B \wedge C)$. \square

Lemma 3.9. $\forall A, \llbracket \text{can}(A) \rrbracket = \llbracket \text{can}^{lo}(A) \rrbracket$.

Proof. Let $\text{can}(A) = \bigwedge_{i=1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$. Hence, $\llbracket \text{can}(A) \rrbracket = \{\mathbf{r} \mid \forall i, \text{ if for } j = 1, \dots, m_i, \mathbf{s}_{ij} \in \llbracket S_{ij} \rrbracket, \text{ then } \pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\mathbf{r})\vec{\mathbf{s}}_i \in \text{SN}\}$, which, by rule (SUBST) is equal to $\{\mathbf{r} \mid \forall i, \text{ if for } j = 1, \dots, m_i, \mathbf{s}_{ij} \in \llbracket S_{ij} \rrbracket, \text{ then } \pi_{\text{can}^{lo}(\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau)}(\mathbf{r})\vec{\mathbf{s}}_i \in \text{SN}\} = \llbracket \text{can}^{lo}(A) \rrbracket$. \square

Corollary 3.10. *If $A \equiv B$, then $\llbracket \text{can}(A) \rrbracket = \llbracket \text{can}(B) \rrbracket$.*

Proof. By Lemma 3.8, $A \equiv B$ implies $\text{can}^{lo}(A) = \text{can}^{lo}(B)$, and by Lemma 3.9, $\llbracket \text{can}(A) \rrbracket = \llbracket \text{can}^{lo}(A) \rrbracket$ for all A . Hence,

$$\llbracket \text{can}(A) \rrbracket = \llbracket \text{can}^{lo}(A) \rrbracket = \llbracket \text{can}^{lo}(B) \rrbracket = \llbracket \text{can}(B) \rrbracket \quad \square$$

Lemma 3.11. $\forall A, \llbracket \text{can}(A) \rrbracket \neq \emptyset$.

Proof. If $\vec{\mathbf{s}} \in \text{SN}$, then both $x^A \vec{\mathbf{s}}$ and $\pi_B(x^A) \vec{\mathbf{s}}$ are in SN, hence for all A , $x^A \in \llbracket \text{can}(A) \rrbracket$. \square

Lemma 3.12. $\forall A, \llbracket \text{can}(A) \rrbracket \subseteq \text{SN}$.

Proof. Let $\text{can}(A) = \bigwedge_{i=1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$ and $\mathbf{r} \in \llbracket \text{can}(A) \rrbracket$. Assume $\mathbf{r} \notin \text{SN}$, then for any $\vec{\mathbf{s}}$, $\pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\mathbf{r})\vec{\mathbf{s}} \notin \text{SN}$. A contradiction. \square

Lemma 3.13. *If $\mathbf{r} \in \text{SN}$, then $\pi_A(\mathbf{r}) \in \text{SN}$.*

Proof. We proceed by induction on the sum the size of \mathbf{r} and the sum of the number of steps to reach the normal form by any path starting on \mathbf{r} . The possible reduction from $\pi_A(\mathbf{r})$ are:

- $\pi_A(\mathbf{r}')$, and so the induction hypothesis applies,
- \mathbf{r}' , with $\mathbf{r}' : A$ and either $\mathbf{r} \rightleftharpoons \mathbf{r}' + \mathbf{t}$ or just $\mathbf{r} \rightleftharpoons \mathbf{r}'$. In any case, since $\mathbf{r} \in \text{SN}$, then $\mathbf{r}' \in \text{SN}$.
- $\pi_{A_1}(\mathbf{r}_1) + \pi_{A_2}(\mathbf{r}_2)$, with $A \equiv A_1 \wedge A_2$, and $\mathbf{r} \rightleftharpoons \mathbf{r}_1 + \mathbf{r}_2$. Since $\mathbf{r} \in \text{SN}$, then $\mathbf{r}_1 \in \text{SN}$ and $\mathbf{r}_2 \in \text{SN}$. Hence the induction hypothesis applies.

- $\pi_{A_1}(\pi_A(\mathbf{r})) + \pi_{A_2}(\pi_A(\mathbf{r}))$, with $A \equiv A_1 \wedge A_2$, and $\mathbf{r} \not\Leftarrow^* \mathbf{r}_1 + \mathbf{r}_2$. Hence we cannot reduce the projection in head position, not π_A , we must reduce \mathbf{r} first. If there is not $\mathbf{r}_1 + \mathbf{r}_2$ in the path to reach the normal form of \mathbf{r} , then we are done. Suppose there is $\mathbf{r}_1 + \mathbf{r}_2$. Then the projection will project either \mathbf{r}_1 or \mathbf{r}_2 . In any case, since $\mathbf{r} \in \text{SN}$, we have $\mathbf{r}_1 \in \text{SN}$ and $\mathbf{r}_2 \in \text{SN}$. \square

Lemma 3.14. *If $\mathbf{r}_1 \in \text{SN}$ and $\mathbf{r}_2 \in \text{SN}$, then $\mathbf{r}_1 + \mathbf{r}_2 \in \text{SN}$*

Proof. First we prove the following property: If $\mathbf{r}_1 + \mathbf{r}_2 \Leftarrow^* \mathbf{s} \hookrightarrow \mathbf{s}'$, then, there exist \mathbf{t}_1 and \mathbf{t}_2 such that $\mathbf{s}' \Leftarrow^* \mathbf{t}_1 + \mathbf{t}_2$, with either $(\mathbf{r}_1 \rightsquigarrow \mathbf{t}_1 \text{ and } \mathbf{r}_2 \rightsquigarrow \mathbf{t}_2)$ or $(\mathbf{r}_1 \rightsquigarrow \mathbf{t}_1 \text{ and } \mathbf{r}_2 = \mathbf{t}_2)$ or $(\mathbf{r}_1 = \mathbf{t}_1 \text{ and } \mathbf{r}_2 \rightsquigarrow \mathbf{t}_2)$. Once this property is proven, we have that if $\mathbf{r}_1 + \mathbf{r}_2$ is not in SN, then for each \mathbf{s} in the infinite reduction path, $\mathbf{s} \Leftarrow^* \mathbf{t}_1 + \mathbf{t}_2$ such that either $\mathbf{r}_1 \rightsquigarrow \mathbf{t}_1$ and $\mathbf{r}_2 \rightsquigarrow \mathbf{t}_2$ or $\mathbf{r}_1 \rightsquigarrow \mathbf{t}_1$ and $\mathbf{r}_2 = \mathbf{t}_2$ or $\mathbf{r}_1 = \mathbf{t}_1$ and $\mathbf{r}_2 \rightsquigarrow \mathbf{t}_2$. In any case, at least one of \mathbf{r}_1 and \mathbf{r}_2 has an infinite path reduction, which is an absurd since \mathbf{r}_1 and \mathbf{r}_2 are in SN.

We proceed to prove the needed property.

The possible terms $\mathbf{s} \Leftarrow^* \mathbf{r}_1 + \mathbf{r}_2$ are:

- $\mathbf{r}'_1 + \mathbf{r}'_2$ with $\mathbf{r}_1 \Leftarrow^* \mathbf{r}'_1$ and $\mathbf{r}_2 \Leftarrow^* \mathbf{r}'_2$. This is the trivial case.
- $\lambda x_1^{A_1} \dots \lambda x_n^{A_n} . (\mathbf{r}'_1 + \mathbf{r}'_2)$, with

$$\begin{aligned} \mathbf{r}_1 &\Leftarrow^* \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}'_1 \\ \mathbf{r}_2 &\Leftarrow^* \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}'_2 \end{aligned}$$

Then the only possible reduction from this term is

$$\lambda x_1^{A_1} \dots \lambda x_n^{A_n} . (\mathbf{r}''_1 + \mathbf{r}''_2)$$

with $(\mathbf{r}'_1 \rightsquigarrow \mathbf{r}''_1 \text{ and } \mathbf{r}'_2 = \mathbf{r}''_2)$, or $(\mathbf{r}'_1 = \mathbf{r}''_1 \text{ and } \mathbf{r}'_2 \rightsquigarrow \mathbf{r}''_2)$.

In any case, it is equivalent to $\lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}''_1 + \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}''_2$, and notice that either

$$\begin{aligned} \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}'_1 &\rightsquigarrow \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}''_1 \\ \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}'_2 &= \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}''_2 \end{aligned}$$

or

$$\begin{aligned} \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}'_1 &= \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}''_1 \\ \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}'_2 &\rightsquigarrow \lambda x_1^{A_1} \dots \lambda x_n^{A_n} . \mathbf{r}''_2 \end{aligned}$$

- $(\mathbf{r}'_1 + \mathbf{r}'_2) \mathbf{s}_1 \dots \mathbf{s}_n$, with

$$\begin{aligned} \mathbf{r}_1 &\Leftarrow^* \mathbf{r}'_1 \mathbf{s}_1 \dots \mathbf{s}_n \\ \mathbf{r}_2 &\Leftarrow^* \mathbf{r}'_2 \mathbf{s}_1 \dots \mathbf{s}_n \end{aligned}$$

The only possible \hookrightarrow -reductions from this term are:

- $(\mathbf{r}'_1 + \mathbf{r}'_2)\mathbf{s}_1 \dots \mathbf{s}'_i \dots \mathbf{s}_n \xleftrightarrow{*} \mathbf{r}'_1\mathbf{s}_1 \dots \mathbf{s}'_i \dots \mathbf{s}_n + \mathbf{r}'_2\mathbf{s}_1 \dots \mathbf{s}'_i \dots \mathbf{s}_n$
with $\mathbf{s}_i \rightsquigarrow \mathbf{s}'_i$.

Notice that

$$\begin{aligned} \mathbf{r}'_1\mathbf{s}_1 \dots \mathbf{s}_n &\rightsquigarrow \mathbf{r}'_1\mathbf{s}_1 \dots \mathbf{s}'_i \dots \mathbf{s}_n \\ \mathbf{r}'_2\mathbf{s}_1 \dots \mathbf{s}_n &\rightsquigarrow \mathbf{r}'_2\mathbf{s}_1 \dots \mathbf{s}'_i \dots \mathbf{s}_n \end{aligned}$$

- $(\mathbf{r}''_1 + \mathbf{r}''_2)\mathbf{s}_1 \dots \mathbf{s}_n$
with either $(\mathbf{r}'_1 \hookrightarrow \mathbf{r}''_1 \text{ and } \mathbf{r}'_2 = \mathbf{r}''_2)$, or $(\mathbf{r}'_1 = \mathbf{r}''_1 \text{ and } \mathbf{r}'_2 \hookrightarrow \mathbf{r}''_2)$.
In any case, it is equivalent to $\mathbf{r}''_1\mathbf{s}_1 \dots \mathbf{s}_n + \mathbf{r}''_2\mathbf{s}_1 \dots \mathbf{s}_n$, and notice that either

$$\begin{aligned} \mathbf{r}'_1\mathbf{s}_1 \dots \mathbf{s}_n &\rightsquigarrow \mathbf{r}''_1\mathbf{s}_1 \dots \mathbf{s}_n \\ \mathbf{r}'_2\mathbf{s}_1 \dots \mathbf{s}_n &= \mathbf{r}''_2\mathbf{s}_1 \dots \mathbf{s}_n \end{aligned}$$

or

$$\begin{aligned} \mathbf{r}'_1\mathbf{s}_1 \dots \mathbf{s}_n &= \mathbf{r}''_1\mathbf{s}_1 \dots \mathbf{s}_n \\ \mathbf{r}'_2\mathbf{s}_1 \dots \mathbf{s}_n &\rightsquigarrow \mathbf{r}''_2\mathbf{s}_1 \dots \mathbf{s}_n \end{aligned}$$

- $\pi_{A_1 \wedge A_2}(\mathbf{r}'_1 + \mathbf{r}'_2)$, with

$$\begin{aligned} \mathbf{r}_1 &\xleftrightarrow{*} \pi_{A_1}(\mathbf{r}_1) \\ \mathbf{r}_2 &\xleftrightarrow{*} \pi_{A_2}(\mathbf{r}_2) \end{aligned}$$

The only possible \hookrightarrow -reductions from this term are:

- $\pi_{A_1 \wedge A_2}(\mathbf{r}''_1 + \mathbf{r}''_2)$
with either $(\mathbf{r}'_1 \hookrightarrow \mathbf{r}''_1)$ and $(\mathbf{r}'_2 = \mathbf{r}''_2)$ or $(\mathbf{r}'_1 = \mathbf{r}''_1)$ and $(\mathbf{r}'_2 \hookrightarrow \mathbf{r}''_2)$.

Notice that either

$$\begin{aligned} \pi_{A_1}(\mathbf{r}'_1) &\rightsquigarrow \pi_{A_1}(\mathbf{r}''_1) \\ \pi_{A_2}(\mathbf{r}'_2) &= \pi_{A_2}(\mathbf{r}''_2) \end{aligned}$$

or

$$\begin{aligned} \pi_{A_1}(\mathbf{r}'_1) &= \pi_{A_1}(\mathbf{r}''_1) \\ \pi_{A_2}(\mathbf{r}'_2) &\rightsquigarrow \pi_{A_2}(\mathbf{r}''_2) \end{aligned}$$

- $\mathbf{t}_1 + \mathbf{t}_2$
with $\mathbf{r}'_1 \xleftrightarrow{*} \mathbf{t}_1 + \mathbf{t}'_1$ and $\mathbf{r}'_2 \xleftrightarrow{*} \mathbf{t}_2 + \mathbf{t}'_2$.

Notice that

$$\begin{aligned} \pi_{A_1}(\mathbf{r}'_1) &\rightsquigarrow \mathbf{t}_1 \\ \pi_{A_2}(\mathbf{r}'_2) &\rightsquigarrow \mathbf{t}_2 \end{aligned}$$

- $\mathbf{r}'_1 + \mathbf{r}'_2$.

Notice that

$$\begin{aligned} \pi_{A_1}(\mathbf{r}'_1) &\rightsquigarrow \mathbf{r}'_1 \\ \pi_{A_2}(\mathbf{r}'_2) &\rightsquigarrow \mathbf{r}'_2 \end{aligned} \quad \square$$

Lemma 3.15. *If $\mathbf{r} \in \text{SN}$, then $\lambda x^A.\mathbf{r} \in \text{SN}$.*

Proof. First we prove the following property: If $\lambda x^A.\mathbf{r} \xleftrightarrow{*} \mathbf{s} \hookrightarrow \mathbf{s}'$, then, there exists \mathbf{t} such that $\mathbf{s}' \xleftrightarrow{*} \lambda x^A.\mathbf{t}$, with $\mathbf{r} \rightsquigarrow \mathbf{t}$. Once this property is proven, we have that if $\lambda x^A.\mathbf{r}$ is not in SN, then for each \mathbf{s} in the infinite reduction path, $\mathbf{s} \xleftrightarrow{*} \lambda x^A.\mathbf{t}$ such that $\mathbf{r} \rightsquigarrow \mathbf{t}$, which is absurd since $\mathbf{r} \in \text{SN}$.

We proceed to prove the needed property. The possible terms $\mathbf{s} \xleftrightarrow{*} \lambda x^A.\mathbf{r}$ are:

- $\lambda x^A.\mathbf{r}'$, with $\mathbf{r} \xleftrightarrow{*} \mathbf{r}'$. This is the trivial case.
- $\lambda x^A.\mathbf{r}_1 + \lambda x^A.\mathbf{r}_2$
with $\mathbf{r} \xleftrightarrow{*} \mathbf{r}_1 + \mathbf{r}_2$.

The only possible \leftrightarrow -reduction from this term is:

$$\lambda x^A.\mathbf{r}'_1 + \lambda x^A.\mathbf{r}'_2$$

with $(\mathbf{r}_1 \leftrightarrow \mathbf{r}'_1 \text{ and } \mathbf{r}_2 = \mathbf{r}'_2)$ or $(\mathbf{r}_1 = \mathbf{r}'_1 \text{ and } \mathbf{r}_2 \leftrightarrow \mathbf{r}'_2)$.

In any case, $\mathbf{r}_1 + \mathbf{r}_2 \rightsquigarrow \mathbf{r}'_1 + \mathbf{r}'_2$.

- $\pi_{A \Rightarrow B_1}(\pi_{A \Rightarrow B_2}(\dots \pi_{A \Rightarrow B_n}(\lambda x^A.\mathbf{r}')))$
with $\mathbf{r} \xleftrightarrow{*} \pi_{B_1}(\pi_{B_2}(\dots \pi_{B_n}(\mathbf{r}')))$.

The only possible \leftrightarrow -reductions from this are:

- $\pi_{A \Rightarrow B_1}(\pi_{A \Rightarrow B_2}(\dots \pi_{A \Rightarrow B_n}(\lambda x^A.\mathbf{r}''))$, with $\mathbf{r}' \leftrightarrow \mathbf{r}''$.
Notice that $\mathbf{r} \rightsquigarrow \pi_{B_1}(\pi_{B_2}(\dots \pi_{B_n}(\mathbf{r}'')))$.

- $\pi_{A \Rightarrow B'_1}(\pi_{A \Rightarrow B_1}(\pi_{A \Rightarrow B_2}(\dots \pi_{A \Rightarrow B_n}(\lambda x^A.\mathbf{r}')))$
 $+ \pi_{A \Rightarrow B'_1}(\pi_{A \Rightarrow B_1}(\pi_{A \Rightarrow B_2}(\dots \pi_{A \Rightarrow B_n}(\lambda x^A.\mathbf{r}''))$
with $B_1 \equiv B'_1 \wedge B''_1$.

Notice that, since $\mathbf{r} \not\xleftrightarrow{*} \mathbf{r}_1 + \mathbf{r}_2$, otherwise the rule δ would not have been applied, we have

$$\mathbf{r} \rightsquigarrow \pi_{B'_1}(\pi_{B_1}(\pi_{B_2}(\dots \pi_{B_n}(\mathbf{r}'')))) + \pi_{B''_1}(\pi_{B_1}(\pi_{B_2}(\dots \pi_{B_n}(\mathbf{r}'')))) \quad \square$$

Lemma 3.16. *If $\mathbf{r} \in \llbracket \text{can}(A) \rrbracket$ and $\mathbf{s} \in \llbracket \text{can}(B) \rrbracket$, then $\mathbf{r} + \mathbf{s} \in \llbracket \text{can}(A \wedge B) \rrbracket$.*

Proof. Let $\text{can}(A) = \bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$ and $\text{can}(B) = \bigwedge_{i=k+1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$, so $\text{can}(A \wedge B) = \bigwedge_{i=1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$. Then we have that for all $i = 1, \dots, k$, if for $j = 1, \dots, m_i$, $\mathbf{t}_{ij} \in \llbracket S_{ij} \rrbracket$, then $\pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\mathbf{r})\vec{\mathbf{t}}_i \in \text{SN}$ and for all $i = k+1, \dots, n$, if for $j = 1, \dots, m_i$, $\mathbf{t}_{ij} \in \llbracket S_{ij} \rrbracket$, then $\pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\mathbf{s})\vec{\mathbf{t}}_i \in \text{SN}$. Therefore, for all $i = 1, \dots, n$, if for $j = 1, \dots, m_i$, $\mathbf{t}_{ij} \in \llbracket S_{ij} \rrbracket$, we have $\pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\mathbf{r} + \mathbf{s})\vec{\mathbf{t}}_i \in \text{SN}$, so $\mathbf{r} + \mathbf{s} \in \llbracket \text{can}(A \wedge B) \rrbracket$. \square

Let σ be a term substitution. We write $\sigma\mathbf{r}$ for \mathbf{r} after the substitutions σ . We say that σ is adequate if for all x^A , $\sigma(x^A) \in \llbracket \text{can}(A) \rrbracket$.

The following lemma shows that any adequate substitution applied to a term, is in the interpretation of the type of such term. This lemma, together with Lemma 3.12, implies that a typed term is strongly normalising (Theorem 3.18).

Lemma 3.17 (Adequacy). *If $\mathbf{r} : A$ and σ adequate, then $\sigma\mathbf{r} \in \llbracket \text{can}(A) \rrbracket$.*

Proof. We proceed by induction on the typing derivation.

- Let $x^A : A$ be a consequence of rule (ax) . Since σ is adequate, $\sigma(x^A) \in \llbracket \text{can}(A) \rrbracket$.

- Let $\mathbf{r} : B$ be a consequence of $\mathbf{r} : A$, $A \equiv B$ and rule (\equiv) . By the induction hypothesis $\forall \sigma$ adequate, $\sigma \mathbf{r} \in \llbracket \text{can}(A) \rrbracket$, so by Lemma 3.10, $\sigma \mathbf{r} \in \llbracket \text{can}(B) \rrbracket$.
- Let $\lambda x^A. \mathbf{r} : A \Rightarrow B$ be a consequence of $\mathbf{r} : B$ and rule (\Rightarrow_i) . Let $\text{can}(A) = \bigwedge_{i=1}^n \overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau$ and $\text{can}(B) = \bigwedge_{j=1}^m \overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau$. By the induction hypothesis, $\sigma \mathbf{r} \in \llbracket \text{can}(B) \rrbracket$, that is, for all j , if $\mathbf{s}_{jk} \in \llbracket R_{jk} \rrbracket$, for $k = 1, \dots, h_j$, then $\pi_{\overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\sigma \mathbf{r}) \vec{\mathbf{s}}_j \in \text{SN}$. Notice that $\sigma \lambda x^A. \mathbf{r} = \lambda x^A. \sigma \mathbf{r}$. We must show that

$$\lambda x^A. \sigma \mathbf{r} \in \left[\bigwedge_{j=1}^m \overline{\overline{\overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}_{i=1}^n} \Rightarrow \overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau \right]$$

that is, we must show that $\forall j$, if for $i = 1, \dots, n$, $\mathbf{t}_i \in \llbracket \overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau \rrbracket$ and for $k = 1, \dots, h_j$, $\mathbf{s}_{jk} \in \llbracket R_{jk} \rrbracket$, then

$$\pi_{\overline{\overline{\overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}_{i=1}^n} \Rightarrow \overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\lambda x^A. \sigma \mathbf{r}) \vec{\mathbf{t}} \vec{\mathbf{s}}_j \in \text{SN}$$

By Lemma 3.3, $A \equiv \text{can}(A)$, so

$$\begin{aligned} & \pi_{\overline{\overline{\overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}_{i=1}^n} \Rightarrow \overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\lambda x^A. \sigma \mathbf{r}) \vec{\mathbf{t}} \vec{\mathbf{s}}_j \\ \Leftrightarrow & \pi_{\overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\lambda x^{\bigwedge_{i=1}^n \overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}. \sigma \mathbf{r}) \vec{\mathbf{t}} \vec{\mathbf{s}}_j \\ \Leftrightarrow^* & \pi_{\overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}((\lambda x^{\bigwedge_{i=1}^n \overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}. \sigma \mathbf{r}) \vec{\mathbf{t}}) \vec{\mathbf{s}}_j \\ \Leftrightarrow^* & \pi_{\overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}((\lambda x^{\bigwedge_{i=1}^n \overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}. \sigma \mathbf{r}) (\sum_{i=1}^n \mathbf{t}_i)) \vec{\mathbf{s}}_j \end{aligned}$$

Since $\sigma \mathbf{r}$ is in SN, by Lemma 3.15, $\lambda x^A. \sigma \mathbf{r} \in \text{SN}$, and then by Lemma 3.13, $\pi_{\overline{\overline{\overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}_{i=1}^n} \Rightarrow \overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\lambda x^A. \sigma \mathbf{r}) \in \text{SN}$, hence $\lambda x^A. \pi_{\overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\sigma \mathbf{r}) \in \text{SN}$. And since also $\vec{\mathbf{t}}, \vec{\mathbf{s}}_i \in \text{SN}$, we can proceed by induction on the sum of the number of steps to reach the normal form of each of these terms. The possible reductions fired from $\pi_{\overline{\overline{\overline{(S_{il})_{l=1}^{p_i}} \Rightarrow \tau}_{i=1}^n} \Rightarrow \overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\lambda x^A. \sigma \mathbf{r}) \vec{\mathbf{t}} \vec{\mathbf{s}}_j$ are:

- reducing one of $\mathbf{t}_i, \mathbf{s}_{jk}$, $\lambda x^A. \sigma \mathbf{r}$ or $\lambda x^A. \pi_{\overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\sigma \mathbf{r})$, then the induction hypothesis applies,
- $\pi_{\overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\sigma \mathbf{r} [\sum_{i=1}^n \mathbf{t}_i / x]) \vec{\mathbf{s}}_j$. Then consider $\sigma' = \sigma, [\sum_{i=1}^n \mathbf{t}_i / x]$. By Lemma 3.16, σ' is adequate, hence

$$\pi_{\overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\sigma \mathbf{r} [\sum_{i=1}^n \mathbf{t}_i / x]) \vec{\mathbf{s}}_j = \pi_{\overline{(R_{jk})_{k=1}^{h_j}} \Rightarrow \tau}(\sigma' \mathbf{r}) \vec{\mathbf{s}}_j \in \text{SN}$$

$$\begin{aligned}
& - \pi_{C_1} \left(\overline{\overline{\overline{(S_{il})_{l=1}^{p_i} \Rightarrow \tau}}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{h_j} \Rightarrow \tau}} \right) (\lambda x^A . \sigma \mathbf{r}) \vec{\mathbf{t}} \vec{\mathbf{s}}_j \\
& + \pi_{C_1} \left(\overline{\overline{\overline{(S_{il})_{l=1}^{p_i} \Rightarrow \tau}}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{h_j} \Rightarrow \tau}} \right) (\lambda x^A . \sigma \mathbf{r}) \vec{\mathbf{t}} \vec{\mathbf{s}}_j
\end{aligned}$$

using rule (δ) . From this term, the only possible reductions are like in the two previous cases ((δ) cannot be applied twice). Hence the term is in SN.

- Let $\mathbf{rs} : B$ be a consequence of $\mathbf{r} : A \Rightarrow B$, $\mathbf{s} : A$ and rule (\Rightarrow_e) . Let $\text{can}(A) = \bigwedge_{i=1}^n \overline{(S_{ih})_{h=1}^{m_i} \Rightarrow \tau}$ and $\text{can}(B) = \bigwedge_{j=1}^o \overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}$, then $\text{can}(A \Rightarrow B) = \bigwedge_{j=1}^m \overline{\overline{\overline{(S_{ih})_{h=1}^{m_i} \Rightarrow \tau}}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}}$. By the induction hypothesis, if σ adequate, $\sigma \mathbf{r} \in \llbracket \text{can}(A \Rightarrow B) \rrbracket$ and $\sigma \mathbf{s} \in \llbracket \text{can}(A) \rrbracket$, that is, for $j = 1, \dots, m$, if for $i = 1, \dots, n$, $\mathbf{t}_{ji} \in \llbracket \overline{(S_{ih})_{h=1}^{m_i} \Rightarrow \tau} \rrbracket$ and for $k = 1, \dots, p_k$, $\mathbf{u}_{jk} \in \llbracket R_{jk} \rrbracket$, then

$$\pi_{\overline{\overline{\overline{(S_{ih})_{h=1}^{m_i} \Rightarrow \tau}}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}}} (\sigma \mathbf{r}) \vec{\mathbf{t}}_j \vec{\mathbf{u}}_j \in \text{SN}$$

Remark that

$$\begin{aligned}
& \pi_{\overline{\overline{\overline{(S_{ih})_{h=1}^{m_i} \Rightarrow \tau}}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}}} (\sigma \mathbf{r}) \vec{\mathbf{t}}_j \vec{\mathbf{u}}_j \\
& \quad \xleftrightarrow{*} \pi_{\overline{\overline{\overline{(S_{ih})_{h=1}^{m_i} \Rightarrow \tau}}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}}} (\sigma \mathbf{r}) \left(\sum_{i=1}^n \mathbf{t}_{ji} \right) \vec{\mathbf{u}}_j
\end{aligned}$$

hence since $\sigma \mathbf{r} \in \llbracket \text{can}(A \Rightarrow B) \rrbracket$, by Lemma 3.16, if $\sum_{i=1}^n \mathbf{t}_{ji} \in \llbracket \text{can}(A) \rrbracket$, then $\pi_{\overline{\overline{\overline{(S_{ih})_{h=1}^{m_i} \Rightarrow \tau}}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}}} (\sigma \mathbf{r}) \left(\sum_{i=1}^n \mathbf{t}_{ji} \right) \vec{\mathbf{u}}_j \in \text{SN}$. Since we have $\sigma \mathbf{s} \in \llbracket \text{can}(A) \rrbracket$, we have that $\pi_{\overline{\overline{\overline{(S_{ih})_{h=1}^{m_i} \Rightarrow \tau}}_{i=1}^n \Rightarrow \overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}}} (\sigma \mathbf{r}) \sigma \mathbf{s} \vec{\mathbf{u}}_j$ is $\xleftrightarrow{*}$ -equivalent to $\pi_{\overline{\overline{\overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}}_{j=1}^o \Rightarrow \tau}} ((\sigma \mathbf{r}) \sigma \mathbf{s}) \vec{\mathbf{u}}_j = \pi_{\overline{\overline{\overline{(R_{jk})_{k=1}^{p_j} \Rightarrow \tau}}_{j=1}^o \Rightarrow \tau}} (\sigma(\mathbf{rs})) \vec{\mathbf{u}}_j \in \text{SN}$, and so $\sigma(\mathbf{rs}) \in \llbracket \text{can}(B) \rrbracket$.

- Let $\mathbf{r} + \mathbf{s} : A \wedge B$ be a consequence of $\mathbf{r} : A$, $\mathbf{s} : B$ and rule (\wedge_i) . By the induction hypothesis, $\forall \sigma$ adequate, $\sigma \mathbf{r} \in \llbracket \text{can}(A) \rrbracket$ and $\sigma \mathbf{s} \in \llbracket \text{can}(B) \rrbracket$, hence by Lemma 3.16, $\sigma \mathbf{r} + \sigma \mathbf{s} \in \llbracket \text{can}(A \wedge B) \rrbracket$. Notice that $\sigma \mathbf{r} + \sigma \mathbf{s} = \sigma(\mathbf{r} + \mathbf{s})$.
- Let $\pi_A(\mathbf{r}) : A$ be a consequence of $\mathbf{r} : A \wedge B$ and rule (\wedge_{e_n}) . By the induction hypothesis, $\forall \sigma$ adequate, $\sigma \mathbf{r} \in \llbracket \text{can}(A \wedge B) \rrbracket$. Let $\text{can}(A) = \bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_i} \Rightarrow \tau}$ and $\text{can}(B) = \bigwedge_{i=k+1}^n \overline{(S_{ij})_{j=1}^{m_i} \Rightarrow \tau}$, then we have $\sigma \mathbf{r} \in \llbracket \text{can}(A \wedge B) \rrbracket$ means that $\forall i$, if $\forall j$, $\mathbf{s}_{ij} \in \llbracket S_{ij} \rrbracket$, then $\pi_{\overline{\overline{\overline{(S_{ij})_{j=1}^{m_i} \Rightarrow \tau}}_{j=1}^m \Rightarrow \tau}} (\sigma \mathbf{r}) \vec{\mathbf{s}}_i \in \text{SN}$.

We need to prove that

$$\pi_{\overline{\overline{\overline{(S_{1j})_{j=1}^{m_1} \Rightarrow \tau}}_{j=1}^m \Rightarrow \tau}} \left(\pi_{\bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_i} \Rightarrow \tau}} (\sigma \mathbf{r}) \right) \vec{\mathbf{s}}_i \xleftrightarrow{*} \pi_{\tau} \left(\pi_{\bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_i} \Rightarrow \tau}} (\sigma \mathbf{r}) \right) \vec{\mathbf{s}}_i \in \text{SN}$$

By Lemma 3.13, it suffices to prove $\pi_{\bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_i} \Rightarrow \tau}} (\sigma \mathbf{r}) \vec{\mathbf{s}}_i \in \text{SN}$. If $k = 1$, then we are done. In other case, we proceed by induction on the sum of the

number of steps to reach the normal form of $\sigma\mathbf{r}$, $\vec{\mathbf{s}}_i$ and $\pi_{\bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_1}} \Rightarrow \tau}(\sigma\mathbf{r})$ (which is in SN by Lemma 3.13). The possible reductions fired from $\pi_{\bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_1}} \Rightarrow \tau}(\sigma\mathbf{r})\vec{\mathbf{s}}_i$ are:

- reducing one of $\sigma\mathbf{r}, \mathbf{s}^1, \dots, \mathbf{s}^j$ or $\pi_{\bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_1}} \Rightarrow \tau}(\sigma\mathbf{r})$, then the induction hypothesis applies,
 - $\mathbf{r}'\vec{\mathbf{s}}_i$, with $\mathbf{r}' : \bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_1}} \Rightarrow \tau$ and $\sigma\mathbf{r} = \mathbf{r}' + \mathbf{t}$ or just $\sigma\mathbf{r} = \mathbf{r}'$. Since $\pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\sigma\mathbf{r})\vec{\mathbf{s}}_i \rightleftharpoons \pi_{\tau}(\sigma\mathbf{r}\vec{\mathbf{s}}_i) \in \text{SN}$ which is equal either to $\pi_{\tau}((\mathbf{r}' + \mathbf{t})\vec{\mathbf{s}}_i) \in \text{SN}$, then we have $\pi_{\tau}(\mathbf{r}'\vec{\mathbf{s}}_i + \mathbf{t}\vec{\mathbf{s}}_i) \in \text{SN}$, or to $\pi_{\tau}(\mathbf{r}'\vec{\mathbf{s}}_i) \in \text{SN}$, in any case we can conclude $\mathbf{r}'\vec{\mathbf{s}}_i \in \text{SN}$.
 - $\pi_{C_1}(\pi_{\bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_1}} \Rightarrow \tau}(\sigma\mathbf{r})\vec{\mathbf{s}}_i) + \pi_{C_1}(\pi_{\bigwedge_{i=1}^k \overline{(S_{ij})_{j=1}^{m_1}} \Rightarrow \tau}(\sigma\mathbf{r})\vec{\mathbf{s}}_i)$, using rule (δ) . From this term, the only possible reductions are like in the two previous cases (δ) cannot be applied twice). Hence the term is in SN.
 - Any other reduction involving first using DIST_{ee} -rule, are analogous to the previous case.
- Let $\pi_A(\mathbf{r}) : A$ be a consequence of $\mathbf{r} : A$ and rule (\wedge_{e_1}) . By the induction hypothesis $\sigma\mathbf{r} \in \llbracket \text{can}(A) \rrbracket$, that is, if $\text{can}(A) = \bigwedge_{i=1}^n \overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau$, for all i , if for all j , $\mathbf{s}_{ij} \in \llbracket \text{can}(S_{ij}) \rrbracket$, then $\pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\sigma\mathbf{r})\vec{\mathbf{s}}_i \in \text{SN}$. Notice that since $\sigma\mathbf{r} : A$, we have $\pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\sigma\mathbf{r})\vec{\mathbf{s}}_i \rightleftharpoons^* \pi_{\tau}((\sigma\mathbf{r})\vec{\mathbf{s}}_i)$, hence $(\sigma\mathbf{r})\vec{\mathbf{s}}_i \in \text{SN}$, so $\pi_A(\sigma\mathbf{r})\vec{\mathbf{s}}_i \in \text{SN}$, which implies $\pi_{\overline{(S_{ij})_{j=1}^{m_i}} \Rightarrow \tau}(\pi_A(\sigma\mathbf{r})\vec{\mathbf{s}}_i) \in \text{SN}$. \square

Now we can prove strong normalisation as a corollary of Lemma 3.17.

Theorem 3.18 (Strong normalisation). *If $\mathbf{r} : A$, then $\mathbf{r} \in \text{SN}$.*

Proof. If $\mathbf{r} : A$, by Lemma 3.17, for all σ adequate, $\sigma\mathbf{r} \in \llbracket \text{can}(A) \rrbracket$. Take $\sigma = \text{identity}$, and notice that it is adequate (cf. proof of Lemma 3.11), then $\sigma\mathbf{r} = \mathbf{r} \in \llbracket \text{can}(A) \rrbracket$, which by Lemma 3.12, is in SN. \square

3.2. Characterisation of Typed Closed Normal Forms

In this section, we give a characterisation of typed closed normal forms (Theorem 3.20), for which we need the following auxiliary result.

Lemma 3.19. *If $\mathbf{r} : A \wedge B$ and $FV(\mathbf{r}) = \emptyset$, then $\pi_A(\mathbf{r})$ reduces using at least one reduction π_n (that is, a projection discarding part of the term, in contrast with reduction π_1 , which keep the whole term).*

Proof. We proceed by structural induction on \mathbf{r} .

- If $\mathbf{r} = \lambda x^C.\mathbf{s}$ then $A \equiv C \Rightarrow A'$ and $B \equiv C \Rightarrow B'$, with $\mathbf{s} : A' \wedge B'$. So, $\pi_{C \Rightarrow A'}(\lambda x^C.\mathbf{s}) \rightleftharpoons \lambda x^C.\pi_{A'}(\mathbf{s})$, which by the induction hypothesis reduces using at least one π_n reduction.

- If $\mathbf{r} = \mathbf{r}_1\mathbf{r}_2$ then $\mathbf{r}_1 : C \Rightarrow (A \wedge B)$, so $\pi_A(\mathbf{r}_1\mathbf{r}_2) \Leftrightarrow \pi_{C \Rightarrow A}(\mathbf{r}_1)\mathbf{r}_2$. We conclude with the induction hypothesis.
- If $\mathbf{r} = \mathbf{r}_1 + \mathbf{r}_2$ the cases are:
 - $\mathbf{r}_1 : A$ and $\mathbf{r}_2 : B$, then $\pi_A(\mathbf{r}) \hookrightarrow_{\pi_n} \mathbf{r}_1$
 - $\mathbf{r}_1 : A \wedge B_1$ and $\mathbf{r}_2 : B_2$, with $B \equiv B_1 \wedge B_2$, then, by the induction hypothesis, $\pi_A(\mathbf{r}_1)$ reduces using at least one π_n reduction, and so $\pi_A(\mathbf{r}_1 + \mathbf{r}_2)$ does the same.
 - $\mathbf{r}_1 : A_1 \wedge B$ and $\mathbf{r}_2 : A_2 \wedge B$, with $A \equiv A_1 \wedge A_2$, then $\pi_A(\mathbf{r}_1 + \mathbf{r}_2) \Leftrightarrow \pi_{A_1 \wedge A_2}(\mathbf{r}_1 + \mathbf{r}_2) \Leftrightarrow \pi_{A_1}(\mathbf{r}_1) + \pi_{A_2}(\mathbf{r}_2)$, and by the induction hypothesis both $\pi_{A_1}(\mathbf{r}_1)$ and $\pi_{A_2}(\mathbf{r}_2)$ reduce using at least one π_n reduction.
- If $\mathbf{r} = \pi_C(\mathbf{s})$, then $C \equiv A \wedge B$ and $\mathbf{s} : A \wedge B \wedge D$, so by the induction hypothesis, $\pi_C(\mathbf{s})$ reduces using at least one π_n reduction, hence $\pi_A(\pi_C(\mathbf{s}))$ does the same. \square

Theorem 3.20 (Characterisation of typed closed normal forms). *If $\mathbf{r} : A$ and $FV(\mathbf{r}) = \text{Red}(\mathbf{r}) = \emptyset$, then there exists $A_1, \dots, A_n, \mathbf{t}_j : B_j$ for $j = 1, \dots, m$ and C_1, \dots, C_m , with $n+m \geq 1$ such that $\mathbf{r} \Leftrightarrow^* \sum_{i=1}^n \lambda x^{A_i}. \mathbf{s}_i + \sum_{j=1}^m (\lambda x^{B_j \wedge C_j}. \mathbf{r}_j) \mathbf{t}_j$.*

Proof. We proceed by structural induction on \mathbf{r} .

- If $\mathbf{r} = \lambda x^A. \mathbf{s}$, then we are done.
- If $\mathbf{r} = \mathbf{r}_1\mathbf{r}_2$, then $\mathbf{r}_1 : B \Rightarrow A$, $\mathbf{r}_2 : B$. So, by the induction hypothesis $\mathbf{r}_1 \Leftrightarrow^* \sum_{i=1}^n \lambda x^{A_i}. \mathbf{s}_i + \sum_{j=1}^m (\lambda x^{C_j \wedge D_j}. \mathbf{r}'_j) \mathbf{t}_j$, hence

$$\begin{aligned} \mathbf{r}_1\mathbf{r}_2 &\Leftrightarrow^* \left(\sum_{i=1}^n \lambda x^{A_i}. \mathbf{s}_i + \sum_{j=1}^m (\lambda x^{C_j \wedge D_j}. \mathbf{r}'_j) \mathbf{t}_j \right) \mathbf{r}_2 \\ &\Leftrightarrow^* \sum_{i=1}^n (\lambda x^{A_i}. \mathbf{s}_i) \mathbf{r}_2 + \sum_{j=1}^m (\lambda x^{C_j \wedge D_j}. \mathbf{r}'_j) \mathbf{t}_j \mathbf{r}_2 \end{aligned}$$

- If $\mathbf{r} = \mathbf{r}_1 + \mathbf{r}_2$, then for $j = 1, 2$, $\mathbf{r}_j : A'_j$, so by the induction hypothesis $\mathbf{r}_1 \Leftrightarrow^* \sum_{i=1}^n \lambda x^{A_i}. \mathbf{s}_i + \sum_{j=1}^m (\lambda x^{B_j \wedge C_j}. \mathbf{r}_j) \mathbf{t}_j$ and $\mathbf{r}_2 \Leftrightarrow^* \sum_{i=n+1}^k \lambda x^{A_i}. \mathbf{s}_i + \sum_{j=m+1}^l (\lambda x^{B_j \wedge C_j}. \mathbf{r}_j) \mathbf{t}_j$, so $\mathbf{r} \Leftrightarrow^* \sum_{i=1}^k \lambda x^{A_i}. \mathbf{s}_i + \sum_{j=1}^l (\lambda x^{B_j \wedge C_j}. \mathbf{r}_j) \mathbf{t}_j$.
- If $\mathbf{r} = \pi_A(\mathbf{s})$, then $\mathbf{s} : A \wedge B$, indeed, \mathbf{s} cannot have type A because $\text{Red}(\pi_A(\mathbf{s})) = \emptyset$. So, by Lemma 3.19, $\text{Red}(\pi_A(\mathbf{s})) \neq \emptyset$. \square

4. Computing with our Calculus

4.1. Pairs (and lists)

Because the symbol $+$ is associative and commutative, our calculus does not contain the usual notion of pairs. However it is possible to encode a deterministic projection, even if we have more than one term of the same type. An example, although there are various possibilities, is given in the following table:

| Standard | Encoding |
|---|--|
| $\langle \mathbf{r}, \mathbf{s} \rangle : A \wedge A$ | $\lambda x^1. \mathbf{r} + \lambda x^2. \mathbf{s} : 1 \Rightarrow A \wedge 2 \Rightarrow A$ |
| $\pi_1 \langle \mathbf{r}, \mathbf{s} \rangle$ | $\pi_{1 \Rightarrow A} (\lambda x^1. \mathbf{r} + \lambda x^2. \mathbf{s}) y^1$ |

where types 1 and 2 are any two different types. This example uses free variables, but it is easy to close it, e.g. use $\lambda y. y$ instead of y^1 in the second line.

Moreover, this technique is not limited to pairs. Due to the associativity nature of $+$, the encoding can be easily extended to lists.

4.2. A deterministic subsystem

In the previous section we have seen how to encode a pair, transforming the non-deterministic projection into a deterministic one via an encoding. Another possibility, is to remove the non-deterministic behaviour of this calculus by dropping the isomorphisms (1) and (2), as well as rules `COMM` and `ASSO`. Despite that such a modification would simplify the calculus—indeed, the projection can be taken as the standard projection—the resulting calculus would still count with distribution of application over conjunction and currfication, two interesting features for a language. The former allows to execute a function only partially, when not all its results are needed. The latter can also be used to optimise programs when there are multiple calls to the same function, but one of its arguments is fixed.

4.3. Booleans

Example 2.8 on booleans actually overlooks an interesting fact: If $A \equiv B$, then both \mathbf{T} and \mathbf{F} behaves as a non-deterministic projector. Indeed, $\mathbf{T} \mathbf{r} \mathbf{s} \hookrightarrow^* \mathbf{r}$, but also $(\lambda x^A. \lambda y^B. x) \mathbf{r} \mathbf{s} \rightleftharpoons (\lambda x^A. \lambda y^A. x) \mathbf{r} \mathbf{s} \rightleftharpoons (\lambda x^A. \lambda y^A. x) (\mathbf{r} + \mathbf{s}) \rightleftharpoons (\lambda x^A. \lambda y^A. x) (\mathbf{s} + \mathbf{r}) \rightleftharpoons (\lambda x^A. \lambda y^A. x) \mathbf{s} \mathbf{r} \hookrightarrow^* \mathbf{s}$.

Similarly, $\mathbf{F} \mathbf{r} \mathbf{s} \hookrightarrow^* \mathbf{s}$ and also $\mathbf{F} \mathbf{r} \mathbf{s} \rightsquigarrow^* \mathbf{r}$. Hence, $A \Rightarrow A \Rightarrow A$ is not suitable to encode the type `Bool`. The type $A \Rightarrow A \Rightarrow A$ has only one term in the underlying equational theory.

Fortunately, there are ways to construct types with more than one term. First, let us define the following notation. For any \mathbf{t} , let write $[\mathbf{t}]^A$, the *canon* of \mathbf{t} , that is, the term $\lambda z^A. \mathbf{t}$, where z^A is a fresh variable not appearing in \mathbf{t} . Also, for any term \mathbf{t} of type $A \Rightarrow B$, we write $\{\mathbf{t}\}^{A \Rightarrow B}$, the *cocanon*, which is the inverse operation, that is, $\{[\mathbf{t}]^A\}^{A \Rightarrow B} = \mathbf{t}$ for any $\mathbf{t} : B$. For the cocanon it suffices to take $\{\mathbf{t}\}^{A \Rightarrow B} = \mathbf{t} \lambda x^A. y^B$. Therefore, the type $((A \Rightarrow A) \Rightarrow B) \Rightarrow B \Rightarrow B$ has the following two different terms: $\mathbf{tt} := \lambda x^B. \lambda y^{(A \Rightarrow A) \Rightarrow B}. x$ and $\mathbf{ff} := \lambda x^{(A \Rightarrow A) \Rightarrow B}. \lambda y^B. \{x\}^{A \Rightarrow A}$. Hence, it is possible to encode an if-then-else conditional expression in the following way: If \mathbf{c} then \mathbf{r} else $\mathbf{s} := \mathbf{cr}[\mathbf{s}]^{A \Rightarrow A}$. So, $\mathbf{tt} \mathbf{r}[\mathbf{s}]^{A \Rightarrow A} \hookrightarrow^* \mathbf{r}$, while $\mathbf{ff} \mathbf{r}[\mathbf{s}]^{A \Rightarrow A} \rightleftharpoons^* \mathbf{ff}[\mathbf{s}]^{A \Rightarrow A} \mathbf{r} \hookrightarrow^* \{[\mathbf{s}]^{A \Rightarrow A}\}^A \hookrightarrow^* \mathbf{s}$.

5. Conclusions, Discussions and Future Work

In this paper we defined a proof system for propositional logic with an associative and commutative conjunction, and a distributive implication with respect to it, where equivalent propositions get the same proofs.

5.1. Related Work

5.1.1. Relation with other non-deterministic calculi

As a consequence of the commutativity of conjunction, the projection in our calculus is not position-oriented but type-oriented, which entails a non-deterministic projection where if a proposition has two possible proofs, the projection of its conjunction can output any of them. For example, if \mathbf{r} and \mathbf{s} are two possible proofs of A , then $\pi_A(\mathbf{r} + \mathbf{s})$ will output either \mathbf{r} or \mathbf{s} .

In several works (cf. [22, §3.4] for a survey), the non-determinism is modelled by two operators: The first is normally written $+$, and instead of distributing over application, it actually makes the non-deterministic choice. Hence $(\mathbf{r} + \mathbf{s})\mathbf{t}$ reduces either to $\mathbf{r}\mathbf{t}$ or to $\mathbf{s}\mathbf{t}$ [10]. The second one, denoted by \parallel , does not make the choice, and therefore $(\mathbf{r} \parallel \mathbf{s})\mathbf{t}$ reduces to $\mathbf{r}\mathbf{t} \parallel \mathbf{s}\mathbf{t}$ [11]. One way to interpret these operators is that the first one is a non-deterministic one, while the second is the parallel composition. Another common interpretation is that $+$ is a *may-convergent* non-deterministic operator, where type systems ensure that at least one branch converges (i.e. terminates), while \parallel is a *must-convergent* non-deterministic operator, where both branches are meant to converge [8, 10, 11, 16]. In our setting, the $+$ operator behaves like \parallel , and an extra operator (π_A) induces the non-deterministic choice. The main point is that this construction arose naturally as a consequence of considering the isomorphisms between types as an equivalence relation. Our type system ensures the termination of all the branches (Theorem 3.18), therefore ensuring must-convergence.

5.1.2. Relation with the selective λ -calculus

In a work by Garrigue and Aït-Kaci [20], only the isomorphism

$$A \Rightarrow (B \Rightarrow C) \equiv B \Rightarrow (A \Rightarrow C). \quad (5)$$

has been treated, which is complete with respect to the function type. Our contribution with respect to this work is that we also consider the conjunction, and hence four isomorphisms. Notice that isomorphism (5), in our setting, is a consequence of currfication and commutation, that is $A \wedge B \equiv B \wedge A$ and $(A \wedge B) \Rightarrow C \equiv A \Rightarrow B \Rightarrow C$.

Their proposal is the selective λ -calculus, a calculus including labellings to identify which argument is being used at each time. Moreover, by considering the Church encoding of pairs, isomorphism (5) implies isomorphism (1) (commutativity of \wedge). However their proposal is different to ours. In particular, we track the term by its type, which is a kind of labelling, but when two terms have the same type, then we leave the system to non-deterministically choose any proof. One of our main novelties is, indeed, the non-deterministic projector. However, we can also get back determinism, by encoding a labelling, as discussed in Section 4, or by dropping some of the isomorphisms (namely, associativity and commutativity of conjunction).

5.2. Future Work

5.2.1. Adding more connectives

A subtle question is how to add a neutral element of the conjunction, which will imply more isomorphisms, e.g. $A \wedge \top \equiv A$, $A \Rightarrow \top \equiv \top$ and $\top \Rightarrow A \equiv A$. Notice that within our system, $\top \Rightarrow \top \equiv \top$ would make it possible to derive $(\lambda x^\top .xx)(\lambda x^\top .xx) : \top$, however this term is not the classical Ω , it is typed by \top , and imposing some restrictions on the beta reduction, it could be forced not to reduce to itself but to discard its argument. For example: “If $A \equiv \top$, then $(\lambda x^A .\mathbf{r})\mathbf{s} \hookrightarrow \lambda x^A .\mathbf{r}$, in other case, do the standard beta-reduction”.

5.2.2. Probabilistic and quantum computing

A second line is the probabilistic interpretation of the non-determinism in our calculus. In [15] a probability space over the set of non-deterministic execution traces is defined. This way, our calculus is transformed into a probabilistic calculus instead of just a non-deterministic one, providing an alternative way for more complex constructions. Moreover, the original motivation behind the linear algebraic extension of lambda calculus [4] and its *vectorial* type system [2] was to encode quantum computing on it by considering not only non-deterministic superpositions, but formal linear combinations of terms. A projection depending on scalars could lead to a measurement operator in a future design. This is a promising future direction we are willing to take.

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