

## Performance analysis of DG and HDG methods for the simulation of seismic wave propagation in harmonic domain

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## Motivation

## Examples of seismic applications


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## Motivation

Imaging method: the full wave inversion

- Iterative procedure using the wavefield in order to obtain quantitative high resolution images of the subsurface physical parameters


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Seismic imaging : time-domain or harmonic-domain?

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- Harmonic-domain : imaging condition simple but huge computational cost


## Motivation

Imaging method: the full wave inversion

- Iterative procedure using the wavefield in order to obtain quantitative high resolution images of the subsurface physical parameters

Seismic imaging : time-domain or harmonic-domain?

- Time-domain : imaging condition complicated but low computational cost
- Harmonic-domain : imaging condition simple but huge computational cost

Forward problem of the inversion process

- Elastic wave propagation in harmonic domain: Helmholtz equation
- Reduction of the size of the linear system


## Motivation

Seismic imaging in heterogeneous complex media

- Complex topography
- High heterogeneities


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Use of unstructured meshes with FE methods

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DG method

- Flexible choice of interpolation orders ( $p$ - adaptativity)
- Highly parallelizable method
- Increased computational cost as compared to classical FEM


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DOF of classical FEM


DOF of DGM
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## Motivation

Objective of this work

- Development of an hybridizable DG (HDG) method
- Comparison with a reference method : a standard nodal DG method


Figure: Degrees of freedom of DGM


Figure: Degrees of freedom of HDGM

## HDG methods

HDG methods

- B. Cockburn, J. Gopalakrishnan, R. Lazarov Unified hybridization of discontinuous Galerkin, mixed and continuous Galerkin methods for second order elliptic problems, SIAM Journal on Numerical Analysis, Vol. 47 (2009)
- S. Lanteri, L. Li, R. Perrussel, Numerical investigation of a high order hybridizable discontinuous Galerkin method for 2d time-harmonic Maxwell's equations, COMPEL, Vol. 32 (2013) (time-harmonic domain)
- N.C. Nguyen, J. Peraire, B. Cockburn, High-order implicit hybridizable discontinuous Galerkin methods for acoustics and elastodynamics, J. of Comput. Physics, Vol. 230 (2011) (time domain for seismic applications)


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2D Helmholtz elastic equations

## Notations and definitions

Hybridizable Discontinuous Galerkin method

Numerical results

## Conclusions-Perspectives

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## 2D Helmholtz elastic equations

First order formulation of Helmholtz wave equations
$\mathbf{x}=(x, y) \in \Omega \subset \mathbb{R}^{2}$,

$$
\left\{\begin{array}{l}
i \omega \rho(\mathbf{x}) v(\mathbf{x})=\nabla \cdot \sigma \cdot \underline{\underline{\sigma}}(\mathbf{x})+f_{s}(\mathbf{x}) \\
i \omega \underline{\underline{\sigma}}(\mathbf{x})=\underline{\underline{C}}(\mathbf{x}) \underline{\underline{\varepsilon}}(v(\mathbf{x}))
\end{array}\right.
$$

- Free surface condition : $\underline{\underline{\sigma}} \mathbf{n}=0$ on $\Gamma_{\text {/ }}$
- Absorbing boundary condition : $\underline{\underline{\sigma}} \mathbf{n}=v_{p}(\mathbf{v} \cdot \mathbf{n}) \mathbf{n}+v_{s}(v \cdot \mathbf{t}) \mathbf{t}$ on $\Gamma_{a}$
- v : velocity vector
- $\underline{\underline{\sigma}}$ : stress tensor
- $\underline{\underline{\varepsilon}}$ : strain tensor


## 2D Helmholtz elastic equations

First order formulation of Helmholtz wave equations
$\mathbf{x}=(x, y) \in \Omega \subset \mathbb{R}^{2}$,

$$
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$$

- Free surface condition : $\underline{\underline{\sigma}} \mathbf{n}=0$ on $\Gamma_{\text {/ }}$
- Absorbing boundary condition : $\underline{\underline{\sigma}} \mathbf{n}=v_{p}(\mathbf{v} \cdot \mathbf{n}) \mathbf{n}+v_{s}(v \cdot \mathbf{t}) \mathbf{t}$ on $\Gamma_{a}$
- $\rho$ : mass density
- C : tensor of elasticity coefficients
- $v_{p}$ : P-wave velocity
- $v_{s}$ : S-wave velocity
- $f_{s}$ : source term, $f_{s} \in L^{2}(\Omega)$


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## Notations and definitions

Notations

- $\mathcal{T}_{h}$ mesh of $\Omega$ composed of triangles $K$



## Notations and definitions

Notations

- $\mathcal{T}_{h}$ mesh of $\Omega$ composed of triangles $K$
- $\mathcal{F}_{h}$ set of all faces F of $\mathcal{T}_{h}$

M. Bonnasse-Gahot - DG and HDG methods for Helmholtz wave equations


## Notations and definitions

Notations

- $\mathcal{T}_{h}$ mesh of $\Omega$ composed of triangles $K$
- $\mathcal{F}_{h}$ set of all faces F of $\mathcal{T}_{h}$
- $\mathbf{n}$ the normal outward vector of an element $K$



## Notations and definitions

Approximations spaces

- $P_{p}(K)$ set of polynomials of degree at most $p$ on $K$
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## Notations and definitions

Approximations spaces

- $P_{p}(K)$ set of polynomials of degree at most $p$ on $K$
- $\mathbf{V}_{h}^{p}=\left\{\mathbf{v} \in\left(L^{2}(\Omega)\right)^{2}:\left.\quad \mathbf{v}\right|_{K} \in \mathbf{V}^{p}(K)=\left(P_{p}(K)\right)^{2}, \forall K \in \mathcal{T}_{h}\right\}$


## Notations and definitions

Approximations spaces

- $P_{p}(K)$ set of polynomials of degree at most $p$ on $K$
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- $\Sigma_{h}^{p}=\left\{\underline{\underline{\sigma}} \in\left(L^{2}(\Omega)\right)^{3}:\left.\quad \underline{\underline{\sigma}}\right|_{K} \in \Sigma^{p}(K)=\left(P_{p}(K)\right)^{3}, \forall K \in \mathcal{T}_{h}\right\}$


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- $P_{p}(K)$ set of polynomials of degree at most $p$ on $K$
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- $\Sigma_{h}^{p}=\left\{\underline{\underline{\sigma}} \in\left(L^{2}(\Omega)\right)^{3}:\left.\quad \underline{\underline{\sigma}}\right|_{K} \in \Sigma^{p}(K)=\left(P_{p}(K)\right)^{3}, \forall K \in \mathcal{T}_{h}\right\}$
- $\mathbf{M}_{h}=\left\{\eta \in\left(L^{2}\left(\mathcal{F}_{h}\right)\right)^{2}:\left.\quad \eta\right|_{F} \in\left(P_{p}(F)\right)^{2}, \forall F \in \mathcal{F}_{h}\right\}$


## Notations and definitions

## Definitions

- Jump $\llbracket \rrbracket$ of a vector $v$ through $F$ :

$$
\llbracket v \rrbracket=v^{+} \cdot \mathbf{n}^{+}+v^{-} \cdot \mathbf{n}^{-}=v^{+} \cdot \mathbf{n}^{+}-v^{-} \cdot \mathbf{n}^{+}
$$

- Jump of a tensor $\underline{\underline{\sigma}}$ through $F$ :


$$
\llbracket \underline{\underline{\sigma}} \rrbracket=\underline{\underline{\sigma}}^{+} \mathbf{n}^{+}+\underline{\underline{\sigma}}^{-} \mathbf{n}^{-}=\underline{\underline{\sigma}}^{+} \mathbf{n}^{+}-\underline{\underline{\sigma}}^{-} \mathbf{n}^{+}
$$

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## HDG formulation of the equations

Local HDG formulation

$$
\left\{\begin{array}{l}
i \omega \rho v-\nabla \cdot \underline{\underline{\sigma}}=0 \\
i \omega \underline{\underline{\sigma}}-\underline{\underline{C \varepsilon}}(\mathbf{v})=0
\end{array}\right.
$$

## HDG formulation of the equations

## Local HDG formulation

$$
\left\{\begin{array}{l}
\int_{K} i \omega \rho^{K} \mathbf{v}^{K} \cdot \mathbf{w}+\int_{K} \underline{\underline{\sigma}}^{K}: \nabla \mathbf{w}-\int_{\partial K} \underline{\underline{\widehat{\sigma}}}^{\partial K} \cdot \mathbf{n} \cdot \mathbf{w}=0 \\
\int_{K} i \omega \underline{\underline{\sigma}}^{K}: \underline{\underline{\xi}}+\int_{K} \mathbf{v}^{K} \cdot \nabla \cdot\left(\underline{\underline{C}}^{K} \underline{\underline{\xi}}\right)-\int_{\partial K} \widehat{\mathbf{v}}^{\partial K} \cdot \underline{\underline{C}}^{K} \underline{\underline{\xi}} \cdot \mathbf{n}=0
\end{array}\right.
$$

$\underline{\underline{\sigma}}^{K}$ and $\widehat{v}^{K}$ are numerical traces of $\underline{\underline{\sigma}}^{K}$ and $v^{K}$ respectively on $\partial K$

## HDG formulation of the equations

Local HDG formulation

$$
\left\{\begin{array}{l}
\int_{K} i \omega \rho^{K} \mathbf{v}^{K} \cdot \mathbf{w}+\int_{K} \underline{\underline{\sigma}}^{K}: \nabla \mathbf{w}-\int_{\partial K} \underline{\underline{\underline{\sigma}}}^{\partial K} \cdot \mathbf{n} \cdot \mathbf{w}=0 \\
\int_{K} i \omega \underline{\underline{\sigma}}^{K}: \underline{\underline{\xi}}+\int_{K} \mathbf{v}^{K} \cdot \nabla \cdot\left(\underline{\underline{C}}^{K} \underline{\underline{\xi}}\right)-\int_{\partial K} \widehat{\mathbf{v}}^{\partial K} \cdot \underline{\underline{C}}^{K} \underline{\underline{\xi}} \cdot \mathbf{n}=0
\end{array}\right.
$$

We define :

$$
\begin{array}{lll}
\hat{\mathbf{v}}^{F} & =\lambda^{F}, & \forall F \in \mathcal{F}_{h}, \\
\hat{\underline{\sigma}}^{\partial K} \cdot \mathbf{n} & =\underline{\underline{\sigma}}^{K} \cdot \mathbf{n}-\tau \mathbf{l}\left(\mathbf{v}^{K}-\lambda^{\partial K}\right), & \text { on } \partial K
\end{array}
$$

where $\tau$ is the stabilization parameter $(\tau>0)$
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## HDG formulation of the equations

## Local HDG formulation

We replace $\widehat{\mathbf{v}}^{K}$ and $\left(\underline{\underline{\widehat{\sigma}}}^{K} \cdot \mathbf{n}\right)$ by their definitions into the local equations

$$
\left\{\begin{array}{l}
\int_{K} i \omega \rho^{K} \mathbf{v}^{K} \cdot \mathbf{w}+\int_{K} \underline{\underline{\sigma}}^{K}: \nabla \mathbf{w}-\int_{\partial K} \underline{\underline{\sigma}}^{K} \cdot \mathbf{n} \cdot \mathbf{w} \\
\quad+\int_{\partial K} \tau \mathbf{l}\left(\mathbf{v}^{K}-\lambda^{\partial K}\right) \cdot \mathbf{w}=0 \\
\int_{K} i \omega \underline{\underline{\sigma}}^{K}: \underline{\underline{\xi}}+\int_{K} \mathbf{v}^{K} \cdot \nabla \cdot\left(\underline{\underline{C}}^{K} \underline{\underline{\xi}}\right)-\int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{C}}^{K} \underline{\underline{\xi}} \cdot \mathbf{n}=0
\end{array}\right.
$$

## HDG formulation of the equations

Local HDG formulation

$$
\left\{\begin{array}{l}
\int_{K} i \omega \rho^{K} \mathbf{v}^{K} \cdot \mathbf{w}-\int_{K}\left(\nabla \cdot \underline{\underline{\sigma}}^{K}\right) \cdot \mathbf{w}+\int_{\partial K} \tau \mathbf{l}\left(\mathbf{v}^{K}-\lambda^{\partial K}\right) \cdot \mathbf{w}=0 \\
\int_{K} i \omega \underline{\underline{\sigma}}^{K}: \underline{\underline{\xi}}+\int_{K} \mathbf{v}^{K} \cdot \nabla \cdot\left(\underline{\underline{C}}^{K} \underline{\underline{\xi}}\right)-\int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{C}}^{K} \underline{\underline{\xi}} \cdot \mathbf{n}=0
\end{array}\right.
$$

## HDG formulation of the equations

Transmission condition
In order to determine $\lambda^{K}$, the continuity of the normal component of $\underline{\underline{\sigma}}^{K}$ is weakly enforced, rendering this numerical trace conservative :

$$
\int_{F} \llbracket \underline{\underline{\sigma}}^{K} \cdot \mathbf{n} \rrbracket \cdot \eta=0
$$

## HDG formulation of the equations

## Transmission condition

In order to determine $\lambda^{K}$, the continuity of the normal component of $\widehat{\underline{\sigma}}^{K}$ is weakly enforced, rendering this numerical trace conservative :

$$
\int_{F} \llbracket \underline{\underline{\sigma}}^{K} \cdot \mathbf{n} \rrbracket \cdot \eta=0
$$

Replacing ( $\underline{\underline{\sigma}}^{K} \cdot \mathbf{n}$ ) and summing over all faces, the transmission condition becomes :

$$
\sum_{K \in \mathcal{T}_{h}} \int_{\partial K}\left(\underline{\underline{\sigma}}^{K} \cdot \mathbf{n}\right) \cdot \eta-\sum_{K \in \mathcal{T}_{h}} \int_{\partial K} \tau \mathbf{I}\left(\mathbf{v}^{K}-\lambda^{\partial K}\right) \cdot \eta=0
$$

## HDG formulation of the equations

Global HDG formulation

$$
\left\{\begin{array}{l}
\int_{K} i \omega \rho^{K} \mathbf{v}^{K} \cdot \mathbf{w}-\int_{K}\left(\nabla \cdot \underline{\underline{\sigma}}^{K}\right) \cdot \mathbf{w}+\int_{\partial K} \tau \mathbf{l}\left(\mathbf{v}^{K}-\lambda^{\partial K}\right) \cdot \mathbf{w}=0 \\
\int_{K} i \omega \underline{\underline{\sigma}}^{K}: \underline{\underline{\xi}}+\int_{K} \mathbf{v}^{K} \cdot \nabla \cdot\left(\underline{\underline{c}}^{K} \underline{\underline{\xi}}\right)-\int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{C_{K}}} \underline{\underline{\xi}} \cdot \mathbf{n}=0 \\
\sum_{K \in \mathcal{T}_{h}} \int_{\partial K}\left(\underline{\underline{\sigma}}^{K} \cdot \mathbf{n}\right) \cdot \eta-\sum_{K \in \mathcal{T}_{h}} \int_{\partial K} \tau \mathbf{I}\left(\mathbf{v}^{K}-\lambda^{\partial K}\right) \cdot \eta=0
\end{array}\right.
$$

## Discretization of the HDG formulation

Local HDG formulation

$$
\left\{\begin{array}{l}
\int_{K} i \omega \rho^{K} \mathbf{v}^{K} \cdot \mathbf{w}-\int_{K}\left(\nabla \cdot \underline{\underline{\sigma}}^{K}\right) \cdot \mathbf{w}+\int_{\partial K} \tau \mathbf{l}\left(\mathbf{v}^{K}-\lambda^{\partial K}\right) \cdot \mathbf{w}=0 \\
\int_{K} i \omega \underline{\underline{\sigma}}^{K}: \underline{\underline{\xi}}+\int_{K} \mathbf{v}^{K} \cdot \nabla \cdot\left(\underline{\underline{C}}^{K} \underline{\underline{\xi}}\right)-\int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{C}}^{K} \underline{\underline{\xi}} \cdot \mathbf{n}=0
\end{array}\right.
$$

We define :
$\underline{W}^{K}=\left(\underline{v_{x}}{ }^{K},{\underline{v_{z}}}^{K}, \underline{\sigma_{x x}}{ }^{K}, \underline{\sigma_{z z}^{K}}, \underline{\sigma_{x z}}{ }^{K}\right)^{T}$
$\underline{\Lambda}=\left(\underline{\Lambda}^{F_{1}}, \underline{\Lambda}^{F_{2}}, \ldots, \underline{\Lambda}^{F_{n_{f}}}\right)^{T}$, where $n_{f}=\operatorname{card}\left(\mathcal{F}_{h}\right)$
Discretization of the local HDG formulation

$$
\mathbb{A}^{K} \underline{W}^{K}+\mathbb{C}^{K} \underline{\Lambda}=0
$$

## Discretization of the HDG formulation

Transmission condition

$$
\sum_{K \in \mathcal{T}_{h}} \int_{\partial K}\left(\underline{\underline{\sigma}}^{K} \cdot \mathbf{n}\right) \cdot \eta-\sum_{K \in \mathcal{T}_{h}} \int_{\partial K} \mathbf{S}\left(\mathbf{v}^{K}-\lambda^{\partial K}\right) \cdot \eta=0
$$

Discretization of the transmission condition

$$
\sum_{K \in \mathcal{T}_{h}}\left[\mathbb{B}^{K} \underline{W^{K}}+\mathbb{L}^{K} \underline{\Lambda}\right]=0
$$

## Discretization of the HDG formulation

Transmission condition

$$
\sum_{K \in \mathcal{T}_{h}}\left[\mathbb{B}^{K} \underline{W}^{K}+\mathbb{L}^{K} \Lambda\right]=0
$$

Local HDG scheme

$$
\mathbb{A}^{K} \underline{W}^{K}+\mathbb{C}^{K} \underline{\Lambda}=0
$$

## Discretization of the HDG formulation

Transmission condition

$$
\sum_{K \in \mathcal{T}_{h}}\left[\mathbb{B}^{K} \underline{W^{K}}+\mathbb{L}^{K} \underline{\Lambda}\right]=0
$$

Expression of $\underline{W}^{K}$ in terms of $\underline{\Lambda}$

$$
\underline{W}^{K}=-\left(\mathbb{A}^{K}\right)^{-1} \mathbb{C}^{K} \underline{\Lambda}
$$

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## Discretization of the HDG formulation

Transmission condition

$$
\sum_{K \in \mathcal{T}_{h}}\left[\mathbb{B}^{K} \underline{W}^{K}+\mathbb{L}^{K} \underline{\Lambda}\right]=0
$$

Expression of $\underline{W}^{K}$ in terms of $\underline{\Lambda}$

$$
\underline{W}^{K}=-\left(\mathbb{A}^{K}\right)^{-1} \mathbb{C}^{K} \underline{\Lambda}
$$

Global HDG system

$$
\mathbb{K} \underline{\Lambda}=0
$$

$$
\text { with } \mathbb{K}=\sum_{K \in \mathcal{T}_{h}}\left[-\mathbb{B}^{K}\left(\mathbb{A}^{K}\right)^{-1} \mathbb{C}^{K}+\mathbb{L}^{K}\right]
$$

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## Plane wave



Computational domain $\Omega$ setting

- Physical parameters:
- $\rho=2000 \mathrm{~kg} \cdot \mathrm{~m}^{-3}$
- $\lambda=16 \mathrm{GPa}$
- $\mu=8 \mathrm{GPa}$
- Plane wave :

$$
u=\nabla e^{i(k \cos \theta x+k \sin \theta y)}
$$

where $k=\frac{\omega}{v_{p}}$

- $\theta=0$
- Three meshes :
- 3000 elements
- 10000 elements
- 45000 elements


## Plane wave



Convergence order of the HDG scheme
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## Disk-shaped scatterer problem



## Disk-shaped scatterer problem



Convergence order of the HDG scheme

## Disk-shaped scatterer problem

| Elements | Order | CPU Time (s) |  | Memory (MB) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | HDG | UDG | IPDG | HDG | UDG | IPDG |
| 1200 | 2 | 0.7 |  |  | 32 |  |  |
| 5100 | 2 | 3.0 |  |  | 161 |  |  |
| 21000 | 2 | 14.0 |  |  | 728 |  |  |
| 1200 | 3 | 1.7 |  |  | 57 |  |  |
| 5100 | 3 | 7.6 |  |  | 283 |  |  |
| 21000 | 3 | 34.8 |  |  | 1284 |  |  |
| 1200 | 4 | 3.9 |  |  | 86 |  |  |
| 5100 | 4 | 17.7 |  |  | 430 |  |  |
| 21000 | 4 | 79.1 |  |  | 1953 |  |  |

## Disk-shaped scatterer problem

| Elements | Order | CPU Time (s) |  |  | Memory (MB) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | HDG | UDG | IPDG | HDG | UDG | IPDG |
| 1200 | 2 | 0.7 | 2.6 | 2.4 | 32 | 269 | 70 |
| 5100 | 2 | 3.0 | 15.0 | 11.9 | 161 | 1360 | 369 |
| 21000 | 2 | 14.0 | 94.8 | 58.0 | 728 | 6578 | 1857 |
| 1200 | 3 | 1.7 | 5.4 | 6.8 | 57 | 525 | 190 |
| 5100 | 3 | 7.6 | 38.8 | 35.9 | 283 | 2921 | 1017 |
| 21000 | 3 | 34.8 | 252.0 | 197.8 | 1284 | 14131 | 5126 |
| 1200 | 4 | 3.9 | 10.5 | 15.7 | 86 | 895 | 428 |
| 5100 | 4 | 17.7 | 67.0 | 87.9 | 430 | 4537 | 2279 |
| 21000 | 4 | 79.1 | 452.8 | 520.7 | 1953 | 21186 | 11503 |

## Disk-shaped scatterer problem

| Elements | Order | CPU Time |  |  | Memory |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | HDG | UDG | IPDG | HDG | UDG | IPDG |
| 1200 | 2 | 1 | 3.7 | 3.4 | 1 | 8.4 | 2.2 |
| 5100 | 2 | 1 | 5.0 | 4.0 | 1 | 8.4 | 2.3 |
| 21000 | 2 | 1 | 6.8 | 4.1 | 1 | 9.0 | 2.6 |
| 1200 | 3 | 1 | 3.1 | 4.0 | 1 | 9.2 | 3.3 |
| 5100 | 3 | 1 | 5.1 | 4.7 | 1 | 10.3 | 3.6 |
| 21000 | 3 | 1 | 7.2 | 5.7 | 1 | 11.0 | 4.0 |
| 1200 | 4 | 1 | 2.7 | 4.0 | 1 | 10.4 | 5.0 |
| 5100 | 4 | 1 | 3.8 | 5.0 | 1 | 10.5 | 5.3 |
| 21000 | 4 | 1 | 5.7 | 6.6 | 1 | 10.8 | 5.9 |

## Disk-shaped scatterer problem

| Elements | Order | CPU Time |  |  | Memory |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | HDG | UDG | IPDG | HDG | UDG | IPDG |
| 1200 | 2 | 1 | 3.7 | 3.4 | 1 | 8.4 | 2.2 |
| 5100 | 2 | 1 | 5.0 | 4.0 | 1 | 8.4 | 2.3 |
| 21000 | 2 | 1 | 6.8 | 4.1 | 1 | 9.0 | 2.6 |
| 1200 | 3 | 1 | 3.1 | 4.0 | 1 | 9.2 | 3.3 |
| 5100 | 3 | 1 | 5.1 | 4.7 | 1 | 10.3 | 3.6 |
| 21000 | 3 | 1 | 7.2 | 5.7 | 1 | 11.0 | 4.0 |
| 1200 | 4 | 1 | 2.7 | 4.0 | 1 | 10.4 | 5.0 |
| 5100 | 4 | 1 | 3.8 | 5.0 | 1 | 10.5 | 5.3 |
| 21000 | 4 | 1 | 5.7 | 6.6 | 1 | 10.8 | 5.9 |

## Marmousi test-case



Computational domain $\Omega$ composed of 235000 triangles
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## Parallel results for the Marmousi test-case with the HDG-P2 scheme



Parallel results for the Marmousi test-case with the HDG-P2 scheme

|  | CPU Time <br> construction (s) | CPU Time <br> resolution. (s) | Maximum <br> Memory (MB) |
| :---: | :---: | :---: | :---: |
| sequential | 67 | 133 | 9927 |
| 2 proc. $(2 / 1)$ | 32 | 93 | 5892 |
| 4 proc. $(2 / 2)$ | 15 | 56 | 3340 |
| 8 proc. $(4 / 2)$ | 8 | 38 | 2092 |
| 16 proc. $(4 / 4)$ | 4 | 39 | 3695 |
| 32 proc. $(4 / 8)$ | 2 | 21 | 1312 |
| 64 proc. $(8 / 8)$ | 1 | 19 | 893 |

Parallel results for the Marmousi test-case with the HDG-P3 scheme

|  | CPU Time <br> construction (s) | CPU Time <br> resolution (s) | Maximum <br> Memory (MB) |
| :---: | :---: | :---: | :---: |
| sequential | 207 | 321 | 17631 |
| 2 proc. $(2 / 1)$ | 96 | 196 | 10048 |
| 4 proc. $(2 / 2)$ | 47 | 116 | 5849 |
| 8 proc. $(4 / 2)$ | 23 | 75 | 5205 |
| 16 proc. $(4 / 4)$ | 12 | 72 | 4628 |
| 32 proc. $(4 / 8)$ | 6 | 42 | 1689 |
| 64 proc. $(8 / 8)$ | 3 | 33 | 1229 |

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## Conclusions-Perspectives

Conclusions

- The HDG scheme has the correct convergence order $(p+1)$
- On a same mesh the HDG formulation is more competitive in terms of memory and computational time than the upwind flux DG formulation and the IPDG method


## Conclusions-Perspectives

Conclusions

- The HDG scheme has the correct convergence order $(p+1)$
- On a same mesh the HDG formulation is more competitive in terms of memory and computational time than the upwind flux DG formulation and the IPDG method


## Perspectives

- Develop 3D Upwind flux DG and HDG formulations for Helmholtz equations
- Solution strategy for the HDG linear system
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## Thank you!



