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Diameter of Minimal Separators in Graphs*

David Coudert^{† ‡}, Guillaume Ducoffe^{† ‡}, Nicolas Nisse^{† ‡}

Project-Teams COATI

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Abstract: We establish general relationships between the topological properties of graphs and their metric properties. For this purpose, we upper-bound the diameter of the minimal separators in any graph by a function of their sizes. More precisely, we prove that, in any graph G, the diameter of any minimal separator S in G is at most $(2\lfloor \frac{\ell(G)}{2} \rfloor - 1) \cdot (|S| - 1)$ where $\ell(G)$ is the maximum length of an isometric cycle in G. We refine this bound in the case of graphs admitting a distance preserving ordering for which we prove that any minimal separator S has diameter at most 2(|S| - 1). Our proofs are mainly based on the property that the minimal separators in a graph G are connected in some power of G.

Our result directly implies that the treelength tl(G) of any graph G is at most $2\lfloor \frac{\ell(G)}{2} \rfloor - 1$ times its treewidth tw(G). In addition, we prove that, for any graph G that excludes an apex graph H as a minor, $tw(G) \leq c_H \cdot tl(G)$ for some constant c_H only depending on H. We refine this constant when G has bounded genus g by showing that $tw(G) = O(g^{3/2}) \cdot tl(G)$ where the "big O" notation hides a small constant. As a consequence, we obtain a $O(\ell(G))$ -approximation algorithm for computing the treewidth of n-node m-edge graphs that exclude an apex graph as a minor in O(nm)-time.

Key-words: Graph; Treewidth; Treelength; Hyperbolicity; Genus;

 $^{^{\}ddagger}$ Univ. Nice Sophia Antipolis, CNRS, I
3S, UMR 7271, 06900 Sophia Antipolis, France



2004 route des Lucioles - BP 93 06902 Sophia Antipolis Cedex

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[†] Inria, France

Diamètre des séparateurs minimaux dans les graphes

Résumé : Nous établissons des relations générales entre les propriétés topologiques des graphes et leurs propriétés métriques. Dans ce but, nous bornons supérieurement le diamètre des séparateurs minimaux dans un graphe par une fonction de leur taille. Plus précisément, nous prouvons que, dans n'importe quel graphe G, le diamètre de tout séparateur minimal S dans G est au plus $(2\lfloor \frac{\ell(G)}{2} \rfloor - 1) \cdot (|S| - 1)$ avec $\ell(G)$ la plus grande taille d'un cycle isométrique dans G. Nous améliorons cette borne dans le cas des graphes pour lesquels il existe un ordre d'élimination isométrique: nous prouvons que tout séparateur minimal S dans un tel graphe a pour diamètre au plus 2(|S| - 1). Nos preuves sont principalement basées sur le fait que les séparateurs minimaux dans un graphe G sont connexes dans l'une de ses puissances.

Une conséquence directe de nos résultats est que pour tout graphe G, la treelength tl(G) est au plus $2\lfloor \frac{\ell(G)}{2} \rfloor - 1$ fois sa treewidth tw(G). En complément de cette relation, nous prouvons que, pour tout graphe G qui exclut un apex graph H comme mineur, $tw(G) \leq c_H \cdot tl(G)$ avec c_H une constante qui ne dépend que de H. Nous améliorons cette constante dans le cas où G est de genre borné. En conséquence de quoi, nous obtenons un algorithme d'approximation en temps O(nm) pour calculer une $O(\ell(G))$ approximation de la treewidth des graphes qui excluent un apex graph comme mineur.

Mots-clés : Graphe; Treewidth; Treelength; Hyperbolicité; Genre;

1 Introduction

It turns out that for a vast range of graph problems, the borderline between tractable and intractable cases depends on the *tree-like properties* of the graphs. Classical parameters such as treewidth [RS86] aim to measure how close is the *structure* of a graph from the structure of a tree, and there are NP-hard problems that can be solved in polynomial-time on bounded-treewidth graphs. However in practice, many real-life graphs, such as the graphs of the Autonomous Systems of the Internet, have a large treewidth [dMSV11] *i.e.*, they are structurally far from a tree. This fact has motivated an alternative approach namely, studying the *metric* tree-likeness of a graph instead of the topological tree-likeness. A classical graph parameter that measures how close is a graph metric from a tree metric is the *hyperbolicity* [Gro87]. In this paper, we combine both approaches in order to establish new relationships between the topological properties of graphs and their metric properties.

A tree-decomposition of a graph [RS86] is a way to represent it by a family of subsets of its vertex-set organized in a tree-like manner and satisfying some connectivity properties. More formally, a tree decomposition of a graph G = (V, E) is a pair (T, \mathcal{X}) where $\mathcal{X} = \{X_t \mid t \in V(T)\}$ is a family of subsets of V, called *bags*, and T is a tree, such that:

1.
$$\bigcup_{t \in V(T)} X_t = V;$$

- 2. for any edge $uv \in E$, there is $t \in V(T)$ such that X_t contains both u and v;
- 3. for any vertex $v \in V$, the set $\{t \in V(T) \mid v \in X_t\}$ induces a subtree of T.

Classically, it is interesting to minimize the size of the bags. The width of (T, \mathcal{X}) equals to $\max_{t \in V(T)} |X_t| - 1$. The treewidth of G, denoted by tw(G), is the minimum width over all tree-decompositions of G. Dourisboure and Gavoille introduced a metric aspect in treedecompositions by studying the diameter of the bags [DG07]. The diameter of a bag X of a tree-decomposition is the maximum distance in G between any pair of vertices in X. The length of a tree-decomposition is the maximum diameter of its bags, and the treelength of G, denoted by tl(G), is the minimum length over all tree-decomposition of G.

Tree-decompositions play an important role in the Graph Minor Theory [RS85]. They have mainly been studied for their algorithmic applications since they are the corner-stone of many dynamic programming algorithms for solving graph problems. For instance, many NP-hard problems can be solved in polynomial-time in the class of bounded-treewidth graphs (e.g., see [Bod88, Bod93]). In particular, problems that are expressible in Monadic Second Order Logic can be solved in linear time when the treewidth is bounded [Cou90]. Another framework where tree-decompositions play an important role is the *bi-dimensionality theory* that allowed the design of sub-exponential-time algorithms for many problems in the class of graphs excluding some fixed graph as a minor [DH08]. In all cases, computing tree-decompositions with small width is a prerequisite. Not surprisingly, computing the treewidth and optimal tree-decomposition is NP-hard in general graphs (more precisely, it is NP-hard in the class of bipartite and cobipartite graphs) [ACP87]. Fixed Parameter Tractable algorithms have been designed (e.g., [Bod96, BDD⁺13]) but they are not efficient in practice. As far as we know, the best approximation algorithm has approximation ratio $O(\sqrt{\log tw(G)})$ for general graph G [FHL08]. There exist constant-ratio approximation algorithms in the case of bounded genus graphs [ST94, FHL08].

Computing the treelength of a graph is also NP-hard. More precisely, deciding whether a graph has treelength at most 2 is NP-hard [Lok10]. Moreover, it is hard to approximate within a factor smaller than 3/2 in weighted graphs [Lok10]. On the positive side, Dourisboure and Gavoille designed a 3-approximation algorithm for treelength, that performs in O(nm)-time in

n-node *m*-edge graphs [DG07]. Treelength has applications in the design of compact routing schemes [Dou05]. Moreover, graphs with bounded treelength also have bounded hyperbolicity¹ [CDE⁺12] and there are hard problems that can be solved efficiently on graphs with a bounded hyperbolicity. For instance, graphs with a bounded hyperbolicity admit a PTAS for the well-known Traveling Salesman problem [KL06]. There are also greedy routing schemes with a low additive stretch [BPK10], and approximation algorithms for several packing, covering, and augmentation problems [CE07] up to an additive constant that are devoted to these graphs.

The main goal of this work is to establish relationships between treewidth and treelength in order to take the algorithmic advantages from both sides. The treelength of a graph and its treewidth are uncomparable in general. Indeed, on the one hand for any cycle C_n with $n \ge 3$ vertices, $tw(C_n) = 2$ and $tl(C_n) = \lfloor \frac{n}{3} \rfloor$. This suggests that having a large treelength relies on large cycles. A subgraph H of a graph G is *isometric* if, for any two vertices of H, the distance between them is the same in H as in G. Note that the size of a longest isometric cycle in a graph can be computed in polynomial-time [Lok09]. It is known that the treelength of a graph G is bounded by the maximum length of a chordless cycle in G [DG07]. However, there are graphs such as grids with bounded-length isometric cycles and arbitrarily large treelength. We show that, in a graph G without long isometric cycles, tl(G) = O(tw(G)). In particular, this is the case in graphs with bounded hyperbolicity.

On the other hand, the complete graph with n vertices has treewidth n-1 and treelength 1. Another interesting example is the graph H obtained by adding a universal vertex to a squaregrid with n^2 vertices, for which it holds tw(H) = n + 1 and tl(H) = 2. Note that such graphs have a large genus. On the other hand, it is known that $tw(G) < 12 \cdot tl(G)$ for any planar graph G [Die09, DG09]. Therefore, it is natural to ask whether having a treewidth arbitrarily larger than the treelength requires a large genus. In this report, we prove that tw(G) = O(tl(G)) in bounded-genus graphs.

Altogether, our results allow us to design a very simple algorithm to compute new bounds for the treewidth in general graphs.

1.1 Our contributions

We introduce a very generic method to upper-bound the diameter of minimal separators in graphs. More precisely, we prove that minimal separators in a graph G induce connected subsets in some of its power G^j , where j only depends on the length of cycles in some arbitrary cycle basis of G. We deduce from our method that, for any graph G with longest isometric cycle of size $\ell(G)$ and for any minimal separator S in G, the diameter of S is upper bounded by $(2\lfloor \frac{\ell(G)}{2} \rfloor - 1) \cdot (|S| - 1)$. Thus it easily follows that, for any graph G which is not a tree, $tl(G) \leq (2\lfloor \frac{\ell(G)}{2} \rfloor - 1)(tw(G) - 1)^2$. Moreover, this implies that $tl(G) \leq 4(\delta + 1) \cdot (tw(G) - 1)$ in any δ -hyperbolic graph.

We then refine our bound in several particular graph classes (the formal definition of these classes are postponed to the technical sections of the paper). For any graph G in the class of nullhomotopic graphs (including the class of dismantable graphs), we prove that $tl(G) \leq tw(G)$. In the class of graphs G that admit a distance preserving ordering, we prove that $tl(G) < 2 \cdot tw(G)$. We emphasize that this latter class contains the cobipartite graphs for which computing the

¹Roughly, the hyperbolicity δ of a simple connected graph G = (V, E), as defined by Gromov [Gro87], is the smallest value such that $\forall u, v, x, y \in V, d(u, v) + d(x, y) \leq \max\{d(u, x) + d(v, y), d(u, y) + d(v, x)\} + 2\delta$. This parameter can be computed in $O(n^{3.69})$ -time [FIV12].

²Very recently and independently of this work, Diestel and Muller proved that $tl(G) \leq \ell(G)(tw(G)-1)$ [DM14]. Unlike our results which apply to any minimal separator in a graph, theirs rely on minimal separators in a specific tree-decomposition called an atomic tree-decomposition.

treewidth is NP-hard. Thus, combined with the 3-approximation for treelength [DG07], our results provide a polynomial-time algorithm for computing a new non trivial lower-bound for treewidth.

Finally, we consider lower-bounds for treelength. We prove that, for any graph excluding an apex graph H as a minor, there is a constant c_H such that $tw(G) \leq c_H \cdot tl(G)$. The constant c_H only depends on H. In the particular case of graphs with bounded genus g, we prove that $tw(G) = O(g^{3/2}) \cdot tl(G)$ where the "big O" notation hides a small constant. As a consequence, the 3-approximation for treelength [DG07] also allows to approximate the treewidth in the class of graphs that exclude an apex graph as a minor and in the class of bounded-genus graphs.

2 Preliminaries

All graphs considered in this paper are simple (*i.e.*, without loops or multiple edges), connected and finite. Given a graph G = (V, E), the number |V| of vertices will always be denoted by nand the number of edges |E| by m.

Minimal separators A set $S \subseteq V$ is a *minimal separator* if there exist $a, b \in V \setminus S$ such that any path from a to b intersects S and, for any proper subset $S' \subset S$, there is a path from a to b which does not intersect S'. We name any such a set S an a-b minimal separator.

A connected component $C \subseteq V \setminus S$ of $G[V \setminus S]$ is *full* with respect to S if any node in S has a neighbour in C. Any *a-b* minimal separator has at least two full components: the one containing a and the one containing b. Conversely, any separator having at least two full components is a minimal separator.

A graph is said *well connected* if each of its minimal separators induces a connected subgraph [DVM86].

Cycle space The set \mathcal{C} of Eulerian subgraphs of G is called the *cycle space* of G. It is well known that \mathcal{C} forms a vector space over \mathbb{F}_2 where the addition of two subgraphs of \mathcal{C} is their symmetric difference. That is, the addition $G_1 \oplus \cdots \oplus G_i$ of several subgraphs of G is equal to the subgraph consisting of the edges that appear an odd number of times in G_1, \cdots, G_i . A graph is said *null homotopic* if its cycle space admits a basis constituted of triangles.

Theorem 1 [DVM86] Any connected null-homotopic graph is well-connected.

For any $X \subseteq V$, let $diam_G(X)$ denote the maximum distance in G between any pair of vertices in X. Last, for any $j \ge 1$, the graph G^j is obtained from G by adding an edge between any two distinct nodes that are at distance at most j in G.

3 Diameter of Minimal Separators in Graphs

In this section, we prove that the diameter of any minimal separator S in a graph G is upperbounded by an $O(\ell(G) \cdot |S|)$, where $\ell(G)$ is the length of a longest isometric cycle in G. For this purpose, we provide an upper-bound on the smallest integer j such that G^j is null-homotopic. We then strengthen our results in some particular graph classes.

3.1 Case of general graphs

The next theorem upper-bounds the least index j such that the power G^{j} is null-homotopic as a function of the length of the cycles of the graph G. By Theorem 1, this implies that G^{j} is well-connected which will be used to upper-bound the diameter of minimal separators in G.

Theorem 2 Let G be connected and such that its cycle space can be generated with cycles of length at most l. Then $G^{\lfloor \frac{l}{2} \rfloor}$ is null-homotopic and so, well-connected.

Proof. We prove that cycles of $G^{\lfloor \frac{l}{2} \rfloor}$ are generated by its triangles, which prove that $G^{\lfloor \frac{l}{2} \rfloor}$ is null-homotopic. The fact that $G^{\lfloor \frac{l}{2} \rfloor}$ is well-connected follows from Theorem 1.

Let $j \ge 1$ and let $e = \{u, v\}$ be an edge of G^j . The *length* of e denotes the distance between u and v in G. Given a cycle C of $G^{\lfloor \frac{l}{2} \rfloor}$, its number of edges in $G^{\lfloor \frac{l}{2} \rfloor}$ is denoted by l(C) and let $w(C) = \sum_{\{x,y\} \in E(C)} d_G(x, y)$ be the sum of the lengths of all its edges. Note that $w(C) \ge l(C)$.

The proof is by induction on (l(C), w(C)) in lexicographic order. The base cases are when l(C) = 3, in which case the cycle C is a triangle. Thus from now on assume l(C) > 3, hence w(C) > 3. There are two cases.

- If there is a chord in C, then we can split it in two smaller cycles C_1, C_2 with $l(C_1), l(C_2) < l(C)$; by the induction hypothesis, both cycles are a sum of triangles and so is cycle C.
- Else, C is induced and we associate to every edge $e = \{x, y\} \in E(C)$ a xy-shortest-path P_e in G. Note that, any vertex z of P_e is adjacent to both x and y in $G^{\lfloor \frac{l}{2} \rfloor}$. Indeed, $dist_G(z, x), dist_G(z, y) \leq dist_G(x, y) \leq \lfloor \frac{l}{2} \rfloor$. Therefore, no node in C can be contained as an internal node of some P_e because otherwise there would be a chord in C.

However, it may be that there are two edges $e \neq e'$ of C such that $P_e, P_{e'}$ have a common internal node, and we will first solve this subcase. Note that if $P_e, P_{e'}$ share a common internal node, then it implies that the sets $e = \{x, y\}, e' = \{x', y'\}$ touch in the graph power G^j , *i.e.*, we have w.l.o.g. either x = x' or $\{x, x'\} \in E(C)$.

- Case 1: x = x'. Let $z \in P_e \cap P_{e'}$ be a common internal node to both paths, let T_1, T_2 be the triangles in $G^{\lfloor \frac{l}{2} \rfloor}$ that are respectively induced by x, y, z and x, y', z. The cycle C' is obtained from C by replacing the path y, x, y' with the path y, z, y' that exists in $G^{\lfloor \frac{l}{2} \rfloor}$. In such case, we have that l(C) = l(C') while w(C') < w(C), hence we can apply the induction hypothesis to conclude that C' is a sum of triangles. Since we have that $C = T_1 \oplus T_2 \oplus C'$, then it implies that the same holds for cycle C.
- Case 2: $\{x, x'\} \in E(C)$. Let $z \in P_e \cap P_{e'}$ be a common interval node to both paths. We consider the triangles T_1, T_2, T_3 in $G^{\lfloor \frac{l}{2} \rfloor}$ that are respectively induced by x, y, z and x', y', z and x, x', z. Let C' be the cycle obtained from C by replacing the path y, x, x', y' with the path y, z, y'. Since l(C') = l(C) - 1, we can apply the induction hypothesis to conclude that C' is a sum of triangles. Since we have that $C = T_1 \oplus T_2 \oplus T_3 \oplus C'$, then it implies that the same holds for cycle C.

Finally, assume for the remaining of the proof that all shortest-paths P_e in G have their internal nodes that are pairwise disjoint. For any edge $e = \{x, y\} \in E(C)$, write $P_e = (x = z_0, z_1, z_2, \ldots, z_{k-1}, y = z_k), k \leq \lfloor \frac{l}{2} \rfloor$. Since P_e is a shortest-path in G, then all sets $x, z_i, z_{i+1}, i < k$, induce a triangle T_i^e in $G^{\lfloor \frac{l}{2} \rfloor}$. So, we can define $C_e = \bigoplus_{1 \leq i \leq k-1} T_i^e$. Note that C_e is the cycle induced by P_e and the edge e. Let C' be obtained from \overline{C} by replacing every edge $e \in E(C)$ with the path P_e . By construction, C' is a cycle in G and so, it is the sum of cycles of length at most l in G by the hypothesis. Furthermore, we claim that each cycle of length at most l in G is a sum of triangles in $G^{\lfloor \frac{l}{2} \rfloor}$, that easily comes from the fact that such a cycle induces a clique in the power. As a result, we have that C' is a sum of triangles in $G^{\lfloor \frac{l}{2} \rfloor}$. The same holds for C as it equals $C' \oplus \left(\bigoplus_{e \in E(C)} C_e\right)$.

Corollary 1 For any connected graph G that is not a tree, we have $G^{\lfloor \frac{l(G)}{2} \rfloor}$ is null-homotopic, where l(G) denotes the length of a longest isometric cycle in G.

Proof. It follows from Theorem 2 combined with the fact that isometric cycles generate the cycle space.

Corollary 2 For any δ -hyperbolic graph G, we have $G^{2\delta+1}$ is null-homotopic and so, well-connected.

Proof. It follows from Corollary 1 combined with the fact that an isometric cycle in a δ -hyperbolic graph has length at most $4\delta + 3$.

Next, we bound the diameter of minimal separators using the fact that some power of a graph is well-connected. We will use the following result.

Lemma 1 (Theorem 1.3,[DVM86]) A connected graph G is well-connected if and only if, for every pair of connected subgraphs G_1, G_2 whose union is G, the graph $G_1 \cap G_2$ is connected.

Theorem 3 Let G be connected, j be a positive integer such that G^j is well-connected. Every minimal separator in G induces a connected subgraph in the power G^{2j-1} .

Proof. Let S be a minimal separator in G and let A, B be two distinct full components of $G \setminus S$. Let S_1, S_2 be an arbitrary bipartition of nodes in S. We claim that $d_G(S_1, S_2) \leq 2j - 1$. Note that it will prove that $G^{2j-1}[S]$ is connected because the bipartition is chosen arbitrarily.

For any $r \ge 0$ and any $X \subseteq V$, let $B_r(X)$ denote the set of vertices at distance at most r from a vertex in X. We say that two subgraphs *touch* each other if they intersect or if there exists an edge between one node of each subgraph. To prove the claim, let us define the following sets:

$$\begin{aligned} X_1 &= \left[B_{\lfloor \frac{j}{2} \rfloor}(S_1) \cap A \right] \cup \left[B_{\lceil \frac{j}{2} \rceil - 1}(S_1) \cap (V(G) \setminus A) \right], \\ X_2 &= \left[B_{\lfloor \frac{j}{2} \rfloor}(S_2) \cap (V(G) \setminus A) \right] \cup \left[B_{\lceil \frac{j}{2} \rceil - 1}(S_2) \cap A \right], \\ X &= X_1 \cup X_2, \end{aligned}$$

and we set G_1, G_2 the subgraphs of G^j that are respectively induced by the subsets $A \cup X$ and $V(G) \setminus (A \setminus X)$. Since we have that A is a full component of $G \setminus S$ by the hypothesis, it follows that $G[A \cup S]$ is connected and so, G_1 is connected in G^j because all nodes in $X \setminus S$ are adjacent to some node in S in G^j . Similarly, we have that B is a full component by the hypothesis, hence $G[B \cup S]$ is connected, that implies $G[V(G) \setminus A]$ is connected because all connected components of $G \setminus (A \cup B \cup S)$ touch the separator S in G. Therefore, G_2 is also connected in G^j .

There are two cases to be considered.

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1. Suppose that subsets $A \setminus X$ and $V(G) \setminus (A \cup X)$ touch in the graph power G^j , and let $u \in A \setminus X, v \in V(G) \setminus (A \cup X)$ be adjacent in G^j . If there is a *uv*-shortest-path in G that intersects both S_1, S_2 , then we obtain $d_G(S_1, S_2) \leq d_G(u, v) - 2 \leq j - 2$, which proves the claim.

Otherwise, we can assume w.l.o.g. that $d_G(u, v) \ge d_G(u, S_1) + d_G(v, S_1) \ge \left(\left\lfloor \frac{j}{2} \right\rfloor + 1\right) + \left(\left(\left\lceil \frac{j}{2} \right\rceil - 1\right) + 1\right) \ge j + 1$, thus contradicting the fact that nodes u, v are adjacent in G^j .

2. Let us assume for the remaining of the proof that $A \setminus X$ and $V(G) \setminus (A \cup X)$ do not touch in the graph power G^j . That is, X is a separator of G^j . We have: $G^j = G_1 \cup G_2$, G_1, G_2 are connected and G^j is well-connected by the hypothesis. Therefore, $X = G_1 \cap G_2$ induces a connected subgraph in G^j by Lemma 1. In such case, let $x_1 \in X_1, x_2 \in X_2$ be adjacent in G^j . Up to replacing one vertex amongst x_1, x_2 with some node in S onto a x_1x_2 -shortestpath in G, we can assume w.l.o.g. $x_1, x_2 \in A \cup S$. Let $y_1 \in S_1, y_2 \in S_2$ be such that $d_G(x_1, y_1) \leq \lfloor \frac{j}{2} \rfloor$ and $d_G(x_2, y_2) \leq \lceil \frac{j}{2} \rceil - 1$. Then we have that $d_G(S_1, S_2) \leq d_G(y_1, y_2) \leq d_G(y_1, x_1) + d_G(x_1, x_2) + d_G(x_2, y_2) \leq \lfloor \frac{j}{2} \rfloor + j + \lceil \frac{j}{2} \rceil - 1 \leq 2j - 1$. This finally proves the claim.

Corollary 3 Let G be connected, j be a positive integer such that G^j is well-connected. For any minimal separator S in G, $diam_G(S) \leq (2j-1)(|S|-1)$.

3.2 Graphs with distance-preserving elimination ordering

In this section, we strengthen the results of previous section in the case of graphs admitting a distance-preserving elimination ordering. We say that G admits a distance-preserving elimination ordering if there exists a total order of V, denoted by v_1, v_2, \ldots, v_n , such that, for any $1 \le i \le n$, the graph $G_i = G \setminus \{v_1, \ldots, v_i\}$ is an isometric subgraph of G.

A graph is dismantable if, for any $1 \leq i < n$, there exists j > i, such that $N[u_i] \setminus \{u_1, \dots, u_{i-1}\} \subseteq N[u_j]$. It is easy to check that, if a graph is dismantable, then it admits a distance-preserving elimination ordering. Furthermore, we have by a result from [BC08] that every graph is an isometric subgraph of some dismantable graph, hence there are dismantable graphs with arbitrarily long isometric cycles.

Another example of graphs that admit a distance-preserving elimination ordering is the class of cobipartite graphs. Note that this implies that computing the treewidth is NP-hard in the class of graphs that admits a distance-preserving elimination ordering.

We first show that, if G is a graph that admits a distance-preserving elimination ordering, then G^2 is null-homotopic. This is an improvement over Corollary 1 in this graph class.

Lemma 2 A graph that admits a distance-preserving elimination ordering has its cycle space generated by all its triangles and quadrangles.

Proof. It is enough to prove the result for induced cycles, because they generate the cycle space. Let (u_1, u_2, \ldots, u_n) be a distance-preserving elimination ordering of G. By contradiction, amongst all induced cycles falsifying the property let C maximize the least index j such that $u_j \in C$. Note that C is a cycle of $G_{j-1} = G[\{v_j, \cdots, v_n\}]$ by the hypothesis. Moreover, all cycles contained into G_j are generated by triangles and quadrangles of G because of the maximality of index j. Let $x, y \in V(C)$ be the two neighbours of u_j in cycle C. By the hypothesis, x, y are not adjacent because C is induced. So, because $x, y, v_j \in G_{j-1}$ which has a distance-preserving

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elimination ordering, there is $u_i, i > j$ such that x, y are adjacent to u_i . Moreover, $u_i \notin C$ because otherwise C would be the quadrangle (u_j, x, u_i, y, u_j) , thus contradicting the fact that it falsifies the property. As a result, $C = Q \oplus C'$, with Q the quadrangle (u_j, x, u_i, y, u_j) and C' is the cycle of G_j obtained from C by replacing the path x, u_j, y with x, u_i, y . Furthermore, cycle C' is a sum of induced cycles of G_j that are themselves a sum of triangles and quadrangles by maximality of j. Hence so is cycle C, which contradicts the fact that it falsifies the property.

Corollary 4 If G admits a distance-preserving elimination ordering, then its square graph G^2 is null-homotopic and so, well-connected.

Note that the combination of Corollary 4 with Theorem 3 implies that every minimal separator in a graph that admits a distance-preserving elimination ordering induces a connected subgraph of its *cube* graph G^3 . By comparison, Lemma 3 proves that the same happens in the square graph G^2 .

Lemma 3 Let G be a graph that admits a distance-preserving elimination ordering. Every minimal separator S in G induces a connected subgraph in the square graph G^2 .

Proof. Let S be a minimal separator in a graph G that admits a distance-preserving elimination ordering v_1, \dots, v_n . The proof is by induction on s = |S|, with the trivial base case when S is reduced to a cut-vertex. For s > 1, let $u_j \in V$ be the first vertex in the distance-preserving elimination ordering such that S is not a minimal separator in $G_j = G \setminus \{v_1, \dots, v_j\}$. Note that G_j also admits a distance-preserving elimination ordering by the hypothesis.

First, let us assume that $u_j \in S$. Let A, B be two distinct full components of $G_{j-1} \setminus S$ (with the convention that $G_0 = G$). Then A, B are also full components of $G_j \setminus S$, hence $S \setminus u_j$ is a minimal separator in G_j . By the induction hypothesis, we have that $G_j^2[S \setminus u_j]$ is connected. Furthermore, let $a \in A, b \in B$ be two neighbours of u_j that are in distinct full components. The fact that G_j is an isometric subgraph by the hypothesis implies that we have $d_{G_j}(a, b) = 2$ and so, $N(a) \cap N(b) \cap (S \setminus u_j) \neq \emptyset$. This implies $d_G(u_j, S \setminus u_j) \leq d_G(u_j, N(a) \cap N(b) \cap (S \setminus u_j)) \leq 2$. As a result, $G^2[S]$ is connected.

From now on, let us assume that $u_i \notin S$. There are several cases to be considered.

- If S is not a separator in G_j , then $S = N(u_j) \setminus \{u_1, \ldots, u_{j-1}\}$ and so, $G^2[S]$ is a complete graph.
- It remains the case where S is a separator in G_j , but not a minimal one. In such a case, S must have exactly two full components A and B, and u_j is in one of them, say $u_j \in A$ (otherwise, there would still be two distinct full components in $G_j \setminus S$). Furthermore, since $A \setminus u_j$ is not a full component of $G_j \setminus S$, either $A \setminus u_j$ is disconnected, or there are nodes in S with no other neighbour in A than u_j (or both). Formally, let A_1, \ldots, A_p be the connected components of $A \setminus u_j$, let $S_i = N(A_i) \cap S$ and let $Z = \{v \in S \mid N(v) \cap A = \{u_j\}\}$. We have p > 1 or $Z \neq \emptyset$.

We claim that, for any $1 \leq i \leq p$, $S_i \subsetneq S$. By contradiction, if $S_i = S$ for some *i* then A_i, B are distinct full components of $G_j \setminus S$ and so, *S* is a minimal separator in G_j , which contradicts the hypothesis. Hence $S_i \subsetneq S$ is a minimal separator in G_j , and A_i, B are distinct full components of $G_j \setminus S_i$.

By the induction hypothesis we get that $G_j^2[S_i]$ is a connected graph. We now claim that the graph $G^2[\bigcup_i S_i] = G^2[S \setminus Z]$ is connected. It is obvious if p = 1, so let us assume p > 1. To prove the claim, it suffices to prove that, for any $1 \leq i < i' \leq p$, the subsets S_i and S'_i intersect. We first note that there is a neighbour of u_j in every connected component of $A \setminus u_j$, and we name $a_i \in A_i, a_{i'} \in A_{i'}$ two neighbours of u_j . Since G_j is an isometric subgraph, then $d_{G_j}(a_i, a_{i'}) = 2$ and so, $N(a_i) \cap N(a_{i'}) \cap S \neq \emptyset$, which in turn implies that $S_i \cap S_{i'} \neq \emptyset$.

Finally, let $z \in Z$ and let $a \in A \setminus u_j$ be a neighbour of u_j . Since G_j is isometric, then we have $d_{G_j}(z, a) = 2$ and so, $N(a) \cap N(z) \cap S \neq \emptyset$. As a result, every vertex in Z, if any, is adjacent to some vertex of $S \setminus Z$, which implies that $G^2[S]$ is connected.

Note that the result of Lemma 3 is the best possible that one can expect for this class of graphs, in the sense that they are graphs admitting a distance-preserving elimination ordering that are not well-connected. This can be easily shown with a cycle with 4 vertices.

Corollary 5 Let G be a graph that admits a distance-preserving elimination ordering. For any minimal separator S in G, $diam_G(S) \leq 2(|S| - 1)$.

To conclude this section, our results can be strenghtened in the case of dismantable graphs. Indeed, it was already noticed in [DVM86] that dismantable graphs are null-homotopic, but the proof was left to the reader. We give it here for self-containment.

Lemma 4 A dismantable graph is null-homotopic and so, well-connected.

Proof. Let G be a dismantable graph. We prove that cycles of G are generated by its triangles, which proves that G is null-homotopic. The fact that G is well-connected follows from Theorem 1.

It is enough to prove that induced cycles are generated by triangles. Let (u_1, u_2, \ldots, u_n) be a dismantling ordering of G. By contradiction, amongst all induced cycles falsifying the property, let C maximize the least index j such that $u_j \in C$. Let $x, y \in V(C)$ be the two neighbours of u_j in cycle C, and let u_i , with i > j, be a dominator of u_j in G_{j-1} . We have that $u_i \notin C$ because C is induced and it has length at least 4 by the hypothesis. As a result, $C = T_1 \oplus T_2 \oplus C'$, with T_1 the triangle induced by nodes u_i, x, u_j ; with T_2 the triangle induced by nodes u_i, y, u_j ; and with C' a cycle of G_j obtained from C by replacing the path x, u_j, y with x, u_i, y . Furthermore, cycle C' is a sum of induced cycles of G_j that are themselves a sum of triangles of G_j by maximality of j. Hence, so is cycle C, which contradicts the fact that it falsifies the property.

Note that Lemma 4 extends a previous result from [JKW03] where it was shown that bridged graphs (which are dismantable by [Che97]) are well-connected.

4 Relating treewidth with treelength

4.1 Preliminaries

In this section, we recall some useful definitions and known results that will be used in the sequel.

A graph is *chordal* if all its induced cycles have length at most 3.

Let G = (V, E) be a graph. A triangulation of G is any chordal supergraph $H = (V, E \cup F)$ of G. A triangulation $H = (V, E \cup F)$ is minimal if, for any $f \in F$, $H' = (V, E \cup F \setminus \{f\})$ is not chordal.

A tree-decomposition of G consists of a pair (T, \mathcal{X}) where T is a tree and $\mathcal{X} = (X_t)_{t \in V(T)}$ is a family of subsets of V, called *bags*, indexed by the nodes of T and that satisfies the following three properties.

- 1. $\bigcup_{t \in V(T)} X_t = V;$
- 2. for any $\{u, v\} \in E$, there is $t \in V(T)$ with $u, v \in X_t$;
- 3. for any $u \in V$, the set of bags containing u induces a subtree of T.

The diameter of a bag X is the maximum distance in G between any two nodes of X. The length of (T, \mathcal{X}) equals the maximum diameter of its bags. The treelength of G, denoted by tl(G), is the minimum length over all tree-decompositions of G.

The width of (T, \mathcal{X}) equals the maximum size of its bags minus one. The treewidth of G, denoted by tw(G), is the minimum width over all tree-decompositions of G. Equivalently, the treewidth of G is the minimum over all minimal triangulations H of G of $\omega(H) - 1$, where $\omega(H)$ is the maximum size of a clique in H.

Let G = (V, E) be a chordal graph. The clique-graph $\mathcal{C}(G)$ of G is the weighted graph $\mathcal{C}(G) = (V_C, E_C, w)$, where $w : E_c \to \mathbb{N}$, V_C is the set of maximal cliques of G, $\{C_1, C_2\} \in E_C$ if $C_1 \cap C_2 \neq \emptyset$ and $w(\{C_1, C_2\}) = |C_1 \cap C_2|$. A clique-tree of G is a tree $T_C = (V_C, F)$ such that for each vertex $x \in V$, the set of maximal cliques containing x induces a subtree of T_C . Note that (T_C, V_C) is a tree-decomposition of G.

Theorem 4 [GHP95] Let G = (V, E) be a chordal graph. Any maximum weighted spanning tree of C(G) is a clique tree of G.

Let S, T be two minimal separators in G. S crosses T if there are two components C, D of $G \setminus T$ that S intersects. If S does not cross T, then S is said *parallel* to T.

Theorem 5 [PS97] H is a minimal triangulation of G if and only if H is obtained by completing all sets of a maximal set of pairwise parallel minimal separators in G.

4.2 Upper-bounds for treelength

Using the results recalled in Section 4.1, we are now able to upper-bound the treelength of a graph by a linear function depending on the size of its minimal separators. We then show that the treelength of a graph is upper-bounded by a function that is linear in its treewidth.

Lemma 5 Let G be a graph and S be a maximal set of pairwise parallel minimal separators in G. If there is a constant c_S such that $diam(S) \leq c_S(|S|-1)$ for any $S \in S$, then $tl(G) \leq \max\{1\} \cup \{c_S \cdot (|S|-1) \mid S \in S\}$.

Proof. Let H be the supergraph of G obtained by completing all sets of S. By Theorem 5, H is a minimal triangulation of G. By Theorem 4, H admits a clique-tree T_C . Moreover, T_C corresponds to a reduced tree-decomposition of G where each clique of H induces a bag. Let Ω be any maximal clique in H, i.e., Ω is any bag of the tree-decomposition T_C . Let $x, y \in \Omega$. By definition of H, either $\{x, y\} \in E(G)$ or there is a minimal separator $S \in S$ that contains both x and y. In the latter case, $d(x, y) \leq diam_G(S) \leq c_S(|S| - 1)$.

Theorem 6 Let G be a graph with treewidth tw(G). If every minimal separator in G induces a connected subgraph in its power G^j , then $tl(G) \leq \max\{1, j \cdot (tw(G) - 1)\}$.

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Proof. Let H be a minimal triangulation of G with maximum clique-size tw(G) + 1. By Theorem 5, there is a maximal set S of pairwise parallel minimal separators of G such that H results from the completion of all elements in S. Note that any $S \in S$ induces a clique in H and therefore S is strictly contained in a maximal clique in H. Hence, $\max_{S \in S} |S| \le tw(G)$. By Lemma 5, $tl(G) \le \max\{1\} \cup \{c_S \cdot (|S|-1) \mid S \in S\} \le \max\{1, j \cdot (tw(G)-1)\}$.

Corollary 6 Let G be a connected graph which is not a tree, then $tl(G) \leq c \cdot (tw(G) - 1)$, where

- c = 2 if G admits a distance-preserving elimination ordering;
- c = 2j 1, where j is the least integer such that G^j is well-connected;
- $c = 2 \left| \frac{l(G)}{2} \right| 1$, where l(G) denotes the length of a longest isometric cycle of G;
- $c = 4\delta + 1$ if G is δ -hyperbolic.

Proof. First item follows from Lemma 3 combined with Theorem 6. Second item follows from Theorem 3 combined with Theorem 6. Third item follows from Corollary 1 combined with Theorem 6. Last item follows from Corollary 2 combined with Theorem 6.

Note that it is NP-hard to compute the treelength of a graph [Lok10], but there exist 3approximation polynomial-time algorithms to compute it [DG07]. Moreover, the hyperbolicity of a graph can be computed in polynomial-time [Gro87, CCL12, FIV12]. Hence, the previous result gives a new way to compute lower-bounds for treewidth.

4.3 Lower-bound in case of bounded-genus graphs

In this section, we prove that the treewidth of a graph is upper-bounded by a function of its treelength and of its genus. Our result is mainly based on the result from [DHT06] stating that any graph with large treewidth and genus contains a large "grid-like" graph as a contraction. We use their terminology.

A partially triangulated $(r \times r)$ -grid is any graph that contains an $(r \times r)$ -grid as a subgraph and is a subgraph of some planar triangulation of the same $(r \times r)$ -grid. A (r, k)-gridoid G is a partially triangulated $(r \times r)$ -grid G' in which k extra edges have been added³.

Theorem 7 [DHT06] Let G be a graph with genus g and tw(G) > 4k(g+1) with $k \ge 12g$, then G contains a (k - 12g, g)-gridoid as a contraction.

We prove that such a gridoid has large treelength and, since the treelength is contractionclosed, such a graph has large treelength too.

Lemma 6 Let G be a partially triangulated $(r \times r)$ -grid. Then, $tl(G) \ge r/(3\sqrt{2}) - 1$.

Proof. The result holds if $r \leq 3$ because in such a case $tl(G) \geq 1 > r/(3\sqrt{2}) - 1$. Else, let G' be the $(r \times r)$ -grid from which G is obtained by planar triangulation. Let V' be the set of vertices of G' that are at distance at least $\lfloor \frac{r-1}{3} \rfloor$ from the external face of G'. The vertices of V' induce a partially triangulated $(r' \times r')$ -grid F in G, $r = 2 \lfloor \frac{r-1}{3} \rfloor + r'$, such that the external face of F has not been triangulated. Moreover, F is isometric in G. Hence, $tl(G) \geq tl(F)$. We show that $tl(F) \geq r/(3\sqrt{2}) - 1$.

³Note that the notion of (r, k)-gridoid is more general in [DHT06].

Let S be a balanced separator in F. That is, any connected component of $F \setminus S$ has size at most $r'^2/2$. Let D-1 be the maximum distance in F between any two vertices of S. We claim that there exists an induced subgraph H of F that is a partially triangulated $(D \times D)$ -grid and such that $S \subseteq V(H)$. Indeed, let x be a top vertex of S in F, let y be a leftmost vertex of S in F, and let H be the subgrid of F with side D and top row containing x and leftmost column containing y. By definition of H, $S \subseteq V(H)$. Furthermore for any $D < r, F \setminus H$ is connected and has $r'^2 - D^2$ nodes. Since $r'^2 - D^2 \leq r'^2/2$, we get that $D^2 \geq \lceil r'^2/2 \rceil$ and so, $D \geq r'/\sqrt{2} \geq r/(3\sqrt{2})$.

It is well known that any tree-decomposition of a graph F has a bag which is a balanced separator of F. By previous paragraph, it has diameter at least $r/(3\sqrt{2}) - 1$ and therefore, $tl(G) \ge r/(3\sqrt{2}) - 1$.

Lemma 7 Let G be a (r,k)-gridoid with $r \ge (3s+1)(\lceil \sqrt{2k} \rceil + 1)$, then $tl(G) \ge s/(3\sqrt{2}) - 1$.

Proof. Because $r \ge (3s + 1)(\lceil \sqrt{2k} \rceil + 1)$, *G* contains at least 2k + 1 vertex-disjoint partially triangulated $((3s + 1) \times (3s + 1))$ -grids as subgraphs. One of them, say *H*, does not contain any node incident to one of the *k* extra edges. Consider the partially triangulated $(s \times s)$ -grid *R* which is in the center of *H*. That is, *R* is a subgraph of *H* and any node of *R* is at distance at least *s* from a node of $G \setminus H$ (it is possible because *H* does not contain an extremity of an extra edge). Therefore, *R* is isometric in *G* and $tl(R) \le tl(G)$. By Lemma 6, $tl(R) \ge s/(3\sqrt{2}) - 1$. ■

Theorem 8 Let G be a graph with genus g and tw(G) > 4k(g+1) with $k \ge 12g$. Then

$$tl(G) = \Omega(tw(G)/g^{3/2}).$$

Proof. By Theorem 7, G contains a (k - 12g, g)-gridoid R as a contraction. Let $k - 12g = (3s + 1)(\lceil \sqrt{2g} \rceil + 1)$ *i.e.*, $s = \frac{k - 12g - \lceil \sqrt{2g} \rceil - 1}{3(\lceil \sqrt{2g} \rceil + 1)}$. By Lemma 7, $tl(R) \ge \frac{k - 12g - \lceil \sqrt{2g} \rceil - 1}{9\sqrt{2}(\lceil \sqrt{2g} \rceil + 1)} - 1$. Thus, by setting k = tw(G)/(4(g + 1)) - 1, we obtain that $tl(R) = \Omega(tw(G)/g^{3/2})$. The result then follows from the fact that treelength is contraction-closed.

An *apex graph* is a graph such that the removal of one vertex creates a planar graph. Similar techniques allow us to deal with graphs that exclude an apex graph as minor.

Let Γ_k be the graph obtained from a $(k \times k)$ -grid by triangulating its internal faces such that all internal vertices become of degree 6, all non-corner external vertices are of degree 4, and then one corner of degree two is joined by edges with all vertices of the external face [FGT11].

Theorem 9 [FGT11] For every apex graph H, there is a $c_H > 0$ such that every connected H-minor-free graph of treewidth at least $c_H \cdot k$ contains Γ_k as a contraction.

Theorem 10 Let H be any apex graph and G be a connected H-minor-free graph of treewidth at least $c_H \cdot k$, where c_H is the constant of Theorem 9. Then $tl(G) \ge tw(G)/(3c_H \cdot \sqrt{2}) - 1$.

Proof. By Theorem 9, G contains Γ_k as a contraction. Moreover, Γ_k is a partially triangulated grid. The result follows from Lemma 6 and the fact that treelength is contraction-closed.

By combining Corollary 6, Theorems 8, 10 and the fact that the treelength can be 3-approximated in $O(n \cdot m)$ -time [DG07], we get the following corollary.

Corollary 7 There is an algorithm that, in any n-node m-edge graph, computes in $O(n \cdot m)$ -time an integer t^* such that:

- $t^* \leq 3 \cdot (2 \left| \frac{\ell(G)}{2} \right| 1) \cdot tw(G)$ where $\ell(G)$ is the size of a longest isometric cycle in G;
- $t^* = \Omega(tw(G)/g^{3/2})$ where g is the genus of G;
- $t^* \geq tw(G)/(3c_H \cdot \sqrt{2}) 1$ if G excludes some apex graph H as a minor.

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