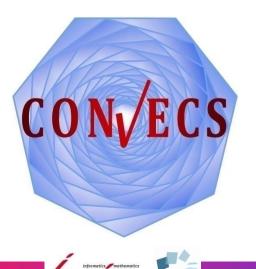
### Automatic Distributed Code Generation from Formal Models of Asynchronous Concurrent Processes

### **Hugues Evrard and Frédéric Lang**

#### **INRIA and LIG – Team CONVECS**

http://convecs.inria.fr



### **Motivation**

- Usage of formal methods
  - specification
  - verification
  - hand-written implementation: time consuming, discrepancies with the specification ?

### Distributed implementation generation

automatically generates a distributed program

## **CADP verification toolbox**

### http://cadp.inria.fr

- Explicit state techniques: LTS (Labeled Transition System) exploration
- 50+ tools for LTS manipulation and verification
  - model checking, compositional verification, test generation...

- Main specification language: LNT
  - LNT semantics formally defined in LTS
- EXEC/CAESAR compiler: LNT to sequential C

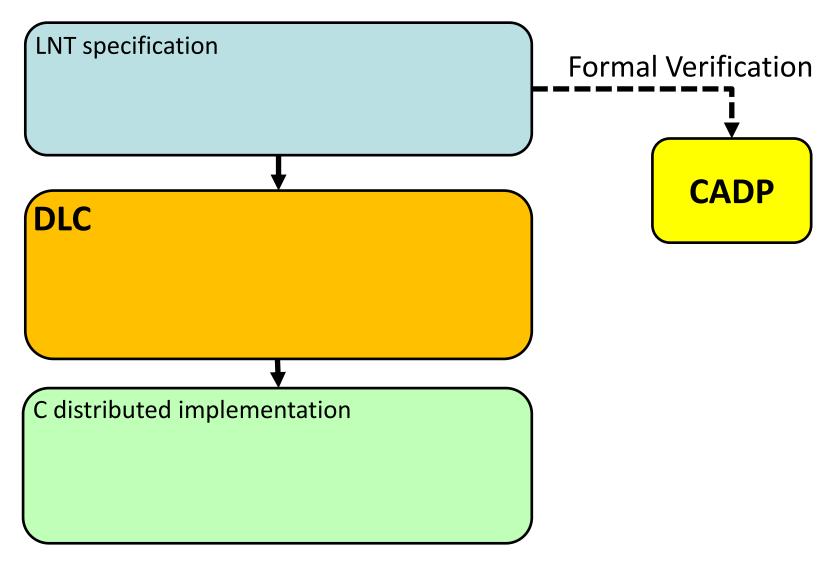
## **This talk**

 Aim: Generate a distributed implementation of a concurrent system from its formal specification (LNT)

### Contributions

- **DLC** (*Distributed LNT Compiler*)
- from LNT to C and TCP sockets
- inter process communication: multiway rendezvous
- interaction with environment: hook functions
- experimentations

## **Distributed LNT Compiler overview**



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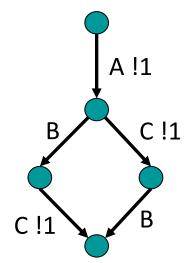
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# LNT (1)

- A process performs actions on gates
- Process interaction by multiway rendezvous on gates
  - Gates are named synchronization points
  - Multiway: n processes synchronize (n >= 2)
  - Possibly exchange data by offers

```
process P1 [A,B] is
   A (1); B
end process
process P2 [A,C] is
   var n:nat in
        A (?n); C(n)
   end var
end process
```

```
(* Parallel composition *)
process MAIN [A,B,C] is
   par A in
        P1 [A,B]
        [| P2 [A,C]
        end par
end process
```



# LNT (2)

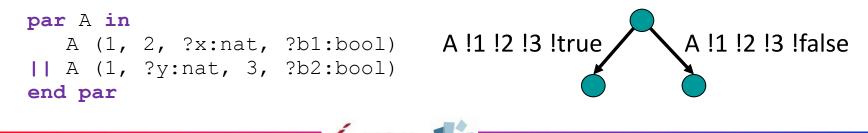
• Non deterministic choice: a process is ready on several actions



• General synchronization: multiple rendezvous per gate, *m*-among-*n* 

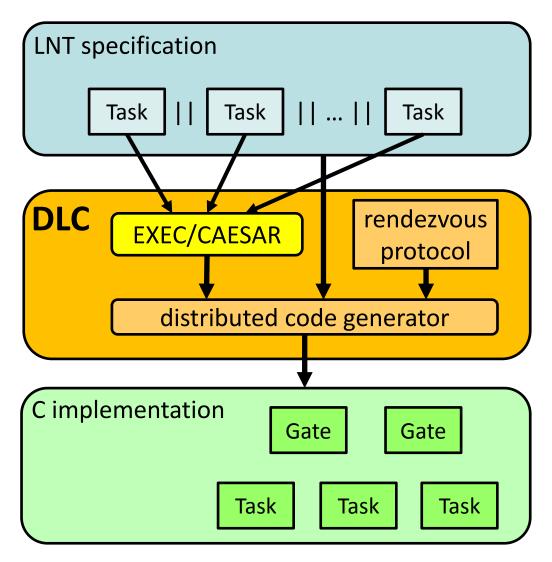
par A, B#2 in	≻ A: (P1,P2,P3)
C -> P1 [A,B,C] P2 [A,B]	➢ B: (P1,P2), (P1,P3), (P2,P3)
C -> P3 [A,B,C]	➤ C: (P1, P3)
end par	

• Value-matching data exchange: send/receive freely combined



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## **Distributed LNT Compiler overview**



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## LNT to sequential C

### • EXEC/CAESAR [Garavel-Viho-Zendri-01]

- C program that explores an execution path inside the LTS
- list possible actions from current state
- still requires code to decide between actions

### • DLC automatically completes the C program of each task

- task may synchronize with others for actions
- adds code to interface with the rendezvous protocol

## **Multiway rendezvous protocol**

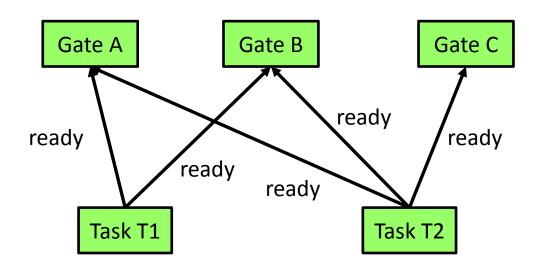
- Role: synchronize task actions
  - a task can be ready on different actions: select A [] B [] ...
  - all tasks of a rendezvous must commit to the same action
- Requirement: distributed implementation
  - avoid unique central synchronizer (performance bottleneck)
  - protocol relies on asynchronous message passing (TCP: reliable, ordered)
- Solution: based on [Parrow-Sjodin-96]
  - One process per gate, one process per task
  - extended: data exchange, general synchronization

par A, B in
 T1 [A,B]
|| T2 [A,B,C]
end par

process T1 [A,B] is
 select
 A
 [] B
 end select
end process

```
process T2 [A,B,C] is
select
        A
  [] B
  [] C; B
  end select
```

end process



• Three phases

- 1. Announces: ready
- 2. Negotiations: lock (ordered to avoid deadlock)

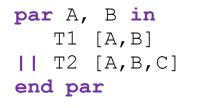
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3. Results: commit/abort

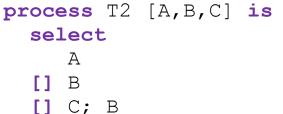
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Gate A



```
process T1 [A,B] is
  select
        A
  [] B
  end select
end process
```



#### end select

end process



lock (A, {T1,T2})

1. Announces: ready

Task T1

2. Negotiations: lock (ordered to avoid deadlock)

Gate B

lock (B, {T1,T2})

3. Results: commit/abort

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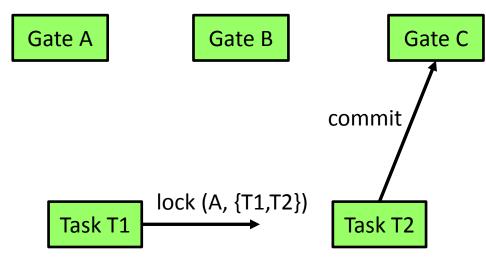
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Gate C

Task T2

lock (C, {T2})

```
par A, B in
   T1 [A,B]
|| T2 [A,B,C]
end par
process T1 [A, B] is
  select
     Α
     B
  Γ1
  end select
end process
process T2 [A,B,C] is
  select
     А
     В
  []
     С; в
  F1
  end select
end process
```



pending: lock (B, {T1,T2})

#### • Three phases

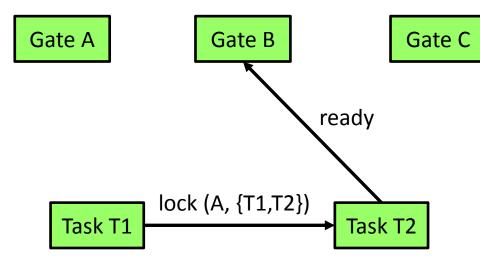
- 1. Announces: ready
- 2. Negotiations: lock (ordered to avoid deadlock)
- 3. Results: commit / abort

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par A, B in T1 [A,B] **||** T2 [A,B,C] end par process T1 [A, B] is select Α B Γ1 end select end process process T2 [A,B,C] is select А В Γ1

[] C; B end select

end process



pending: lock (B, {T1,T2})

• Three phases

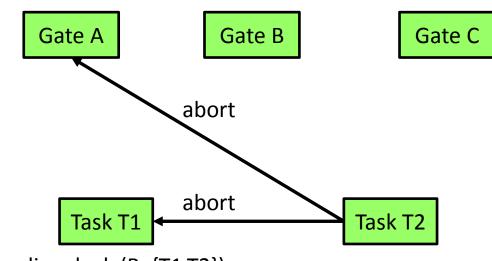
- 1. Announces: ready
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par A, B in
 T1 [A,B]
 II T2 [A,B,C]
end par
process T1 [A,B] is
 select
 A
 [] B
 end select
end process

```
process T2 [A,B,C] is
  select
        A
  [] B
  [] C; B
  end select
end process
```



pending: lock (B, {T1,T2})

#### • Three phases

- 1. Announces: ready
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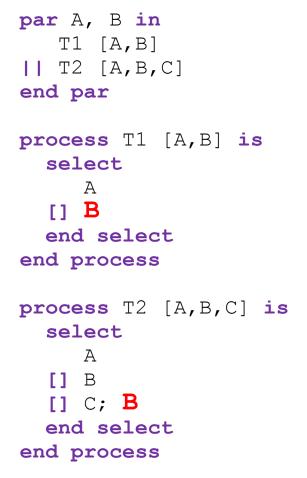
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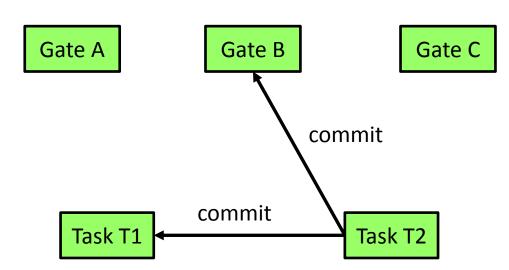
<pre>par A, B in     T1 [A,B]    T2 [A,B,C] end par</pre>		Gate A	Gate B	Gate C
process T1 [A,B] is				
A				
[] B			lock (B, {T1,T2})	
end select		Task T1	•••••(2) (12) (2)	Task T2
end process			L T4 T2))	
	per	nding: lock (B, {	1, 2})	
process T2 [A,B,C] is				
A	) Thr	ee phases		
[] B		•		
[] C; B	1.	Announces:	ready	
end select end process	2.	Negotiations: lock (ordered to avoid deadlock)		
*	3.	Results: con	nmit / abort	

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• Three phases

- 1. Announces: ready
- 2. Negotiations: lock (ordered to avoid deadlock)

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3. Results: commit / abort

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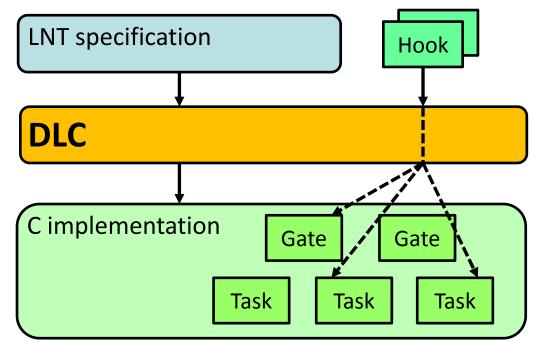
### **Protocol correctness**

• Formal verification with LNT and CADP [Evrard-Lang-13]

- model checking : absence of protocol livelock/deadlock
- equivalence checking between implementation & specification
- "The devil is in the detail"
  - [Parrow-Sjodin-96] can deadlock with asynchronous messages, fixed version in [Evrard-Lang-13]
  - [Perez-04] can deadlock, fixed version in [Katz-Peled-10]
- DLC version of the protocol
  - protocol logic isolated in a library
  - only glue code that calls protocol is generated for each specification

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# Interaction with environment: hook functions



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- Optional user-defined C function
  - side effects, call external software, ...
- Triggered by actions

## Three types of hook functions

### • pre-negotiation hook (one per gate)

- called before starting a negotiation
- return bool: authorize negotiation or not
- role: prevent useless negotiation to hamper others

### **post-negotiation hook** (one per gate)

- called on negotiation success (tasks are locked, no commit yet)
- return bool: authorize action or not
- role: final decision to realize action
- Iocal hook (one per task)
  - called by each task that realizes an action
  - role: local side effects at the task level

## **Exchange data with the environment**

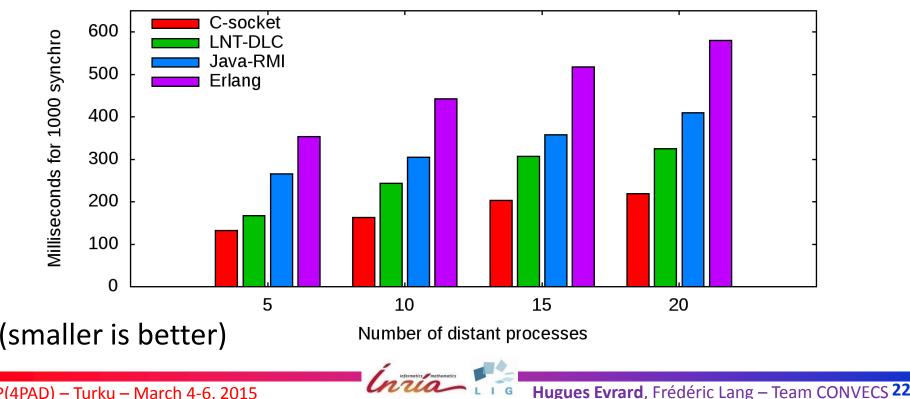
- Hook functions access data offers
- From system to environment
  - offer in send mode: A (x)
- From environment to system
  - offer in receive mode: A (?x)
  - pre-/post-negotiation hook must define the offer

```
action->offer[0]->value = get_value(); //external function
action->offer[0]->mode = DLC_MODE_SEND;
```

 check at runtime: all offers in send mode at the time of negotiation commit

## **Experimentation:** synchro. barrier

- **\*** Grid'5000 Experimentations on Grid5000 0
- Compare inter-process interaction perf. with C, Java, ...
  - They lack multiway rendezvous (neither built-in nor mature lib)
  - Use distributed synchronization barrier for comparison —



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### **Experimentation: Raft consensus**

- Raft [Ongaro-Ousterhout-14] consensus algorithm (like Paxos)
  - used to build fault tolerant service (replicated state machine)
- Service: storage (read, write)
- LNT Raft cluster
  - use hook functions to implement access from external client
  - 1000 writes replicated on 7 servers: 14000 actions in 5.5 sec
- Comparison with Consul (in Golang, by Hashicorp)
  - Consul is 10 times faster... batches requests!
  - Raft-level optimization that DLC cannot handle yet

### Conclusions

- Generate a distributed implementation from an LNT specification
- Reuse CADP tools for sequential, focus on distribution
- Multiway rendezvous implemented by a verified protocol
- Hook functions enable interaction with environment
- Acceptable performances for rapid prototyping
- new tool DLC: automatized compilation, "push button"

### **Future work**

- More case studies of distributed algorithms
  - model in LNT, verify with CADP, compile with DLC
- Improve rendezvous protocol performances (e.g. detect synchronization patterns that require less messages)
- Handle more LNT constructions
  - complex data types (record, list, array...) in action offers
  - guarded actions: A (?x) where x > 0

# Parrow-Sjodin-96 communication hypothesis

- "Designing a Multiway Synchronization Protocol"
- Extract:

#### 2 A Model of Multiway Synchronization

We assume that there are n processes, in the following called *client processes*, communicating over a communication network providing asynchronous point-to-point connections (see Fig. 1). Thus messages will arrive after an unknown and variable delay, and the network never loses messages.

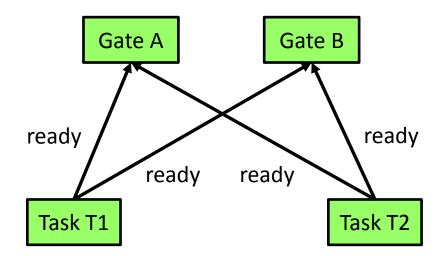
We further assume that there are several multiway synchronization actions denoted a b

### **Experimentation: Raft consensus**

- Raft consensus algorithm [Ongaro-Ousterhout-14]
  - similar to Paxos, but easier to understand, hence to implement
  - used to build fault tolerant service (replicated state machine)
- Service: storage (read, write)
- LNT Raft cluster
  - use hook functions to implement access from external client
  - 1000 writes replicated on cluster of 7 servers: 5.5 sec
  - triggers 14000 actions: approx. 0.4ms per action
- Comparison with Consul (in Golang, by Hashicorp)
  - Consul is 10 times faster... batches requests!
  - Raft-level optimization that DLC cannot handle yet

par A, B in
 T [A,B]
 [I] T [A,B]
end par

process T [A,B] is
 select A [] B end select
end process



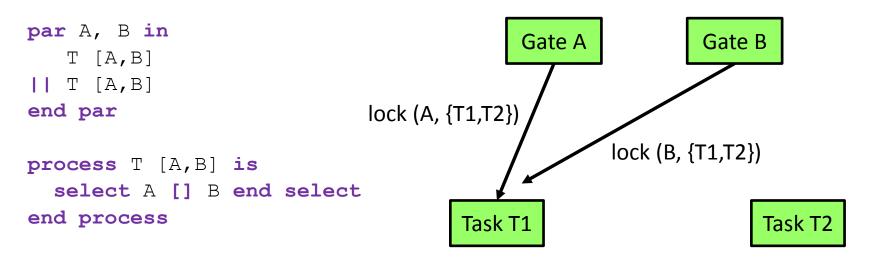
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- Three phases
  - 1. Announces
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3. Results

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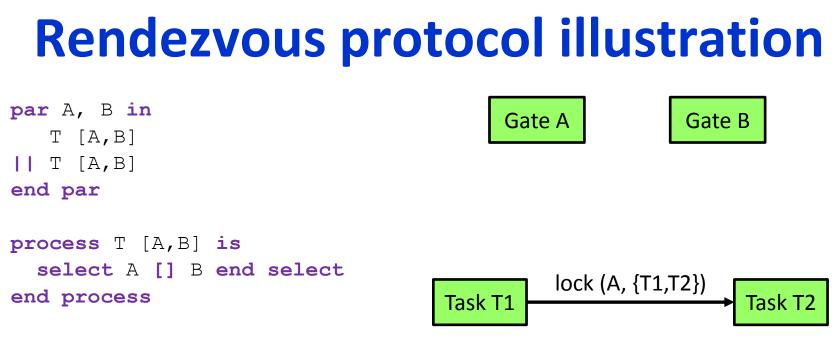
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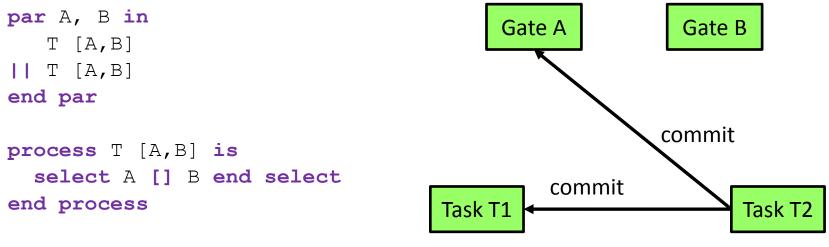
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pending: lock (B, {T1,T2})

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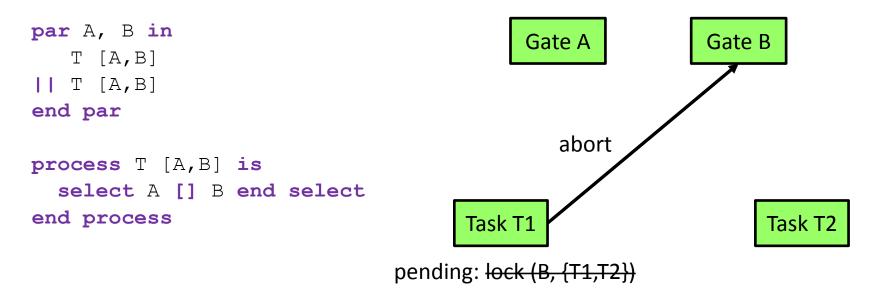


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