# How to make sure the iterates of FISTA converge Antonin Chambolle, Charles H Dossal 

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# How to make sure the iterates of "FISTA" converge. 

A. Chambolle and Ch. Dossal

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## Introduction

Let $\mathcal{H}$ be an Hilbert space and $f$ and $g$ two convex, l.s.c functions from $\mathcal{H}$ to $\mathbb{R}$ such that $f$ is differentiable with $L$-Lipschitz continuous gradient, and $g$ is "simple", meaning that its "proximal map"

$$
x \mapsto \arg \min _{y \in \mathcal{H}} g(y)+\frac{\|x-y\|^{2}}{2 \tau}
$$

can be easily computed.
We consider the following minimization problem

$$
\begin{equation*}
\min _{x \in \mathcal{H}} F(x):=f(x)+g(x) \tag{1}
\end{equation*}
$$

and we assume that this problem has at least a solution (and possibly an infinite set of solutions).

Among the many algorithms which exist to tackle such problems, the proximal splitting algorithms, which perform alternating descents in $f$ and in $g$, are frequently used, because of their simplicity and relatively small per-iteration complexity. One can mention the Forward-Backward (FB) splitting, the Douglas-Rachford splitting, the ADMM (alternating direction method of multipliers), ${ }^{1}$ which all have been proved to be efficient in many imaging problem such as denoising, inpainting, deconvolution, color transfert and many others.

This work focuses on the so-called "Fast Iterative Soft Thresholding Algorithm" (FISTA) which is an accelerated variant of the Forward-Backward algorithm proposed by Beck and Teboulle [2], built upon ideas of Nesterov [11] and Güler [7].

[^0]The FB is a descent algorithm which defines a sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$ by performing an explicit descent in $f$ and implicit in $g$. It is then shown that there exist $C>0$, such that for all $n \in \mathbb{N} F\left(x_{n}\right)-F\left(x^{*}\right) \leqslant \frac{C}{n}$ where $x^{*}$ is a minimizer of $F$. Moreover the sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$ weakly converges in $\mathcal{H}$. See for instance [13] or [2] for a simple derivation of this rate.

The sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$ defined by the accelerated variant "FISTA" [2] satisfies, on the other hand, $F\left(x_{n}\right)-F\left(x^{*}\right) \leqslant \frac{C^{\prime}}{n^{2}}$ for a suitable real number $C^{\prime}$, however no convergence of $\left(x_{n}\right)_{n \in \mathbb{N}}$ as been proved so far.

The FISTA algorithm is based on a simple over-relaxation step with varying parameter, and several choices of parameters yield roughly the same rate of convergence. This paper provides complementary results on the convergence of $F\left(x_{n}\right)-F\left(x^{*}\right)$ for some "good" choices of these parameters, for which the weak convergence of the iterates can also be proved.

In the next section, we introduce a few definitions and our main notation. In a second part, the main result on the convergence of FISTA is recalled, and we give new results on the convergence of the values of $F\left(x_{n}\right)$, for other over-relaxation sequences. In the third part we show the convergence of the iterates. This part is strongly inspired from a recent paper of Pock and Lorenz [9], inspired by works of Alvarez and Attouch [1]. The last part is focused on numerical experiments.

## 1 Notation and definitions

In the following $x^{*}$ denotes a solution of (1), even if this solution is not unique the value $F\left(x^{*}\right)$ is uniquely defined.

A key tool of FISTA is the proximal map. To any proper, convex and l.s.c function $h$ is associated the proximal map $\operatorname{Prox}_{h}$ which is a function from $\mathcal{H}$ to $\mathcal{H}$ defined by

$$
\operatorname{Prox}_{h}(x)=\arg \min _{y \in \mathcal{H}} h(y)+\frac{1}{2}\|x-y\|^{2} .
$$

This function is uniquely defined and generalizes the projection on a closed convex set to convex functions.

In the sequel, $\gamma$ denotes a non negative real number such that $\gamma \leq \frac{1}{L}$ where $L$ is the Lipschitz constant of $\nabla f$ and $T$ the mapping from $\mathcal{H}$ to $\mathcal{H}$ defined by

$$
T(x):=\operatorname{Prox}_{\gamma g}(x-\gamma \nabla f(x)),
$$

The idea of FB is to apply this mapping from any $x_{0} \in \mathcal{H}$ using Krasnosel'ski Mann iterations to get a weak convergence to a minimizer $x^{*}$ of $F$. The idea of FISTA is to apply this mapping using a suitable extragradient rule to accelerate the convergence.

FISTA is defined by a sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ of real numbers greater than 1 and a point $x_{0} \in \mathcal{H}$. Let $\left(t_{n}\right)_{n \in \mathbb{N}^{*}}$ be a sequence of non negative real numbers and $x_{0} \in \mathcal{H}$, the sequences $\left(x_{n}\right)_{n \in \mathbb{N}},\left(y_{n}\right)_{n \in \mathbb{N}}$ and $\left(u_{n}\right)_{n \in \mathbb{N}}$ and $\left(y_{n}\right)_{n \in \mathbb{N}}$ are defined by $y_{0}=u_{0}=x_{0}$ and for all $n \geqslant 1$,

$$
\begin{array}{r}
x_{n}=T\left(y_{n-1}\right) \\
y_{n}=\left(1-\frac{1}{t_{n+1}}\right) x_{n}+\frac{1}{t_{n+1}} u_{n} \\
u_{n}=x_{n-1}+t_{n}\left(x_{n}-x_{n-1}\right) . \tag{4}
\end{array}
$$

The point $y_{n}$ may also be defined from points $x_{n}$ and $x_{n-1}$ by

$$
\begin{equation*}
y_{n}=x_{n}+\alpha_{n}\left(x_{n}-x_{n-1}\right) \text { with } \alpha_{n}:=\frac{t_{n}-1}{t_{n+1}} \tag{5}
\end{equation*}
$$

For suitable choices of $\left(t_{n}\right)_{n \in \mathbb{N}^{*}}$ the sequence $\left(F\left(x_{n}\right)\right)_{n \in \mathbb{N}}$ converge to $F\left(x^{*}\right)$, i.e the sequence $\left(w_{n}\right)_{n \in \mathbb{N}}$, defined as follows,

$$
\begin{equation*}
w_{n}:=F\left(x_{n}\right)-F\left(x^{*}\right) \tag{6}
\end{equation*}
$$

tends to 0 when $n$ goes to infinity.
Several proofs use bounds on the local variation of the sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$, which we will denote $\left(\delta_{n}\right)_{n \in \mathbb{N}}$ : variation :

$$
\delta_{n}:=\frac{1}{2}\left\|x_{n}-x_{n-1}\right\|_{2}^{2}
$$

The sequence $\left(v_{n}\right)_{n \in \mathbb{N}}$ denoting the distance between $u_{n}$ and a fixed minimizer $x^{*}$ of $F$ will also be useful:

$$
v_{n}:=\frac{1}{2}\left\|u_{n}-x^{*}\right\|_{2}^{2} .
$$

To complete this part devoted to our notation, we define a sequence $\left(\rho_{n}\right)_{n \in \mathbb{N}}$, associated to $\left(t_{n}\right)_{n \in \mathbb{N}^{*}}$, whose positivity will ensure the convergence of the FISTA iterations:

$$
\rho_{n}:=t_{n-1}^{2}-t_{n}^{2}+t_{n} .
$$

## 2 Basic and complementary results on FISTA

The main result of [2] is the following Theorem :
Theorem 1 ([2, Thm. 4.1]). For any $x_{0} \in \mathcal{H}$, if the sequence $\left(t_{n}\right)_{n \in \mathbb{N}^{*}}$ satisfies

$$
\begin{equation*}
\forall n \geqslant 2 \quad t_{n}^{2}-t_{n} \leqslant t_{n-1}^{2} \tag{7}
\end{equation*}
$$

and $t_{1}=1$, if $\gamma \leqslant \frac{1}{L}$ then the sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$ satisfies for all $n \in \mathbb{N}$

$$
\begin{equation*}
w_{n} \leqslant \frac{1}{2 \gamma t_{n}^{2}}\left\|x_{0}-x^{*}\right\|_{2}^{2} \tag{8}
\end{equation*}
$$

for any minimizer $x^{*}$ of $F$.
Condition (7) can also be stated using the sequence $\left(\rho_{n}\right)_{n \in \mathbb{N}}: \forall n \geqslant 2, \rho_{n} \geqslant 0$. The sequence defined by $t_{1}=1$ and

$$
\begin{equation*}
\forall n \in \mathbb{N}^{*} \quad t_{n+1}=\sqrt{t_{n}^{2}+\frac{1}{4}}+\frac{1}{2} \tag{9}
\end{equation*}
$$

achieves the equality in (7).Also, it turns out that the sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ defined by $t_{n}=\frac{n+1}{2}$ satisfies condition (7). But more generally, for any $a \geqslant 2$ the sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ defined by $t_{n}=\frac{n+a-1}{a}$ satisfies (7). Indeed,

$$
\begin{equation*}
\rho_{n}=\frac{1}{a^{2}}\left((n+a-2)^{2}-(n+a-1)^{2}+a(n+a-1)\right)=\frac{1}{a^{2}}\left((a-2) n+a^{2}-3 a+3\right) \geqslant 0 . \tag{10}
\end{equation*}
$$

An induction proves that any sequence satisfying (7) (hence an inequality in (9)) and $t_{1}=1$ satisfies $t_{n} \leqslant n$. Hence for any sequence defined above, Theorem 1 ensures that

$$
\begin{equation*}
\forall n \in \mathbb{N} \quad w_{n} \leqslant \frac{C}{n^{2}} \tag{11}
\end{equation*}
$$

where $C$ depends on the exact choice of the sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$.
A priori, the best constant " $C$ " in this bound $\frac{C}{n^{2}}$ will be reached if the sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ is the one achieving the equality in (7), given by (9), ensuring the highest value of $t_{n}$. This is the choice in [2], and it turns out that it is nearly optimal (since for any $n$ there exists a problem which has lower bound of the same order, see $[10,12]$ ). We will soon see, however, that not achieving this equality may have some advantages.

This first Theorem can easily be made more precise, as follows:
Theorem 2. If the sequence $\left(t_{n}\right)_{n \in N}$ satisfies (7) and $t_{1}=1$, if $\gamma \leqslant \frac{1}{L}$ then for any $N \geqslant 2$,

$$
\begin{equation*}
t_{N+1}^{2} w_{N+1}+\sum_{n=1}^{N} \rho_{n+1} w_{n} \leqslant \frac{v_{0}-v_{N+1}}{\gamma} \tag{12}
\end{equation*}
$$

Using the several choices of sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ described above, Theorem 2 ensures the same decay for $w_{n}\left(w_{n} \leqslant \frac{C}{n^{2}}\right)$ as the previous. But using (10), we readily see that for a "good" choice of the sequence $\left(t_{n}\right)_{n \in \mathbb{N}^{*}}$, one obtains the following corollary:

Corollary 1. Let $a>2$ and for $n \geqslant 1, t_{n}=\frac{n+a-1}{a}$. Then the sequence $\left(n w_{n}\right)_{\in \mathbb{N}}$ belongs to $\ell_{1}(\mathbb{N})$. In particular, $\lim \inf _{n \rightarrow \infty} n^{2} \ln n w_{n}=0$.

The classical choice (9) for the sequence $\left(t_{n}\right)_{n \in \mathbb{N}^{*}}$ may yield the best rate of convergence for the objective, but other sequences can give better global properties of the sequence $\left(n w_{n}\right)_{n \in \mathbb{N}}$. (Also notice that the other classical choice corresponding to $a=2$ will not ensure this summability.) An important remark, here, is that this result is not in contradiction with the lower bounds of Nemirovski and Yudin (see [10, 12]). Indeed, they show that for any integer $n_{0}$ one can build a specific problem for which one will have, after $n_{0}$ iterations, $n_{0} w_{n_{0}} \geq C / n_{0}$, however this does not mean that the sequence $\left(n w_{n}\right)_{n}$ is not eventually summable.

Proof of Theorem 2 The proof is similar to the one of Theorem 1 in [2], however for the ease of the reader we will sketch it here. A first (standard) technical descent Lemma is useful:

Lemma 1. Let $\left.\gamma \in] 0, \frac{1}{L}\right]$, where $L$ is the Lipschitz constant of $\nabla f, \bar{x} \in \mathcal{H}$ and $\hat{x}=T \bar{x}$. Then

$$
\begin{equation*}
\forall x \in \mathcal{H} \quad F(\hat{x})+\frac{\|\hat{x}-x\|^{2}}{2 \gamma} \leqslant F(x)+\frac{\|x-\bar{x}\|^{2}}{2 \gamma} \tag{13}
\end{equation*}
$$

Proof. Many proofs exist of this result, we give an elementary one which is inspired from [15]. By definition of the proximal map, $\hat{x}$ is the minimizer of the $\frac{1}{\gamma}$-strongly convex function

$$
z \longmapsto f(z)+g(\bar{x})+\langle\nabla g(\bar{x}), z-\bar{x}\rangle+\frac{1}{2 \gamma}\|z-\bar{x}\|^{2}
$$

hence for all $z \in \mathcal{H}$

$$
\begin{aligned}
f(\hat{x})+g(\bar{x})+\langle\nabla g(\bar{x}), \hat{x}-\bar{x}\rangle+ & \frac{\|\bar{x}-\hat{x}\|^{2}}{2 \gamma}+\frac{\|z-\hat{x}\|^{2}}{2 \gamma} \\
& \leqslant f(z)+g(\bar{x})+\langle\nabla g(\bar{x}), z-\bar{x}\rangle+\frac{\|z-\bar{x}\|^{2}}{2 \gamma} .
\end{aligned}
$$

Since $\gamma \leq 1 / L$, it follows

$$
f(\hat{x})+g(\hat{x})+\frac{1}{2 \gamma}\|z-\hat{x}\|^{2} \leqslant f(z)+g(\bar{x})+\langle\nabla g(\bar{x}), z-\bar{x}\rangle+\frac{1}{2 \gamma}\|z-\bar{x}\|^{2} .
$$

By convexity, $g(\bar{x})+\langle\nabla g(\bar{x}), z-\bar{x}\rangle \leqslant g(z)$. We deduce that (13) holds and the Lemma is proved.

Proof of Theorem 2. Applying this Lemma to $\bar{x}=y_{n}, \hat{x}=x_{n+1}$ and $x=(1-$ $\left.\frac{1}{t_{n+1}}\right) x_{n}+\frac{1}{t_{n+1}} x^{*}$, we find

$$
F\left(x_{n+1}\right)+\frac{\left\|\frac{1}{t_{n+1}} u_{n+1}-\frac{1}{t_{n+1}} x^{*}\right\|_{2}^{2}}{2 \gamma}
$$

$$
\leqslant F\left(\left(1-\frac{1}{t_{n+1}}\right) x_{n}+\frac{1}{t_{n+1}} x^{*}\right)+\frac{\left\|\frac{1}{t_{n+1}} x^{*}-\frac{1}{t_{n+1}} u_{n}\right\|_{2}^{2}}{2 \gamma}
$$

Using the convexity of $F$ it follows

$$
\begin{aligned}
F\left(x_{n+1}\right)-F\left(x^{*}\right)-\left(1-\frac{1}{t_{n+1}}\right)\left(F\left(x_{n}\right)-F\left(x^{*}\right)\right) & \\
& \leqslant \frac{\left\|u_{n}-x^{*}\right\|_{2}^{2}}{2 \gamma t_{n+1}^{2}}-\frac{\left\|u_{n+1}-x^{*}\right\|_{2}^{2}}{2 \gamma t_{n+1}^{2}}
\end{aligned}
$$

Using definitions of $w_{n}$ and $v_{n}$ this inequality can be stated

$$
\begin{equation*}
t_{n+1}^{2} w_{n+1}-\left(t_{n+1}^{2}-t_{n+1}\right) w_{n} \leqslant \frac{v_{n}-v_{n+1}}{\gamma} \tag{14}
\end{equation*}
$$

Summing these inequalities from $n=1$ to $n=N$ leads to

$$
\begin{equation*}
t_{N+1}^{2} w_{N+1}+\sum_{n=1}^{N} \rho_{n+1} w_{n} \leqslant \frac{v_{0}-v_{N+1}}{\gamma} . \tag{15}
\end{equation*}
$$

which ends the proof of Theorem 2.
We can deduce another useful corollary:
Corollary 2. Let $a>2$ and for $n \geqslant 1, t_{n}=\frac{n+a-1}{a}$. Then the sequence $\left(n \delta_{n}\right)_{\in \mathbb{N}}$ belongs to $\ell_{1}(\mathbb{N})$, in particular $\lim _{\inf _{n \rightarrow \infty}} n^{2} \ln n \delta_{n}=0$. In addition, there exists $C>0$ such that for all $n \in \mathbb{N}^{*}, \delta_{n} \leqslant \frac{C}{n^{2}}$.

This results which is a consequence of previous corollary is the key to prove the convergence of the sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$.

Proof. Applying Lemma 1 to $\bar{x}=y_{n}=x_{n}+\alpha_{n}\left(x_{n}-x_{n-1}\right)$, and $x=x_{n}$ leads to

$$
F\left(x_{n+1}\right)+\frac{\left\|x_{n}-x_{n+1}\right\|^{2}}{2 \gamma} \leqslant F\left(x_{n}\right)+\frac{\alpha_{n}^{2}\left\|x_{n}-x_{n-1}\right\|^{2}}{2 \gamma}
$$

which can be written with definitions of $w_{n}$ and $\delta_{n}$

$$
\delta_{n+1}-\alpha_{n}^{2} \delta_{n} \leqslant \gamma\left(w_{n}-w_{n+1}\right)
$$

If $t_{n}=\frac{n+a-1}{a}, \alpha_{n}=\frac{t_{n}-1}{t_{n+1}}=\frac{n-1}{n+a}$.
Multiplying this inequality by $(n+a)^{2}$ and adding from $n=1$ to $n=N$ leads to

$$
\sum_{n=1}^{N}(n+a)^{2}\left(\delta_{n+1}-\alpha_{n}^{2} \delta_{n}\right) \leqslant \gamma \sum_{n=1}^{N}(n+a)^{2}\left(w_{n}-w_{n+1}\right)
$$

which gives

$$
\begin{aligned}
& (N+a)^{2} \delta_{N+1}+\sum_{n=2}^{N}\left((n+a-1)^{2}-(n+a)^{2} \alpha_{n}^{2}\right) \delta_{n} \leqslant \\
& \gamma\left((a+1)^{2} w_{1}-(N+a)^{2} w_{N+1}+\sum_{n=2}^{N}\left((n+a)^{2}-(n+a-1)^{2}\right) w_{n}\right)
\end{aligned}
$$

that is

$$
\begin{aligned}
& (N+a)^{2} \delta_{N+1}+\sum_{n=2}^{N} a(2 n-2+a) \delta_{n} \\
& \\
& \quad \leqslant \gamma\left((a+1)^{2} w_{1}-(N+a)^{2} w_{N+1}+\sum_{n=2}^{N}(2 n+2 a-1) w_{n}\right)
\end{aligned}
$$

By Corollary 1 and since we have assumed $a>2$, the right part of the inequality is uniformly bounded independently of $N$, which ensures that the sequence $\left(n \delta_{n}\right)_{n \in \mathbb{N}}$ belongs to $\ell_{1}(\mathbb{N})$.

## 3 Convergence of the iterates of FISTA

In this section, we show the following Theorem
Theorem 3. Let $a>2$ be a positive real number, and for all $n \in \mathbb{N}$ let $t_{n}=\frac{n+a-1}{a}$. Then the sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$ given by FISTA weakly converges to a minimizer of $F$.

The proof of the theorem follows the ideas of Pock and Lorenz, in the proof of Theorem 1 in [9]-see also [1]. The two main differences between our setting and the setting of [9] are:

1. We do not assume the existence of $\alpha<1$ such that $\forall n \geqslant 1, \alpha_{n} \leqslant \alpha$;
2. The sequence $\left(\delta_{n}\right)_{n \in \mathbb{N}}$ produced by FISTA, with a good choice of the sequence $\left(t_{n}\right)$, has stronger properties than in [9].

It turns out that Corollary 2 is crucial, while classical bounds on $\delta_{n}$ which only show the existence of a constant $C>0$ such that $\delta_{n} \leqslant \frac{C}{n^{2}}$ are not sufficient.

Before giving the complete proof of this result, several remarks can be done.

1. From Corollary 2 it follows that the sequence $\left(n\left(x_{n+1}-x_{n}\right)\right)_{n \in \mathbb{N}}$ is bounded, moreover the sequence $\left(v_{n}\right)_{n \in \mathbb{N}}$ is also bounded which implies that the sequence $\left(\left(x_{n}\right)_{n \in \mathbb{N}}\right)$ is bounded.
2. Hence there exists a subsequence of $\left(\left(x_{n}\right)_{n \in \mathbb{N}}\right)$ that weakly converges to a $\tilde{x} \in \mathcal{H}, x_{\nu} \rightharpoonup \tilde{x}$.
3. Since the sequence $\left(\delta_{n}\right)_{n \in \mathbb{N}}$ tends to $0, y_{\nu} \rightharpoonup \tilde{x}$ which implies that $\tilde{x}$ is a fixed point of the non expansive operator $T$, hence a minimizer of $F$.

If we are able to prove that the sequence $\left\|x_{n}-x^{*}\right\|$ has a limit for any minimizer $x^{*}$ of $F$, Theorem 3 will follow, taking for $x^{*}$ the weak limit $\tilde{x}$ of our subsequence and invoking Opial's Theorem [14].

Proof of Theorem 3. Let us define for all $j \geqslant 1$ and for all $k \geqslant j$

$$
\beta_{j, k}=\prod_{l=j}^{k} \alpha_{l}=\prod_{l=j}^{k} \frac{l-1}{l+a} .
$$

and $\beta_{j, k}=1$ if $j>k$.
Since $\alpha_{1}=0, \forall k>1, \beta_{1, k}=0$. Moreover since $a>2$,

$$
\beta_{j, k} \leqslant \prod_{l=j}^{k} \frac{l-1}{l+2}
$$

Hence, for all $j \geqslant 2$ and for all $k \geqslant 1, \beta_{j, k} \leqslant 1$, while if $k-j \geqslant 2$,

$$
\beta_{j, k} \leqslant\left(\frac{j+1}{k}\right)^{3}
$$

It follows that for all $j \geqslant 2$,

$$
\begin{aligned}
\sum_{k=j}^{+\infty} \beta_{j, k} & \leqslant 2+\sum_{k=j+2}^{+\infty} \beta_{j, k} \leqslant 2+\sum_{k=j+2}^{+\infty}\left(\frac{j+1}{k}\right)^{3} \leqslant 2+(j+1)^{3} \sum_{k=j+2}^{+\infty} \frac{1}{k^{3}} \\
& \leqslant 2+(j+1)^{3} \int_{t=j+1}^{+\infty} \frac{d t}{t^{3}} \leqslant 2+(j+1)^{3} \frac{1}{2(j+1)^{2}}
\end{aligned}
$$

and then

$$
\begin{equation*}
\sum_{k=j}^{+\infty} \beta_{j+1, k} \leqslant \frac{j+5}{2} \tag{16}
\end{equation*}
$$

Let us define

$$
\Phi_{n}=\frac{1}{2}\left\|x_{n}-x^{*}\right\|_{2}^{2} \quad \text { and } \quad \Gamma_{n}=\frac{1}{2}\left\|x_{n+1}-y_{n}\right\|_{2}^{2}
$$

From the identity

$$
\begin{equation*}
\langle a-b, a-c\rangle=\frac{1}{2}\|a-b\|_{2}^{2}+\frac{1}{2}\|a-c\|_{2}^{2}-\frac{1}{2}\|b-c\|_{2}^{2} \tag{17}
\end{equation*}
$$

we have by using the definition of $y_{n}$

$$
\begin{equation*}
\Phi_{n}-\Phi_{n+1}=\delta_{n+1}+\left\langle y_{n}-x_{n+1}, x_{n+1}-x^{*}\right\rangle-\alpha_{n}\left\langle x_{n}-x_{n-1}, x_{n+1}-x^{*}\right\rangle \tag{18}
\end{equation*}
$$

Then, using the monoticity of $\partial g$, we deduce that for any $z_{n+1} \in \partial g\left(x_{n+1}\right)$ and for any $z^{*} \in \partial g\left(x^{*}\right)$

$$
\left\langle\gamma z_{n+1}-\gamma z^{*}, x_{n+1}-x^{*}\right\rangle \geqslant 0
$$

By definition of $x^{*},-\nabla\left(f\left(x^{*}\right)\right) \in \partial g\left(x^{*}\right)$ and $y_{n}-x_{n+1}-\gamma \nabla f\left(y_{n}\right) \in \gamma \partial g\left(x_{n+1}\right)$.
It follows

$$
\begin{array}{r}
\left\langle y_{n}-x_{n+1}-\gamma \nabla f\left(y_{n}\right)+\gamma \nabla f\left(x^{*}\right), x_{n+1}-x^{*}\right\rangle \geqslant 0 \\
\left\langle y_{n}-x_{n+1}, x_{n+1}-x^{*}\right\rangle+\gamma\left\langle\nabla f\left(x^{*}\right)-\nabla f\left(y_{n}\right), x_{n+1}-x^{*}\right\rangle \geqslant 0
\end{array}
$$

Combining with (18) we obtain

$$
\begin{equation*}
\Phi_{n}-\Phi_{n+1} \geqslant \delta_{n+1}+\gamma\left\langle\nabla f\left(y_{n}\right)-\nabla f\left(x^{*}\right), x_{n+1}-x^{*}\right\rangle-\alpha_{n}\left\langle x_{n}-x_{n-1}, x_{n+1}-x^{*}\right\rangle . \tag{19}
\end{equation*}
$$

From the co-coercivity of $\nabla f$, we have

$$
\begin{aligned}
\left\langle\nabla f\left(y_{n}\right)-\nabla f\left(x^{*}\right)\right. & \left., x_{n+1}-x^{*}\right\rangle \\
& =\left\langle\nabla f\left(y_{n}\right)-\nabla f\left(x^{*}\right), x_{n+1}-y_{n}+y_{n}-x^{*}\right\rangle \\
& \geqslant \frac{1}{L}\left\|\nabla f\left(y_{n}\right)-\nabla f\left(x^{*}\right)\right\|_{2}^{2}+\left\langle\nabla f\left(y_{n}\right)-\nabla f\left(x^{*}\right), x_{n+1}-y_{n}\right\rangle \\
& \geqslant \frac{1}{L}\left\|\nabla f\left(y_{n}\right)-\nabla f\left(x^{*}\right)\right\|_{2}^{2}-\frac{1}{L}\left\|\nabla f\left(y_{n}\right)-\nabla f\left(x^{*}\right)\right\|_{2}^{2}-\frac{L}{2} \Gamma_{n} \\
& \geqslant-\frac{L}{2} \Gamma_{n} .
\end{aligned}
$$

Substituting back into (19), we get

$$
\Phi_{n}-\Phi_{n+1} \geqslant \delta_{n+1}-\frac{\gamma L}{2} \Gamma_{n}-\alpha_{n}\left\langle x_{n}-x_{n-1}, x_{n+1}-x^{*}\right\rangle,
$$

and invoking (17) it follows that

$$
\begin{aligned}
\Phi_{n+1}-\Phi_{n}-\alpha_{n}\left(\Phi_{n}-\Phi_{n-1}\right) \leqslant & -\delta_{n+1}+\frac{\gamma L}{2} \Gamma_{n} \\
& +\alpha_{n}\left(\delta_{n}+\left\langle x_{n}-x_{n-1}, x_{n+1}-x_{n}\right\rangle\right) \\
& =-\Gamma_{n}+\frac{\gamma L}{2} \Gamma_{n}+\left(\alpha_{n}+\alpha_{n}^{2}\right) \delta_{n}
\end{aligned}
$$

where we have used the fact that

$$
\delta_{n+1}-\alpha_{n}\left\langle x_{n}-x_{n-1}, x_{n+1}-x_{n}\right\rangle=\alpha_{n}^{2} \frac{\left\|x_{n}-x_{n-1}\right\|^{2}}{2}-\frac{\left\|x_{n+1}-y_{n}\right\|^{2}}{2} .
$$

Using $\frac{\alpha_{n}+\alpha_{n}^{2}}{2} \leqslant \alpha_{n}$ we obtain

$$
\begin{equation*}
\Phi_{n+1}-\Phi_{n}-\alpha_{n}\left(\Phi_{n}-\Phi_{n-1}\right) \leqslant-\left(1-\frac{\gamma L}{2}\right) \Gamma_{n}+2 \alpha_{n} \delta_{n} \tag{20}
\end{equation*}
$$

with $1-\frac{\gamma L}{2}>0$.
Now defining $\theta_{n}=\max \left(0, \Phi_{n}-\Phi_{n-1}\right)$ we obtain

$$
\begin{equation*}
\theta_{n+1} \leqslant \alpha_{n}\left(\theta_{n}+2 \delta_{n}\right) \tag{21}
\end{equation*}
$$

Applying recursively (21) it follows that for all $n \geqslant 2$ ( $\alpha_{1}=0$, and in particular $\theta_{1}, \theta_{2}=0$ ).

$$
\begin{equation*}
\theta_{n+1} \leqslant 2 \sum_{j=2}^{n}\left(\prod_{l=j}^{n} \alpha_{l}\right) \delta_{j}=2 \sum_{j=2}^{n} \beta_{j, n} \delta_{j} . \tag{22}
\end{equation*}
$$

Hence (using (16)),

$$
\begin{aligned}
\sum_{n=2}^{+\infty} \theta_{n} & \leqslant 2 \sum_{n=1}^{+\infty} \sum_{j=2}^{n} \beta_{j, n} \delta_{j} \\
& \leqslant 2 \sum_{j=2}^{\infty} \delta_{j} \sum_{n=j}^{\infty} \beta_{j, n} \\
& \leqslant 2 \sum_{j=1}^{\infty} \delta_{j} \frac{j+5}{2}
\end{aligned}
$$

From Corollary 2 the right side of the last inequality is finite if $a>2$, therefore the sequence $\left(\theta_{n}\right)_{n \in \mathbb{N}}$ belongs to $\ell_{1}(\mathbb{N})$.

The end of the proof follows Lorenz and Pock [9]. We set $s_{n}=\Phi_{n}-\sum_{i=1}^{n} \theta_{i}$ and since $\Phi_{n} \geqslant 0$ and $\sum_{i=1}^{n} \theta_{i}$ is bounded independently of $n$, we see that $s_{n}$ is bounded from below. 0n the other hand

$$
s_{n+1}=\Phi_{n+1}-\theta_{n}-\sum_{i=1}^{n} \theta_{n} \leqslant \Phi_{n+1}-\Phi_{n+1}+\Phi_{n}-\sum_{i=1}^{n} \theta_{i}=s_{n}
$$

and hence $\left(s_{n}\right)_{n \in \mathbb{N}}$ is a non-decreasing sequence and thus is convergent. This implies that $\Phi_{n}$ is convergent, which concludes the proof of Theorem 3.

## 4 Numerical Experiments

In previous parts, it was shown that non classical choices of the sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ ensure weak convergence of iterates $\left(x_{n}\right)_{n \in \mathbb{N}}$ and good properties for the sequence $\left(F\left(x_{n}\right)-F\left(x^{*}\right)\right)_{n \epsilon_{N}}$. On two examples, inpainting, and deblurring, we compare several choices of parameters.

For each example the 4 following sequences are tested:

- $t_{1}=1$ and $\forall n \in \mathbb{N}, t_{n+1}=\sqrt{t_{n}^{2}+\frac{1}{4}}+\frac{1}{2}$,
- $t_{n}=\frac{n+a+1}{a}, \forall n \in \mathbb{N}$ with $a=2,3$ and 4 .

For each problem, at each iteration $n$, the values $\left\|x_{n}-x_{n-1}\right\|_{2}^{2}$ and $F\left(x^{n}\right)-F\left(x^{*}\right)$ are computed. Since $F\left(x^{*}\right)$ can not be eaxctly computed, the value $F\left(x^{*}\right)$ is estimated by the the minimum of the values computed on 500 iterations for the four methods. The graph of the logarithm of these two quantities is thus given from $n=1$ to $n=400$.

Inpainting Let us consider here a degraded image $y^{0}=M x^{0}$ where $x^{0}$ is an unkown source image and $M$ a mask operator. In our example $50 \%$ of the pixels are removed. The image $x^{0}$ can be estimated from $y^{0}$ minimizing

$$
\begin{equation*}
F(x)=\frac{1}{2}\left\|y^{0}-M x\right\|_{2}^{2}+\lambda\|T x\|_{1} \tag{23}
\end{equation*}
$$

where $\lambda$ is a small non negative real number and $T$ is an orthogonal (Daubechies) wavelet transform.

Considering $f(x)=\frac{1}{2}\left\|y^{0}-M x\right\|_{2}^{2}$ and $g(x)=\lambda\|T x\|_{1}$, FISTA may be applied to minimize $F$.


Left: the masked image $y^{0}$. Right: an image $\hat{x}$ estimated minimizing $F$ with FISTA. ${ }^{2}$



Left: values of $\log \left(F\left(x_{n}\right)-F\left(x^{*}\right)\right)$. Right: values of $\log \left(\left\|x_{n}-x_{n-1}\right\|_{2}^{2}\right)$.
Blue dot line classical FISTA, red dashed-dot line $a=2$, black solid line $a=3$ and magenta dashed line $a=4$.

On this example, the choices $a=3$ or $a=4$ seems better than classical choices after 100 iterations. One can notice that classical FISTA is better for a small number of iterations.

Deblurring In this second example $y^{0}=h \star x^{0}+n$ is the noisy image of a blurred images $x^{0}$, where $h$ is a gaussian filter and $n$ is a random gaussian noise. The image $x^{0}$ can be estimated minimizing

$$
\begin{equation*}
F(x)=\frac{1}{2}\left\|y^{0}-h \star x\right\|_{2}^{2}+\lambda\|T x\|_{1} \tag{24}
\end{equation*}
$$

where $\lambda$ is a small non negative real number which value depends on the noise level and $T$ is an orthogonal (Daubechies) wavelet transform.

[^1]Considering $f(x)=\frac{1}{2}\left\|y^{0}-h \star x\right\|_{2}^{2}$ and $g(x)=\lambda\|T x\|_{1}$, FISTA may be applied to minimize $F$.


Left: the blurred image $y^{0}$. Right: an image $\hat{x}$ estimated minimizing $F$ with FISTA.



Left: values of $\log \left(F\left(x_{n}\right)-F\left(x^{*}\right)\right)$. Right: values of $\log \left(\left\|x_{n}-x_{n-1}\right\|_{2}^{2}\right)$.
Blue dot line classical FISTA, red dashed-dot line $a=2$, black solid line $a=3$ and magenta dashed line $a=4$.

On this example, the choices the classical FISTA seems better after 200 iterations, but the decreasing of $\delta_{n}$ seems still better for $a=3$ and $a=4$.

TV denoising Let us consider now a noisy image $y^{0}=x^{0}+n$. The image $x^{0}$ may be estimated from $y^{0}$ minimizing

$$
\begin{equation*}
F(x)=\frac{1}{2}\left\|y^{0}-x\right\|_{2}^{2}+\lambda\|\nabla x\|_{1} \tag{25}
\end{equation*}
$$

where $\nabla x$ is the gradient of the image $x$ and $\|\nabla x\|_{1}$ is the isotropic $\ell_{1}$-norm of the gradient. This regularization is also called Total Variation (TV) regularization. The proximal map of the function $x \mapsto\|\nabla x\|_{1}$ does not have a close form and

FISTA is difficult to use directly here nevertheless by duality this minimization problem is equivalent to minimize

$$
\begin{equation*}
G(p)=\frac{1}{2}\left\|y^{0}+\operatorname{div} p\right\|_{2}^{2}+i_{\|\cdot\|_{\infty} \leqslant \lambda}(p) \tag{26}
\end{equation*}
$$

where $i_{C}$ denotes the function such that $i_{C}(x)=0$ if $x \in C$ and $i_{C}(x)=+\infty$ if $x \notin C$ and where $x \mapsto-\operatorname{div} x$ is the divergence operator, conjugate of the gradient $\nabla$.
These two problems are equivalent and for any solution $p^{*}$ of the second minimization problem, $y^{0}+\operatorname{div} p^{*}$ is a solution of the first minimization problem.

This second problem can be solved using FISTA since the gradient of $p \mapsto$ $\frac{1}{2}\|y+\operatorname{div} \mathrm{p}\|_{2}^{2}$ is Lipschitz and the proximal map of $p \mapsto i_{\|\cdot\|_{+\infty} \leqslant \lambda}(p)$ is a simple projection.


Left: noisy image $y^{0}$. Right: the image $\hat{x}$ estimated minimizing $F$ with FISTA.



Left: values of $\log \left(G\left(p_{n}\right)-G\left(p^{*}\right)\right)$. Right: values of $\log \left(\left\|p_{n}-p_{n-1}\right\|_{2}^{2}\right)$.
Blue dot line classical FISTA, red dashed-dot line $a=2$, black solid line $a=3$ and magenta dashed line $a=4$.

These three examples shows that choosing a priori a sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ for FISTA is difficult and that for a given problem, it would be useful to test various options.

Sometimes the classical parameters proposed by Beck and Teboulle are better to get a faster minimization, sometimes the use of $a=3$ or $a=4$ is better. But on the three examples the norm of the variation $\delta_{n}$ is smaller for $a=3$ or $a=4$ than $a=2$ or the classical FISTA, which may indicate that the convergence of the iterates is faster.

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[^0]:    ${ }^{1}$ See for instance $[4,8,5,6,3]$.

[^1]:    ${ }^{2}$ The images provided by the 4 versions of FISTA look very similar, the difference appears in the values of the variation of functionnal $F$ through the iterations.

