



# Numerical approach for Hamilton-Jacobi equations on a network: application to traffic

Guillaume Costeseque

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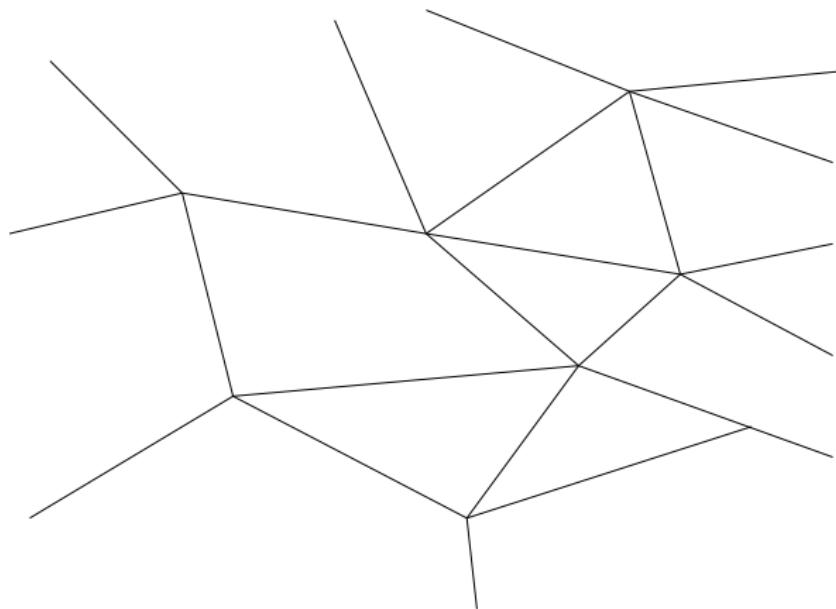
# Numerical approach for Hamilton-Jacobi equations on a network: application to traffic

Guillaume Costeseque  
(PhD with supervisors R. Monneau & J-P. Lebacque)

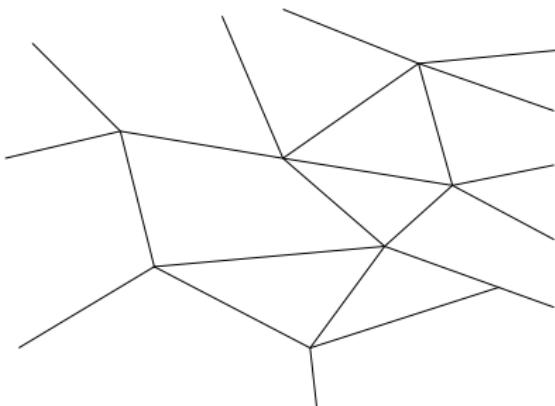
Université Paris Est, Ecole des Ponts ParisTech & IFSTTAR

NETCO Conference - Tours,  
June 24, 2014

# Flows on a network



# Flows on a network



A network is like a (oriented) **graph** made of **edges** and **vertices**

## Examples:

- traffic flow,
- gas pipelines,
- blood vessels,
- shallow water,
- internet communications...

# Outline

- 1 Introduction
- 2 Numerical scheme
- 3 Traffic interpretation
- 4 Numerical simulation
- 5 Recent developments

# Motivation

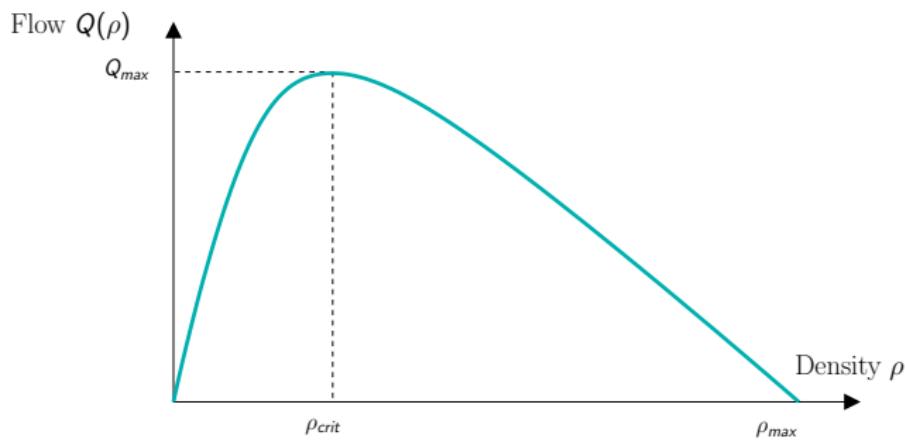
Classical approaches (see A. Bressan's lectures):

- Macroscopic modeling on (homogeneous) sections
- Coupling conditions at (pointwise) junction

For instance, consider

$$\begin{cases} \rho_t + (Q(\rho))_x = 0, & \text{scalar conservation law,} \\ \rho(., t=0) = \rho_0(.), & \text{initial conditions,} \\ \psi(\rho(x=0^-, t), \rho(x=0^+, t)) = 0, & \text{coupling condition.} \end{cases} \quad (1)$$

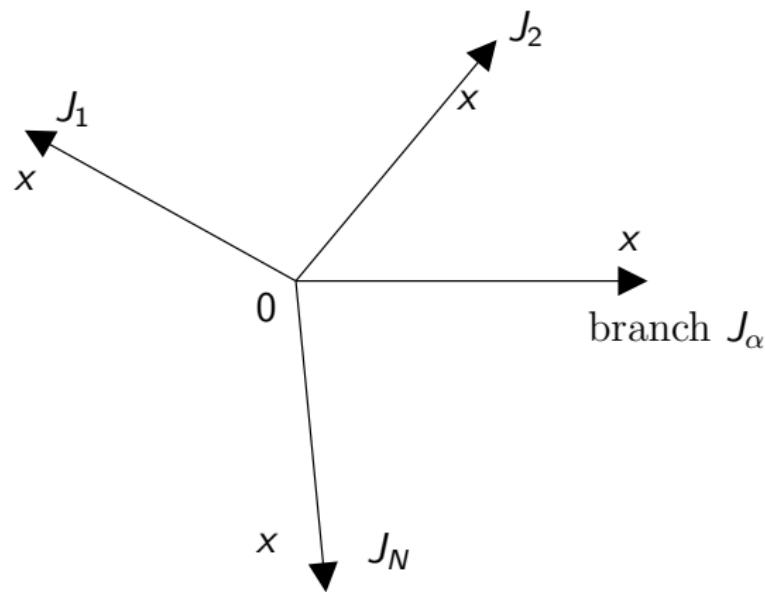
See Garavello, Piccoli [3], Lebacque, Khoshyaran [6] and Bressan et al. [1]



$$Q(\rho) = \rho V(\rho) \quad \text{with} \quad V(\rho) = \text{velocity function}$$

▶ DFs

# Star-shaped junction



# Junction model

## Proposition (Junction model [IMZ, '13])

That leads to the following junction model (see [5])

$$\begin{cases} u_t^\alpha + H_\alpha(u_x^\alpha) = 0, & x > 0, \quad \alpha = 1, \dots, N \\ u^\alpha = u^\beta =: u, & x = 0, \\ u_t + \mathcal{H}(u_x^1, \dots, u_x^N) = 0, & x = 0 \end{cases} \quad (2)$$

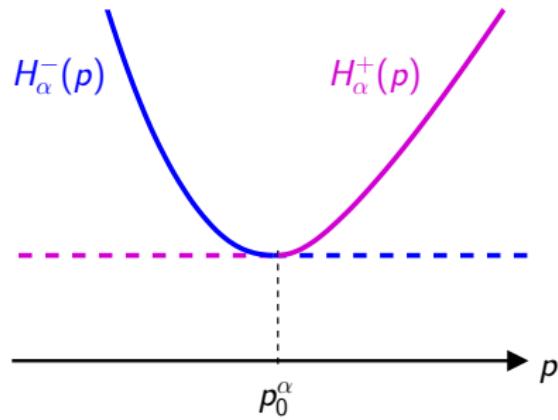
with initial condition  $u^\alpha(0, x) = u_0^\alpha(x)$  and

$$\mathcal{H}(u_x^1, \dots, u_x^N) = \underbrace{\max_{\alpha=1, \dots, N} \{H_\alpha^-(u_x^\alpha)\}}_{\text{from optimal control}}.$$

# Basic assumptions

For all  $\alpha = 1, \dots, N$ ,

- (A0) The initial condition  $u_0^\alpha$  is Lipschitz continuous.
- (A1) The Hamiltonians  $H_\alpha$  are  $C^1(\mathbb{R})$  and convex such that:



# Numerics on networks

Godunov scheme mainly used for conservation laws:

- [Bretti, Natalini, Piccoli '06, '07]: Godunov scheme compared to kinetic schemes / fast algorithms
- [Blandin, Bretti, Cutolo, Piccoli '09]: Godunov scheme adapted for Colombo model (only tested for  $1 \times 1$  junctions)

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For Hamilton-Jacobi equations on networks:

- [Göttlich, Ziegler, Herty '13]: Lax-Freidrichs scheme outside the junction + coupling conditions (density) at the junction
- [Han, Piccoli, Friesz, Yao '12]: Lax-Hopf formula for HJ equation coupled with a Riemann solver at junction
- [Camilli, Festa, Schieborn '13]: semi-Lagrangian scheme only designed for Eikonal equations

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# Presentation of the scheme

## Proposition (Numerical Scheme)

Let us consider the discrete space and time derivatives:

$$p_i^{\alpha,n} := \frac{U_{i+1}^{\alpha,n} - U_i^{\alpha,n}}{\Delta x} \quad \text{and} \quad (D_t U)_i^{\alpha,n} := \frac{U_i^{\alpha,n+1} - U_i^{\alpha,n}}{\Delta t}$$

Then we have the following numerical scheme:

$$\begin{cases} (D_t U)_i^{\alpha,n} + \max\{H_\alpha^+(p_{i-1}^{\alpha,n}), H_\alpha^-(p_i^{\alpha,n})\} = 0, & i \geq 1 \\ U_0^n := U_0^{\alpha,n}, & i = 0, \quad \alpha = 1, \dots, N \\ (D_t U)_0^n + \max_{\alpha=1,\dots,N} H_\alpha^-(p_0^{\alpha,n}) = 0, & i = 0 \end{cases} \quad (3)$$

With the initial condition  $U_i^{\alpha,0} := u_0^\alpha(i\Delta x)$ .

$\Delta x$  and  $\Delta t$  = space and time steps satisfying a CFL condition

# CFL condition

The natural CFL condition is given by:

$$\frac{\Delta x}{\Delta t} \geq \sup_{\substack{\alpha=1,\dots,N \\ i \geq 0, \ 0 \leq n \leq n_T}} |H'_\alpha(p_i^{\alpha,n})| \quad (4)$$

# Gradient estimates

## Theorem (Time and Space Gradient estimates)

Assume (A0)-(A1). If the CFL condition (4) is satisfied, then we have that:

- (i) Considering  $M^n = \sup_{\alpha,i} (D_t U)_i^{\alpha,n}$  and  $m^n = \inf_{\alpha,i} (D_t U)_i^{\alpha,n}$ , we have the following time derivative estimate:

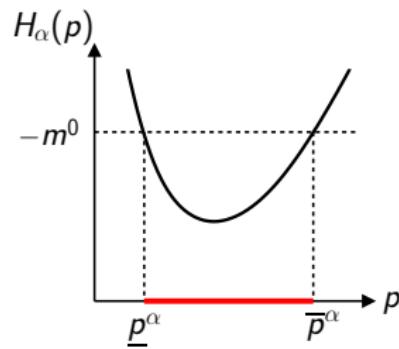
$$m^0 \leq m^n \leq m^{n+1} \leq M^{n+1} \leq M^n \leq M^0$$

- (ii) Considering  $\underline{p}_\alpha = (H_\alpha^-)^{-1}(-m^0)$  and  $\bar{p}_\alpha = (H_\alpha^+)^{-1}(-m^0)$ , we have the following gradient estimate:

$$\underline{p}_\alpha \leq p_i^{\alpha,n} \leq \bar{p}_\alpha, \quad \text{for all } i \geq 0, \quad n \geq 0 \quad \text{and} \quad \alpha = 1, \dots, N$$

▶ Proof

# Stronger CFL condition



As for any  $\alpha = 1, \dots, N$ , we have that:

$$\underline{p}_\alpha \leq p_i^{\alpha, n} \leq \bar{p}_\alpha \quad \text{for all } i, n \geq 0$$

Then the CFL condition becomes:

$$\frac{\Delta x}{\Delta t} \geq \sup_{\substack{\alpha=1,\dots,N \\ p_\alpha \in [\underline{p}_\alpha, \bar{p}_\alpha]}} |H'_\alpha(p_\alpha)| \tag{5}$$

# Existence and uniqueness

(A2) Technical assumption (Legendre-Fenchel transform)

$$H_\alpha(p) = \sup_{q \in \mathbb{R}} (pq - L_\alpha(q)) \quad \text{with} \quad L_\alpha'' \geq \delta > 0, \quad \text{for all index } \alpha$$

# Existence and uniqueness

(A2) Technical assumption (Legendre-Fenchel transform)

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Theorem (Existence and uniqueness [IMZ, '13])

Under (A0)-(A1)-(A2), there exists a *unique viscosity solution*  $u$  of (2) on the junction, satisfying for some constant  $C_T > 0$

$$|u(t, y) - u_0(y)| \leq C_T \quad \text{for all } (t, y) \in J_T.$$

Moreover the function  $u$  is Lipschitz continuous with respect to  $(t, y)$ .

# Convergence

Theorem (Convergence from discrete to continuous [CML, '13])

Assume that (A0)-(A1)-(A2) and the CFL condition (5) are satisfied.

Then the numerical solution converges uniformly to  $u$  the unique viscosity solution of (2) when  $\varepsilon \rightarrow 0$ , locally uniformly on any compact set  $\mathcal{K}$ :

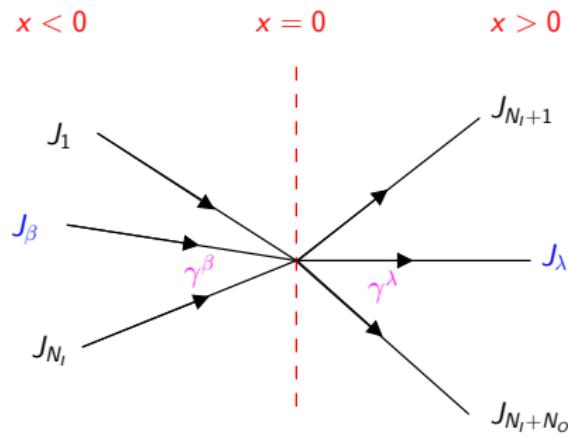
$$\limsup_{\varepsilon \rightarrow 0} \sup_{(n\Delta t, i\Delta x) \in \mathcal{K}} |u^\alpha(n\Delta t, i\Delta x) - U_i^{\alpha, n}| = 0$$

▶ Proof

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# Setting



$N_l$  incoming and  $N_O$  outgoing roads

# Car densities

The car density  $\rho^\alpha$  solves the LWR equation on branch  $\alpha$ :

$$\rho_t^\alpha + (Q^\alpha(\rho^\alpha))_x = 0$$

By definition

$$\rho^\alpha = \gamma^\alpha \partial_x U^\alpha \quad \text{on branch } \alpha$$

And

$$\begin{cases} u^\alpha(x, t) = -U^\alpha(-x, t), & x > 0, \text{ for incoming roads} \\ u^\alpha(x, t) = -U^\alpha(x, t), & x > 0, \text{ for outgoing roads} \end{cases}$$

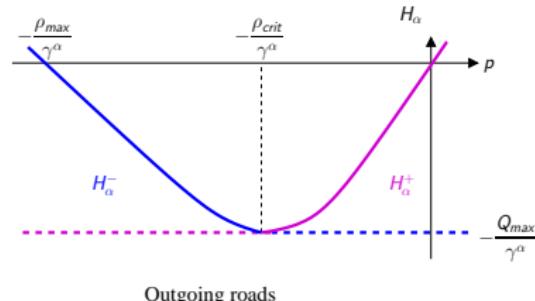
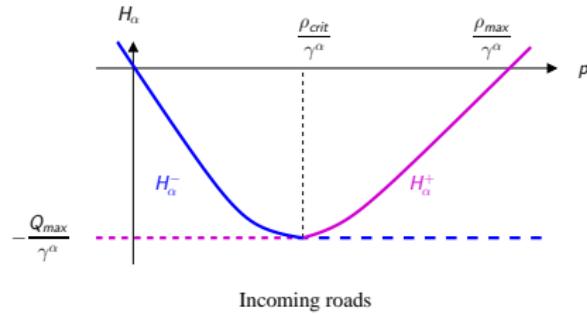
where the car index  $u^\alpha$  solves the HJ equation on branch  $\alpha$ :

$$u_t^\alpha + H^\alpha(u_x^\alpha) = 0, \quad \text{for } x > 0$$

▶ Setting

# Flow

$$H_\alpha(p) := \begin{cases} -\frac{1}{\gamma^\alpha} Q^\alpha(\gamma^\alpha p) & \text{for } \alpha = 1, \dots, N_I \\ -\frac{1}{\gamma^\alpha} Q^\alpha(-\gamma^\alpha p) & \text{for } \alpha = N_I + 1, \dots, N_I + N_O \end{cases}$$

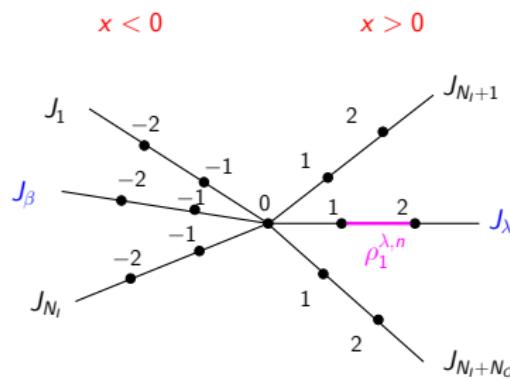


# Links with “classical” approach

Definition (Discrete car density)

The discrete car density  $\rho_i^{\alpha,n}$  with  $n \geq 0$  and  $i \in \mathbb{Z}$  is given by:

$$\rho_i^{\alpha,n} := \begin{cases} \gamma^\alpha p_{|i|-1}^{\alpha,n} & \text{for } \alpha = 1, \dots, N_I, \quad i \leq -1 \\ -\gamma^\alpha p_i^{\alpha,n} & \text{for } \alpha = N_I + 1, \dots, N_I + N_O, \quad i \geq 0 \end{cases} \quad (6)$$



# Traffic interpretation

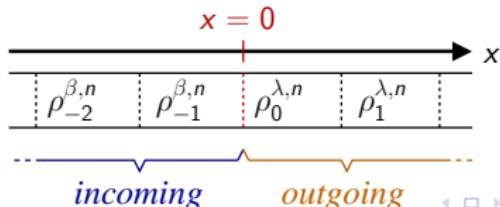
## Proposition (Scheme for vehicles densities)

The scheme deduced from (3) for the discrete densities is given by:

$$\frac{\Delta x}{\Delta t} \{ \rho_i^{\alpha,n+1} - \rho_i^{\alpha,n} \} = \begin{cases} F^\alpha(\rho_{i-1}^{\alpha,n}, \rho_i^{\alpha,n}) - F^\alpha(\rho_i^{\alpha,n}, \rho_{i+1}^{\alpha,n}) & \text{for } i \neq 0, -1 \\ F_0^\alpha(\rho_0^{\cdot,n}) - F^\alpha(\rho_i^{\alpha,n}, \rho_{i+1}^{\alpha,n}) & \text{for } i = 0 \\ F^\alpha(\rho_{i-1}^{\alpha,n}, \rho_i^{\alpha,n}) - F_0^\alpha(\rho_0^{\cdot,n}) & \text{for } i = -1 \end{cases}$$

With

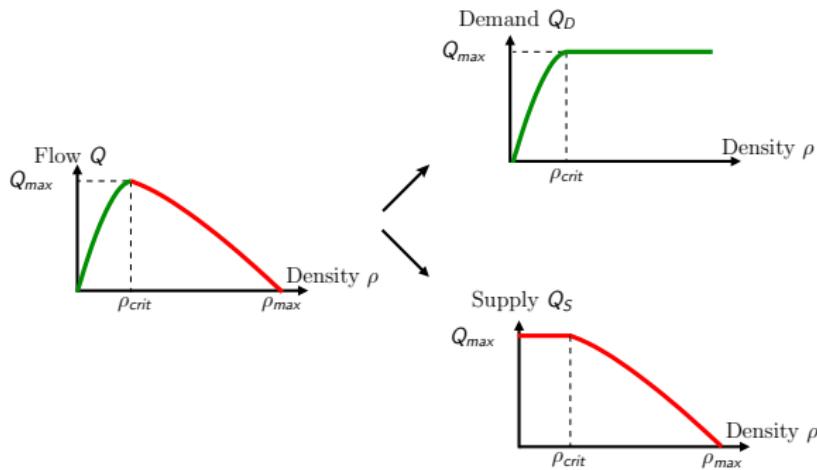
$$\begin{cases} F^\alpha(\rho_{i-1}^{\alpha,n}, \rho_i^{\alpha,n}) := \min \{ Q_D^\alpha(\rho_{i-1}^{\alpha,n}), Q_S^\alpha(\rho_i^{\alpha,n}) \} \\ F_0^\alpha(\rho_0^{\cdot,n}) := \gamma^\alpha \min \left\{ \min_{\beta \leq N_I} \frac{1}{\gamma^\beta} Q_D^\beta(\rho_0^{\beta,n}), \min_{\lambda > N_I} \frac{1}{\gamma^\lambda} Q_S^\lambda(\rho_0^{\lambda,n}) \right\} \end{cases}$$



## Supply and demand functions

## Remark

It recovers the seminal Godunov scheme with passing flow = minimum between upstream demand  $Q_D$  and downstream supply  $Q_s$ .



From [Lebacque '93, '96]

# Supply and demand VS Hamiltonian

$$H_{\alpha}^{-}(p) = \begin{cases} -\frac{1}{\gamma^{\alpha}} Q_D^{\alpha}(\gamma^{\alpha} p) & \text{for } \alpha = 1, \dots, N_I \\ -\frac{1}{\gamma^{\alpha}} Q_S^{\alpha}(-\gamma^{\alpha} p) & \text{for } \alpha = N_I + 1, \dots, N_I + N_O \end{cases}$$

And

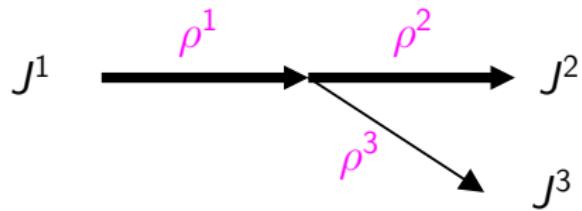
$$H_{\alpha}^{+}(p) = \begin{cases} -\frac{1}{\gamma^{\alpha}} Q_S^{\alpha}(\gamma^{\alpha} p) & \text{for } \alpha = 1, \dots, N_I \\ -\frac{1}{\gamma^{\alpha}} Q_D^{\alpha}(-\gamma^{\alpha} p) & \text{for } \alpha = N_I + 1, \dots, N_I + N_O \end{cases}$$

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# Example of a Diverge

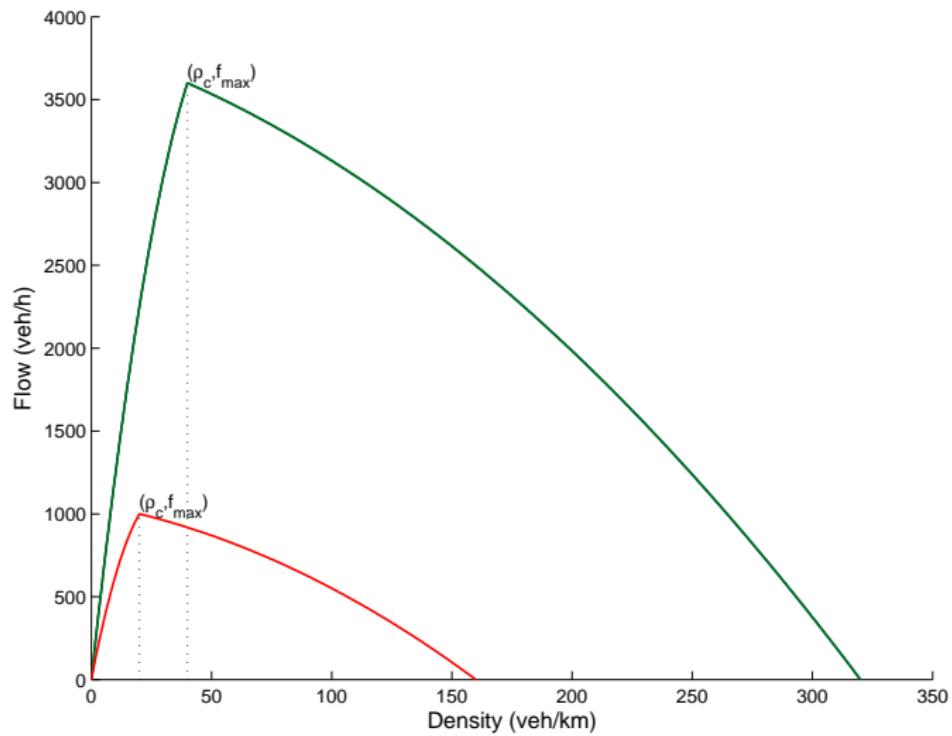
An off-ramp:



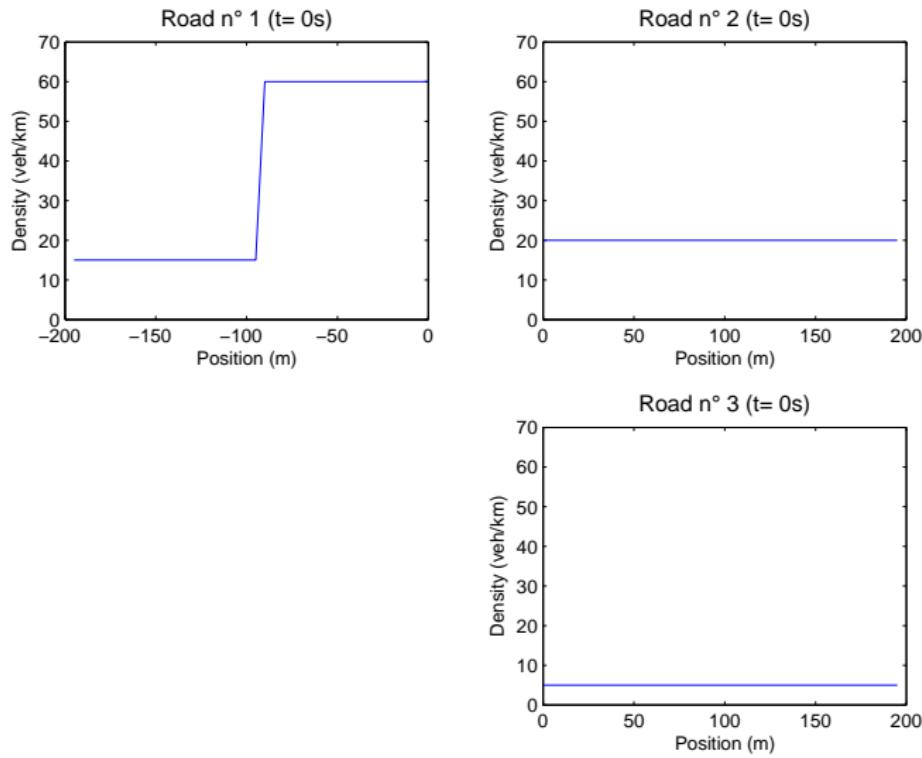
with

$$\begin{cases} \gamma^e = 1, \\ \gamma^l = 0.75, \\ \gamma^r = 0.25 \end{cases}$$

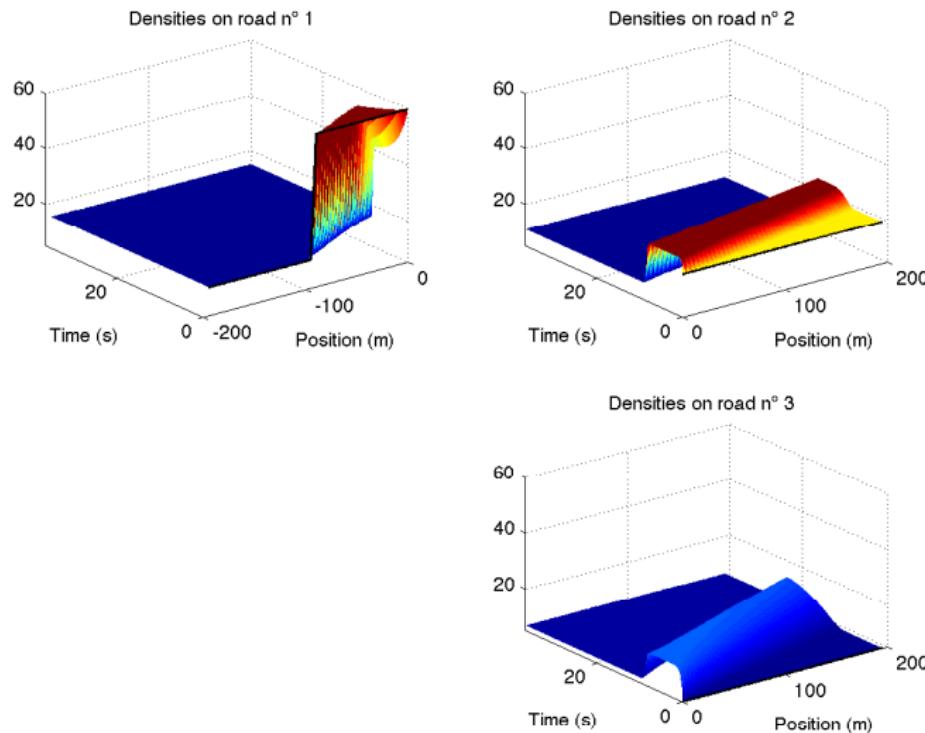
# Fundamental Diagrams



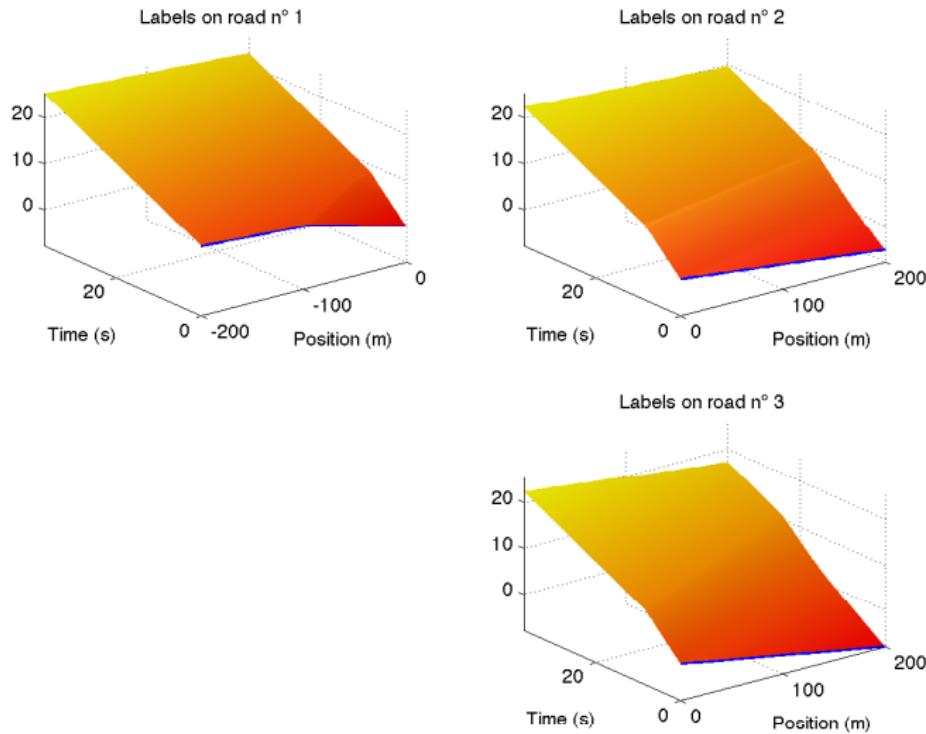
# Initial conditions ( $t=0s$ )



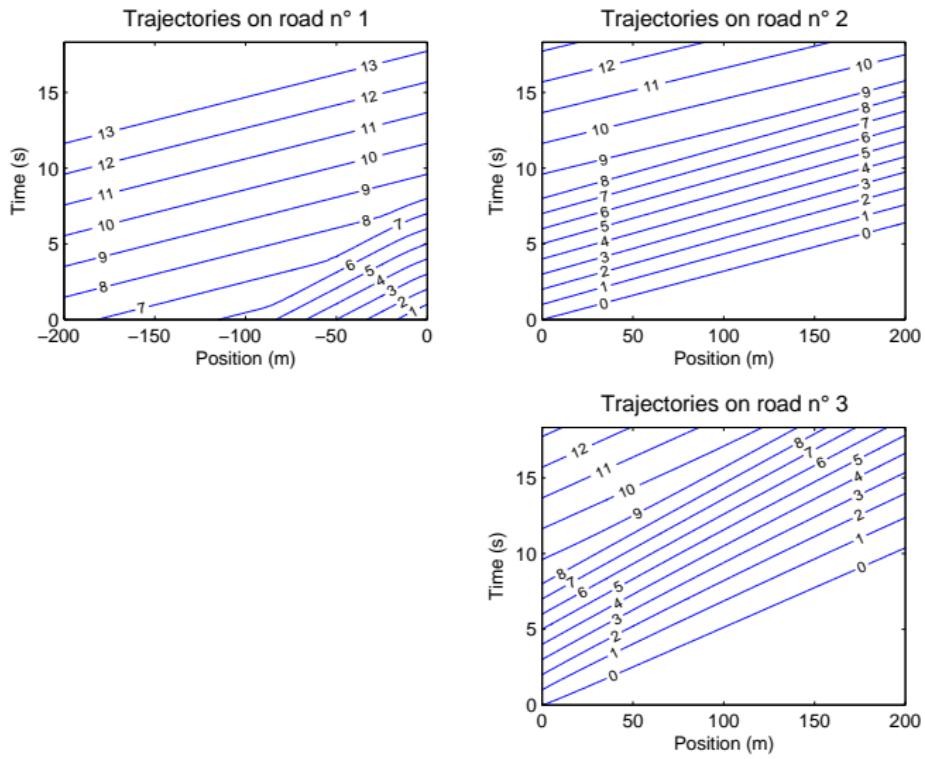
# Numerical solution: densities



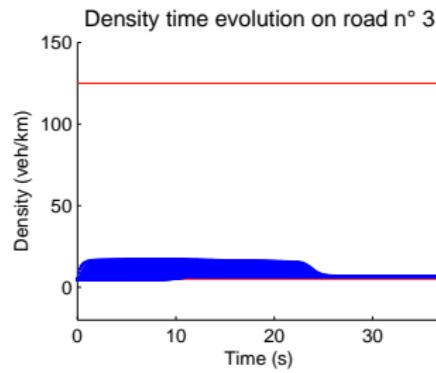
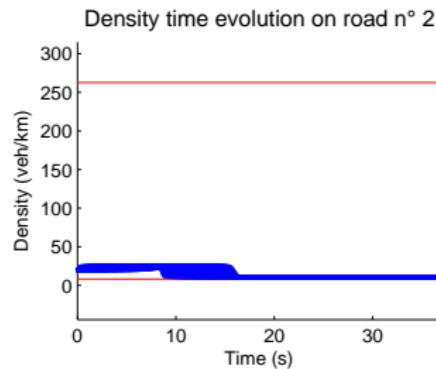
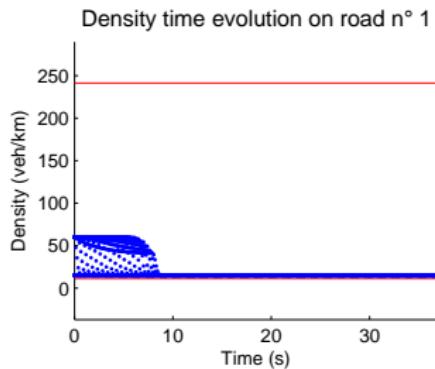
# Numerical solution: Hamilton-Jacobi



# Trajectories



# Gradient estimates



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# New junction model

**Proposition (Junction model [IM, '14])**

From [4], we have

$$\begin{cases} u_t^\alpha + H_\alpha(u_x^\alpha) = 0, & x > 0, \alpha = 1, \dots, N \\ u^\alpha = u^\beta =: u, & x = 0, \\ u_t + \mathcal{H}(u_x^1, \dots, u_x^N) = 0, & x = 0 \end{cases} \quad (7)$$

with initial condition  $u^\alpha(0, x) = u_0^\alpha(x)$  and

$$\mathcal{H}(u_x^1, \dots, u_x^N) = \max \left[ \underbrace{\mathcal{L}}_{\substack{\text{flux limiter} \\ \text{minimum between} \\ \text{demand and supply}}} \, , \, \underbrace{\max_{\alpha=1, \dots, N} \{H_\alpha^-(u_x^\alpha)\}}_{\substack{\text{minimum between} \\ \text{demand and supply}}} \right].$$

# Weaker assumptions on the Hamiltonians

For all  $\alpha = 1, \dots, N$ ,

(A0) The initial condition  $u_0^\alpha$  is Lipschitz continuous.

(A1) The Hamiltonians  $H_\alpha$  are continuous and **quasi-convex** i.e. there exists points  $p_0^\alpha$  such that

$$\begin{cases} H_\alpha \text{ is non-increasing on } (-\infty, p_0^\alpha], \\ H_\alpha \text{ is non-decreasing on } [p_0^\alpha, +\infty). \end{cases}$$

# Homogenization on a network

## Proposition (Homogenization on a periodic network [IM'14])

Assume (A0)-(A1). Consider a *periodic* network.

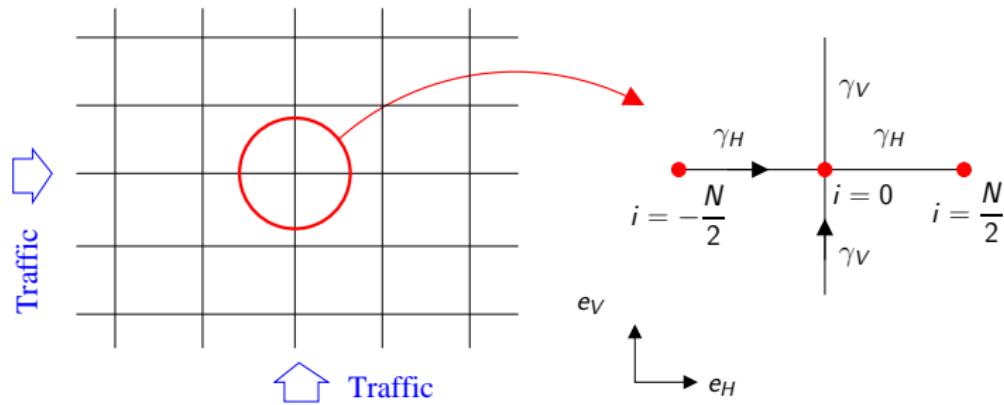
If  $u^\varepsilon$  satisfies (oscillating) HJ equation on network,  
then  $u^\varepsilon$  converges uniformly towards  $u^0$  when  $\varepsilon \rightarrow 0$ ,  
with  $u^0$  solution of

$$u_t^0 + \overline{H}(\nabla_x u^0) = 0, \quad t > 0, \quad x \in \mathbb{R}^d \quad (8)$$

See Prof. R. Monneau's lecture and [4]

# Numerical homogenization on a network

Numerical scheme adapted to the **cell problem**



# First example

## Proposition (Effective Hamiltonian for fixed coefficients [IM'14])

If  $(\gamma^H, \gamma^V)$  are fixed, then the

- (Hamiltonian) **effective Hamiltonian**  $\overline{H}$  is given by

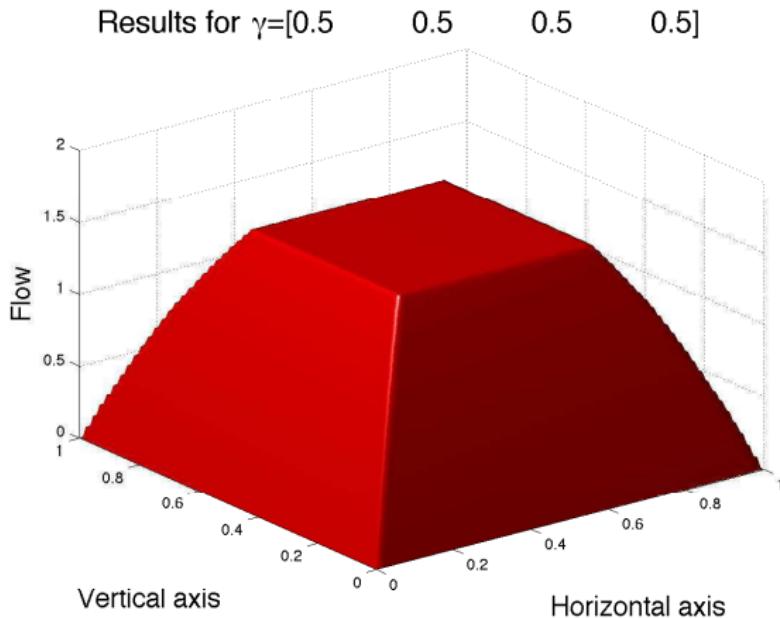
$$\overline{H}(u_{H,x}, u_{V,x}) = \max \left\{ \mathcal{L}, \max_{i=\{H,V\}} H(u_{i,x}) \right\},$$

- (traffic flow) **effective flow**  $\overline{Q}$  is given by

$$\overline{Q}(\rho_H, \rho_V) = \min \left\{ -\mathcal{L}, \frac{Q(\rho_H)}{\gamma^H}, \frac{Q(\rho_V)}{\gamma^V} \right\}.$$

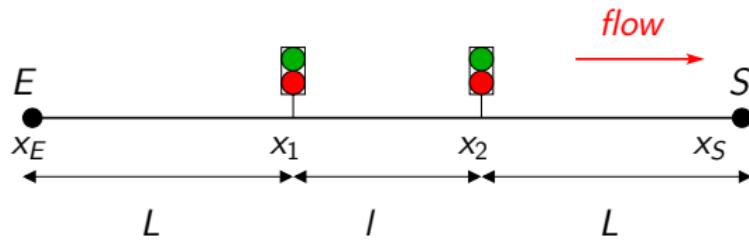
# First example

Numerics: assume  $Q(\rho) = 4\rho(1 - \rho)$  and  $\mathcal{L} = -1.5$ ,



## Second example

Two consecutive traffic signals on a 1D road

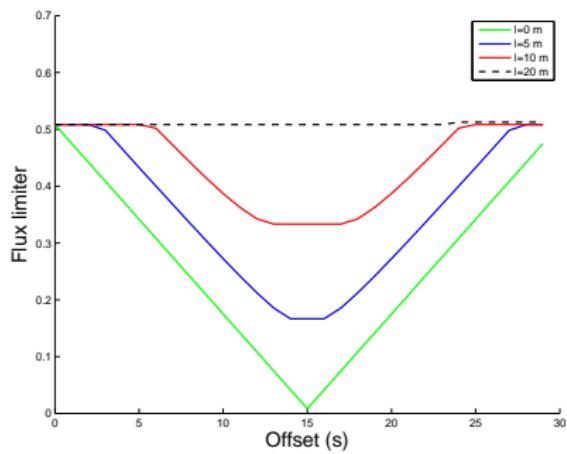
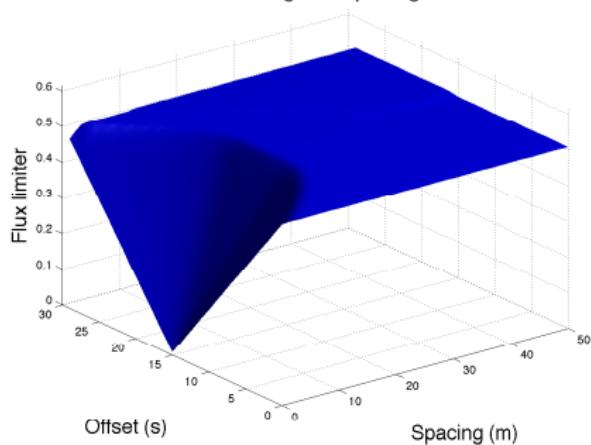


Homogenization theory by [G. Galise, C. Imbert, R. Monneau, '14]

## Second example

Effective flux limiter  $-\bar{\mathcal{L}}$  (numerics only)

Flux limiter w.r.t. signals spacing and offset



THANKS FOR YOUR ATTENTION

guillaume.costeseque@cermics.enpc.fr

guillaume.costeseque@ifsttar.fr

# Some references I

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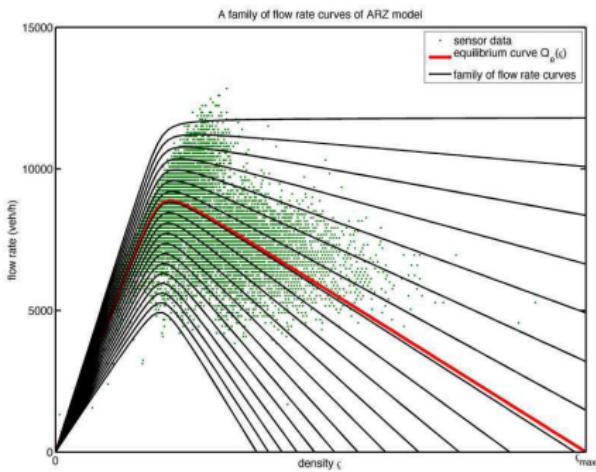
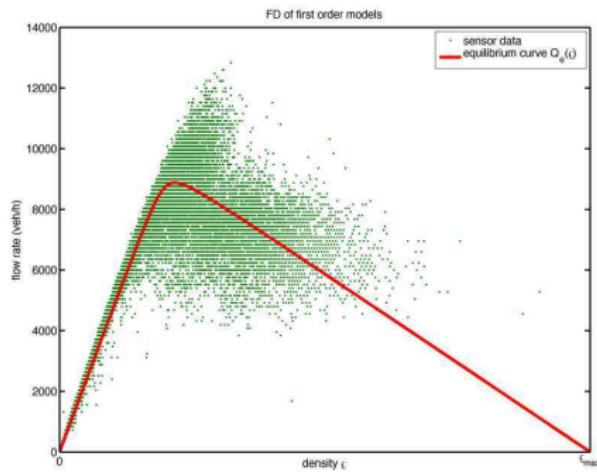
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J.-P. LEBACQUE AND M. M. KHOSHYARAN, *First-order macroscopic traffic flow models: Intersection modeling, network modeling*, in Transportation and Traffic Theory. Flow, Dynamics and Human Interaction. 16th International Symposium on Transportation and Traffic Theory, 2005.

# Fundamental diagram

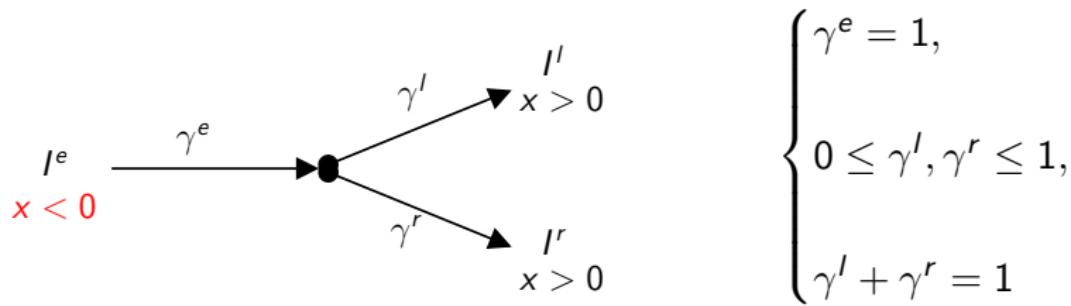
Fundamental diagram: multi-valued in congested case



[S. Fan, M. Herty, B. Seibold, 2013], NGSIM dataset

◀ Back

# Motivation: the simple divergent road



LWR model [Lighthill, Whitham '55; Richards '56] on each **branch  $\alpha$** :

$$\rho_t^\alpha + (Q^\alpha(\rho^\alpha))_x = 0$$

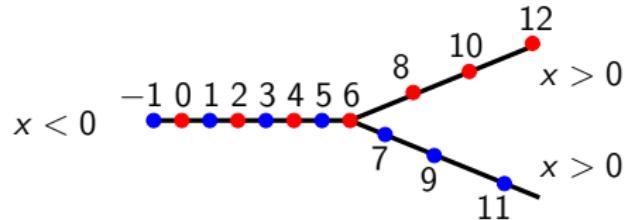
# Getting the Hamilton-Jacobi equation

LWR model on each branch (outside the junction point)

$$\rho_t^\alpha + (Q^\alpha(\rho^\alpha))_x = 0 \quad \text{on branch } \alpha$$

Primitive:

$$\begin{cases} U^\alpha(x, t) = U^\alpha(0, t) + \frac{1}{\gamma^\alpha} \int_0^x \rho^\alpha(y, t) dy, \\ U^\alpha(0, t) = g(t) = \text{index of the single car at the junction point} \end{cases}$$



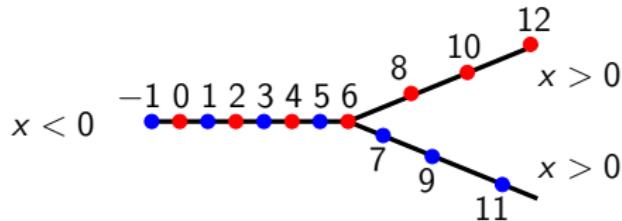
# Getting the Hamilton-Jacobi equation

LWR model on each branch (outside the junction point)

$$\rho_t^\alpha + (Q^\alpha(\rho^\alpha))_x = 0 \quad \text{on branch } \alpha$$

Primitive:

$$\begin{cases} U^\alpha(x, t) = U^\alpha(0, t) + \frac{1}{\gamma^\alpha} \int_0^x \rho^\alpha(y, t) dy, \\ U^\alpha(0, t) = g(t) = \text{index of the single car at the junction point} \end{cases}$$



$$\begin{aligned} U_t^\alpha + \frac{1}{\gamma^\alpha} Q^\alpha(\gamma^\alpha U_x^\alpha) &= g'(t) + \frac{1}{\gamma^\alpha} Q^\alpha(\rho^\alpha(0, t)) \\ &= 0 \quad \text{for a good choice of } g \end{aligned}$$

# Sketch of the proof (gradient estimates):

## Time derivative estimate:

1. Estimate on  $m^{\alpha,n} = \inf_i (D_t U)_i^{\alpha,n}$  and partial result for  $m^n = \inf_{\alpha} m^{\alpha,n}$
2. Similar estimate for  $M^n$
3. Conclusion

## Space derivative estimate:

1. New bounded Hamiltonian  $\tilde{H}_{\alpha}(p)$  for  $p \leq \underline{p}_{\alpha}$  and  $p \geq \bar{p}_{\alpha}$
2. Time derivative estimate from above
3. Lemma: if for any  $(i, n, \alpha)$ ,  $(D_t U)_i^{\alpha,n} \geq m^0$  then

$$\underline{p}_{\alpha} \leq p_i^{\alpha,n} \leq \bar{p}_{\alpha}$$

4. Conclusion as  $\tilde{H}_{\alpha} = H_{\alpha}$  on  $[\underline{p}_{\alpha}, \bar{p}_{\alpha}]$

See [2]

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# Convergence with uniqueness assumption

**Sketch of the proof:** (Comparison principle very helpful)

1.  $\bar{u}^\alpha(t, x) := \limsup_{\varepsilon} U_i^{\alpha, n}$  is a subsolution of (2) (contradiction on Definition inequality with a test function  $\varphi$ )
2. Similarly,  $\underline{u}^\alpha$  is a supersolution of (2)
3. Conclusion:  $\bar{u}^\alpha = \underline{u}^\alpha$  viscosity solution of (2)

See [2]

# Convergence without uniqueness assumption

**Sketch of the proof:** (No comparison principle)

1. Discrete Lipschitz bounds on  $u_\varepsilon^\alpha(n\Delta t, i\Delta x) := U_i^{\alpha,n}$
2. Extension by continuity of  $u_\varepsilon^\alpha$
3. Ascoli theorem (convergent subsequence on every compact set)
4. The limit of one convergent subsequence  $(u_\varepsilon^\alpha)_\varepsilon$  is super and sub-solution of (2)

See [2]

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