

WWV 2013

Deconstructing Complex Distributed Platforms

A Report from the Trenches

François Taïani



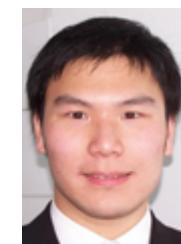
Joint work with



- Matti Hiltunen
- Rick Schlichting

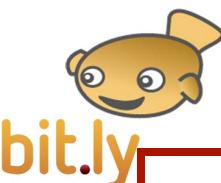


- Shen Lin
- Tom Ormerod
- Linden Ball



Distributed Software Today

facebook



External services

Large, complex, multi-party

Geosocial app, est. 2009



10M Users



JSON
JavaScript Object Notation

Standards

External
developers



Middleware

mongoDB

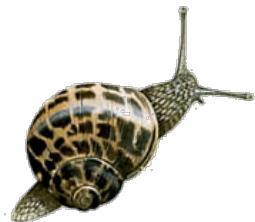


amazon
web services™

Why deconstruct software? (in particular distributed)

- Needed for **diagnosis / modifications**
 - ➔ Harden software (FT, replication)
 - ➔ To address non-functional issues (e.g. performance)

- Assembled from **third party** components
 - ➔ Unfamiliar software
 - ➔ Frankenstein effect

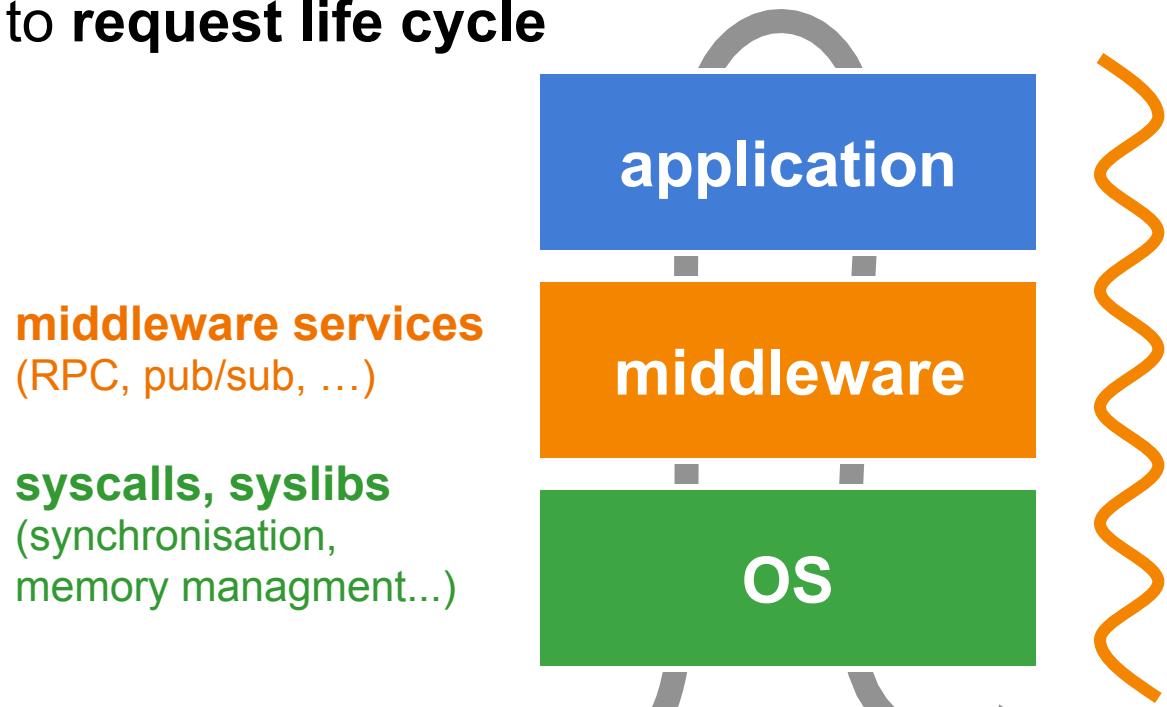


Why is it difficult?

- Software easier to construct than to **understand**
- Particularly true for **emergent dynamic behaviours**
 - ➔ e.g. **dependability** and **performance**
 - ➔ arise from interactions within/ without target system
- **Dynamic** observation data difficult to make sense of
 - ➔ **large** size (up to 1,000,000 invocations for a few sec)
 - ➔ likely to involves **poorly understood** parts

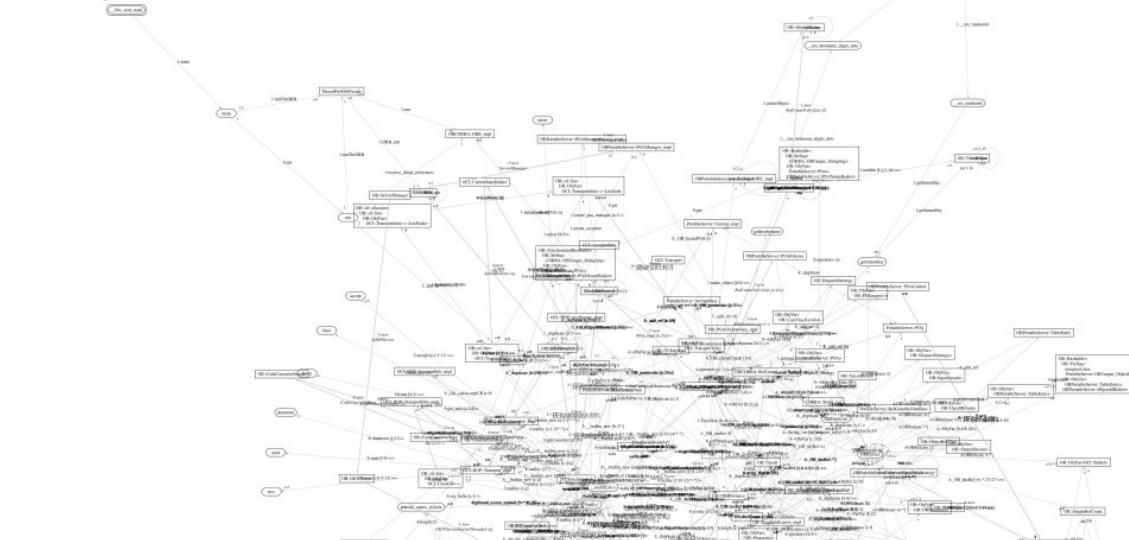
Example 1: Replication

- Replicating COTS applications: **non-determinism**
 - ➔ Observe mutex activities
 - ➔ Link mutexes to **request life cycle**



Approach: dynamic reverse engineering

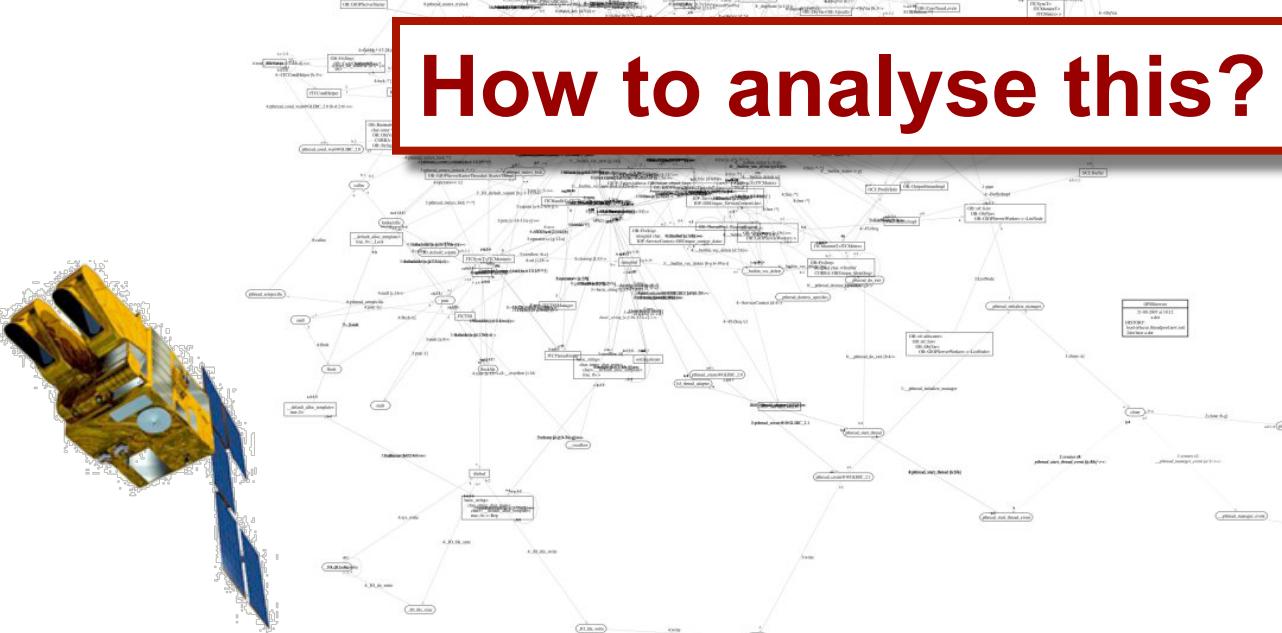
Dynamic Reverse Engineering



ORBacus 1 Request

*one request,
2065 individual invocations,
over 50 C-functions and 140
C++ classes.*

How to analyse this?



Example 2: Profiling

- **Globus** (Argonne): ref. implementation for Grid
 - ➔ Grid Computing + Web Services
- Transition to WS stack (Version 3.9.x, 2005)
 - ➔ within a short time (a few months)
 - ➔ large, complex, collaborative (IBM, Apache,...) ↗ reuse
- **But ... poor performances**
 - ➔ Up to **30s** to **create** a simple distributed object (counter)
 - ➔ Up to **2s** for a roundtrip remote **add** operation



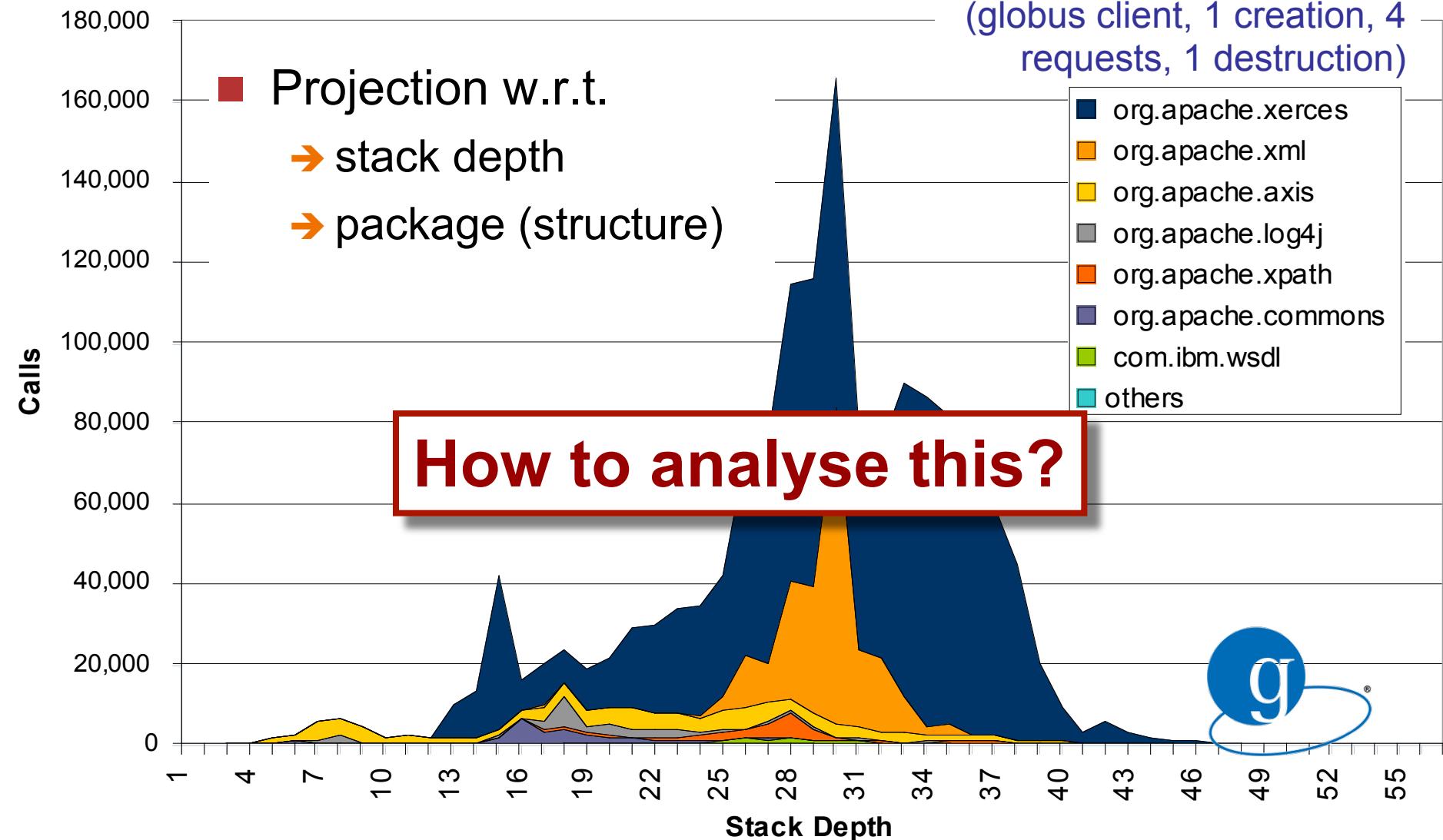
Profiling

- Large piece of software (3.9.x)
 - ➔ 123,839 lines in Java (w/o reused libraries)
- Many libraries layered
 - ➔ XML, WSDL (Descr. Lang), WSRF (Resource Fwork)
 - ➔ Axis (SOAP), Xerces (XML Parsing), com.ibm.wsdl
- Java: exhaustive tracing (outside the JVM libs)
 - ➔ client : **1,544,734** local method call (sic)
 - ➔ server : **6,466,652** local method calls (sic) [+time out]

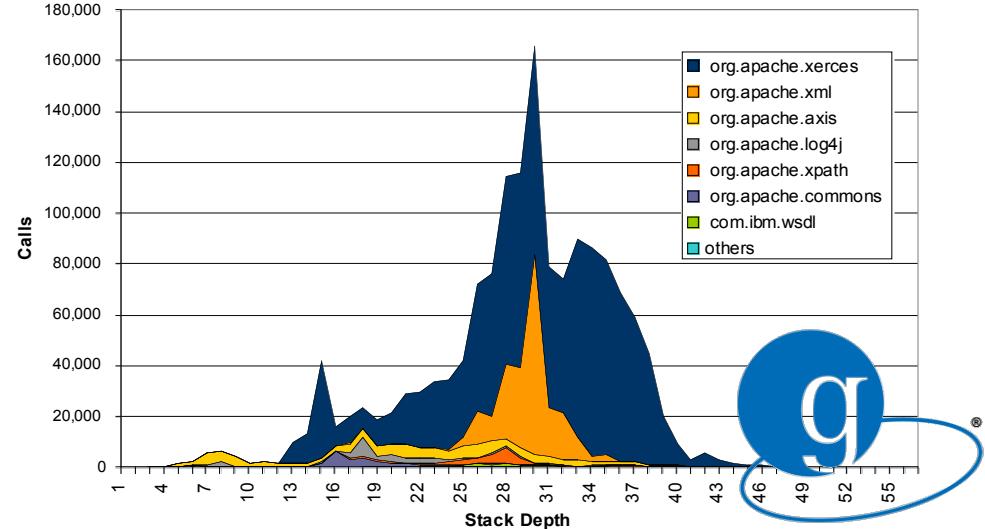
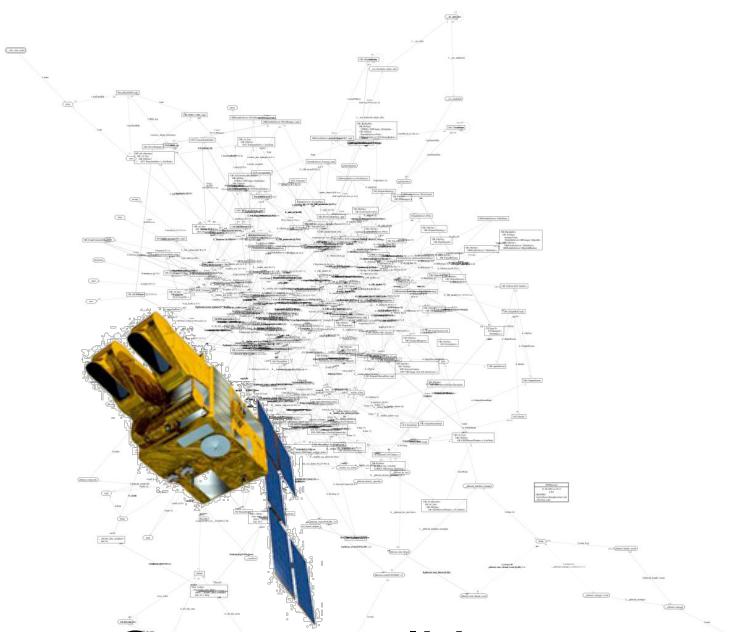


Profiling

(globus client, 1 creation, 4 requests, 1 destruction)



The Deconstruction Problem



■ Commonalities

- ➔ Large scale, software intensive, composite
- ➔ Unfamiliar

■ Our general philosophy

- ➔ Pragmatic, semi-automatic, interactive

Outline

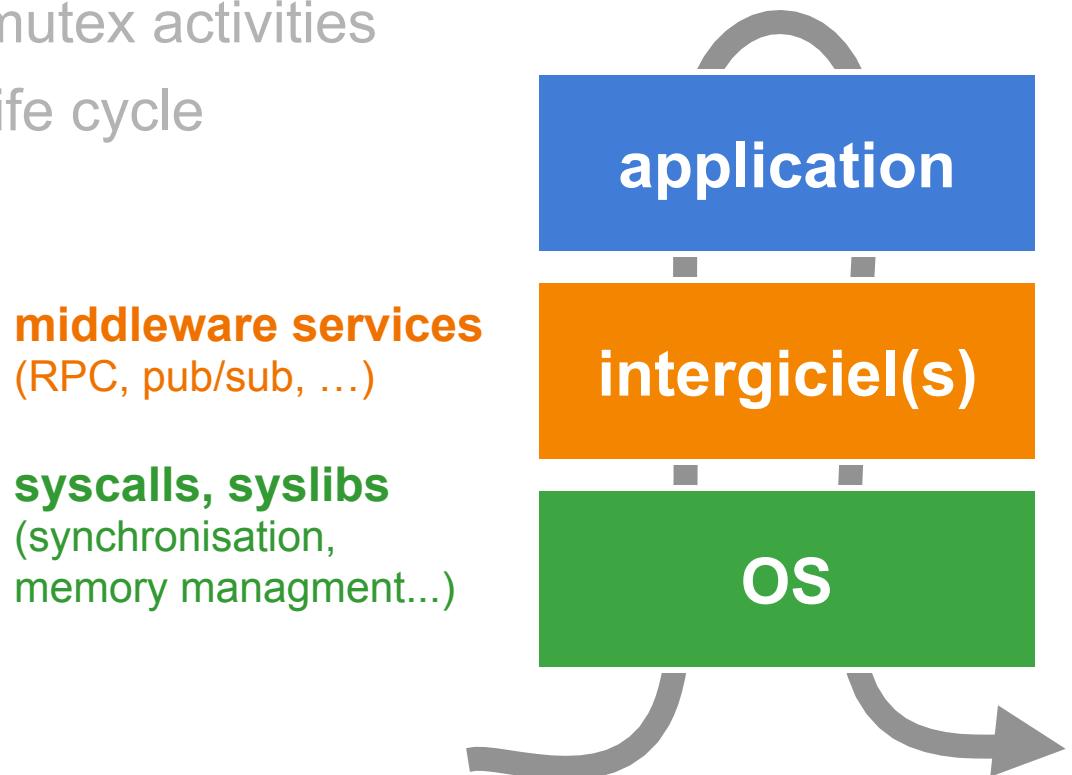
- Motivation
- Example 1:
 - ➔ Analysing **locking behaviour** in industrial ORB
- Example 2:
 - ➔ Visualizing **performance anomalies** in Grid MW
- Some concluding words



Back to Example 1

■ Original goal

- Control non-determinism in industry grade middleware
- Observation of mutex activities
- Link to request life cycle



Back to Example 1

- Original goal
 - Control non-determinism in industry grade middleware
 - Observation of mutex activities
 - Link to request life cycle

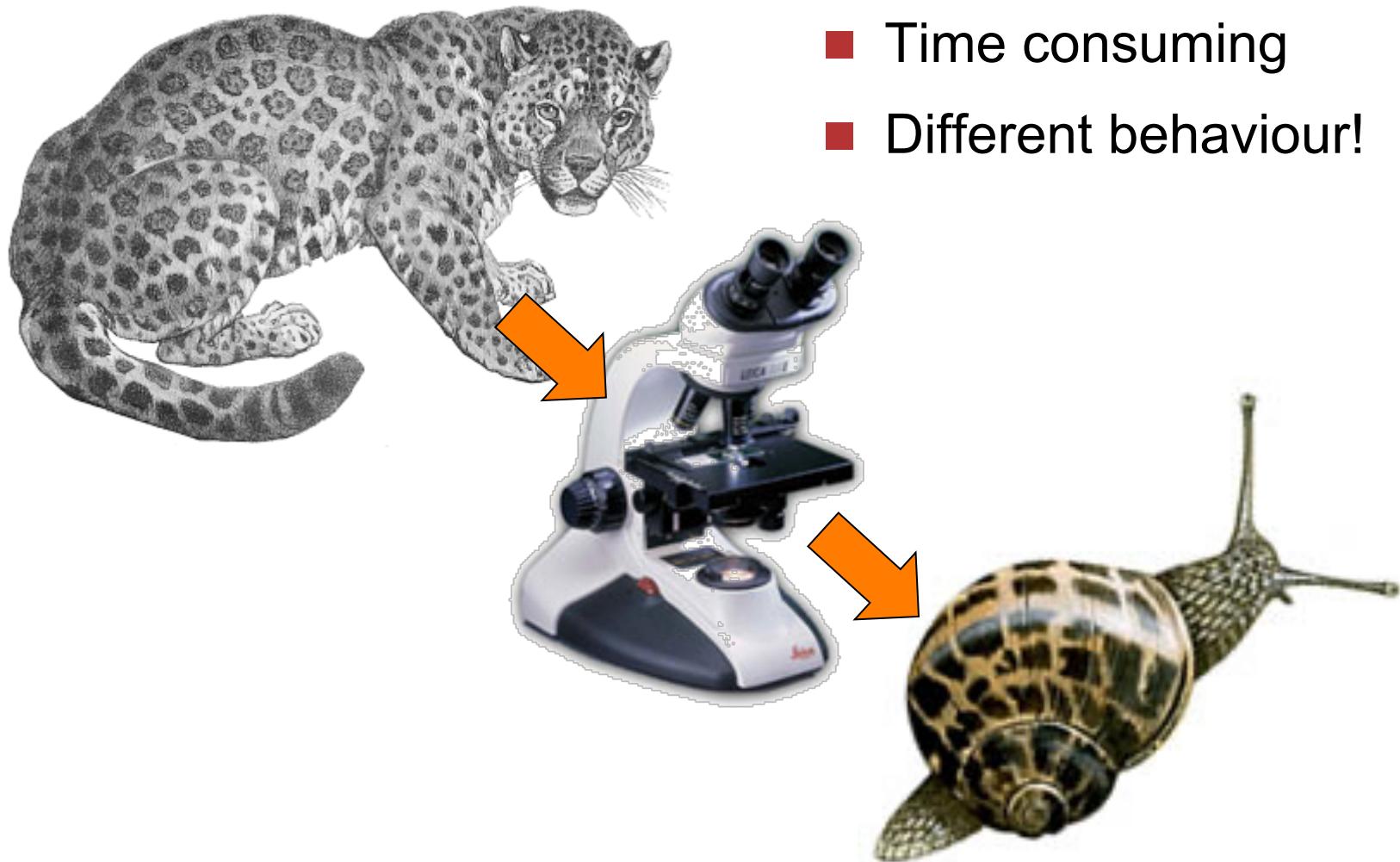
- Complex & layered system
- Hard to observe and analyse

Problem 1: Observation cost

Problem 2: Cross-layer entangling



Problem 1: Observation costs



- Time consuming
- Different behaviour!

Problem 2: Cross-layer entangling

dummy1

dummy2

```
int main () {  
    pthread_t threadN1, threadN2 ;  
    pthread_create(&threadN1, NULL, dummy1, NULL) ;  
    pthread_create(&threadN2, NULL, dummy2, NULL) ;  
};
```

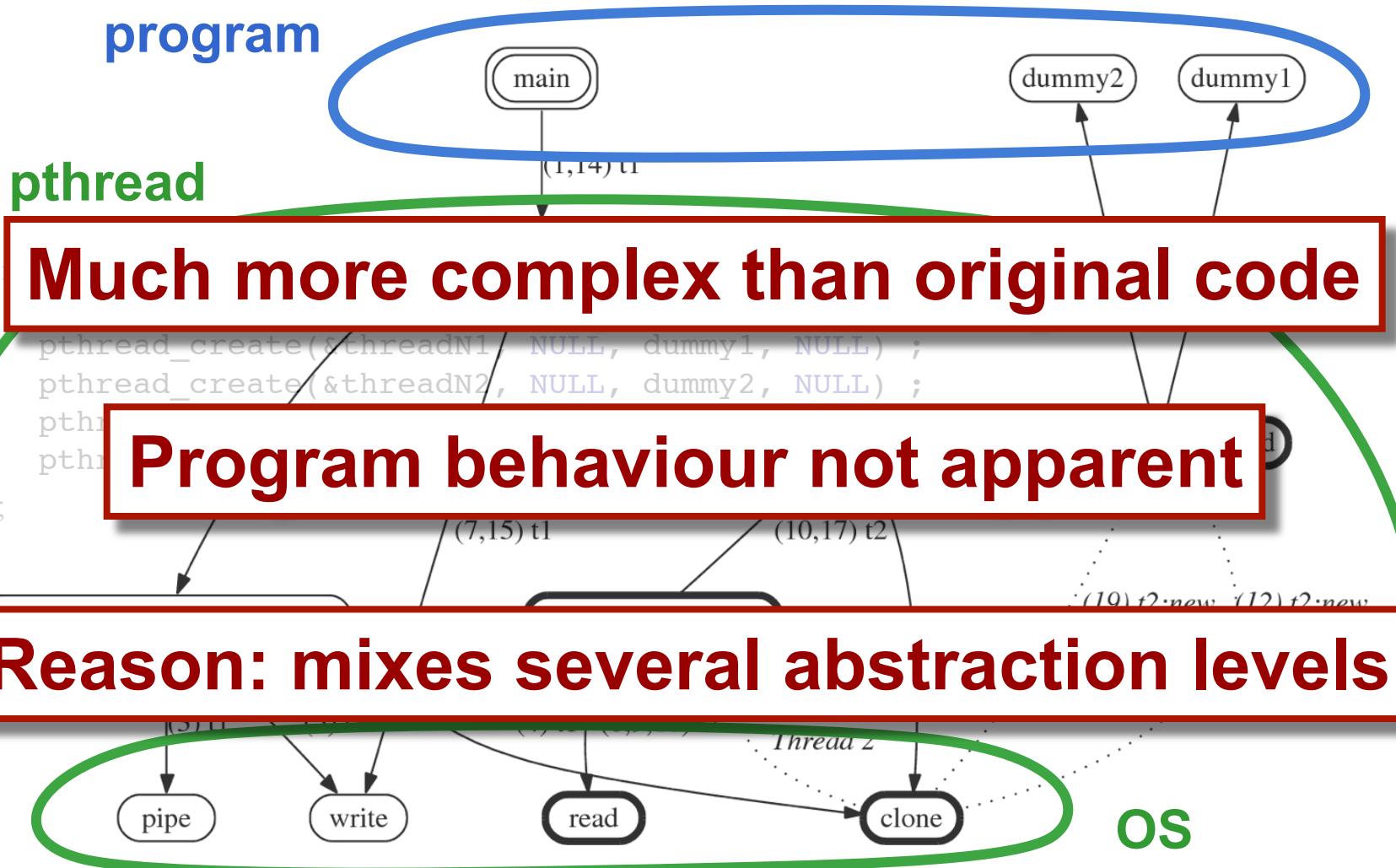
Can we reconstruct main's behaviour?

OS

observe

by tracing

Problem 2: Cross-layer entangling



Approach: “interferometry”

- **Limit** observation costs: **more for less**
 - ➔ capture stack traces (more)
 - ➔ limit observation points to component boundaries (less)
- **Filter** out unneeded data: “interferometry”
 - ➔ graph manipulation script language
 - ➔ reusable filters



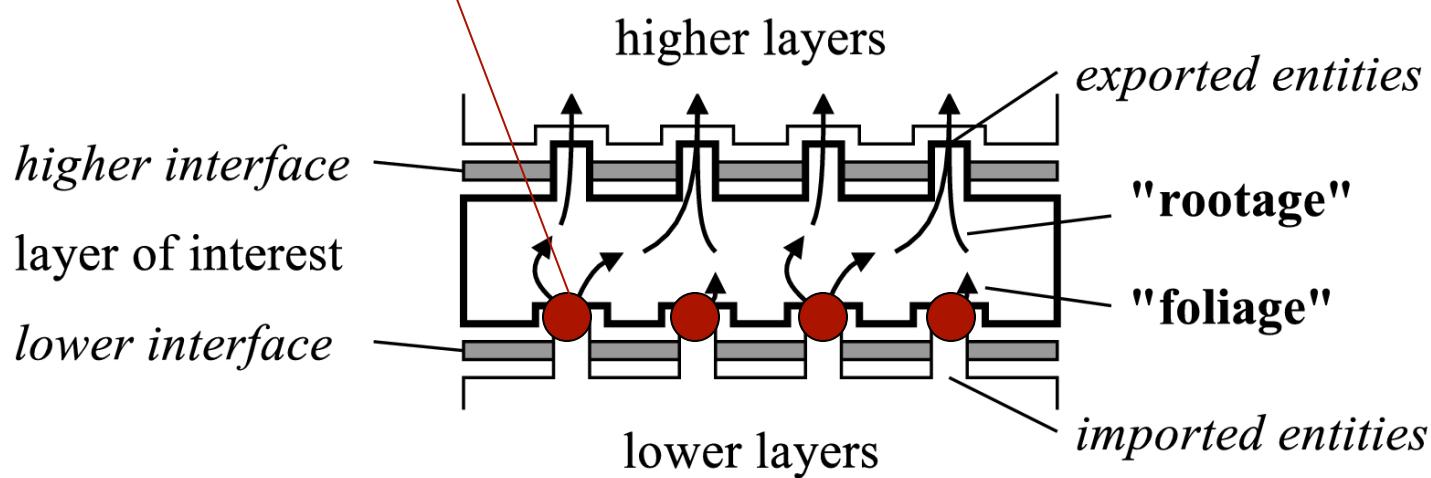
no turbulence
but very costly

vs.

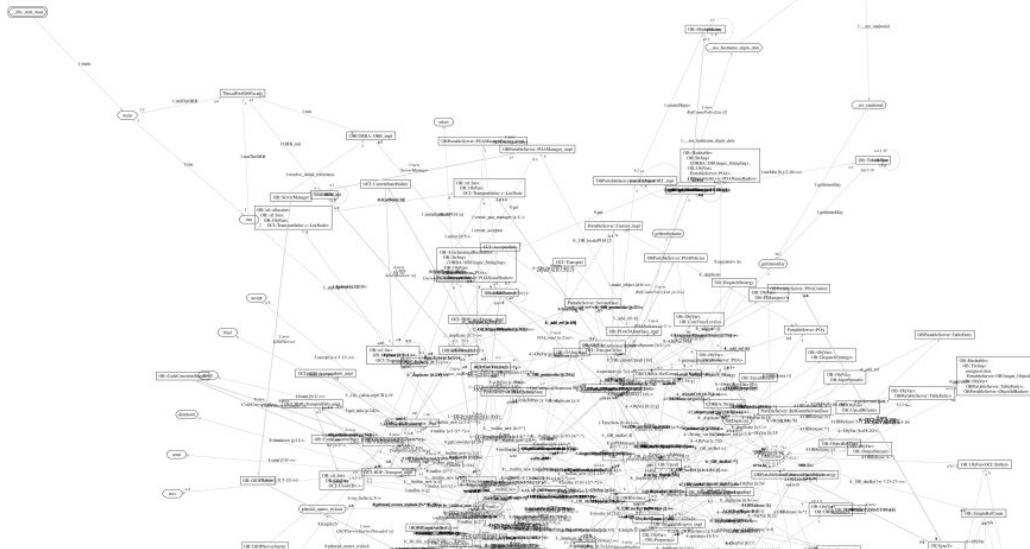


Tackling Observation Costs

```
#0 0x405c8f20 in send () from /lib/libpthread.so.0
#1 0x4015804a in omni::tcpConnection::Send ()
#2 0x4011364c in omni::giopStream::sendChunk ()
[...]
#8 0x400bdb0a in omniAsyncWorker::run ()
#9 0x405abbdf in omni_thread_wrapper ()
#10 0x405c2bf0 in pthread_start_thread ()
#11 0x405c2c6f in pthread_start_thread_event ()
```



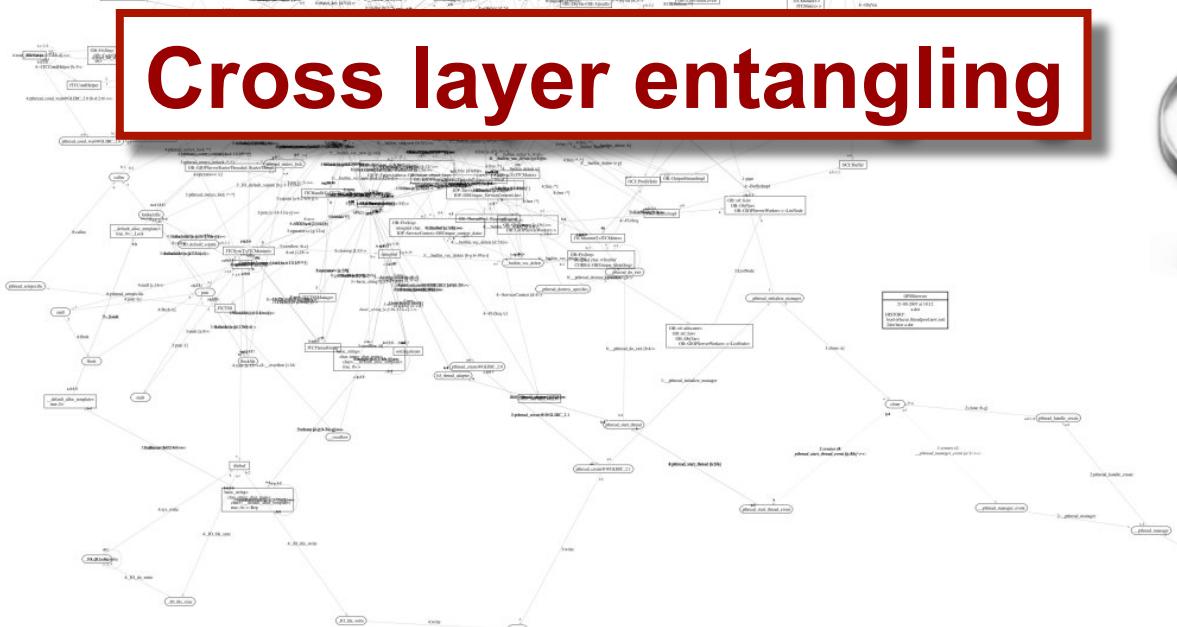
Result from Observation



ORBacus 1 Request

one request,
2065 individual invocations,
over 50 C-functions and 140
C++ classes.

Cross layer entangling



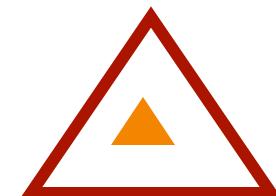
Tackling Entangling

A number of graph **operators**

Interactive graph scripting language

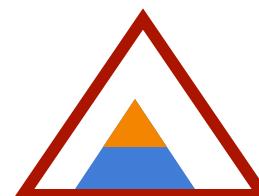
- **selection**

```
put ::pthread_create* G CREATE
```



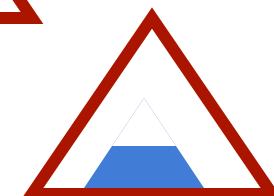
- **recursive extension**

```
forward CREATE G
```



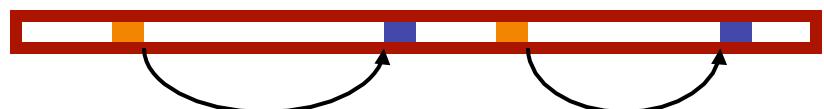
- **boolean algebra**

```
remove ::pthread_create* CREATE
```

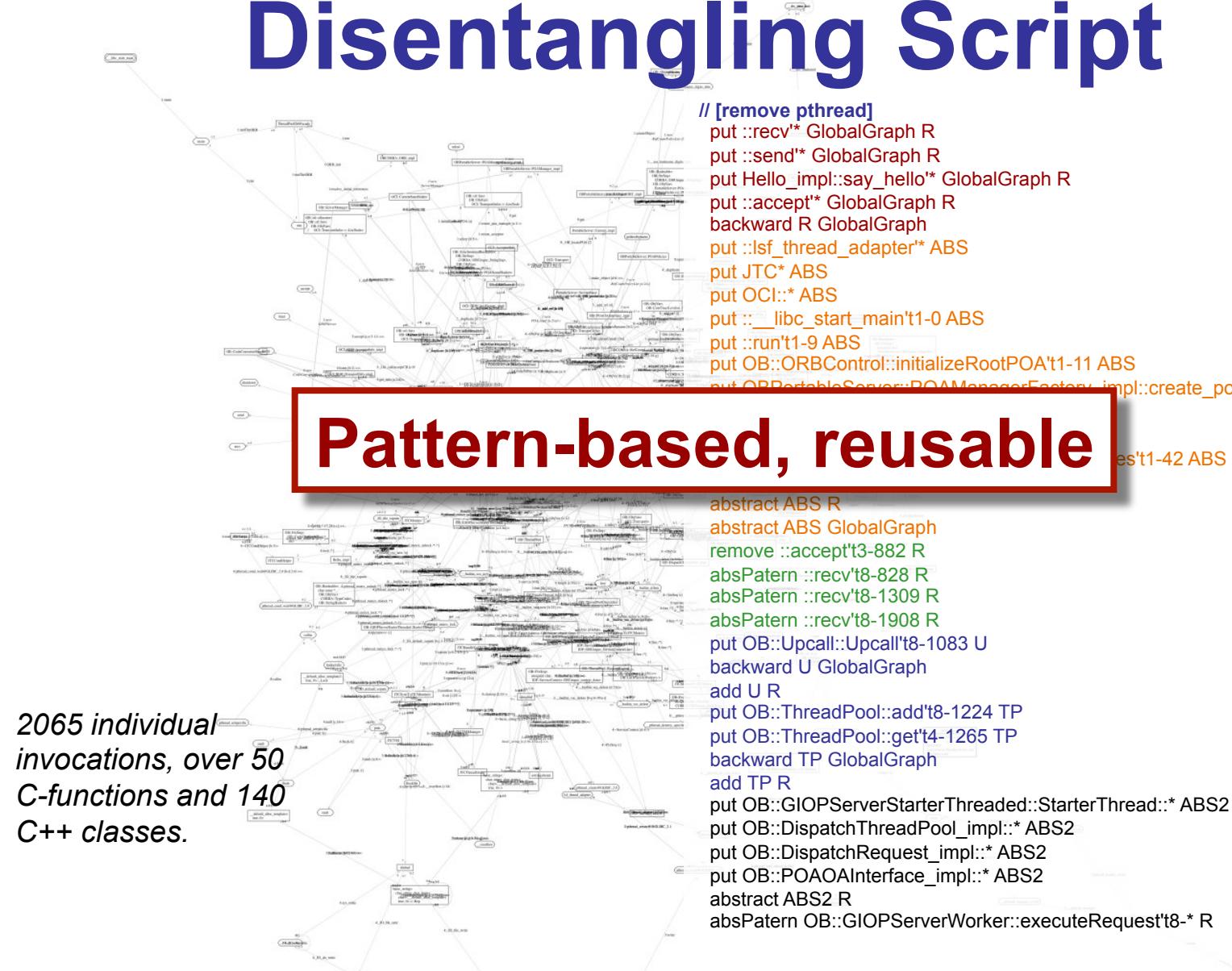


- **temporal operations**

```
fuse ::pthread_create* ::pthread_start_thread* G
```



Disentangling Script

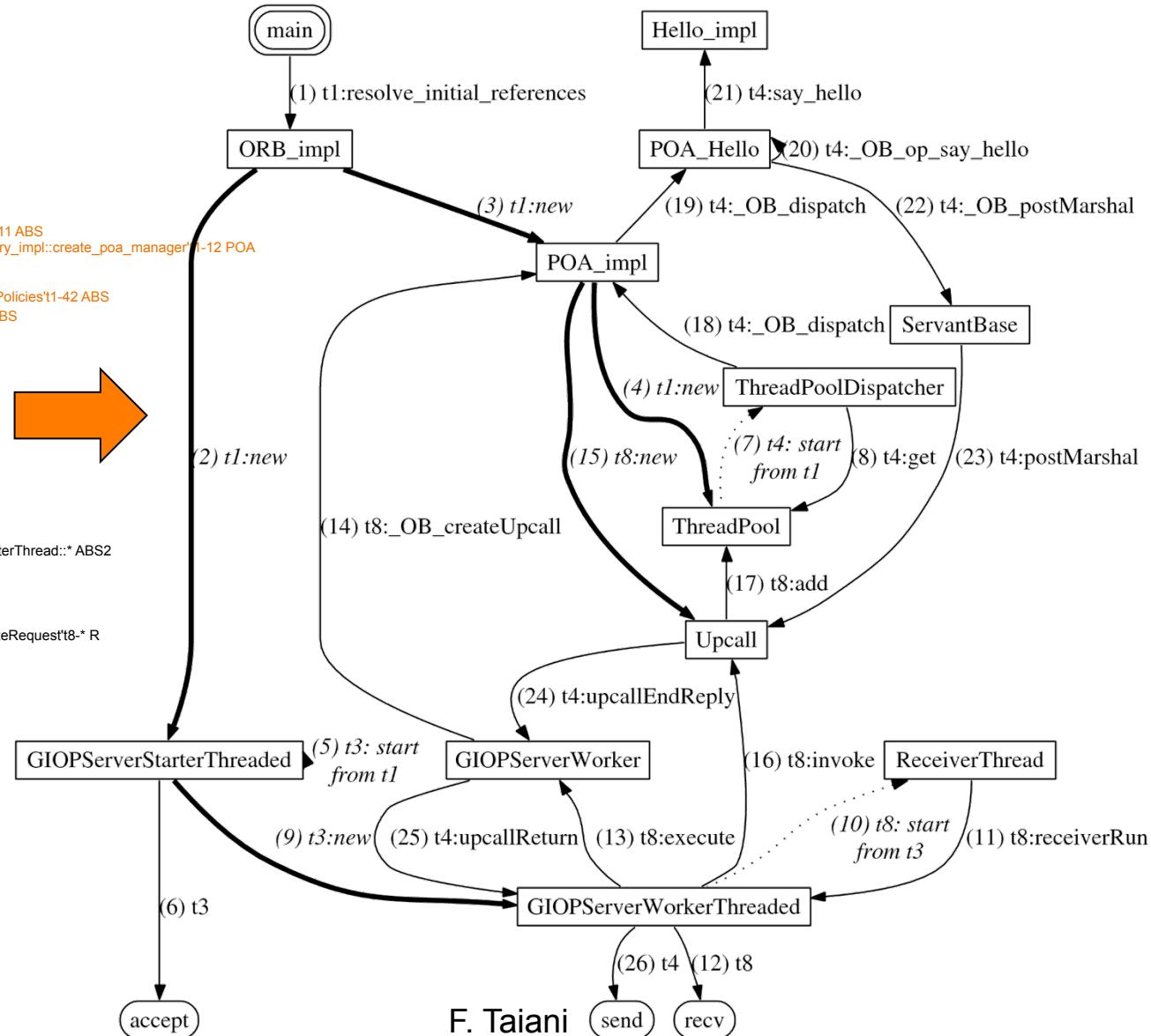


Result

```

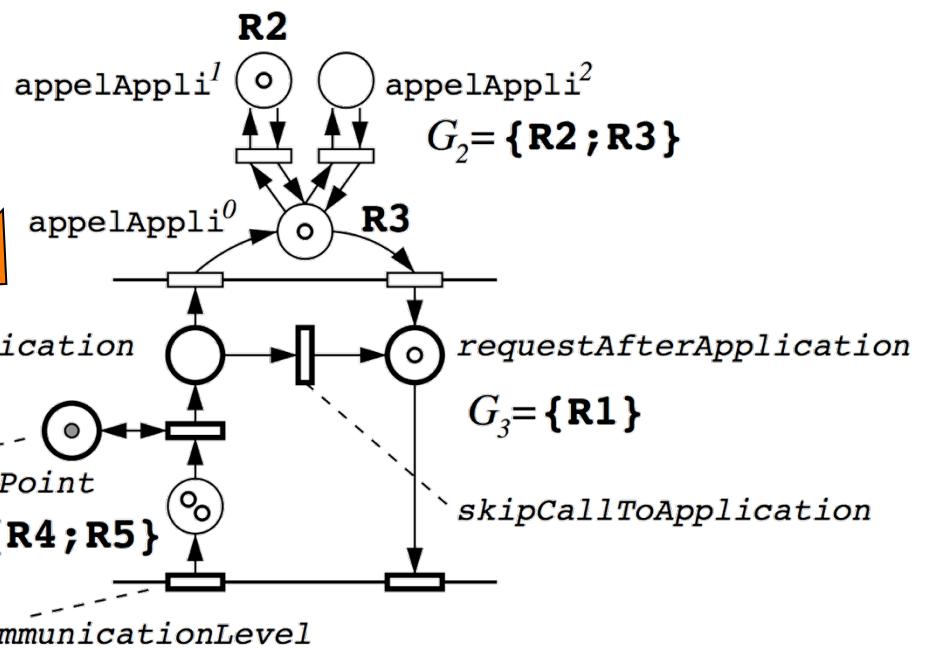
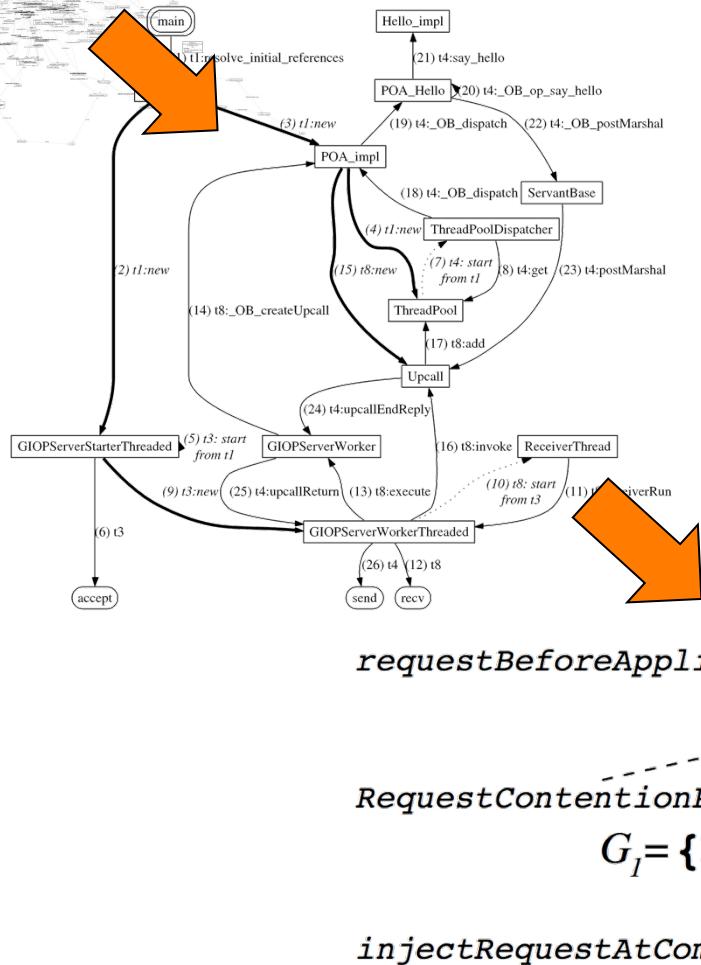
// [remove pthread]
put ::recv* GlobalGraph R
put ::send* GlobalGraph R
put Hello_Impl::say_hello* GlobalGraph R
put ::accept* GlobalGraph R
backward R GlobalGraph
put ::lf_thread_adapter* ABS
put JTC* ABS
put OCI::* ABS
put ::_libc_start_main't1-0 ABS
put ::run't1-9 ABS
put OB::OBControl::initializeRootPOA't1-11 ABS
put OBPortableServer::POAManagerFactory_Impl::create_poa_manager't1-12 POA
forwn 3 POA R
add POA ABS
put OBPortableServer::POAPolicies::POAPolicies't1-42 ABS
put OB::DispatchStrategyFactory_Impl::* ABS
abstract ABS R
abstract ABS GlobalGraph
remove ::accept't3-882 R
absPatern ::recv't8-828 R
absPatern ::recv't8-1309 R
absPatern ::recv't8-1908 R
put OB::Upcall::Upcall't8-1083 U
backward U GlobalGraph
add U R
put OB::ThreadPool::add't8-1224 TP
put OB::ThreadPool::get't4-1265 TP
backward TP GlobalGraph
add TP R
put OB::GIOPServerStarterThreaded::StarterThread::* ABS2
put OB::DispatchThreadPool_Impl::* ABS2
put OB::DispatchRequest_Impl::* ABS2
put OB::POAOAInterface_Impl::* ABS2
abstract ABS2 R
absPatern OB::GIOPServerWorker::executeRequest't8-* R

```



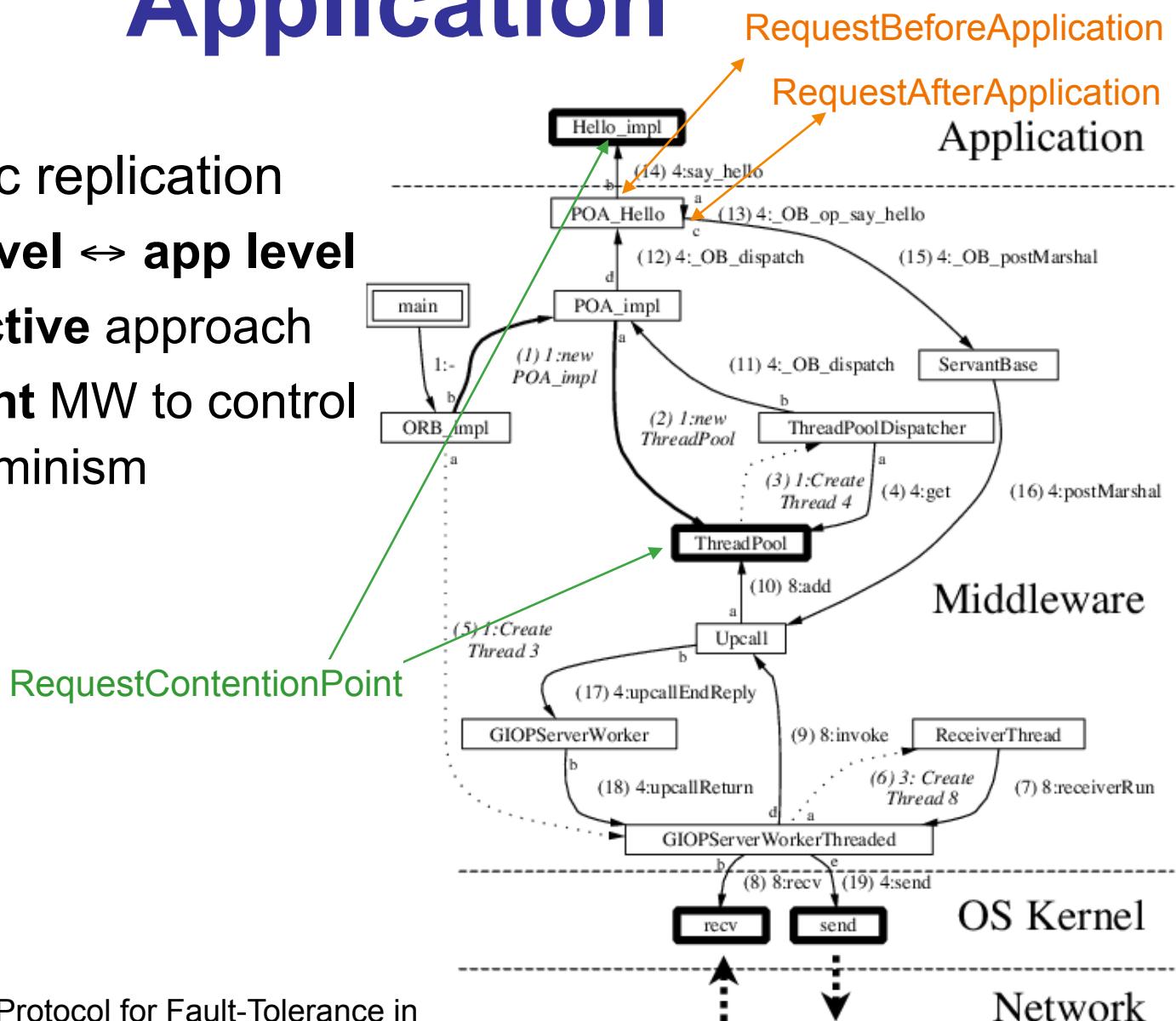
Use

- Modelling
- Analysis



Application

- Deterministic replication
 - link **OS level** ↔ **app level**
 - use **reflective** approach
 - instrument MW to control non-determinism



Outline

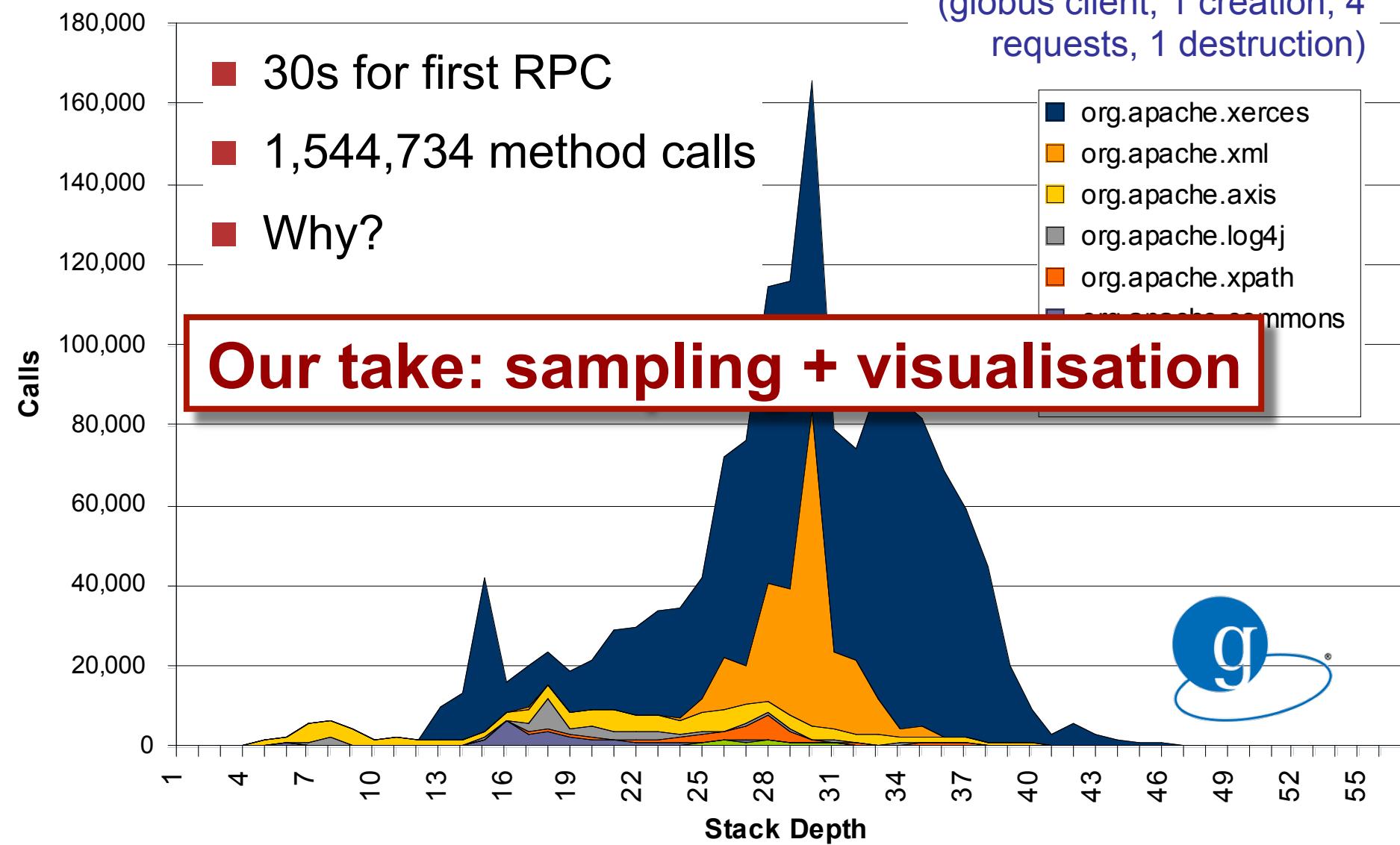


- Example 1:
 - Analysing locking behaviour in industrial ORB
- Example 2:
 - Visualizing performance anomalies in Grid MW
- Some concluding words

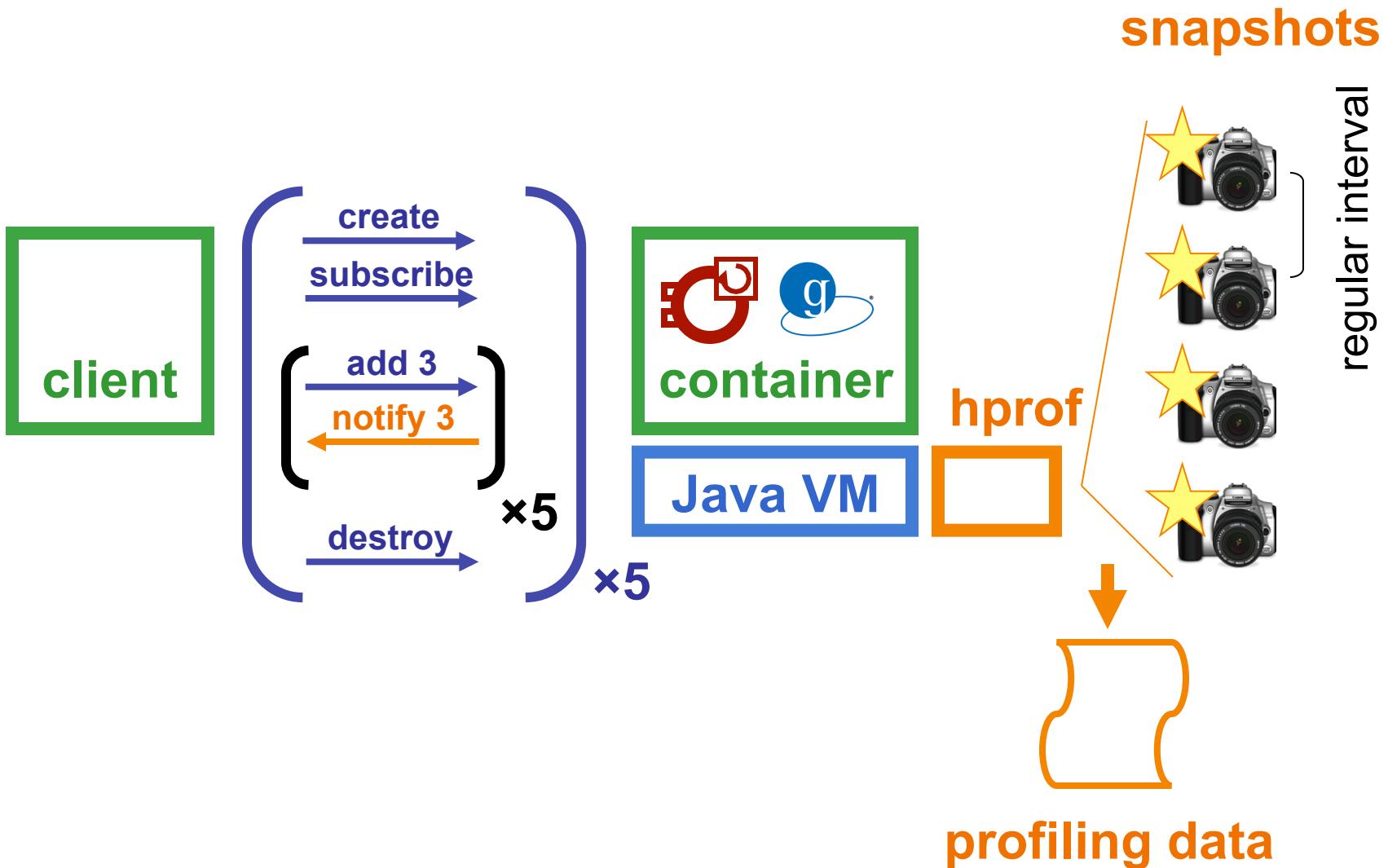


Example 2 : Profiling

(globus client, 1 creation, 4 requests, 1 destruction)



Sample-based profiling



Sample-based profiling

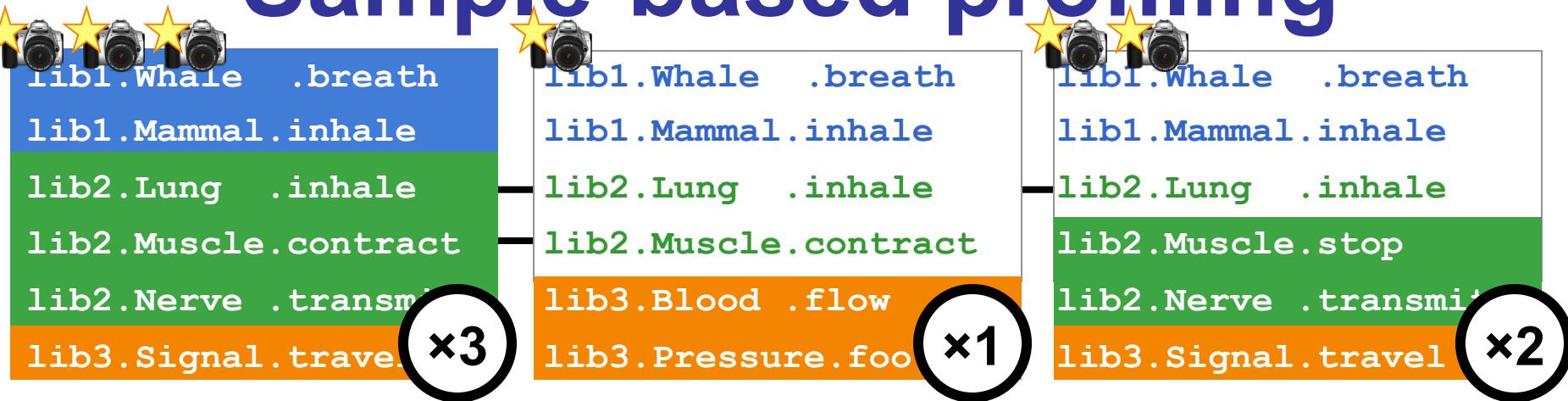
```
lib1.Whale .breath  
lib1.Mammal.inhale  
  
lib2.Lung .inhale  
lib2.Muscle.contract  
lib2.Nerve .transmit  
  
lib3.Signal.travel
```

```
lib3.Blood .flow  
lib3.Pressure.foo
```

```
lib2.Muscle.stop  
lib2.Nerve .transmit  
lib3.Signal.travel
```



Sample-based profiling



Sampling yields a set of weighted stack traces (weight reflects time spent)

- Problem: **Data explosion remains.** On Globus :
 - ➔ 55550 method invocations
 - ➔ 1861 methods
 - ➔ 724 classes
 - ➔ 182 Java packages.
 - ➔ 32 threads

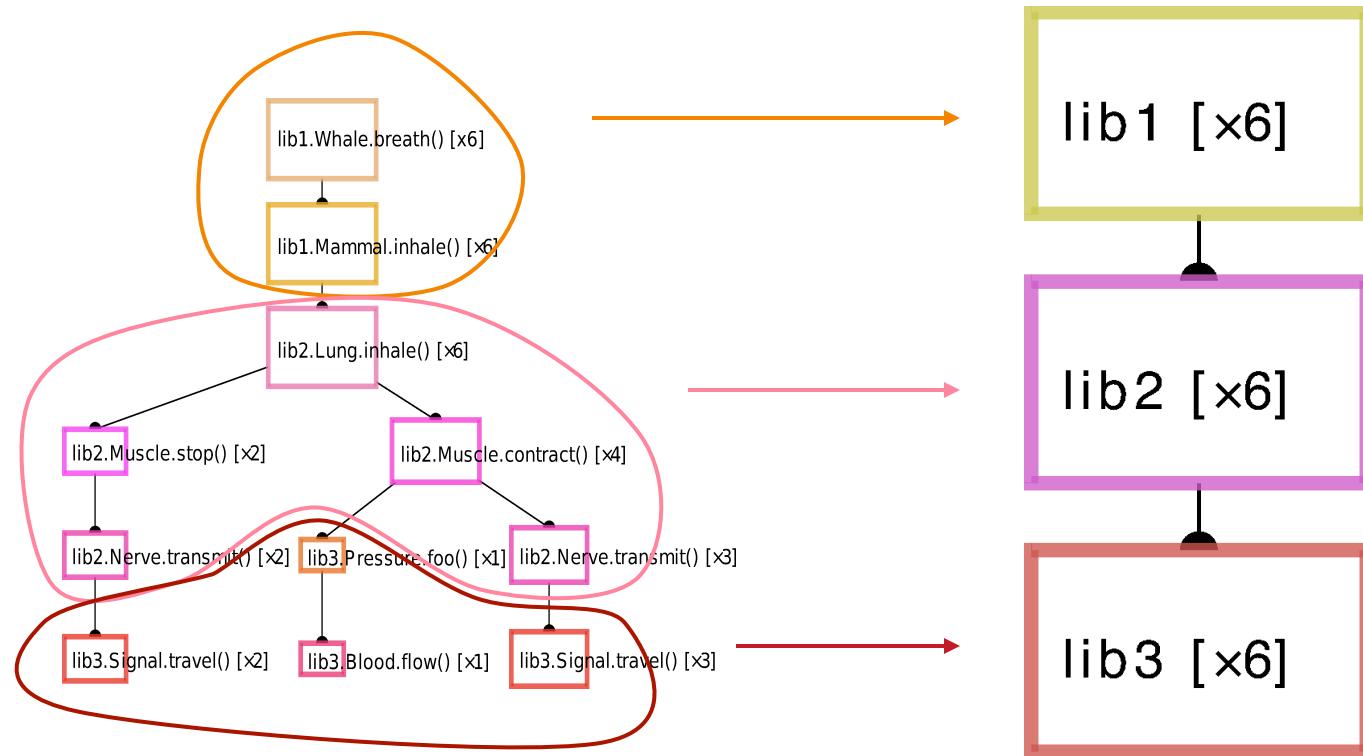


Visualising Dynamic Data

- Strategies: extract **salient features**
 - ➔ collapse recurring patterns (e.g. Jinsight)
 - ➔ remove and focus (e.g. CosmOpen)
 - ➔ data-mining (e.g. PCA in Xu et. al, SOSP'09)
- Our strategy
 - ➔ use **structural information** in dynamic data
 - e.g. `org.apache.axis.utils.ClassUtils.forName()`
 - ➔ vary '**local abstraction**' level at which data is shown
- Contributions
 - ➔ application of structural compaction to **dynamic data**
 - ➔ algorithm for **localised structural compaction**
 - ➔ prototype and **explorative user study**

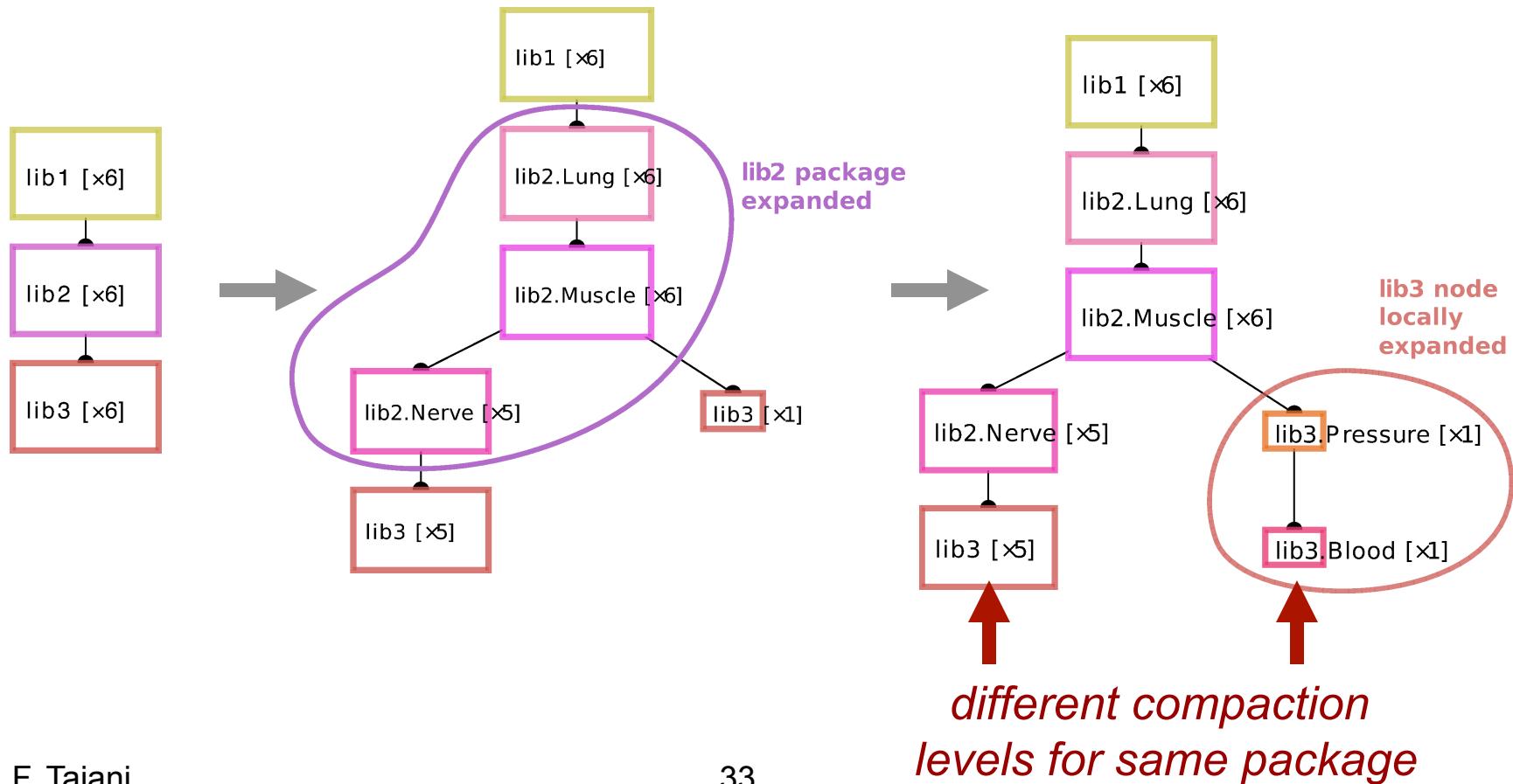
Compaction

- Only highest level packages visible

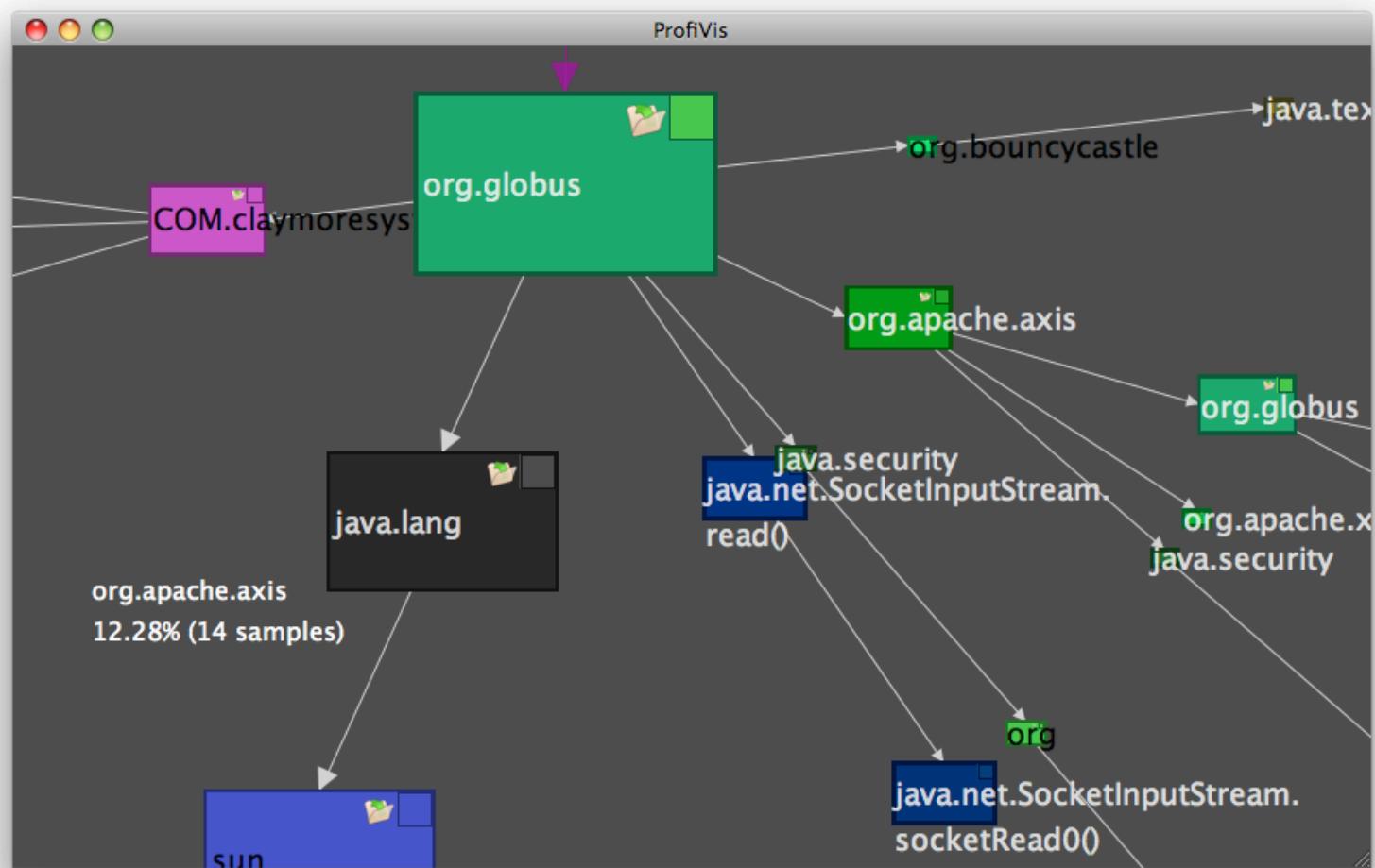


Progressive exploration

- Different levels of compaction in different parts of graph
→ including for the same package (here lib3)



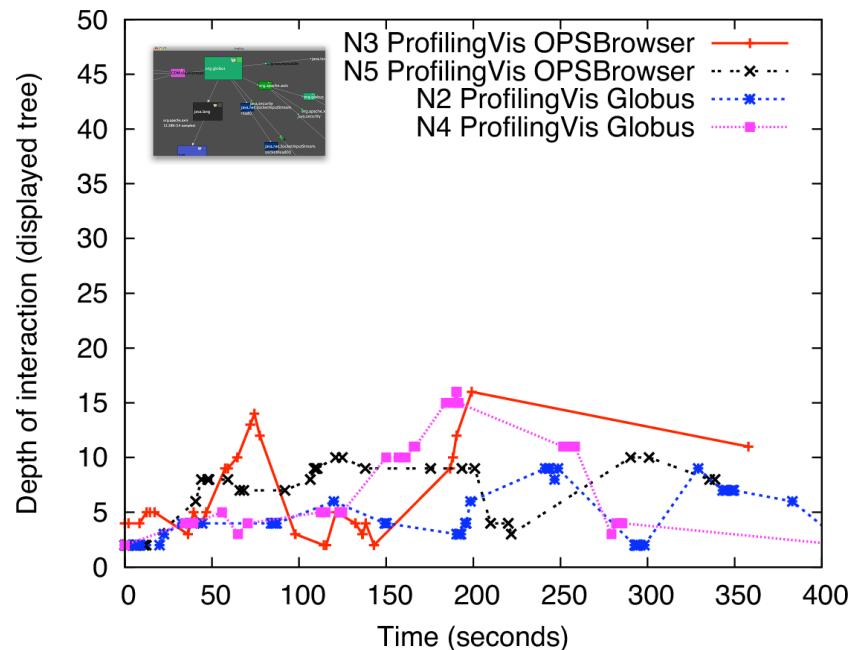
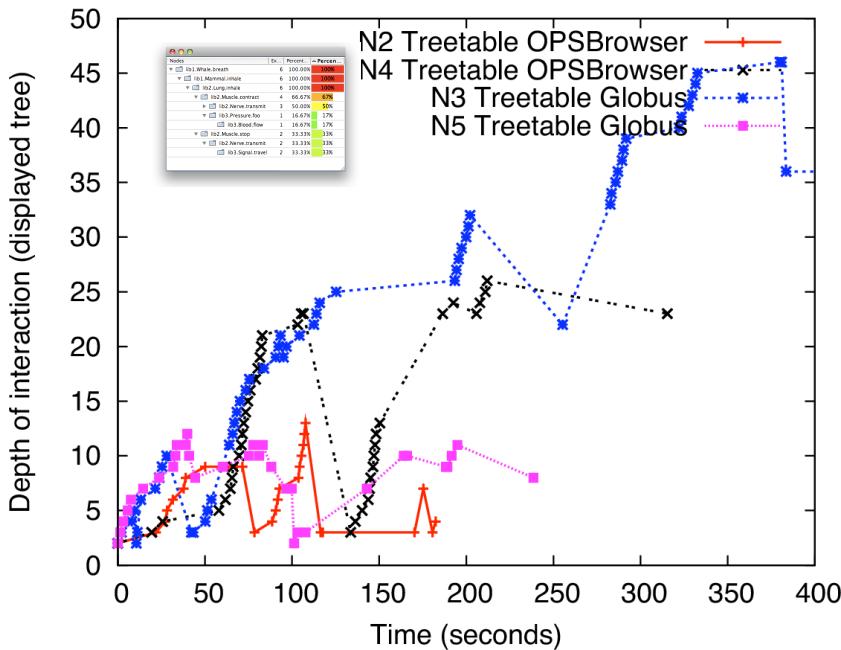
Demo



Towards anomaly comprehension: Using structural compression to navigate profiling call-trees S. Lin, F. Taiani, T. C. Ormerod, L. J. Ball, ACM SoftVis'2010
<http://ftaiani.ouvaton.org/7-software/profvis.html>

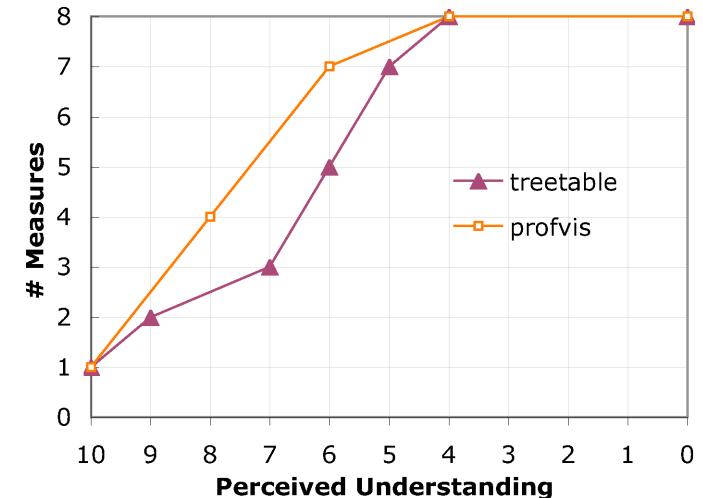
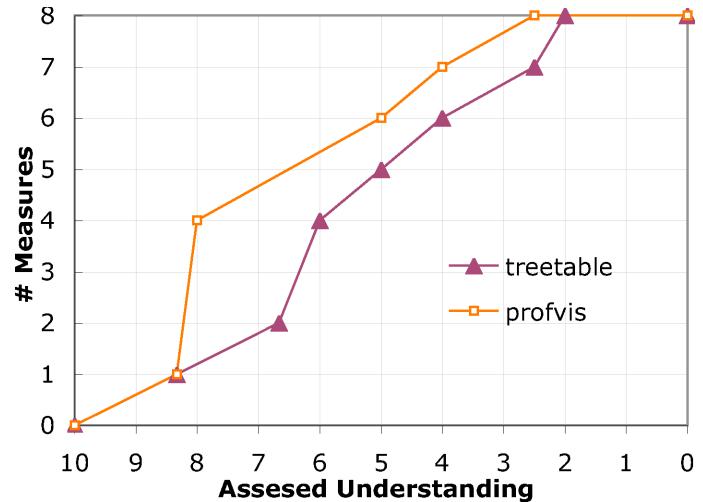
Evaluation: User Study

- Visual presentation high impact on exploration pattern
 - users go deep w/ TreeTable, tend to hover w/ ProfVis



Evaluation: User Study

- Understanding
 - ➔ slight advantage for Provis
- But
 - ➔ very small study!
 - ➔ informally, users preferred TreeTable
- Questions raised
 - ➔ acceptability
 - ➔ ergonomics
 - ➔ design combination



Conclusion

■ **Distributed Systems**

- ➔ Increased reused → layered systems
- ➔ Frankenstein effect : abstraction leaks

■ **Pragmatic approaches to dynamic reverse engineering**

- ➔ addresses complex layered software
- ➔ aim: help user construct mental models of system

■ **Future questions**

- ➔ To which extent can this be automated (slicing? SA?)
- ➔ Useful for verification?

Thank you

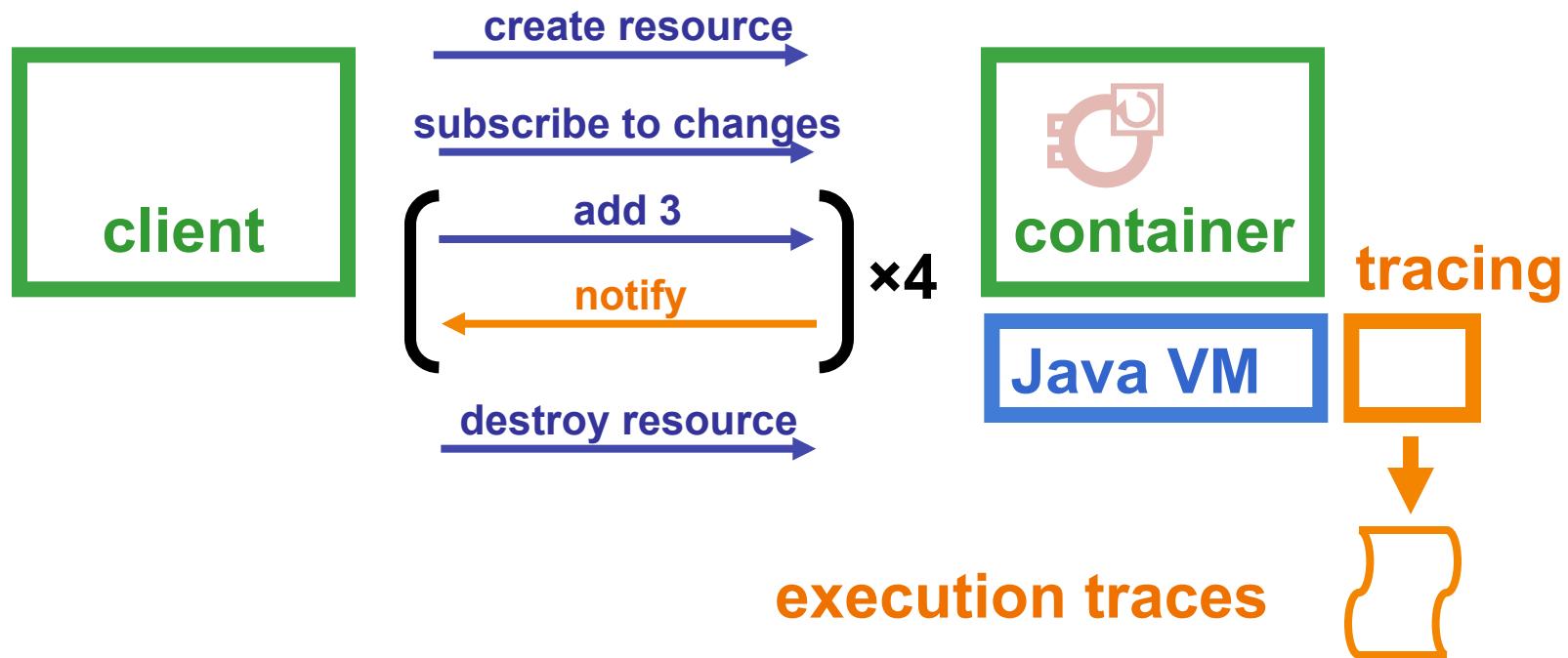
(Some) references

- Taïani F, Killijian MO, Fabre JC, CosmOpen: Dynamic reverse-engineering on a budget (journal version), Software: Practice and Experience, Wiley, 39(18): (Dec. 2009) pp. 1467-1514 (48p.)
- Taïani F, Hiltunen M, Schlichting R, The Impact of Web Service Integration on Grid Performance, The 14th IEEE Int. Symp. on High Performance Dist. Comp. (HPDC-14), 2005, pp.14-23 (10 p.)
- Chen YFR, Gansner ER, and Koutsofios E. A C++ data model supporting reachability analysis and dead code detection. SIGSOFT Softw. Eng. Notes 1997; 22(6):414-431
- Jerding DF, Stasko JT, and Ball T. Visualizing interactions in program executions. Proc. of the 19th Int. Conf. on Software Engineering (ICSE'97), ACM Press, 1997; 360-370
- Walker RJ, Murphy GC, Freeman-Benson B, Wright D, Swanson D, Isaak J. Visualizing Dynamic Software System Information through High-Level Models. OOPSLA'98, ACM Press, 1998; 271-283

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- Wolf F, Mohr B, Dongarra J, Moore S: Efficient Pattern Search in Large Traces through Successive Refinement. Proc. of the 2004 European Conf. on Parallel Computing (Euro-Par), Lecture Notes in Computer Science, Springer, 2004; 3149:47-54.
- Arnold DC, Ahn DH, de Supinski BR, Lee GL, Miller BP, Schulz M. Stack Trace Analysis for Large Scale Debugging. Proc. of the IEEE Int. Parallel & Distributed Processing Symposium (IPDPS 2007), Long Beach, CA, 2007. DOI: 10.1109/IPDPS.2007.370254

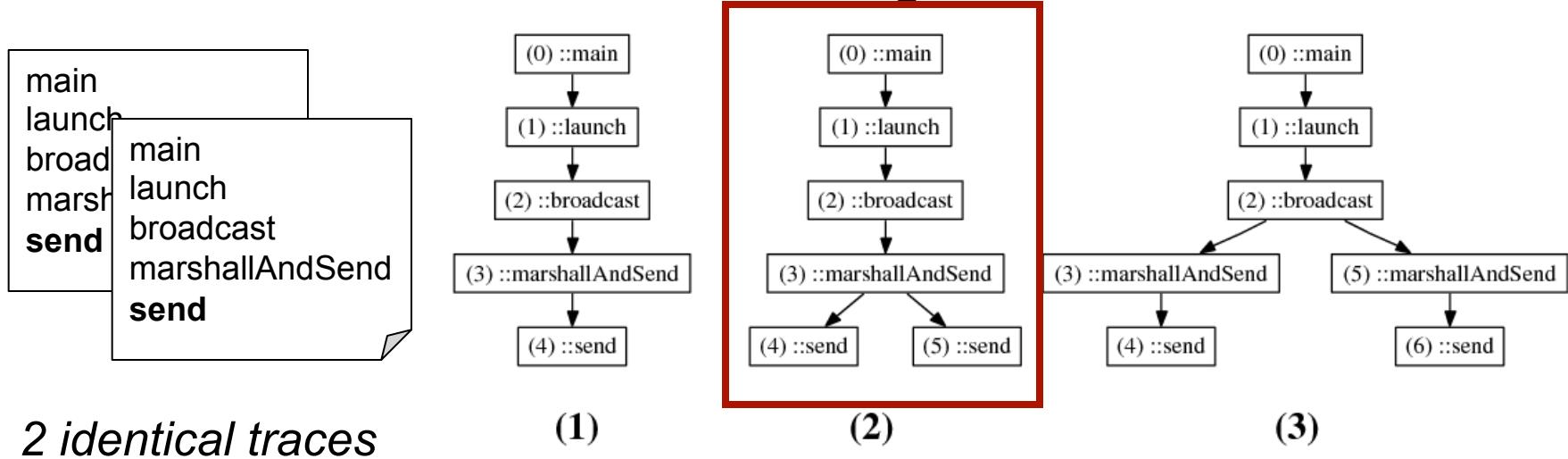
Methodology I + First Results



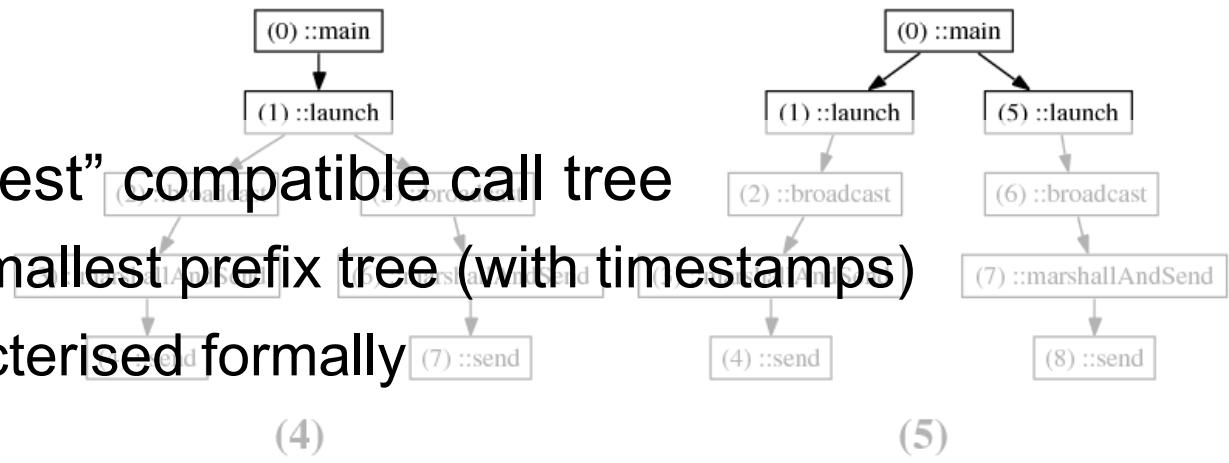
- First attempt: tracing everything (outside the JVM libs)
 - ➔ client : **1,544,734** local method call (sic)
 - ➔ server : **6,466,652** local method calls (sic) [+time out]
- **How to visualize such results?**

Reconstructing a call tree

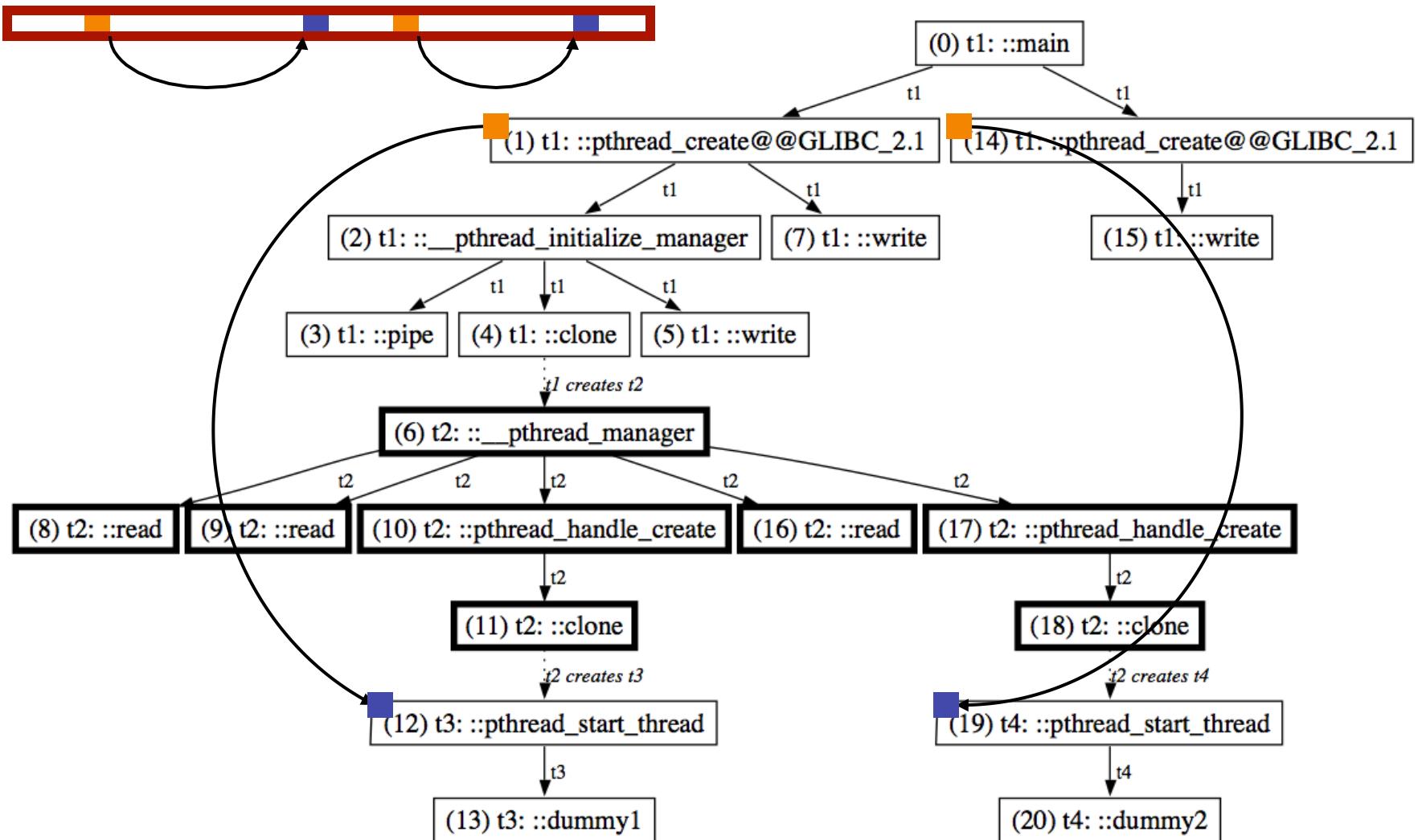
- Problem: stack traces are **ambiguous**



- Choice: “smallest” compatible call tree
a variant of smallest prefix tree (with timestamps)
can be characterised formally



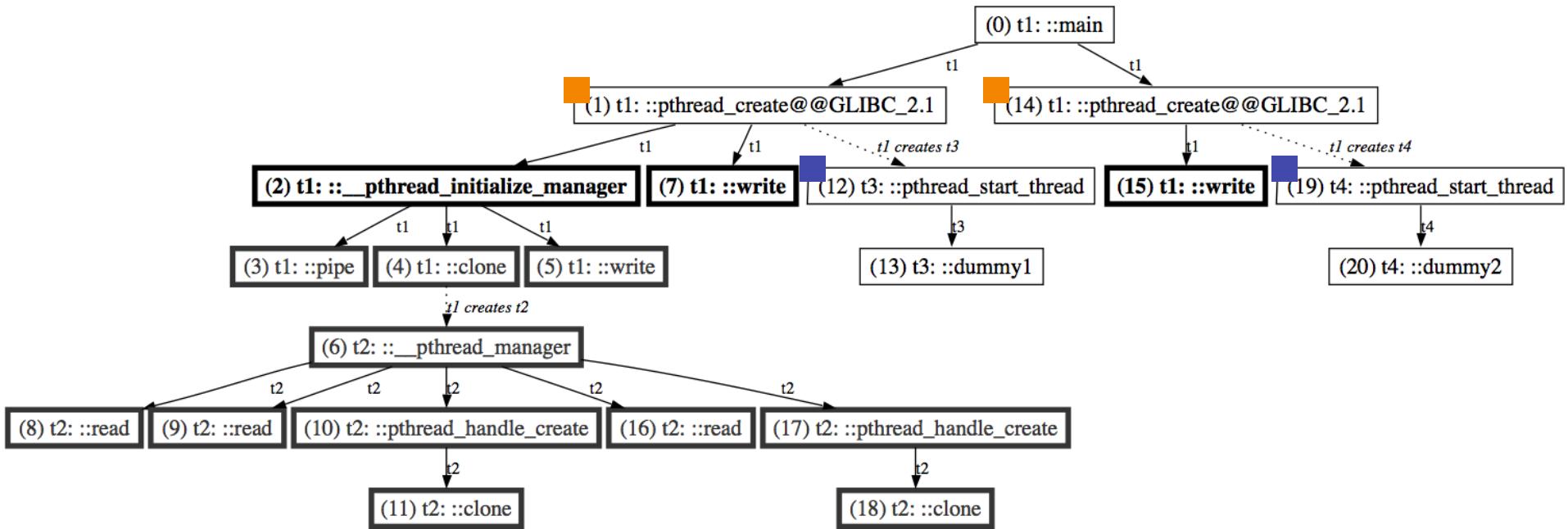
Revisiting pthread



fuse ::pthread_create* ::pthread_start_thread* G 31

Revisiting pthread

- ‘Reconstructing’ data-flow from temporal succession

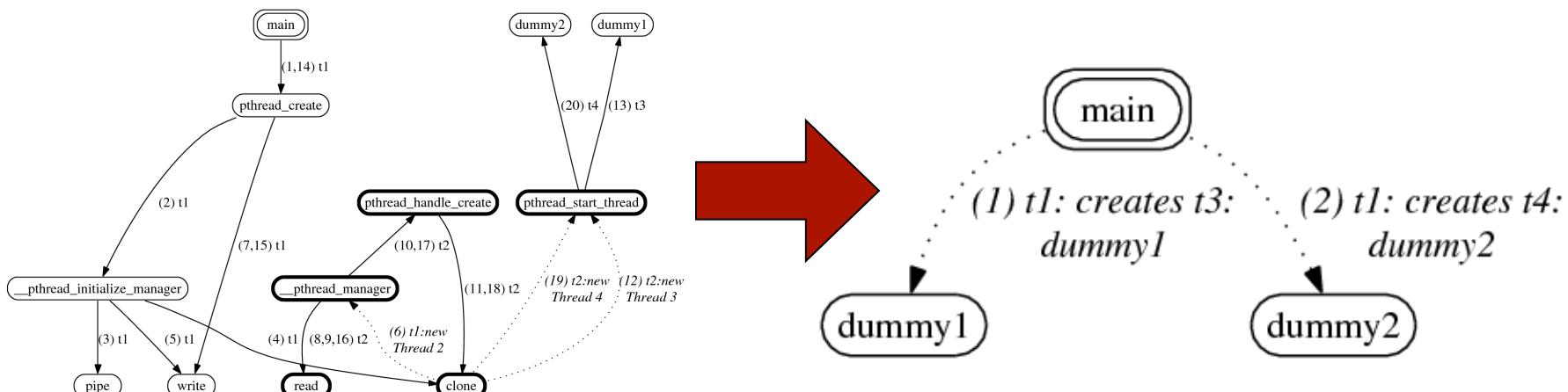


Revisiting pthread

```
fuse      ::pthread_create* ::pthread_start_thread* G
put      ::pthread_create* G CREATE
forwN    1 CREATE G
```

Generic script: applies to any pthread code

```
exclude CREATE G  
absPatern ::pthread_create* G  
absPatern ::pthread_start_thread* G
```



Case study

- 3 C/C++ industry-grade CORBA products
 - ➔ ORBacus, omniORB, TAO
- Set up
 - ➔ ~ 60 breakpoints (locks, memory, threading, callbacks)
 - ➔ one ping-pong request
 - ➔ 1GHz Pentium III, Linux kernel 2.4, gdb 5.1-1
- Observation **overheads** (Orbacus)
 - ➔ non-instrumented: < 1s
 - ➔ fully instrumented: 1h 2m 11s
 - ➔ lock tracing disabled during initialisation: 4m 53s

Stack capture speedup

```
#0 0x405c8f20 in send () from /lib/libpthread.so.0
#1 0x4015804a in omni::tcpConnection::Send ()
#2 0x4011364c in omni::giopStream::sendChunk ()
[...]
#8 0x400bdb0a in omniAsyncWorker::run ()
#9 0x405abbdf in omni_thread_wrapper ()
#10 0x405c2bf0 in pthread_start_thread ()
#11 0x405c2c6f in pthread_start_thread_event ()
```

ORB	threads	traces	frames	invocations	invocations/traces
ORBACUS 4.1	8	658	9178	2066	3.13
OMNIORB 4	7	1828	16807	3088	1.68
TAO 1.2.1	6	512	11260	1352	2.64

breakpoint
activation
= cost

reconstructed tree
= added value

ratio
= speedup

(with lock tracing disabled during initialisation)