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Abstract—The validation of formal models is a challenge for formal methods. We propose JeB, a framework which generates and executes simulations of Event-B models, even highly non-deterministic ones. JeB allows users to safely insert pieces of code to supply deterministic computations where the automatic translation fails. We present how JeB translates Event-B model into JavaScript. We define *Fidelity* as the formal notion which captures the idea of the correctness of a simulation. We define it through proof-obligations.

Keywords-Formal methods, Event-B, Validation, Simulation, JavaScript, Proof-Obligations

I. INTRODUCTION

Formal methods promise the production of software which are *correct,* i.e., proven to meet their specification. Hence, getting the *right* formal specification is crucial.

The validation of formal models through execution is an old issue [1], [2], [3]. Actually, the main difficulty revolves around the level of determinism: good practice advocates the slow refinement of highly abstract and non-deterministic specifications [4] while execution tools require deterministic or quasi-deterministic models.

Event-B [5] is a modeling language of the B family [11] based on refinement; it is supported by the Rodin environment [6]. Event-B has a dynamic semantics which is implemented by the available compilers [7], [8] and animators [9], [10]. However, while the semantics accounts well for non-determinism, the current tools often fail on early models in developments. Hence, those cannot be validated.

JeB, a JavaScript framework for executing Event-B specifications, answers this issue. JeB consists of a translator which compiles the Event-B model into JavaScript code and generates enough "hooks" for developers to provide their own hand-coded resolution of non-determinism. Obviously, hand-coded functions could be "incorrect." *Fidelity* formally expresses this notion of correctness. It is defined so we can derive proof obligations.

JavaScript looks an unlikely choice in a formal context, yet it has technical features which fit well with our purpose. Furthermore, the browsers running JavaScript allow to set up easily graphical displays.

We first present Event-B. Then, we discuss JeB's design and the translator's implementation. Last, we show the formal definition of *fidelity* and the associated proof obligations.

II. EVENT-B

A. Notations

A specification in Event-B consists of a state and events. The state maps names to values; it is constrained by an invariant. For practical purposes, models are split into *Contexts* and *Machines.* The values are built inductively from integers, booleans and symbols by using power sets and cartesian products. Special cases such as binary relations, partial functions, or injections enjoy specific notations. The typing system is equivalent to set membership and inclusion. The invariant is a first-order formula on the state. It is a conjunction of smaller formulas called *axioms* in contexts and *invariants* in machines.

Events model the evolution of the state. Formally, they are guarded substitutions. Guards are first-order formulas on the state; they may contain free variables called *event parameters.* Substitutions change some values, all at the same time. An event is *enabled* when its guard is true, it can then be fired.

The formal semantics of an Event-B model is based on the *feasibility* (*fis*) property expressing two ideas:

- a legal state with actual values must exist, and
- firing enabled events leads from legal states to legal states.

The specification language is designed so that *fis* can be cast as a set of small logical formulas, called *proof-obligations.* A model is correct when all its POs have been discharged.

Figure 1 shows the first model of a platooning system. Vehicles are required to maintain a minimum distance *dmin* between themselves. At this level, the distance function *dist*, the representation of the geometric surface *Plane* and the movement of the platoon *move* are abstractions.

B. Refinement

Event-B embodies two ideas about programs: they are elaborated by stepwise refinements, and they can be *correct by construction.* In this context, *correct* means "mathematically proven to meet their specification."

A model M_r is a *refinement* of a model M_a, if:

- M_r is consistent (i.e., it defines one actual state, invariants are preserved through the actions),
- there is an abstraction function from the M_r state and events to the M_a state and events,
- M_r legal states are abstracted as M_a legal states, and
- all events fired in M_r preserve the invariant of M_a.

```
CONTEXT space
SETS Plane Vehicles
CONSTANTS dist dmin
AXIOMS
  axm1: dmin ∈ ℕ₁
  axm2: dist ∈ Plane × Plane → ℕ₁
  axm3: ∀x, y.dist(x ↦ y) = dist(y ↦ x)
  axm4: ∀x.dist(x ↦ x) = 0
END
```

```
MACHINE platoon SEES space
VARIABLES pos
INVARIANTS
  inv1: pos ∈ Vehicles → Plane
  inv2: ∀v1, v2·v1 ≠ v2 ⇒ dist(pos(v1) ↦ pos(v2)) > dmin
EVENTS
  INITIALISATION ≙
  BEGIN
    act1: pos :| ∀v1, v2·v1 ≠ v2 ⇒
          dist(pos'(v1) ↦ pos'(v2)) > dmin
  END

  move ≙ STATUS ordinary
  ANY np
  WHERE
    grd1: np ∈ Vehicles → Plane
    grd2: ∀v1, v2·v1 ≠ v2 ⇒ dist(np(v1) ↦ np(v2)) > dmin
  THEN
    act1: pos := np
  END
END
```

Figure 1.   Initial model of a platooning system

These properties generate POs. Discharging all POs of all refinements in a chain guarantees that the most concrete model preserves the invariant of the most abstract model.

Refinement is embedded in the framework at two levels. The language contains a syntax to express the refinement relationship (refines or extends) and the abstraction function (with clause). The support tools generates the POs.

In Event-B, refinements add information into a model. Users can see a refinement as one of four kinds:

- adding new invariants; this reinforces the properties of interest and the constraint on the domain,
- adding new variables and constants unconnected to previous ones; this introduces new concepts and properties,
- adding new variables and constants to implement previous ones; this is the usual data-refinement, or
- adding new events; this splits an abstract "large" event into several concrete "smaller" events.

C. Event-B Operational Semantics

The operational semantics of Event-B is a three-step cycle:

1) compute the set of enabled events,
2) pick one enabled event and values for its parameters,
3) apply the substitution on the state.

The INITIALISATION event starts the cycle which ends when no event is enabled. Depending on the modeled system, stopping can be a desired feature (termination) or not (deadlock).

Non-determinism is present at three levels: free variables can take any value which makes the guards true, substituted values can be described non-constructively by a property ("any value such that"), and any enabled event can be fired. As a practical consequence, execution tools must deal with non-determinism and the associated combinatorial explosion.

III. JEB DESIGN

A. Motivations

The claim that a proven Event-B model is therefore correct in the broad sense is too strong as the three cases below show.

A first case is the introduction of new axioms during a refinement. The new model may then become logically inconsistent, which is a non-decidable property. We must resort to test-like procedures like proving formulas such as $true = false$.

A second case concerns the limitation on provable properties. In Event-B, temporal properties are notoriously difficult to state and to prove. Therefore, some may be left unchecked.

A third case concerns the introduction of new events, that is, new behaviors. Even when requirement documents guide the specifiers, emergent behaviors may slip in then and stay unnoticed until the model is actually executed.

So, the equivalence between "proven" and "correct" can only be claimed if all properties have been expressed in the initial models. Stated another way: we must have complete requirements before developing. Unfortunately, we know that we do not for most actual projects [12].

B. Target Language

We use JavaScript/HTML as the target language because:

- JavaScript [13] is embedded and interpreted in most Web browsers. Those environments provide efficient and lightweight tools to build generic and ad-hoc GUI.
- JavaScript supports sophisticated OOP techniques which helped solve two issues: the name conflicts and the traceability between the JavaScript and the Event-B codes. The generated code is clean and easy to read.
- JavaScript uses dynamic interpretation that allows users to switch between different implementations even at run-time. We use this feature to separate user hand-coded functions from the main simulator code.
- JavaScript has first-class functions, which eased the translation of nested expressions and quantifications.

The architecture of JeB reflects our philosophy that a simulation is the result of a cooperation between tools and humans. The former provides the efficiency and safety of automation, the latter provide the insights to overcome non-determinism. Humans are involved at three levels:

- specifiers provide hand-coded functions for some uninterpreted functions,
- experts provide values for constants and event parameters in different scenarios; they set up graphic visualizations,
- users run simulations, observe and analyze behaviors to check that an Event-B model meets their expectations.

Table I
NAMESPACES USED IN THE SIMULATOR CODE (EXCERPT)

Namespace	Prefix	Description
jeb	jeb	the top namespace
jeb.axiom	$axm	axioms
jeb.event	$evt	machine events
$evt.<eventId>.arg	$arg	event parameters
$B	$B	JavaScript library for Event-B

Table II
STRUCTURAL MAPPING OF A CONTEXT

Event-B	JavaScript/HTML
CONTEXT name	(1) name.js (context model)
	(2) name.html (user interface)
EXTENDS context_names	list of context_name in the HTML page for navigation
SETS identifiers	list of $cst.identifier
CONSTANTS identifiers	list of $cst.identifier
AXIOMS predicates	list of jeb.lang.Axiom instances
END	

IV. JeB REALIZATION

Technically, a simulation consists in three parts: the generated code, a runtime library, and the hand-coded functions provided by the users.

A. Generated code

1) Namespace: Generated names must not conflict between themselves or existing names in the target environment, and should be traceable back to Event-B. With prefixes on global object properties, we can achieve the same effect as with namespaces; Table I shows some examples.

2) Translation of Contexts: Each context is translated into a file which contains the translation of the axioms as JavaScript objects. The overall structure of the file is derived from the structure of the Event-B code, as shown on Table II.

a) Sets and Constants: They are translated as standard identifiers prefixed by $cst. They are given values in the configuration files. Enumerated sets are instantiated by collecting elements already defined in the CONSTANTS clause. The JeB library supports the instantiation of a carrier set either as a collection of symbolic strings or as a class in the OOP sense.

b) Axioms: JeB translates each axiom as an instance of jeb.lang.Axiom, prefixed by $axm:

```
jeb.lang.Axiom = function( id, label ) {
    this.id = id;
    this.label = label;
    this.domNode = jeb.ui.$( id );
    this.predicate = function(){};
    ...
};
```

where id is a unique reference; label is axiom's name as written in the context; domNode links this instance to the HTML page to display its evaluation; predicate is a method to evaluate the axiom.

3) Translation of Machines: The translation of a machine generates three files: an executable version of the model, a configuration file (both JavaScript), and a simulation GUI (HTML). The configuration file contains stubs and default implementation of non-deterministic features.

a) Variables: Each variable is translated as an instance of jeb.lang.Variable, prefixed by $var:

```
jeb.lang.Variable = function( id ) {
    this.id = id;
    this.value = undefined;
    this._value = undefined;
    this.domNode = jeb.ui.$( id );
    ...
};
jeb.lang.Variable.prototype.updateView = function() {
    this.domNode.innerHTML = this.value;
};
```

where id is a unique reference; value is the current value; _value is the primed value; domNode binds to an element in the HTML page which displays its value; updateView is the method used for updating the user interface. The variable value can be any Event-B mathematical object. It is checked by computing the invariant after each simulation cycle.

b) Invariants: They are translated like axioms, using jeb.lang.Invariant instead of jeb.lang.Axiom.

c) Events: JeB generates an independent simulation for each refinement, so the refinement links (refines and with) are ignored. The guards and actions are translated as two different functions. Events' parameters require a special treatment described thereafter. Each event is translated as an instance of jeb.lang.Event:

```
jeb.lang.Event = function( id, label ) {
    this.id = id;
    this.label = label;
    this.domNode = jeb.ui.$( id );
    this.enabled = true;
    this.parameter = {};
    this.guard = {};
    this.action = {};
    this.bindArguments = function(){};
    ...
};
jeb.Event.prototype.evaluateGuards = function(){...};
jeb.Event.prototype.testGuards = function(){...};
jeb.Event.prototype.updateParametersView = function(){
    ...};
jeb.Event.prototype.doActions = function(){...};
```

where id, label, and domNode have the same role as for axioms. The property enabled contains the result of the evaluation of the guards. The properties parameter, guard, and action are namespaces for the event's parameters, guards and actions, respectively. The four functions are helpers for implementing the simulation cycle: evaluateGuards and testGuards are used for determining parameter values, updateParametersView and doActions do what their names imply.

d) Event Parameters: The so-called "event parameters" in Event-B are the variables introduced in the ANY clause

act1: $a := b$	act1: $a :\mid a' = b$
act2: $b := a$	act2: $b :\mid b' = a$
act3: $c :\in S$	act3: $c :\mid c' \in S$
act4: $x, y :\mid x' > y \wedge y' < x' + z$	act4: $x, y :\mid x' > y \wedge y' < x' + z$

Figure 2. Assignments

of events. They are of two kinds: deterministic variables are actually local variables, their value is automatically computed by JeB; non deterministic variables are true parameters in the common programming sense.

Each true parameter *par* is associated with an argument generator function *get_par* which is bound to the input field in the HTML page. The JeB translator generates it into a configuration file as a function stub or, when possible, as a default implementation. Users should provide their own implementation for a realistic simulation in the auto-run mode of execution. Before each simulation cycle, the `bindArguments` method binds each parameters to a *get_par* function, which can then be changed "on the fly."

The order in which the parameters are declared is irrelevant in Event-B, but not in JavaScript. When necessary, the JeB translator adjusts the order of parameters in the GUI and in the `bindArguments` function so they get a value before being used.

Each identifier declared in an ANY clause is translated as an instance of `jeb.lang.Parameter`:

```
jeb.lang.Parameter = function( id, type, eventId ) {
    this.id = id;
    this.type = type;
    this.domNode = jeb.ui.$( id );
    this.domNodeInput = jeb.ui.$( id + '.input' );
    this.eventId = eventId;
    ...
};
```

where `id` is a unique reference; `type` indicates its nature (local variable or true parameter); `domNode` (resp. `domNodeInput`) binds to an element in the HTML page for display (resp. input), `eventId` references the event;

e) Event Guards: An event guard is a predicate formula. The enabled status of an event is the result of computing all its guards. Guards are translated like axioms with an added reference to the event.

f) Event Actions: Actions are assignments with two features: they occur simultaneously and they can involve non-deterministic values ("becomes such that" for instance).

The left-hand side of Figure 2 is a classical trap. The idea is to use only :| assignments and "primed values" as shown on the right-hand side. The order of execution becomes then irrelevant. Technically, the assignments are realized on the variables' property `_value` and copied to the `value` property after all assignments have been made.

The non-deterministic assignments generate stubs in the configuration file which call default implementation in the runtime library. Users may override them to provide their own, deterministic, implementation.

Each action is coded as an instance of

```
jeb.lang.Action = function(id, label, eventId ) {
    this.id = id;
    this.label = label;
    this.eventId = eventId;
    this.assignment = function(){};
    ...
};
```

where `assignment` is the method to realize the assignment.

4) Translation of Formulas: Each operator is coded as a call to the runtime library. The API of the library is a one-to-one mapping of the Event-B mathematical notation. So, the translation algorithm is based on Event-B syntax and independent of the target language. Proving the correctness of the translation resolves into proving the library functions. Table III shows some translation rules.

B. Runtime Library

1) Simulation Scheduler: The operational semantics is implemented as follows:

```
(1) setup contexts, prompt user if needed
(2) trigger the INITIALISATION event
(3) do
   (1) save the state of variables
   (2) update the variable view
   (3) compute the invariants, stop if one is false
   (4) build the set of enabled events, stop if empty
   (5) pick an enabled event to trigger
   (6) save the state of arguments
   (7) execute the actions of the selected event
```

The step (3.3) is useless when executing a fully proven model, but it is a useful feature for the preliminary exploration of complex refinements. Step (3.4) is a computation of all the guards of the events based on the state values and the values chosen for the parameters, either through user's input in the GUI or computation of the *get_par* functions.

2) JavaScript Library for Event-B: The computation core of the expressions is delegated to a library which implements set theory and first order logic. Its realization aims at two goals: a clear interface and efficient computations.

Technically, the APIs are modeled on the mathematical language of Event-B. The translation from Event-B to JavaScript is mostly syntactic. The APIs contain about 90 profiles.

The representation of numbers is an important issue. In Event-B, integers are unbounded; contrary to JavaScript primitive numbers. Discretization of computations, tiny units or large multiplicative constants are standard modeling tricks to model $\mathbb{R}$ or functions such as `sin`. They induce very large numbers. The library implements arbitrary large integers.

3) Graphical User Interface: The simulation interface is implemented as an HTML page [14]. JeB provides a generic page with the code needed to control it.

C. Hand-Coded Add-Ons

An important feature of JeB is to allow users to provide safely pieces of code to improve the simulation.

Table III
FORMULA TRANSLATION RULES (EXCERPTS) (^{TR} AND ^{TR*} DENOTES RECURSIVE CHILD TREE TRAVERSAL)

Event-B Notation	Event-B Syntax	Translation
	Predicates	
True predicate	$\top$	$\$B.bTrue()$
Implication	$P \Rightarrow Q$	$\$B.implication(P^{TR}, Q^{TR})$
Universal	$\forall x_1, \ldots, x_n \cdot P\ (n \geq 1)$	$\$B.forAll(P^{TR*}, [x_1^{TR*}, \ldots, x_n^{TR*}])$
Set membership	$E \in S$	$\$B.belong(E^{TR}, S^{TR})$
	identifiers / Atomic values / Expressions	
Free identifier	χ	1) $\$cst.\chi$ if χ is a constant
		2) $\$var.\chi.value$ if χ is a variable
		3) $\$arg.\chi.value$ if χ is a parameter
Boolean TRUE	TRUE	$\$B.TRUE$
Bool expression	$bool(P)$	$\$B.bool(P^{TR})$
Integer literal	α	$\$B('\alpha')$
Bool expression	$bool(P)$	$\$B.bool(P^{TR})$
Subtraction	$m - n$	$\$B.minus(m^{TR}, n^{TR})$
	Sets / Relations	
Empty set	$\varnothing$	$\$B.EmptySet$
Interval	$m .. n$	$\$B.UpTo(m^{TR}, n^{TR})$
Natural numbers	$\mathbb{N}$	$\$B.NATURAL$
Set extension	$\{E_1, \ldots, E_n\}\ (n \geq 1)$	$\$B.SetExtension(E_1^{TR}, \ldots, E_n^{TR})$
Ordered pair	$E \mapsto F$	$\$B.Pair(E^{TR}, F^{TR})$
Relations	$S \leftrightarrow T$	$\$B.Relations(S^{TR}, T^{TR})$
Partial functions	$S \nrightarrow T$	$\$B.PartialFunctions(S^{TR}, T^{TR})$
Function image	$f(E)$	$\$B.functionImage(f^{TR}, E^{TR})$
	Assignments	
Becomes such that	$x_1, \ldots, x_n : \mid Q(x_1', \ldots, x_n')\ (n \geq 1)$	$\$B.becomesSuchThat([x_1^{TR}, \ldots, x_n^{TR}], Q^{TR*}, [x_1'^{TR*}, \ldots, x_n'^{TR*}])$

1) Graphical Display: The generic GUI contains two stubs:

- `jeb.animator.init` to initialize the display area,
- `jeb.animator.draw` to draw the system's state.

The second function is called at each cycle, the first one is called only once during initialization.

2) Parameters of Events: They are the main controls when running a simulation. The value of each "true parameter" is obtained by getting the content of the input fields in the GUI. Those fields can contain either a literal value or a function call. In the latter case, the execution mechanism looks for an implementation in the configuration files. Users can switch between values and functions at any time during a simulation.

V. CORRECTNESS OF SIMULATION

The notion of correctness is captured by the idea of *fidelity*.

A. Definition of Fidelity

The execution of an Event-B model M is formalized as a *trace* [15]. Intuitively, a trace is a succession of instances of firings of events[1], starting with the E^0 (INITIALISATION), which goes through a succession of legal states. Formally, $E^0 e_1 e_2 \ldots e_n$ is a trace iff

$$\forall j . j \in 1..n \Rightarrow e_j \in Evts(M)$$

and

$$\text{fis}(E^0; e_1; e_2; \ldots e_n) \Leftrightarrow true$$

where *fis* is the feasibility predicate defined as the point-wise application of the feasibility PO of the machine M [11]:

$$Axm(s,c) \Rightarrow \exists v' \cdot BAP_{E^0}(s,c,v')$$

[1] lowercase e_i denotes instances, uppercase E^i denotes events

$$\bigwedge_{i=1}^{m} Axm(s,c) \wedge Inv(s,c,v) \wedge Grd_{E^i}(x_{E^i},s,c,v) \Rightarrow$$
$$\exists v' \cdot BAP_{E^i}(x_{E^i},s,c,v,v')$$

where s,c,v are the Sets, Constants and Variables of the state, *Inv* and *Axm* the invariants and axioms, *BAP* the Before-After predicate of a substitution, and v' is the After-value. $Traces(M)$ is the set of all traces of the machine M.

Intuitively, *fidelity* is seen as the inclusion of the set of traces of the executable model into $Traces(M)$. However, one set belongs to the JavaScript world, while the other belongs to the Event-B world. So, we introduce three abstraction-functions:

- $f \in V_J \rightarrow V_B$ which maps values in JavaScript to their equivalent in Event-B,
- *eval* which evaluates the JavaScript translation $f_\Psi()$ of the Event-B predicate Ψ. *eval* is assumed such that:

$$eval(x^t = x_0); eval(f_\Psi()) == true\ (resp.\ false) \Leftrightarrow$$
$$bool([x := f(x_0)]\Psi) = TRUE\ (resp.\ FALSE)$$

where $[a := b]\Psi$ is the substitution of a by b in Ψ.

- $f_{Trace} \in f_{Evts(M)} \rightarrow Evts(M)$ which maps the JavaScript translation of each event to each Event-B event.

Assuming f and *eval* and noting $x_{f_{e_j}}$ the event's parameters, the set of "interesting" traces in a simulation is defined as

$$f_{E^0}(); f_{e_1}(x_{f_{e_1}}); f_{e_2}(x_{f_{e_2}}); \ldots; f_{e_n}(x_{f_{e_n}})$$

belongs to $TraceSimulation(M)$ if

$$\bigwedge_{j=1}^{n} eval(f_{e_j}.f_{Grd}(x_{f_{e_j}})) == true$$

The definition of *fidelity* is simply that all traces in $TraceSimulation(M)$ can be abstracted to a trace of M

$$\forall t \cdot t \in TraceSimulation(M) \Rightarrow map(t, f_{Trace}) \in Traces(M)$$

B. Proof Obligations

The general definition can be broken down into local properties, which allow to associate a specific PO to each hand-coded element [16]. Six cases have been identified

1) Valuation of constants. The PO checks the axioms hold.

$$bool([s,c := f(s_J), f(c_J)]Axm(s,c)) = TRUE$$

2) Valuation of parameters. The PO checks the guards hold.

$$\bigwedge_{j=1}^{n} bool([x_{e_j} := f(x_{f_{e_j}})]Grd_{e_j}(x_{e_j},s,c,v)) = TRUE$$

3) Parameter generator. The produced value is checked against the event's guards, no proof is needed.

4) Predicate in an invariant or a guard. Let f_Ψ be the user implementation of the predicate Ψ, the PO is

$$eval(f_\Psi()) == true \quad \Leftrightarrow \quad bool(\Psi) = TRUE$$

5) Value for an action. Let f_{act} the user implementation. The PO ensures that computed values are admissible values.

$$\{f(v_J) \mid v_J = f_{act}()\} \subseteq \{v' \mid BAP_{act}(x_{E^i},s,c,v,v')\}$$

6) Function defined by non-constructive properties. Technically, this is the most difficult case. An axiom defining a function g has the form

$$\forall v_1,...,v_n \cdot type(v_1) \wedge ... \wedge type(v_n) \Rightarrow \Psi(g,v_1,...,v_n)$$

where Ψ contains several application of g, and $type(v_k)$ is a typing predicate for v_k. Ψ is translated into a program, `Prog`, using JeB rules for predicates and calls to the user's implementation, g_{user}, for each appearance of g. Let f_Ψ be the translation in JavaScript of Ψ using the *definition* of g, then the PO is

$$wp(Prog,f_\Psi) \Rightarrow \bigwedge_{k=1}^{n} f_{type}(v_k)$$

where wp is the usual weakest-precondition transformer. POs 1, 2 and 5 can be discharged within the Event-B system; POs 4 and 6 must be discharged within JavaScript semantics.

C. Assumptions

The discussion of *fidelity* focused on our main contribution: the safe inclusion of hand-coded pieces of code. Discharging the POs proves the *fidelity* under four assumptions:

A1 Event-B values can be represented in JavaScript,
A2 Event-B expressions can be translated into an observational equivalent JavaScript expression,
A3 Event-B AST can be syntactically mapped to library calls,
A4 Event-B operational semantic cycle can be implemented into a scheduler in JavaScript.

SETL [17] shows that A1 is reasonable. Existing translators such as B2C [7] and EB2ALL [8] show that A2 makes sense. The design of our run library, whose API covers all Event-B notations, establishes the validity of A3. A4 grounds tools such as ProB [9] and Brama [10]. We are confident that the assumptions can be proven. Such proofs would use the well-established techniques of proving compilers.

VI. CONCLUSION

In [18] we showed how a formally correct model can be safely transformed into an "incorrect" animatable model which keeps the same behaviors. Here, we showed how to produce simulations which are guaranteed to preserve a subset of the behaviors. So, we have the theoretical framework necessary to validate most refinements in a development.

The design and implementations of support tools for proving *fidelity* is the next challenge: the mix of different formal frameworks raises interesting questions. Another challenge lies in the invention of techniques to create, manage and replay validation scenarios using simulations and animations.

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