## A Theoretical study of the optimal control problem for the metastases

We consider the problem

$$
\begin{cases}\partial_{t} \rho(t, X ; u)+\operatorname{div}(\rho(t, X ; u)(G(X)-B(X) u(t)))=0 & ] 0, T[\times \Omega  \tag{1}\\ -\bar{G}(t, \sigma ; u) \cdot \nu(\sigma) \rho(t, \sigma ; u)=N(\sigma)\left\{\int_{\Omega} \beta(X) \rho(t, X ; u) d X+\beta\left(X_{p}(t ; u)\right)\right\} & ] 0, T[\times \partial \Omega \\ \rho(0, X ; u)=\rho^{0}(X) & \Omega\end{cases}
$$

where we denoted $X=(V, K)$ and consider some general coefficients and initial data $G, B, \beta, N$ and $\rho^{0}$.
Let us define $Q:=] 0, T[\times \Omega$ and do the following assumptions on the data

$$
\begin{equation*}
\beta \in W^{1, \infty}(\Omega), \rho^{0} \in W^{1, \infty}(Q), \rho^{0} \geq 0, N \in W^{1, \infty}(\partial \Omega), N \geq 0, \int_{\partial \Omega} N(\sigma) d \sigma=1 \tag{2}
\end{equation*}
$$

Defining $\Sigma=\left\{\left(V_{0}, K\right) ; 1<K<\left(\frac{c}{d}\right)^{3 / 2}\right\}$ we also assume that there exists $\delta>0$ such that

$$
\begin{equation*}
\operatorname{supp} N \subset \Sigma, \quad-\bar{G}(t, \sigma) \cdot \nu(\sigma) \geq \delta>0, \text { a.e. }(t, \sigma) \in[0, T] \times \Sigma \tag{3}
\end{equation*}
$$

Finally, although in the particular case of the coefficients of our model it is not true, we assume the following compatibility condition for regularity issues, in order to simplify the problem

$$
\begin{equation*}
-\bar{G}(t, \sigma) \cdot \nu(\sigma) \rho^{0}(\sigma)=N(\sigma)\left\{\int_{\Omega} \beta(X) \rho^{0}(X) d X+\beta\left(X_{p}(0)\right)\right\} \tag{4}
\end{equation*}
$$

In the present theoretical analysis, we take the objective to be given by

$$
J(u)=\int_{\Omega} a(X) \rho(t, X ; u) d X
$$

with $a \in \mathcal{C}^{\infty}(\bar{\Omega})$, which covers both cases of total number of metastases and metastatic burden that we used in the simulations. We will prove existence of an optimal control and derive a first order optimality system.

## A. 1 Existence of an optimal solution

We first prove existence of a solution to the optimal control problem defined on the metastases (the following proposition as well as its proof still holds verbatim for $J_{M}$ ).

Theorem 1. Under the assumptions (2), (3) and (4) there exists $u^{*} \in \mathcal{U}_{\text {ad }}$ such that

$$
J\left(u^{*}\right) \leq J(u), \quad \forall u \in \mathcal{U}_{a d}
$$

The proof of the theorem is based on the following proposition establishing $W^{1, \infty}$ bounds on the solution $\rho$ of (1).

Proposition 2. Under the assumptions (2), (3) and (4) if $\rho(u)$ is the solution of (1), then $\rho(u) \in$ $W^{1, \infty}(Q)$ and there exists a continuous function $C$ which can be explicited in terms of $\|\beta\|_{W^{1, \infty}(\Omega)}$, $\|N\|_{W^{1, \infty}(\partial \Omega)},\|G\|_{L^{\infty}(\Omega)}$ and $\|B\|_{L^{\infty}(\Omega)}$ such that, for all $u \in \mathcal{U}_{a d}$

$$
\begin{equation*}
\|\rho(u)\|_{W^{1, \infty}(Q)} \leq C\left(\|u\|_{L^{\infty}(Q)}\right) \tag{5}
\end{equation*}
$$

Proof. For $u \in \mathcal{U}_{a d}$, let $\rho(u)=\rho(t, X ; u)$ be the solution of (1). Following the method of previous papers $(17,18)$, we use the flow $\Phi(t, \tau, \sigma ; u)$ associated to the $\operatorname{EDO} \frac{d}{d t} \Phi=\bar{G}(\Phi ; u)$, that is $\Phi(t, \tau, \sigma ; u)$ is the
solution of this ODE being in $\sigma$ at time $\tau$. We consider the entrance time $\tau^{t}(X)$ and entrance point $\sigma^{t}(X)$ for a point $X \in \Omega$ given by

$$
\tau^{t}(X):=\inf \{0 \leq \tau \leq t ; \Phi(\tau ; t, X) \in \Omega\}, \sigma^{t}(X):=\Phi\left(\tau^{t}(X) ; t, X\right)
$$

and introduce the sets

$$
\Omega_{1}^{t}=\left\{X \in \Omega ; \tau^{t}(X)>0\right\}, \Omega_{2}^{t}=\left\{X \in \Omega ; \tau^{t}(X)=0\right\}
$$

as well as

$$
Q_{1}:=\left\{(t, X) \in[0, T] \times \bar{\Omega} ; X \in \bar{\Omega}_{1}^{t}\right\}, Q_{2}:=\left\{(t, X) \in[0, T] \times \bar{\Omega} ; X \in \bar{\Omega}_{2}^{t}\right\}
$$

and also define $\widetilde{Q_{1}}:=\{(t, \tau, \sigma) ; 0 \leq \tau \leq t \leq T, \sigma \in \partial \Omega\}=\Phi^{-1}\left(Q_{1}\right)$. We define the two following changes of variables

$$
\Phi_{1}: \begin{array}{ccccc}
\widetilde{Q}_{1} & \rightarrow & Q_{1} \\
(t, \tau, \sigma) & \mapsto & (t, \Phi(t ; \tau, \sigma ; u))
\end{array} \quad \text { and } \Phi_{2}: \begin{array}{ccc}
{[0, T] \times \bar{\Omega}} & \rightarrow & Q_{2} \\
(t, Y) & \mapsto & (t, \Phi(t ; 0, Y ; u))
\end{array}
$$

and set
(6) $\quad \widetilde{\rho}_{1}(t, \tau, \sigma ; u):=\rho\left(\Phi_{1}(t ; \tau, \sigma ; u)\right) J_{1}(t ; \tau, \sigma ; u)$ and $\widetilde{\rho}_{2}(t, Y ; u):=\rho\left(\Phi_{2}(t, 0, Y ; u)\right) J_{2}(t, Y ; u)$
with

$$
\begin{equation*}
J_{1}(t, \tau, \sigma ; u)=|\bar{G}(\tau, \sigma) \cdot \nu(\sigma)| e^{\int_{\tau}^{t} \operatorname{div} \bar{G}(s, \Phi(s, \tau, \sigma ; u)) d s} \text { and } J_{2}(t, Y ; u)=e^{\int_{0}^{t} \operatorname{div} \bar{G}(\Phi(s, 0, Y ; u)) d s} \tag{7}
\end{equation*}
$$

We have
(8)

$$
\rho(t, X ; u):=\widetilde{\rho}_{1}\left(\Phi_{1}^{-1}(t, X ; u)\right) J_{1}^{-1}\left(\Phi_{1}^{-1}(t, X ; u)\right) \mathbf{1}_{(t, X) \in Q_{1}}+\widetilde{\rho}_{2}\left(\Phi_{2}^{-1}(t, X ; u)\right) J_{2}^{-1}\left(\Phi_{2}^{-1}(t, X ; u)\right) \mathbf{1}_{(t, X) \in Q_{2}}
$$

with $\left(\widetilde{\rho}_{1}, \widetilde{\rho}_{2}\right)$ solving the problems

$$
\begin{cases}\partial_{t} \widetilde{\rho}_{1}(t, \tau, \sigma ; u)=0 & 0<\tau \leq t<T, \sigma \in \partial \Omega  \tag{9}\\ \widetilde{\rho}_{1}(\tau, \tau, \sigma ; u)=N(\sigma)\left\{\widetilde{B}\left(\tau, \widetilde{\rho}_{1}, \widetilde{\rho}_{2}\right)+\beta\left(X_{p}(\tau ; u)\right)\right\} & 0<\tau<T, \sigma \in \partial \Omega\end{cases}
$$

where we denoted

$$
\widetilde{B}\left(\tau, \widetilde{\rho}_{1}, \widetilde{\rho}_{2}\right)=\int_{0}^{\tau} \int_{\partial \Omega} \beta(\Phi(\tau ; s, \sigma ; u)) \widetilde{\rho}_{1}(\tau, s, \sigma ; u) d \sigma d s+\int_{\Omega} \beta(\Phi(\tau ; 0, Y ; u)) \widetilde{\rho}_{2}(\tau, Y ; u) d Y
$$

and

$$
\left\{\begin{array}{cl}
\partial_{t} \widetilde{\rho}_{2}(t, Y ; u)=0 & t>0, Y \in \Omega  \tag{10}\\
\widetilde{\rho}_{2}(0, Y ; u)=\rho^{0}(Y) & Y \in \Omega
\end{array}\right.
$$

We prove now the following lemma on the regularity of $\widetilde{\rho}_{1}$ solving (9).
Lemma 3. Let $F, \beta \in W^{1, \infty}\left(\widetilde{Q}_{1}\right), N \in W^{1, \infty}(\partial \Omega), T>0$ and $\rho \in L^{\infty}\left(\widetilde{Q}_{1}\right)$ be the solution of the following problem

$$
\begin{cases}\partial_{t} \rho=0 & \widetilde{Q}  \tag{11}\\ \rho(\tau, \tau, \sigma)=N(\sigma) \int_{0}^{\tau} \int_{\partial \Omega} \beta\left(\tau, \tau^{\prime}, \sigma^{\prime}\right) \rho\left(\tau, \tau^{\prime}, \sigma^{\prime}\right) d \tau d \sigma^{\prime}+F(\tau, \sigma) & {[0, T] \times \partial \Omega}\end{cases}
$$

We also assume $\operatorname{supp} N, \operatorname{supp}_{\sigma} F \subset \Sigma$. Then $\rho \in W^{1, \infty}\left(\widetilde{Q}_{1}\right)$, with support in $R:=\{(t, \tau, \sigma) \in \widetilde{Q} ; \sigma \in \Sigma\}$ and

$$
\|\rho\|_{W^{1, \infty}} \leq C\left(\|\beta\|_{L^{\infty}},\left\|\partial_{t} \beta\right\|_{L^{\infty}},\|N\|_{W^{1, \infty}},\|F\|_{W^{1, \infty}}\right)
$$

with $C$ being a continuous function.

Proof. From the equation, we have $\partial_{t} \rho \in L^{\infty}\left(\widetilde{Q}_{1}\right)$. Then, the solution of (11) is given by, for almost every $(t, \tau, \sigma) \in \widetilde{Q}_{1}$

$$
\begin{equation*}
\rho(t, \tau, \sigma)=N(\sigma) \int_{0}^{\tau} \int_{\partial \Omega} \beta\left(\tau, s, \sigma^{\prime}\right) \rho\left(\tau, s, \sigma^{\prime}\right) d s d \sigma^{\prime}+F(\tau, \sigma) \tag{12}
\end{equation*}
$$

from which we get, in the distribution sense

$$
\begin{aligned}
& \partial_{\tau} \rho(t, \tau, \sigma)=N(\sigma)\left\{\int_{\partial \Omega} \beta\left(\tau, \tau, \sigma^{\prime}\right) N\left(\sigma^{\prime}\right) \int_{0}^{\tau} \int_{\partial \Omega} \beta\left(\tau, s, \sigma^{\prime \prime}\right) \rho\left(\tau, s, \sigma^{\prime \prime}\right) d s d \sigma^{\prime \prime}+F\left(\tau, \sigma^{\prime}\right)\right. \\
&\left.+\int_{0}^{\tau} \int_{\partial \Omega} \partial_{\tau} \beta\left(\tau, s, \sigma^{\prime}\right) \rho\left(\tau, s, \sigma^{\prime}\right)+\beta\left(\tau, s, \sigma^{\prime}\right) \partial_{t} \rho\left(\tau, s, \sigma^{\prime}\right) d s d \sigma^{\prime}\right\}+\partial_{\tau} F(\tau, \sigma)
\end{aligned}
$$

as well as

$$
\partial_{\sigma} \rho(t, \tau, \sigma)=\partial_{\sigma} N(\sigma) \int_{0}^{\tau} \int_{\partial \Omega} \beta\left(\tau, s, \sigma^{\prime}\right) \rho\left(\tau, s, \sigma^{\prime}\right) d s d \sigma^{\prime}+\partial_{\sigma} F(\tau, \sigma)
$$

and prove that $\rho \in W^{1, \infty}\left(\widetilde{Q}_{1}\right)$. Formula (12) also proves the assertion on the support of $\rho$.
The $W^{1, \infty}$ bound (5) comes from the above explicit expressions and the following $L^{1}$ bound : for all $t \in[0, T]$

$$
\int_{0}^{t} \int_{\partial \Omega}|\rho(t, s, \sigma)| d s d \sigma \leq \int_{0}^{t} e^{(t-s)\|\beta\|_{L^{\infty}}} \int_{\partial \Omega}|F(s, \sigma)| d s d \sigma
$$

It is derived by applying a Gronwall lemma to the following inequality, obtained from equation (11)

$$
\frac{d}{d t} \int_{0}^{t} \int_{\partial \Omega}|\rho(t, \tau, \sigma)| d \sigma d \tau \leq\|\beta\|_{L^{\infty}} \int_{0}^{t} \int_{\partial \Omega}|\rho(t, \tau, \sigma)| d \sigma d \tau+\int_{\partial \Omega}|F(t, \sigma)| d \sigma
$$

We apply the previous lemma to $\widetilde{\rho}_{1}$ solving (9) by using $\widetilde{\beta}(t, \tau, \sigma)=\beta(\Phi(t, \tau, \sigma ; u))$ and

$$
\begin{aligned}
F(\tau, \sigma) & =N(\sigma)\left\{\int_{\Omega} \beta\left(\Phi(\tau, 0, Y ; u) \widetilde{\rho}_{2}(\tau, Y) d Y+\beta\left(X_{p}(\tau)\right)\right\}\right. \\
& =N(\sigma)\left\{\int_{\Omega} \beta\left(\Phi(\tau, 0, Y ; u) \rho^{0}(\tau, Y) d Y+\beta\left(X_{p}(\tau)\right)\right\} .\right.
\end{aligned}
$$

We observe that $\|\widetilde{\beta}\|_{L^{\infty}(\widetilde{Q})}=\|\beta\|_{L^{\infty}(\Omega)}$ and

$$
\partial_{t} \widetilde{\beta}=\nabla \beta \cdot \partial_{t} \Phi=\nabla \beta \cdot G(X)-\nabla \beta \cdot B u
$$

so

$$
\left\|\partial_{t} \beta\right\|_{L^{\infty}(\widetilde{Q})} \leq\|\nabla \beta\|_{L^{\infty}(\Omega)}\left\{\|G\|_{L^{\infty}(\Omega)}+\|B\|_{L^{\infty}(\Omega)}\|u\|_{L^{\infty}(0, T)}\right\} .
$$

Thus we have, since the $W^{1, \infty}$ norm of $F$ is controlled by the $W^{1, \infty}$ norms of $N, \beta$ and $\rho^{0}$ that

$$
\left\|\widetilde{\rho}_{1}(u)\right\|_{W^{1, \infty}\left(\widetilde{Q}_{1}\right)} \leq C\left(\|u\|_{L^{\infty}(0, T)}\right)
$$

with $C$ a continuous function.
We wish now to end the proof by recovering regularity on $\rho$ using formula (8).

- From the assumption (3), we have that $\Phi_{1}$ is an homeomorphism bilipschitz on $R$. Hence the chain rule applies on $R$ and $\widetilde{\rho}_{1} \circ \Phi_{1}^{-1} \in W^{1, \infty}\left(\Phi_{1}(R)\right)$ and also

$$
\rho_{1}:=\widetilde{\rho}_{1} \circ \Phi_{1}^{-1} J_{1}^{-1} \in W^{1, \infty}\left(\Phi_{1}(R)\right) .
$$

- Since supp $\widetilde{\rho}_{1} \subset R$, then $\widetilde{\rho}_{1} \circ \Phi_{1}^{-1} J_{1}^{-1}=\widetilde{\rho}_{1} \circ \Phi_{1}^{-1} J_{1}^{-1} \mathbf{1}_{\left\{\Phi_{1}(R)\right\}} \in W^{1, \infty}\left(Q_{1}\right)$
- $\Phi_{2}$ is always bilipschitz thus $\rho_{2}:=\widetilde{\rho}_{2} \circ \Phi_{2}^{-1} J_{2}^{-1} \in W^{1, \infty}\left(Q_{2}\right)$.

Now we rewrite formula (8) as $\rho=\rho_{1} \mathbf{1}_{\left\{Q_{1}\right\}}+\rho_{2} \mathbf{1}_{\left\{Q_{2}\right\}}$. Since $Q_{1} \cap Q_{2}=\{\Phi(t, 0, \sigma ; u), ; t \in[0, T], \sigma \in \partial \Omega\}$, we compute

$$
\begin{aligned}
& \rho_{1}(t, \Phi(t, 0, \sigma ; u))=-(\bar{G}(0, \sigma) \cdot \nu(\sigma))^{-1} \widetilde{\rho}_{1}(t, 0, \sigma) e^{-\int_{0}^{t} \operatorname{div} \bar{G}(s, \Phi(s, \tau, \sigma ; u)) d s} \\
& \quad=(\bar{G}(0, \sigma) \cdot \nu(\sigma))^{-1} N(\sigma)\left\{\int_{\Omega} \beta\left(\Phi(\tau, 0, Y ; u) \rho^{0}(\tau, Y) d Y+\beta\left(X_{p}(\tau)\right)\right\} e^{-\int_{0}^{t} \operatorname{div} \bar{G}(s, \Phi(s, \tau, \sigma ; u)) d s}\right.
\end{aligned}
$$

and

$$
\rho_{2}(t, \Phi(t, 0, \sigma ; u))=\widetilde{\rho}_{2}(t, \sigma) e^{-\int_{0}^{t} \operatorname{div} \bar{G}(s, \Phi(s, \tau, \sigma ; u)) d s}=\rho^{0}(\sigma) e^{-\int_{0}^{t} \operatorname{div} \bar{G}(s, \Phi(s, \tau, \sigma ; u)) d s}
$$

Hence, using the compatibility condition (4) we obtain that $\rho \in \mathcal{C}(Q)$ which, combined with $\rho_{\mid Q_{1}} \in$ $W^{1, \infty}\left(Q_{1}\right)$ and $\rho_{\mid Q_{2}} \in W^{1, \infty}\left(Q_{2}\right)$ gives $\rho \in W^{1, \infty}(Q)$. The $W^{1, \infty}$ bound (5) follows from formula (8), the $W^{1, \infty}$ bounds on $\widetilde{\rho}_{1}$ and on $\widetilde{\rho}_{2}$ (this last one coming from explicit solution of (10)), the chain rule and $W^{1, \infty}$ estimates on $\Phi_{1 \mid \Phi(R)}^{-1}$ (using assumption (3)) as well as on $\Phi_{2}^{-1}, J_{1}^{-1}$ and $J_{2}^{-1}$.
Since $\left\{J(u) ; u \in \mathcal{U}_{a d}\right\}$ is bounded by zero by below from the positivity of the solution it has a finite lower bound and there exists a sequence $u_{n}$ in $\mathcal{U}_{a d}$ such that

$$
\begin{equation*}
J\left(u_{n}\right) \xrightarrow[n \rightarrow \infty]{ } \inf _{u \in \mathcal{U}_{a d}} J(u) \tag{13}
\end{equation*}
$$

Since $\mathcal{U}_{a d}$ is bounded, from the estimate (5) we obtain that the family $\rho\left(u_{n}\right)$ is bounded in $W^{1, \infty}(Q)$. Using Ascoli-Arzela theorem there exists $\rho^{*} \in \mathcal{C}(Q)$ and a subsequence still denoted $\rho\left(u_{n}\right)$ such that $\rho\left(u_{n}\right) \xrightarrow[n \rightarrow \infty]{\mathcal{C}(Q)} \rho^{*}$. The weak formulation of the problem (1) writes : for all $\phi \in \mathcal{C}_{c}^{1}([0, T[\times \bar{\Omega})$

$$
\begin{aligned}
\int_{0}^{T} & \int_{\Omega} \rho\left(t, X ; u_{n}\right)\left[\partial_{t} \phi(t, X)+G(X) \cdot \nabla \phi(t, X)-u_{n}(t) B(X) \cdot \nabla \phi(t, X)\right] d t d X+ \\
& \int_{\Omega} \rho^{0}(X) \phi(0, X) d X+\int_{0}^{T} \int_{\partial \Omega} \phi(t, \sigma) N(\sigma)\left\{\int_{\Omega} \beta(X) \rho\left(t, X ; u_{n}\right) d X+\beta\left(X p\left(t ; u_{n}\right)\right)\right\} d \sigma d t=0
\end{aligned}
$$

and thus the convergence of $\rho\left(u_{n}\right)$ in $\mathcal{C}(Q)$ and the $*$ - weak $L^{\infty}$ convergence of $u_{n}$ are sufficient to pass to the limit in order to obtain, using uniqueness of the solution to the problem (1) (see (18)), that $\rho^{*}=\rho\left(u^{*}\right)$. Now

$$
J\left(u_{n}\right)=\int_{\Omega} a(X) \rho\left(T, X ; u_{n}\right) d X \underset{n \rightarrow \infty}{ } \int_{\Omega} a(X) \rho\left(T, X ; u^{*}\right) d X=J\left(u^{*}\right)
$$

Using (13) we get $J\left(u^{*}\right)=\inf _{u \in \mathcal{U}_{a d}} J(u)$, which ends the proof of the theorem.

## A. 2 Optimality system

We shall now derive first order necessary conditions on the optimal control. Let $u^{*}$ is a solution of the optimal control problem, we have

$$
J^{\prime}\left(u^{*}\right) \cdot\left(v-u^{*}\right) \geq 0, \quad \forall v \in \mathcal{U}_{a d}
$$

Here we have, for all $u, v \in L^{2}(Q)$

$$
J^{\prime}(u) \cdot(v-u)=\int_{\Omega} a(X) z\left(T, X ; \rho^{*}, u^{*}, v\right) d X
$$

where $z=z\left(\rho^{*}, u^{*}, v\right)=D_{u} \rho\left(u^{*}\right) \cdot\left(v-u^{*}\right)$ and $\rho^{*}=\rho\left(u^{*}\right)$. Hence

$$
\begin{equation*}
\int_{\Omega} a z\left(T ; \rho^{*}, u^{*}, v\right) d X \geq 0, \quad \forall v \in \mathcal{U}_{a d} \tag{14}
\end{equation*}
$$

Notice that $z$ solves the following problem
(15)

$$
\left\{\begin{array}{c}
\partial_{t} z+\operatorname{div}\left(z \bar{G}\left(X, u^{*}\right)\right)=\operatorname{div}\left(\rho^{*} B(X) \cdot\left(v-u^{*}\right)\right) \\
-\bar{G} \cdot \nu\left(t, \sigma ; u^{*}\right) z\left(t, \sigma ; u^{*}\right)=N(\sigma)\left\{\int_{\Omega} \beta(X) z\left(t, X ; u^{*}\right) d X+\nabla \beta\left(X_{p}\left(t ; u^{*}\right)\right) \cdot D_{u} X_{p}\left(t ; u^{*}\right) \cdot\left(v-u^{*}\right)\right\} \\
z\left(0, X ; u^{*}\right)=0
\end{array}\right.
$$

We will also need the Cauchy problem solved by $Y\left(t ; u^{*}\right):=D_{u} X_{p}\left(t ; u^{*}\right) \cdot\left(v-u^{*}\right) \in \mathbb{R}^{2}$ which is

$$
\left\{\begin{array}{l}
\dot{Y}\left(t ; u^{*}\right)=D_{X} \bar{G}\left(X_{p}\left(t ; u^{*}\right)\right) Y\left(t ; u^{*}\right)-B\left(X_{p}\left(t ; u^{*}\right)\right)\left(v-u^{*}\right)  \tag{16}\\
Y\left(0 ; u^{*}\right)=0
\end{array}\right.
$$

In order to simplify the optimality condition (14), we introduce the adjoint problem of (15). Let $p^{*} \in$ $H^{1}(Q)$ solving

$$
\left\{\begin{array}{c}
-\partial_{t} p^{*}\left(t, X ; u^{*}\right)-\bar{G}\left(X ; u^{*}\right) \nabla p^{*}\left(t, X ; u^{*}\right)-\beta(X) \int_{\partial \Omega} N(\sigma) p^{*}(t, \sigma) d \sigma=0  \tag{17}\\
p^{*}(T, X)=-a(X)
\end{array}\right.
$$

We also introduce the adjoint $\xi^{*}(t ; u) \in \mathbb{R}^{2}$ of the problem (16) with a particular source term

$$
\left\{\begin{array}{l}
\xi\left(t ; u^{*}\right)=-\left(D_{X} \bar{G}\right)^{T}\left(t, X_{p}^{*}\left(t ; u^{*}\right)\right) \xi\left(t ; u^{*}\right)-\nabla \beta\left(X_{p}^{*}\left(t ; u^{*}\right)\right) \int_{\partial \Omega} N(\sigma) p^{*}\left(t, \sigma ; u^{*}\right) d \sigma \\
\xi(T)=0
\end{array}\right.
$$

We replace $a$ from the first equation of (17) into (14) to obtain

$$
\int_{\Omega} p^{*}(T, X) z(T, X) d x \leq 0, \quad \forall v \in \mathcal{U}_{a d}
$$

By integration by part in time we have

$$
\begin{gathered}
\int_{Q}\left(-\bar{G}\left(X ; u^{*}\right) \nabla p^{*}\left(t, X ; u^{*}\right)-\beta(X) \int_{\partial \Omega} N(\sigma) p(t, \sigma) d \sigma\right) z d x d t \leq 0, \quad \forall v \in \mathcal{U}_{a d} \\
\int_{0}^{T} \int_{\Omega} p^{*} \operatorname{div}\left(\rho^{*} B\left(v-u^{*}\right)\right) d X-\left[\dot{\xi}+\left(D_{X} \bar{G}\right)^{T} \xi\right] \cdot Y d t \leq 0 \quad \forall v \in \mathcal{U}_{a d}
\end{gathered}
$$

and another integration by part in time yields

$$
\int_{0}^{T} \int_{\Omega} p^{*} \operatorname{div}\left(\rho^{*} B\left(v-u^{*}\right)\right) d X-\xi B\left(X_{p}\left(u^{*}\right)\right)\left(v-u^{*}\right) d t \leq 0 \quad \forall v \in \mathcal{U}_{a d}
$$

We deduce the following optimality system :

$$
\left\{\begin{array}{c}
\partial_{t} \rho^{*}+\operatorname{div}\left(\rho^{*} \bar{G}\left(u^{*}\right)\right)=0  \tag{18}\\
N(\sigma)\left\{\int_{\Omega} \beta(X) \rho^{*}\left(t, X ; u^{*}\right) d X+\beta\left(X_{p}\left(t ; u^{*}\right)\right\}\right. \\
\rho^{*}\left(0, X ; u^{*}\right)=\rho^{0} \\
\dot{X}_{p}\left(t ; u^{*}\right)=\bar{G}\left(t, X_{p}\left(t ; u^{*}\right) ; u^{*}\right) \\
X_{p}\left(0 ; u^{*}\right)=0 \\
-\partial_{t} p^{*}\left(t, X ; u^{*}\right) \rho^{*}\left(t, \sigma ; u^{*}\right)-\bar{G}\left(X ; u^{*}\right) \nabla p^{*}\left(t, X ; u^{*}\right)-\beta(X) \int_{\partial \Omega} N(\sigma) p^{*}(t, \sigma) d \sigma=0 \\
p^{*}(T)=-a \\
\xi\left(t ; u^{*}\right)=-\left(D_{X} \bar{G}\right)^{T}\left(t, X_{p}^{*}\left(t ; u^{*}\right)\right) \xi\left(t ; u^{*}\right)-\nabla \beta\left(X_{p}^{*}\left(t ; u^{*}\right)\right) \int_{\partial \Omega} N(\sigma) p^{*}\left(t, \sigma ; u^{*}\right) d \sigma \\
\xi(T)=0 \\
<\int_{\Omega} \operatorname{div}\left(B \rho^{*}\right) p^{*} d X-\xi B\left(X_{p}\left(u^{*}\right)\right),\left(v-u^{*}\right)>_{L^{2}(0, T)^{2}} \leq 0, \quad \forall v \in \mathcal{U}_{a d} .
\end{array}\right.
$$

where $\operatorname{div}\left(\rho^{*} B\right)$ stands for the vector $\left(\operatorname{div}\left(\rho^{*} B^{1}\right), \operatorname{div}\left(\rho^{*} B^{2}\right)\right)$ with $B^{1}, B^{2}$ being the columns of $B$.

