CADP Tutorial

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I. INTRODUCTION



CADP

(Construction and Analysis of Distributed Processes)

- A modular toolbox for asynchronous systems
- At the crossroads between:
 - concurrency theory
 - formal methods
 - computer-aided verification
 - compiler construction
- A long-run effort:
 - development of CADP started in the mid 80s
 - initially: only 2 tools (CÆSAR and ALDEBARAN)
 - last stable version: CADP 2006
 - today: nearly 50 tools in CADP 2010 (close to stable)







CADP: main features

Specification languages

- Formal semantics
- Based on process calculi
- User-friendly syntax

Verification paradigms

- Model checking (modal μ-calculus)
- Equivalence checking (bisimulations)
- Visual checking (graph drawing)

• Verification techniques

- Reachability analysis
- On-the-fly verification
- Compositional verification
- Distributed verification
- Static analysis
- Other features
 - Step-by-step simulation
 - Rapid prototyping
 - Test-case generation
 - Performance evaluation



CADP w.r.t. other model checkers

- Parallel programs (rather than sequential programs)
- Message passing (rather than shared memory)
- Languages with a formal semantics (process calculi)
- Dynamic data structures (records, lists, trees...)
- Explicit-state (rather than symbolic)
- Action-based (rather than state-based)
- Branching-time logic (rather than linear-time logic)



Application domains

- Not restricted to a particular application domain
- Case studies cover the following domains:

avionics, bioinformatics, business processes, cognitive systems, communication protocols, component-based systems, constraint programming, control systems, coordination architectures, critical infrastructures, cryptography, database protocols, distributed algorithms, distributed systems, e-commerce, e-democracy, embedded software, grid services, hardware design, hardware/software co-design, healthcare, human-computer interaction, industrial manufacturing systems, middleware, mobile agents, model-driven engineering, networks, object-oriented languages, performance evaluation, planning, radiotherapy equipments, real-time systems, security, sensor networks, service-oriented computing, software adaptation, software architectures, stochastic systems, systems on chip, telephony, transport safety, Web services

list of case studies: <u>http://cadp.inria.fr/case-studies</u>



Plan

- I. Introduction
- II. Architecture and verification technology
- III. Modeling languages (LNT tutorial)
- IV. From languages to models
- V. Functional verification
- VI. Performance evaluation
- VII. Script Verification Language (SVL tutorial)
- VIII. Conclusion



RUNNING EXAMPLE: MCS QUEUE LOCK



MCS queue lock

- mutual exclusion protocol for shared memory multiprocessor architectures with coherent caches
- guarantees FIFO ordering, uses "local spinning"
- original pseudo-code [Mellor-Crummey-Scott-91]



II. ARCHITECTURE AND VERIFICATION TECHNOLOGY



II.1 LTS (LABELED TRANSITION SYSTEM)



Labeled Transition Systems

- State-transition graph
- no information attached to states (except the initial state)
- information ("labels" or "actions") attached to transitions



Two kinds of LTS

• Explicit LTS (enumerative, global)

- comprehensive sets of states, transitions, labels
- BCG: a file format for storing large LTSs
- a set of tools for handling BCG files
- CADP 2010: BCG limits extended from 2²⁹ to 2⁴⁴

• Implicit LTS (on-the-fly, local)

- defined by initial state and transition function
- Open/Cæsar: a language-independent API
- many languages connected to Open/Cæsar
- many tools developed on top of Open/Cæsar

informatics mathematics

II.2 BES (BOOLEAN EQUATION SYSTEM)



Boolean Equation Systems

- least (μ) and greatest (ν) fixed point equations
- DAG (directed acyclic graph) of equation blocks (no cycles – alternation-free)



Support for BES

- BES can be given:
 - explicitly (stored in a file)
 - or implicitly (generated on the fly)
- CÆSAR_SOLVE: a solver for implicit BES
 - works on the fly: explores while solving
 - translates dynamically BES into Boolean graphs
 - implements 9 resolution algorithms A0-A8 (general vs specialized)
 - generates diagnostics (witnesses or counterexamples)
 - fully documented API
- BES_SOLVE: a solver for explicit BES



III. MODELING LANGUAGES (LNT TUTORIAL)



Modeling languages

- formal languages for modeling and specification
- CADP 2006: LOTOS only
- CADP 2010: numerous languages
 - wide spectrum from abstract calculi to automata
 - translations to benefit from existing optimized tools
- here: focus on LNT



Languages supported by CADP





Support for LOTOS

- LOTOS (ISO standard 8807):
 - Types/functions: algebraic data types
 - Processes: process algebra based on CCS and CSP
- Tools: CÆSAR, CÆSAR.ADT, CÆSAR.OPEN, etc.
- Features:
 - Optimal implementation of natural numbers
 - Bounded hash tables to canonically store structured types (tuples, unions, lists, trees, strings, sets, etc.)
 - Numerous optimizations of the intermediate Petri net model extended with data
 - Dynamically resizable state tables
 - Code specialization according to the amount of available RAM
 - Rapid prototyping and code generation



Support for FSP

- FSP (Finite State Processes) [Magee-Kramer]
 - A simple, concise process calculus
 - Supported by the LTSA tool
- Tools: FSP2LOTOS and FSP.OPEN
 - Translation from FSP to LOTOS + EXP + SVL
 - On-the-fly state space generation for FSP
 - Benefits with respect to LTSA:
 - Non-guarded process recursion is handled
 - 64-bit support for larger state spaces
 - Easy interfacing with all other CADP tools

Motivation behind LNT

- Advantages of process algebras:
 - Appropriate to model asynchronous systems formally
 - Equipped with formal verification tools (took years)
- But unpopular in industry due to
 - Steep learning curve
 - Lack of trained designers/engineers
- Need for new formal description techniques
 - more appropriate for industry (e.g., imperative style)
 - enable reuse of existing tools at minimal cost
- \Rightarrow LNT:
 - subset of E-LOTOS proposed by VASY (since 1995)
 - uniform language:

e.g., functions are a particular case of processes



Short history of LOTOS NT & LNT

- 1995-1998: participation to the standardization of E-LOTOS definition of LOTOS NT by Sighireanu and Garavel
- 2000: release of TRAIAN
 - data part of LOTOS NT into C
 - since then, compiler development of VASY based on TRAIAN:
 SVL, Exp.Open 2.0, Evaluator 3.0, NTIF, chp2lotos, Int2lotos, ...
- 2004-2007: FormalFamePlus Contract (VASY Bull)
 - use of LOTOS NT to model critical parts of Bull's high-end servers
 - funding for the development of a LOTOS NT to LOTOS translator
- 2006: release of Int2lotos (data part of LOTOS NT)
- 2008: release of Int2lotos (full LOTOS NT)
- 2010: integration into CADP (release of Int.open)
- 2011: renaming of LOTOS NT to LNT



LNT tutorial: Plan

- LNT: Language overview
 - Modules
 - Types
 - Functions
 - Processes
- Running example: MCS queue lock

More information in the reference manual:

http://vasy.inria.fr/Publications/Champelovier-Clerc-Garavel-et-al-10.pdf (regularly updated as \$CADP/doc/pdf/Champelovier-Clerc-Garavel-et-al-10.pdf)



III.1 LNT MODULES



LNT modules

- Compilation unit
- One module = one file (of the same name)
- Modules can import other modules: currently: no difference between interface and implementation
- Principal module containing the root process (by default, called "MAIN")

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- Case insensitive module names, but
 - all modules in the same directory
 - no two files differing only by case



Module Imports: Naming Conventions

- Problem: LNT case insensitive, but not the OS (except Windows[®])
- Chosen approach:
 - all identifiers are converted into upper case
 - for all but the principal module: all generated filenames are in uppercase
 - for principal module:
 keep case of case as input file
 - search of imported modules (LNT source):
 - first with the case as in the import line
 - then converted into upper case



III.2 LNT TYPES



LNT types

Inductive types

- set of constructors with named and typed parameters
- special cases: enumerations, records, unions, trees, etc.
- shorthand notations for arrays, (sorted) lists, and sets
- subtypes: range types and predicate types
- automatic definition of standard functions: "==", "<=", "<", ">=", ">", field selectors and updaters
- pragmas to control the generated names in C and LOTOS

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- Notations for constants (C syntax):
 - natural numbers: 123, 0xAD, 0o746, 0b1011
 - integer numbers: -421, -0xFD, -0o76, -0b110
 - floating point numbers: 0.5, 2E-3, 10.
 - characters: 'a', '0', '\n', '\\', '\''
 - character strings: "hello world", "hi!\n"

- Enumerated type
 type Weekday is (* LOTOS-style comment *)
 Mon, Tue, Wed, Thu, Fri, Sat, Sun
 end type
- Record type

type Date is -- ADA-style comment (to the end of the line) date (day: Nat, weekday: Weekday, month: Nat, year: Nat) end type

Inductive Type

```
type Nat_Tree is
    leaf (value: Nat),
    node (left: Nat_Tree, right: Nat_Tree)
end type
```



 Control of generated LOTOS & C names type BYTE is !representedby "LOTOS_BYTE" !implementedby "C_BYTE" !printedby "PRINT_BYTE" BYTE (B0, B1, B2, B3, B4, B5, B6, B7) end type

 Implementation by external C types type INT_32 is -- record type
 !external
 !implementedby "int"
 end type

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Shorthand notation

type Nat_List is list of Nat end type



Automatic definition of standard functions

```
type Num is
    one, two, three
    with "==", "<=", "<", ">=", ">"
end type
type Date is
    date (d: Nat, wd: Weekday, month: Nat, year: Nat)
    with "get", "set" (* for selectors X.D, ... and updaters X.{D => E} *)
end type
```



 One-dimensional array type Vector is -- four-dimensional vector array [0 .. 3] of Int end type

- Two-dimensional array
 type Matrix is -- four-dimensional square-matrix array [0..3] of Vector
 end type
- Array of records
 type Date_Array is

 array [0..1] of DATE
 end type





- Range types (intervals) type Index is range 0 .. 5 of Nat with "==", "!=" end type
 Predicate types type EVEN is
 - n: NAT where n mod 2 == 0 end type type PID is i: Index where i != 0 end type

further automatically definable functions: first, last, card



MCS queue lock: data types

- type Index is
 range 0 .. 5 of Nat
 with "==", "!="
 end type
- type Pid is
 pid: Index where pid != 0
 with "==", "!="
 end type

type Operation is
 Read_next, Read_locked,
 Write_next, Write_locked,
 Fetch_and_Store, Compare_and_Swap
end type

type Qnode is Qnode (next: Index, locked: Bool) with "get", "set" end type

type Memory is array [1 .. 5] of Qnode end type




LNT Module Pragmas

- Automatic generation of predefined functions module M with "get", "set", "card" is ...
- Width and range of predefined types module M is !nat_bits 3 ...
 - nat_bits/int_bits:
 bits for storing Nat/Int type
 - nat_inf/int_inf & nat_sup/int_sup:
 lower & upper bound of Nat/Int type
 - nat_check/int_check:
 (de)activate bound checks for Nat/Int type
 - string_card:

maximum number of strings (size of the hash table)

more functions: see type definition

0: deactivate 1: activate (default)

III.3 LNT FUNCTIONS



LNT functions

- Pure functions (without side effects) in imperative syntax ensured by type checking and initialization analysis
- Functions defined using standard algorithmic statements:
 - Local variable declarations and assignments: "var"
 - Sequential composition: ";"
 - Breakable loops: "while" and "for"
 - Conditionals: "If-then-else"
 - Pattern matching: "case"
 - (Uncatchable) exceptions: "raise"
- Three parameter passing modes:
 - "in" (call by value)
 - "out" and "inout" (call by reference)
- Function overloading
- Support for external implementations (LOTOS and C)

call syntax requires "eval" keyword

Sample LNT functions

Constants

function pi: Real is return 3.14159265 end function

Field access

 – function get_weekday (d: Date): Weekday is return d.wd

end function

- function set_weekday (inout d: Date, new_wd: Weekday) is
 d := d.{wd => new_wd}
end function

Sample LNT functions

 Update of the element (i,j) of a matrix M function update (inout M: Matrix, i, j: Nat, new_e: Nat) is var v: Vector in v := M[i]; v[j] := new_e; M[i] := v end var

```
end function
```

 Access to the first element of a list L function get_head (L: Nat_List) : Nat raises Empty_List: none is case L in var head: Nat in nil -> raise Empty_List | cons (head, any Nat_List) -> return head end case end function

Sample LNT functions

function reset_diagonal_elements (M: Matrix) : Matrix is var

```
result: Matrix,
```

i: Nat

```
in
```

```
result := M;
   for i := 0 while i < 3 by i := i + 1 loop
     eval update (!?result, i, i, 0)
   end loop;
   return result
 end var
end function
```



MCS queue lock: functions

- function nil: Index is (* constant definition *) return Index (0) end function
- function Nat (pid: Pid) : Nat is (* explicit type cast *) return Nat (Index (pid)) end function
- function _!=_ (p: Pid, i: Index) : Bool is (* infix comparison *) return (Index (p) != i) end function



III.4 LNT PROCESSES



LNT processes

• Processes are a superset of functions (except return):

- symmetric sequential composition
- variable assignment, "if-then-else", "case", "loop", etc.
- Additional operators:
 - communication: rendezvous with value communication
 - parallel composition: "par"
 - gate hiding: "hide"
 - nondeterministic choice: "select"
 - "disrupt", etc.
- Static semantics constraints
 - variable initialization
 - typed channels (with polymorphism and "any" type)



LNT rendezvous

- Polymorphic channel types
- Exchange of several values (*offers* O_i)
- Combination of inputs and outputs
- Value matching / constraint solving
- Pattern matching
- For short: LOTOS-style rendezvous plus
 - pattern matching
 - polymorphic gate typing (channel)

Sample LNT channels

channel None is end channel channel C1 is (Nat) end channel channel C2 is (Signal, Nat), (Signal, Nat, Nat) end channel

 predefined channel: any rendezvous without type-check for offers (LOTOS style)

MCS queue lock: channels

- channel Resource Access is
- (Pid)
- end channel
- channel Memory_Access is
- (Operation, Pid, Index, Pid),
- (Operation, Pid, Bool, Pid)
- end channel
- channel Lock Access is
- (Operation, Index, Index, Pid),
- (Operation, Index, Index, Bool, Pid) -- compare-and-swap end channel
- channel Latency is
 - (Pid),
 - (Operation)
- end channel

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-- read/write field next -- read/write field locked

- -- fetch-and-store



"Hello, world!"

- without channel typing module hello_world is process MAIN [G:any] is G ("Hello, world!\n") end process end module
- with channel typing module hello_world is channel String_channel is (String) end channel process MAIN [G:String_channel] is G ("Hello, world!\n") end process end module

Sample LNT process

```
type option is none, some (x: Nat) end type
channel option channel is (o: Option) end channel
channel nat_channel is (n: Nat) end channel
process FILTER [GET: option channel, PUT: nat channel] (b: Nat) is
    var opt: Option in
      loop L in
       GET (?opt);
       case opt in var x: Nat in
                               -> null
          none
        | some (x) where x > b \rightarrow PUT (x)
       end case
      end loop
                                                      FILTER (b)
                                           GET
                                                                      PUT
    end var
end process
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```

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MCS queue lock: competing process

```
process P [NCS, CS_Enter, CS_Leave: Resource_Access,
          L: Lock Access, M: Memory Access]
          (pid: Pid) is
 loop
  NCS (pid);
  acquire_lock [L, M] (pid);
  CS Enter (pid); CS Leave (pid);
  release lock [L, M] (pid)
 end loop
end process
```



MCS queue lock: acquire_lock

process acquire_lock [L: Lock_Access, M: Memory_Access] (pid: Pid) is
var predecessor: Index, locked: Bool in

M (W_next, pid, nil of Index, pid);

- L (Fetch_and_Store, ?predecessor, Index (pid), pid);
- if (predecessor != nil) then

M (W_locked, pid, true, pid);

M (W_next, Pid (predecessor), Index (pid), pid);

loop L in

M (R_locked, pid, ?locked, pid); if not (locked) then break L end if end loop end if

end var

end process

```
proc acquire_lock (L : ^lock, I : ^qnode)
I->next := nil
predecessor : ^qnode :=
  fetch_and_store (L, I)
if predecessor != nil
I->locked := true
predecessor->next := I
repeat while I->locked // spin
```



MCS queue lock: release_lock

```
process release lock [L: Lock Access, M: Memory Access] (pid: Pid) is
 var next: Index, swap: Bool in
   M (R_next, pid, ?next, pid);
   if next == nil then
     L (Compare_and_Swap, Index (pid), nil of Index, ?swap, pid);
     if swap == false then
       loop L in
         M (R next, pid, ?next, pid);
         if next != nil then break L end if
       end loop;
       M (W_locked, Pid (next), false, pid)
     end if
                                                     proc release lock (L : ^lock, I : ^qnode)
   else
                                                      if I->next = nil // no known successor
                                                       if compare and swap (L, I, nil)
     M (W locked, Pid (next), false, pid)
                                                       // true iff swapped
   end if
                                                        return
  end var
                                                       repeat while I->next = nil // spin
                                                      I->next->locked := false
end process
```

MCS queue lock: Global variable

```
process Lock [L: Lock Access] is
 var i, new_i, j: Index in
   i := nil;
   loop select
     L (Fetch_and_Store, i, ?new_i, ?any Pid);
     i:= new i
    Н
     L (Compare_and_Swap, ?j, ?new_i, true, ?any Pid) where i == j;
     i:=new i
    L (Compare_and_Swap, ?j, ?new_i, false, ?any Pid) where i != j
     -- ignore new i
   end select end loop
 end var
end process
```

MCS queue lock: Shared variables

process Memory [M: Memory Access] is var m: Memory, pid: Pid, next: Index, locked: Bool in m := Memory (Qnode (nil, false)); loop select M (Read next, ?pid, ?next, ?any Pid) where next == m[Nat (pid)].next [] M (Read locked, ?pid, ?locked, ?any Pid) where locked == m[Nat (pid)].locked [] M (Write next, ?pid, ?next, ?any Pid); $m[Nat (pid)] := m[Nat (pid)].{next => next}$ [] M (Write locked, ?pid, ?locked, ?any Pid); m[Nat (pid)] := m[Nat (pid)].{locked => locked} end select end loop end var end process

MCS queue lock for five processes

process Protocol [NCS, CS_Enter, CS_Leave: Resource_Access, L: Lock_Access, M: Memory_Access] is

par M, L in

par

```
P [NCS, CS_Enter, CS_Leave, L, M] (Pid (1))
```

```
| P [NCS, CS_Enter, CS_Leave, L, M] (Pid (2))
```

```
|| P [NCS, CS_Enter, CS_Leave, L, M] (Pid (3))
```

```
|| P [NCS, CS_Enter, CS_Leave, L, M] (Pid (4))
```

```
|| P [NCS, CS_Enter, CS_Leave, L, M] (Pid (5))
end par
```

par Lock [L] || Memory [M] end par end par end process

MCS queue lock: service (1/3)

```
type Pid_list is
 list of Pid with "==", "!="
end type
function _is_in_ (pid: Pid, fifo: Pid_list) : Bool is
 -- return true iff pid is in the list fifo
 case fifo in
 var head: Pid, tail: Pid list in
   nil ->
                         return false
 | cons (head, tail) -> if (head == pid) then
                           return true
                          else
                           return pid is in tail
                          end if
```

end case end function

MCS queue lock: service (2/3)

```
function pop (inout fifo: Pid_list, out pid: Pid)
raises Empty list: none
is -- remove last element of the list fifo
 case fifo in
 var head: Pid, tail: Pid list in
  {} ->
     raise Empty list
 | { head } ->
     pid := head; fifo := {}
 | cons (head, tail) ->
     eval pop (!?tail, ?pid); fifo := cons (head, tail)
 end case
end function
```

MCS queue lock: service (3/3)

```
process Service [CS_Enter, CS_Leave: Resource_Access] is
 var pid: Pid, fifo: Pid_list, current: Index in
  fifo := nil; current := nil;
  loop select
   pid := any Pid where (not (pid is_in fifo)) and (pid != current);
   fifo := cons (pid, fifo); i
  Ш
   if (current == nil) and (fifo != nil) then
    eval pop (!?fifo, ?pid); CS_Enter (pid); current := Index (pid)
   else stop end if
  []
   if current != nil then
    CS Leave (Pid (current)); current := nil
   else stop end if
  end select end loop
end var end process
```

Check of semantic constraints

- Semantic checks performed by Int2lotos
 - Correct declaration (variables, gates)
 - Correct initialization (variables / parameters)
 - Non-ambiguous overloading
 - Breaks inside matching loops
 - Path constraints (e.g., presence of a return)
 - Parameters usage
- Semantic checks performed by Cæsar(.adt) / CC
 - Type constraints (expressions and gates)
 - Availability of used types, functions, and processes
 - Exhaustiveness of case statements
 - Availability of external code (LOTOS, C)
 - Range/overflow checks for numbers

See the reference manual for details!

by Int_check on the C code generated by Cæsar(.adt)



IV. FROM LANGUAGES TO MODELS



IV.1 BCG (BINARY CODED GRAPH)



BCG format

- Text-based formats are not satisfactory to store large LTSs in computer files
 - disk space consuming (Gbytes)
 - slow (read/write operations are costly)
- BCG (Binary-Coded Graphs):
 - a compact file format for storing LTSs
 - a set of APIs
 - a set of software libraries
 - a set of tools (binary programs and scripts)



BCG libraries and APIs

• BCG_WRITE

API to create a BCG file

BCG_READ

API to read a BCG file

BCG_TRANSITION

API to store a transition relation in memory:

- successor function, or
- predecessor function, or
- successor and predecessor functions



Basic BCG tools

- bcg_info: extract info from a BCG file
- bcg_io: convert BCG from and to other formats
- bcg_labels: hide and/or rename labels
- bcg_draw, bcg_edit: visualize LTSs
- bcg_graph: generation of particular BCG graphs (chaos automata, FIFO buffers, bag automata)
- bcg_open: connection to Open/Cæsar applications



IV.2 OPEN/CÆSAR API



Motivations

- Most model checkers dedicated to one particular input language (e.g. Spin, SMV, ...)
- They can't be reused easily for other languages
- Idea: introduce modularity by separating
 - language-dependent aspects:
 compiling language into LTS model
 - language-independent algorithms: algorithms for LTS exploration



OPEN/CÆSAR



OPEN/CÆSAR API

• Primitives to represent an implicit LTS

- Opaque type for the representation of a state
- Initial state function
- Successor function
- etc.
- Provided by Open/Cæsar compilers
- Used by Open/Cæsar compliant tools



OPEN/CÆSAR libraries

• A set of predefined data structures

- EDGE: list of transitions (e.g., successor lists)
- HASH: catalog of hash functions
- STACK_1: stacks of states and/or labels
- DIAGNOSTIC_1: set of execution paths
- TABLE_1: hash table for states, labels, strings, etc.
- BITMAP: Holzmann's "bit state" tables
- RENAME_1: handling of label renaming options
- Specific primitives for on the fly verification
 - possibility to attach additional information to states
 - stack or table overflow => backtracking
 - etc.



Some OPEN/CÆSAR applications

- EXECUTOR: random walk
- OCIS: interactive simulation (graphical)
- **GENERATOR**: exhaustive LTS generation
- **REDUCTOR**: LTS generation with reduction
- **PROJECTOR**: LTS generation with constraints
- TERMINATOR: Holzmann's bit-space algorithm
- EXHIBITOR: search paths defined by reg. expr.
- EVALUATOR: evaluation of mu-calculus formulas
- TGV: test sequence generation
- **DISTRIBUTOR**: distributed state space generation
- CUNCTATOR: Markov chain steady-state simulator



Example: GENERATOR (1/2)

```
#include "caesar graph.h"
#include "caesar edge.h"
#include "caesar table 1.h"
#include "bcg user.h"
int main (int argc, char *argv[]) {
  char *filename;
  CAESAR TYPE TABLE 1 t; CAESAR TYPE STATE s1, s2;
  CAESAR TYPE EDGE e1 en, e; CAESAR TYPE LABEL I;
  CAESAR_TYPE_INDEX_TABLE_1 n1, n2, initial_state ; CAESAR_TYPE_POINTER dummy;
  filename = argv[0];
  CAESAR INIT GRAPH ();
  CAESAR INIT EDGE (CAESAR FALSE, CAESAR TRUE, CAESAR TRUE, 0, 0);
  CAESAR CREATE TABLE 1 (&t, 0, 0, 0, 0, TRUE, NULL, NULL, NULL, NULL);
  if (t == NULL) CAESAR ERROR ("not enough memory for table");
  CAESAR START STATE ((CAESAR TYPE STATE) CAESAR PUT BASE TABLE 1 (t));
  CAESAR PUT TABLE 1 (t);
  initial state = CAESAR_GET_INDEX_TABLE_1 (t);
  BCG_INIT (); BCG_IO_WRITE_BCG_BEGIN (filename, initial_state, 2, "", 0);
```
Example: GENERATOR (2/2)

```
while (!CAESAR EXPLORED TABLE 1 (t)) {
  s1 = (CAESAR TYPE STATE) CAESAR GET BASE TABLE 1 (t);
  n1 = CAESAR_GET_INDEX_TABLE_1 (t);
  CAESAR GET TABLE 1 (t);
```

```
CAESAR CREATE EDGE LIST (s1, &e1 en, 1);
if (CAESAR TRUNCATION EDGE LIST () != 0)
  CAESAR ERROR ("not enough memory for edge lists");
```

```
CAESAR ITERATE LN EDGE LIST (e1 en, e, l, s2) {
    CAESAR_COPY_STATE ((CAESAR_TYPE_STATE) CAESAR_PUT_BASE_TABLE_1 (t), s2);
    (void) CAESAR SEARCH AND PUT TABLE 1 (t, &n2, &dummy);
    BCG IO WRITE BCG EDGE (n1, CAESAR STRING LABEL (I), n2);
  CAESAR DELETE EDGE LIST (&e1 en);
BCG IO_WRITE_BCG_END ();
return (0)
```



}

IV.3 TOOLS FOR STATE SPACE GENERATION



State space generation

- Motivation: generate an explicit LTS (BCG) from an implicit one (Open/Cæsar), for verification
- Use GENERATOR for direct generation
- Problem: possible state explosion, e.g. when the number of concurrent processes grows
- Several solutions to fight against state explosion:
 - Compositional verification
 - Distributed state space generation
 - (Combined with static analysis, partial order reductions, …)



Compositional verification

- "Divide and conquer" to fight state explosion
 - Partition the system into subsystems
 - Minimize each subsystem modulo a strong or weak bisimulation preserving the properties to verify
 - Recombine the subsystems to get a system equivalent to the initial one
- Refined compositional verification:
 - Tightly-coupled processes constrain each other
 - Separating them may lead to explosion
 - "Interfaces" used to model synchronization constraints
- SVL (Script Verification Language) provides high-level support for compositional verification (see later)



Minimization tools

Aldebaran

- no longer supported after July 2008 (64-bit issue)
- functionalities retained with Aldebaran 7.0 script
- BCG_MIN
 - minimization of explicit LTSs
 - strong and branching bisimulation
 - new signature-based algorithm
 - supports LTS with $10^9 10^{10}$ states
- Reductor
 - on-the-fly (partial) reduction of implicit LTSs
 - 8 equivalence relations supported: strong, branching, tau*.a, safety, trace (aka automata determinization), weak trace, tau-confluence, tau-compression, and tau-divergence



EXP.OPEN 2.0

- A language for describing networks of LTS
 - LTS encoded in AUT or BCG format
 - synchronization vectors + parallel composition operators (LOTOS, CCS, CSP, mCRL, etc.)
 - label hiding, renaming, cutting (using regexps)
 - "priority" operator
- An Open/Cæsar compiler
 - on-the-fly partial order reductions (branching eq., weak trace eq., stochastic/probabilistic eq.)

Informatics mathematics

PROJECTOR 3.0

- To achieve refined compositional verification
- Implements ideas of Graf & Steffen, Krimm & Mounier
- Computes on the fly the restriction of an LTS modulo interface constraints
 - Interface = LTS understood as a set of traces
 - Eliminates states and transitions of a process never reached while following all traces of its interface
 - User-given interfaces involve predicate generation to check their correctness

Distributed state space generation

- Exploit workstation networks, clusters and grids
- Cumulate CPU and RAM across the network
- GCF (*Grid Configuration File*) to configure:
 - number and names of machines
 - local directories
 - CADP installation directories
 - communication protocols, addresses
- Socket-based internal communication library (SSH connections, TCP sockets)



DISTRIBUTOR

- Distributed state space generation
- Generates distributed BCG fragments referenced in a PBG (*Partitioned BCG graph*) file
- Enables tau-compression and tau-confluence (partial order) reductions preserving branching bisimulation



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Tools to handle PBG files

• pbg_info:

- compute global state space information by combining state space information of the fragments
- check consistency of the PBG file
- pbg_cp, pbg_mv, and pbg_rm:
 - convenient handling
 - single command to modify all fragments of a PBG
- pbg_open: connection to the Open/Cæsar API



BCG_MERGE

- Merges a distributed state space produced by DISTRIBUTOR into a monolithic labelled transition system
- Same functionality as pbg_open/generator but more efficient



V. FUNCTIONAL VERIFICATION



V.1 VISUAL CHECKING



OCIS (Open/Cæsar Interactive Simulator)



OCIS (Open/Cæsar Interactive Simulator)

File Edit Motion Window Options	Help			
	ø 💓			
MSC format Text format Tree format				
Expanded tree	🖕 Fired 🗳			
START i(0) CS_ENTER 12 CS_ENTER 11 CS_ENTER 12 CS_ENTER 12 CS_ENTER 12 CS_ENTER 12 CS_ENTER 12 CS_ENTER 12 CS_ENTER 12 CS_ENTER 12 CS_ENTER 11 CS_ENTER 11 CS_ENTER 11 CS_ENTER 11 CS_ENTER 12 CS_ENTER 12 CS_EN	1/2 2/2 1/1 1/2 1/2 0/1 1/2 2/2 0/2 1/2 1/2 0/1			
	(Free			
Li(0)				
2. CS_ENTER II				
Use button left-click to select a transition				

- Ianguage-independent
- tree-like scenarios
- save/load scenarios
- source code access
- dynamic recompile

Bcg_Draw and Bcg_Edit

- View BCG graph
- Edit postscript interactively
- Applicable to small LTSs (e.g., after hiding internal actions & minimization)





V.2 EQUIVALENCE CHECKING



BISIMULATOR

- On-the-fly comparison of an implicit LTS (Open/Cæsar graph) and an explicit LTS (BCG graph)
- Uses Boolean Equation Systems (CÆSAR_SOLVE)
- Checks equivalence (=) or inclusion (\leq or \geq)
- Seven equivalence relations supported (strong, branching, observational, tau*.a, safety, trace, and weak trace)
- Generates counterexamples (common LTS fragments leading to differences)

V.3 MODEL CHECKING WITH MCL

MCL language

- Extended temporal logic
 - Alternation-free mu-calculus
 - + Regular sequences
 - + Fairness operators (alternation 2)
 - + Data handling
 - + Libraries of derived operators
- Supported by the EVALUATOR 4.0 tool
 - BES resolution (CÆSAR_SOLVE)
 - Several optimized resolution algorithms
 - Tau-confluence reduction
 - Diagnostic generation

MCL examples (1/4)

- Deadlock freeness
 - [true*] < true > true
- Mutual exclusion

[true* .
 { CS !"ENTER" ?i:Nat } .
 (not { CS !"LEAVE" !i })* .
 { CS !"ENTER" ?j:Nat where j <> i }
] false

MCL examples (2/4)

• Independent progress (N == number of processes)

(if a process stops in its non-critical section, the other processes can still access their critical sections)

MCL examples (3/4)

Bounded overtaking

```
(process j overtakes process i exactly max times)
```

```
< true* . { NCS !i } .
     (not { ?G:String ... !i where (G <> "NCS") and (G <> "CS") })* .
     { ?G:String ... !i where (G <> "NCS") and (G <> "CS") }.
     ( for k:nat from 0 to n-1 do
        (not { CS ... !i })* .
        { ?G:String ... !k where (k = i) implies (G <> "CS") }
      end for.
      (not { CS ?any !i })* . { CS !"ENTER" !j }
     ) { max }
> true
```


MCS examples (4/4)

Livelock freedom

(there is no cycle in which each process executes an instruction but no one enters its critical section)

informatics / mathe

MCL summary

- Characterization of finite trees using cascading of (strong/weak) regular modalities
- Characterization of infinite trees using *infinite looping* operator < R > @ and the dual *saturation* operator [R] |
- Subsumes HML, ACTL, PDL, temporal patterns of Dwyer, and Transition-Based Generalized Büchi Automata (for LTL verification)
- Allows simulation of pushdown automata (context-free properties)

The quest for a powerful TL

VI. PERFORMANCE EVALUATION

Performance evaluation

• Answer to *quantitative questions* such as:

- Is the system efficient? (performance estimation)
- Which probability for a failure? (*dependability*)
- Use extended Markovian models combining
 - Functional models specified in high-level languages (e.g., LOTOS or LNT)
 - Performance data based on Markov chains

The initial picture

Extended Markovian models

Extended Markovian model = LTS (Labeled Transition System) + probabilistic transitions ("prob 0.8") +

stochastic transitions ("rate 3.1")

BCG: supported Markovian transitions

- ordinary transitions
- stochastic transitions "rate r" ($r \in R^+$)
- labeled stochastic transitions "a; rate r" ($r \in \mathbb{R}^+$)
- probabilistic transitions "prob p" ($p \in [0, 1]$)
- labeled probabilistic transitions "a; prob p" ($p \in [0, 1]$)

Markovian models supported by CADP

Model	LTS transitions	Stochastic transitions	Probabilistic transitions
LTS (Labeled Transition System)		*	×
CTMC (Continuous Time Markov Chain)	×	\checkmark	×
DTMC (Discrete Time Markov Chain)	×	×	✓
IMC (Interactive Markov Chain) [Hermanns 02]	\checkmark	\checkmark	×
IPC (<i>Interactive Probabilistic Chain</i>) [Coste 10]	\checkmark	×	\checkmark
Extended Markovian models [CADP]	\checkmark	\checkmark	\checkmark

Models subsumed by CADP's extended Markovian models (among others)

Performance evaluation techniques

• Technique #1:

- Generation of a Markovian model
- Analysis using a Markovian solver

State explosion sometimes occurs!

- Technique #2:
 - Random simulation and on-the-fly analysis

VI.1 MARKOVIAN MODEL GENERATION TOOLS

High-level Markovian models

- Functional model (e.g. in LNT)
- Two ways to model performance aspects
 - Symbolic rate transitions with ordinary labels,
 later on instantiated (i.e., renamed) with actual rates
 - Constraint-oriented compositional delay insertion
 Example: insert between successive actions A and B a delay

Α

1.10

1.23

0.01

7.89

represented by the red CTMC

Β

4.56
MCS queue lock: delay insertion (1/2)

compositionnal delay-insertion between operations

```
process Main [NCS, CS_Enter, CS_Leave: Resource_Access,
L: Lock_Access, M: Memory_Access,
Lambda, Mu, Nu: Latency]
```

is

```
par NCS, CS_Enter, CS_Leave, L, M in
    Protocol [NCS, CS_Enter, CS_Leave, L, M]
    []
    Latency [NCS, CS_Enter, CS_Leave, L, M, Lambda, Mu, Nu]
    end par
end process
```



MCS queue lock: delay insertion (2/2)

process Latency [NCS, CS_Enter, CS_Leave: Resource_Access,

L: Lock_Access, M: Memory_Access,

Lambda, Mu, Nu: Latency] is

var pid: Pid, op: Operation in

loop select

NCS (?pid); Lambda (pid)

[] L (?op, ?any Index, ?any Index, ?any Pid); Mu (op)

[] L (?op, ?any Index, ?any Index, ?any Bool, ?any Pid); Mu (op)

[] M (?op, ?any Pid, ?any Index, ?any Pid); Mu (op)

[] M (?op, ?any Pid, ?any Bool, ?any Pid); Mu (op)

[] CS_Enter (?pid); Nu (pid)

[] CS_Leave (?any Pid) -- no delay

end select end loop

end var end process



Extensions of EXP.OPEN and BCG_MIN

- BCG_MIN:
 - stochastic and probabilistic equivalences:
 strong and branching bisimulation + lumpability



- recent improvements (for extended Markovian models):
 - 500 times faster and 4 times less memory than BCG_MIN 1.0
 - minimization of graphs up to 10⁷ states and 10⁸ transitions
- EXP.OPEN:
 - parallel composition of extended Markovian models
 - no synchronization on "rate"/"prob" transitions
 - on-the-fly reduction for stochastic and probabilistic equivalences



DETERMINATOR

On-the-fly Markov chain generation

- local transformations to remove stochastic non-determinism
- determinacy check ("well specified" stochastic process)
- algorithm: variant of [Deavours-Sanders-99]
- Input:
 - On-the-fly extended Markovian model

• Output:

- either BCG graph (extended CTMC)
- or an error message



VI.2 NUMERICAL ANALYSIS OF EXTENDED MARKOVIAN MODELS

BCG_TRANSIENT

- Numerical solver for Markov chains
- Transient analysis
- Inputs:
 - Extended Markovian model in the BCG format
 - List of time instants
- Outputs:
 - Numerical data usable by Excel, Gnuplot...
- Method:
 - BCG graph converted into a sparse matrix
 - Uniformisation method to compute Poisson probabilities
 - Fox-Glynn algorithm [Stewart-94]



BCG_STEADY

- Numerical solver for Markov chains
- Steady-state analysis (equilibrium)
- Inputs:
 - Extended Markovian model in the BCG format
 - No deadlock allowed
- Outputs:
 - Numerical data usable by Excel, Gnuplot...
- Method:
 - BCG graph converted into a sparse matrix
 - Computation of a probabilistic vector solution
 - Iterative algorithm using Gauss-Seidel [Stewart-94]



VI.3 ON-THE-FLY SIMULATION OF EXTENDED MARKOVIAN MODELS



CUNCTATOR

- A steady-state random simulator for IMCs
- On-the-fly label hiding and renaming to produce a (labeled) CTMC with internal actions
- On-the-fly exploration of a sequence:



- Compute the throughput of each stochastic action "*a*; rate *r*"
- Different scheduling strategies for internal acions
- Save/restore context of simulation
- Caching of internal sequences of transitions

VII. SVL (SCRIPT VERIFICATION LANGUAGE)



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Interface: Graphics vs Scripts





Why Scripting ?

- Verification scenarios can be complex
- They can be repetitive
- Many objects/formats to handle:
 - High-level process descriptions (e.g., LNT, FSP, LOTOS)
 - Networks of communicating LTSs
 - Explicit and implicit LTSs
- Many operations to perform:
 - LTS generation of a process, a network of LTSs
 - Label hiding, label renaming
 - LTS minimization/comparison modulo equivalences
 - Verification (deadlock, livelock, temporal logic formula)

Informatics / mathematics

- Various verification techniques:
 - enumerative, on-the-fly, compositional, etc.

What is SVL?

- An acronym: *Script Verification Language*
- A language for describing (compositional) verification scenarios
- A compiler (SVL 2.1) for executing scenarios writen in this language
- A software component of CADP



SVL Components

Two types of components can be mixed

- SVL verification statements (written S)
 - Compute and store an LTS or network of LTSs in a file
 - Verify temporal properties
 - Compare LTSs, etc.
- Bourne shell constructs (lines starting with %)
 - Variables, functions, conditionals, loops, ...
 - All Unix commands



SVL Behaviours

- Algebraic expressions used in statements
- Several operators
 - Parallel composition
 - LTS generation and minimization
 - Label hiding and renaming, etc.
- Several types of behaviours
 - LTSs (several formats)
 - Networks of communicating LTSs
 - LNT, LOTOS, and FSP descriptions
 - Particular processes in LNT, LOTOS, and FSP descriptions



Abstract Syntax of Behaviours

$$B ::= "F.bcg" | "F.aut" | "F.seq" | "F.exp"$$

$$| "F.Int" | "F.Int" : P [G_{1}, ..., G_{n}]$$

$$| "F.lotos" | "F.lotos" : P [G_{1}, ..., G_{n}]$$

$$| "F.lts" | "F.lts" : P [G_{1}, ..., G_{n}]$$

$$| B_{1} | [G_{1}, ..., G_{n}] | B_{2} | B_{1} | | | B_{2} | B_{1} | | B_{2}$$

$$| par G_{1}, ..., G_{n} in \\ [G_{0,1}, ..., G_{0,m1} \rightarrow] B_{0} | | ... | | [G_{p,1}, ..., G_{p,mp} \rightarrow] B_{p} end par$$

$$| generation of B_{0}$$

$$| R reduction [with T] of B_{0}$$

$$| [S] hide [all but] L_{1}, ..., L_{n} in B_{0}$$

$$| [S] rename L_{1} \rightarrow L_{1}', ..., L_{n} \rightarrow L_{n}' in B_{0}$$

$$| [user] abstraction B_{1}[sync G_{1}, ..., G_{n}] of B_{2}$$



Explicit LTSs

- States and transitions listed exhaustively
- LTSs in several formats

B ::= "F.bcg"Binary Coded Graphs| "F.aut"Aldébaran ASCII format| "F.seq"Set of traces

Format conversions are fully automatic



Implicit LTSs

- LNT, LOTOS, or FSP descriptions ("F.Int", "F.lotos", "F.lts")
- Particular LNT, LOTOS, or FSP processes
 ("F.Int": P [G₁, ..., G_n], ...)
- Networks of communicating automata ("F.exp")



Explicit vs Implicit LTSs

SVL principles:

- Keep LTSs implicit as long as possible
 - Explicit LTS generation is expensive (state explosion)
 - Not all properties necessitate to explore the whole LTS
- Explicit LTS generation is done only if required explicitly by the user



LTS Generation

Conversion from an implicit LTS to an explicit LTS

B ::= generation of **B**₀

Examples

- generation of "spec.Int"
 Use LNT.OPEN and GENERATOR
- generation of "spec.Int" : P [G]

Use LNT.OPEN (option –root) and GENERATOR

– generation of "spec.exp"

Use EXP.OPEN and GENERATOR

generation of par G₁ in "spec₁.bcg" || "spec₂.aut" end par
 Use EXP.OPEN and Generator



Parallel Composition

$$B ::= B_{1} | [G_{1}, ..., G_{n}] | B_{2} | B_{1} | | | B_{2} | B_{1} | | B_{2} | par G_{1}, ..., G_{n} in [G_{0,1}, ..., G_{0,m0} \rightarrow] B_{0} | | ... | | [G_{p,1}, ..., G_{p,mp} \rightarrow] B_{p} end par | LNT$$

LOTOS and LNT operators

 $\bullet B_1, B_2, \dots$ can be LTSs, but also any SVL behaviour

Generation of intermediate EXP.OPEN files

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Label Hiding

 $B ::= [M] \text{ hide } L_{1}, ..., L_{n} \text{ in } B_{0}$ | [M] hide all but $L_{1}, ..., L_{n} \text{ in } B_{0}$

- An extension of LOTOS hiding, where
 - L is either
 - a gate name
 - a label string (e.g. "G !3.14 !TRUE")
 - a regular expression (e.g. "G !.* !TRUE")
 - M ::= gate | total | partial is a matching semantics for regular expressions
 - all but means complementation of the set of labels
- Tools used: BCG_LABELS or EXP.OPEN



Label Hiding: Examples

[gate] hide G, H in "test.bcg"

invokes BCG_LABELS (-hide) and returns an LTS in which labels whose gate is G or H are hidden

total hide "G ![AB].*" in "test.bcg"

invokes **BCG_LABELS** and returns an LTS in which labels matching "G ![AB].*" are hidden

partial hide G in "test.bcg"

invokes **BCG_LABELS** and returns an LTS in which labels containing G are hidden



Label Renaming

 $B ::= [M] \text{ rename } L_1 \rightarrow L_1', ..., L_n \rightarrow L_n' \text{ in } B_0$

where

- each $L \rightarrow L'$ is a Unix-like substitution containing regular expressions
- M is a matching semantics

M ::= gate | total | single | multiple

• Tools used: BCG_LABELS or EXP.OPEN



Label Renaming: Examples

[gate] rename $G \rightarrow H, H \rightarrow G$ in "test.bcg"

invokes BCG LABELS (-rename) and returns LTS in which gate G is renamed into H and H into G total rename "G !A !TRUE" \rightarrow "A TRUE" in "test.bcg" invokes **BCG** LABELS and returns an LTS in which label "G !A !TRUE" is renamed into A TRUE total rename "G !\(.*\) !\(.*\)" \rightarrow "G \2 \1" in "test.bcg" invokes **BCG** LABELS and returns an LTS in which offers of labels whose gate is G are swapped

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Reduction (Minimization)

LTS Minimization modulo an equivalence relation

B ::= R reduction [with T] of B_0

• Several relations R

[probabilistic|stochastic] strong, branching, safety, tau*.a, (weak) trace, tau-confluence, tau-compression, tau-divergence, etc.

Several tools T

bcg_min, reductor

Tools used: BCG_MIN or REDUCTOR



Reduction: Examples

- strong reduction of "test.bcg" [with bcg_min] invokes BCG_MIN (default tool for strong bisimulation) and returns an LTS minimized for strong bisimulation
- stochastic branching reduction of "test.bcg" invokes BCG_MIN (default tool for branching bisimulation) and returns an LTS minimized for stochastic branching bisimulation
- trace reduction of "test.bcg" [with reductor] invokes BCG_OPEN/REDUCTOR and returns an LTS minimized for trace equivalence



Abstraction

• LTS generation of B_2 abstracted w.r.t. interface B_1

B ::= abstraction B₁ of B₂

user abstraction B₁ of B₂

• Equivalent syntax

 $B ::= B_2 - || B_1$ $| B_2 - ||? B_1$

where ? has the same meaning as user

- Invokes PROJECTOR
- Detailed in Section on Compositional verification (later)



Other operators

- Priorities between transitions (invokes EXP.OPEN)
- Transition cutting (invokes EXP.OPEN)
- Particular automata (invokes BCG_GRAPH):
 - stop (empty automaton)
 - chaos automaton (parameterized by a set of labels)
 - FIFO or bag buffer (parameterized by a size and receive/send sets of labels)



Abstract Syntax of Statements

$S ::= "F.E" = B_0$

- "F.E" = R comparison B_1 [== | <= | >=] B_2
 - "F.E" = deadlock [with T] of B_0
 - "F.E" = livelock [with T] of B_0
 - $["F_1.E" =]$ verify " $F_2.mcl"$ in B_0

Assignment Statement

 $S ::= "F.E" = B_0$

- Computes B_0 and stores it in file "F.E"
- Extension E tells the format for "F.E" (aut, bcg, exp, or seq, but not Int, lotos, Its)
- Principles:
 - Format conversions are implicit (BCG_IO)

e.g. "spec.bcg" = "spec.aut" is permitted

No implicit LTS generation

If *E* is an explicit LTS format (i.e. all but *exp*) then B_0 must not denote an implicit LTS \Rightarrow generation must be used explicitly (otherwise a warning is issued)

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Comparison of Behaviours

- S ::= "F.E" = R comparison $B_1 == B_2$
 - "F.E" = R comparison $B_1 \le B_2$
 - | "F.E" = R comparison $B_1 >= B_2$
- Compares B₁ and B₂ and stores the distinguishing path(s) (if any) in "F.E"
- Equivalence or preorders
- Several relations R
- Invokes BISIMULATOR



Deadlock and Livelock Checking

 $S ::= "F.E" = \text{deadlock} [\text{with } T] \text{ of } B_0$ $| "F.E" = \text{livelock} [\text{with } T] \text{ of } B_0$

- Detects deadlocks or livelocks using tool T (*exhibitor* or *evaluator*)
- Results in a (set of) paths leading to deadlock or livelock states (if any) and stored in "F.E"
- Verification may be on-the-fly (EXHIBITOR or EVALUATOR with OPEN/CÆSAR)



Temporal Property Verification

 $S ::= ["F_1.E" =]$ verify " $F_2.mcl"$ in B_0

- Checks whether B₀ satisfies the temporal logic property contained in "F₂.mcl"
- May generate a diagnostic and store it in "F₁.E" (example or counter-example which explains the resulting truth value)
- Verification may be on-the-fly (OPEN/CAESAR and EVALUATOR)



Shell Constructs in SVL Scripts

Shell commands can be inserted (%)

- Direct call to Unix commands ("echo"...)
- Setting of SVL shell variables
 - % DEFAULT_REDUCTION_RELATION=branching
 - % GENERATOR_OPTIONS=-monitor
- Enables the use of all shell control structures
 - "if-then-else" conditional
 - "for" loop
 - function definitions
 - etc.



Compositional Verification (key features)

- Support for basic compositional verification
 Example: alternating bit protocol
- Script Simplification using meta-operations
- Support for refined compositional verification
 Example: rel/REL protocol
- Support for smart heuristics
- Compositional Performance Evaluation
 Examples: SCSI-2 and Mutual Exclusion Protocols
Meta-operations

B ::= leaf R reduction [with T] of B₀
| root leaf R reduction [with T] of B₀
| node R reduction [with T] of B₀

- Three "static" compositional verification strategies:
 - Reduction of LTSs at the leaves of parallel compositions in B_0
 - Reduction of LTSs at the leaves of parallel composition in B_0 and then reduction of the whole behaviour
 - Reduction at every node of B_0
- Meta-operations expand to basic SVL behaviours



The Abstraction Behaviour

- Implements refined compositional verification
- The LTS of a behaviour *B* may be larger than the LTS of a behaviour containing *B* because of *context constraints*
- Example

par G in

par in "User1.bcg" || "User2.bcg" end par
|| "Medium.bcg"

end par

"Medium.bcg" may constrain the interleaving

 Restrict the interleaving using abstraction: par in "User1.bcg" || "User2.bcg" end par -[[G]] "Medium.bcg"



Smart heuristics

B ::= smart R reduction [with T] of B₀

- Compositional verification strategy determined by a metric on B₀
- Incrementally select the subset of concurrent processes to compose and minimize, that:
 - yield as much internal transitions as possible (likely eliminated by reduction) and
 - are as tightly coupled as possible (less interleaving)
- Necessarily approximate
 - the heuristics consider both reachable and unreachable transitions
- Most often: good results, especially on large networks



SVL example: verification of MCS

```
% DEFAULT_PROCESS_FILE="mcs.lnt"
% DEFAULT_SMART_LIMIT=7
```

```
"mcs.bcg" = smart branching reduction of
hide all but CS_ENTER, CS_LEAVE in
par M, L in
par in P1 || P2 || P3 || P4 || P5 end par
||
par in Lock || Memory end par
end par;
```

"mcs_diag_branching.bcg" = branching comparison
"mcs.bcg" == Service;



VIII. CONCLUSION



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Further features of CADP

- Cosimulation and rapid prototyping (EXEC/CÆSAR framework)
- Test generation (TGV)
- XTL query language on BCG graphs
- Distributed BES resolution (work in progress)



Distribution of CADP

- Commercial license for industrial users
- Free distribution to academic users
 - Until July 2011:
 - signed paper contract with the academic organization
 - one license per machine
 - Since July 2011:
 - personal license for each CADP user, authenticated by valid academic email address and academic web page
 - license terms available in French and in English
- http://cadp.inria.fr/registration

Some figures about CADP

Wide dissemination

- \geq 441 academic license contracts
- CADP installed on 613 machines in 2011
- ≥ 139 published case studies using CADP since 1990 (<u>http://cadp.inria.fr/case-studies</u>)
- ≥ 57 third-party tools connected to CADP since 1996 (<u>http://cadp.inria.fr/software</u>)
- ≥ 196 users and ≥ 1300 messages in the CADP forum since 2007 (<u>http://cadp.inria.fr/forum.html</u>)
- Various supported architectures
 - processors: Itanium, PowerPC, Sparc, x86, x64
 - operating systems: Linux, MacOS X, Solaris, Windows
 - C compilers: gcc3, gcc4, Intel, Sun
- Significant testing effort (Contributor tool)

A promising future

- Ubiquitous concurrency
 - Hardware: multi-/many-core CPUs, clusters, grids, clouds
 - Software: concurrency required to exploit new hardware
- Industry awareness
 - Increasing need for hardware and software reliability
 - Models (even non-formal) become standard practice
- "Applied concurrency" starts being effective



For more information...

 CADP Web site: <u>http://cadp.inria.fr</u>

• CADP forum:

http://cadp.inria.fr/forum.html http://cadp.forumotion.com

• CADP on-line manual pages: <u>http://cadp.inria.fr/man</u>





