

# The SOMMA model: cortically inspired maps for multimodal learning

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## The SOMMA model: cortically inspired maps for multimodal learning



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#### Aim:

- to learn correlations (meaning recurrent spatial patterns) from a multimodal
- to generalize these correlations in order to adapt to unknown situations

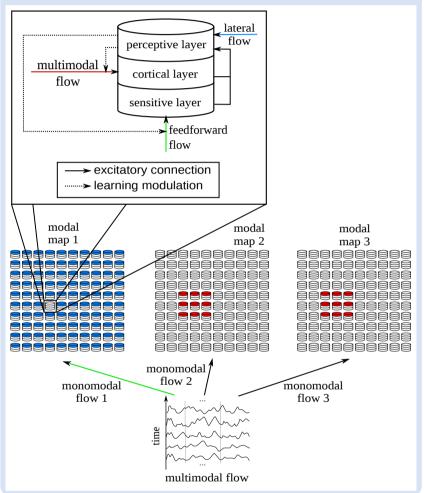
#### Constraints:

- connectionist paradigm: computation is local, generic and decentralized
- learning is continuous and unsupervized

#### Means:

- 1) splitting of the data flow into multiple monomodal flows
- 2) self-organization of monomodal correlations in low dimension topology
- 3) reciprocal and topological connections between monomodal maps
- 4) learning of multimodal correlations by constrained monomodal self-organizations

#### **Architecture:**



#### **Dynamics:**

stimulus

with a tabular coding in the sensitive layer 888 ē 

A

88 8

1 - autonomous emergence of a representation of the current stimulus

2 - emergence of a monomodal perception in the perceptive layer

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3 - each perception influences the other ones via the cortical layer

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4) resonance between maps converges to an unified multimodal perception

e 

88 

#### **Model description:**

- sensitive layer provides a tabular coding of the current stimulus
- cortical layer provides information from the other monomodal perceptions
- perceptive layer (dynamic neural fields) represents, by a spatial coding, the perception of the current stimulus as a consensus between the local (monomodal) and the multimodal activities

#### Learning description:

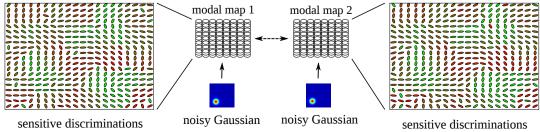
#### afferent weights:

- BCMu learning rule: discrimination of a correlation in the feedforward flow
- modulation by the perceptive activity combined with a synaptic regulation term: provides the multimodal self-organization of the discriminations

#### multimodal weights:

Widrow Hoff learning rule: the cortical activity converges on the perceptive one

#### **Results:**



a multimodal stimulus is made up of the same stimulus for each modality (here a Gaussian whose location is random)

The bidimensional localisation of each sensitive discriminated Gaussian is represented by the orientation and the color of the bar.

#### We can observe

1) the self-organization of the modal correlations in each modal map 2) as the same input is provided to both maps, the learning of multimodal correlations forces the modal selforganizations to be similar