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A Mechanized Semantics for C++ Object Construction and Destruction, with Applications to Resource Management

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Abstract

We present a formal operational semantics and its Coq mechanization for the C++ object model, featuring object construction and destruction, shared and repeated multiple inheritance, and virtual function call dispatch. These are key C++ language features for high-level system programming, in particular for predictable and reliable resource management. This paper is the first to present a formal mechanized account of the metatheory of construction and destruction in C++, and applications to popular programming techniques such as “resource acquisition is initialization.” We also report on irregularities and apparent contradictions in the ISO C++03 and C++11 standards.

Categories and Subject Descriptors D.1.5 [Programming techniques]: Object-oriented Programming; D.2.0 [Software Engineering]: General—Standards; D.2.2 [Software Engineering]: Design Tools and Techniques—Object-oriented design methods; D.2.4 [Software Engineering]: Software/Program Verification—Correctness proofs; D.3.3 [Programming Languages]: Language Constructs and Features—Classes and objects, Inheritance; F.3.3 [Logics and meanings of programs]: Studies of program constructs—Object-oriented constructs

General Terms Languages, Verification

1. Introduction

One of the earliest decisions for C++ (in 1979) was to provide language support for the construction and destruction of objects [13], programmer-supplied code fragments called constructors are automatically executed when a new object is created and before it is made available to the rest of the program; these constructors can execute arbitrary code sequences and are intended to establish the execution environment for operations by initializing fields and maintaining class-level invariants. Symmetrically, the language also supports destructors, which are executed before an object is destroyed at precisely-defined times. Such general constructors are now available in most programming languages supporting object-oriented programming. Many languages also provides some support for clean-up of objects at the end of their lifetime, e.g. finalizers executed asynchronously at loosely-specified times or dispose statements allowing a programmer to explicitly request clean-up.

Because it is enforced by the programming language itself and not by coding conventions, the object construction and destruction protocol provides strong guarantees that can be leveraged by good programming practices. This is the case for Resource Acquisition Is Initialization (RAII), a popular C++ programming idiom for safely managing system resources such as file descriptors. With RAII, resource acquisition is always performed in constructors, and resource release in the corresponding destructors. Since C++ guarantees that every execution of a constructor is eventually matched by an execution of a destructor, RAII minimizes the risk of leaking resources.

As practically useful as they are, constructors and destructors raise delicate issues for the programmers, for static analysis tools, and even for language designers. While an object is being constructed or destructed, it is not in a fully operational state. This raises the question of what operations constructor/destructor code should be allowed to perform on this object, and what semantics to give to these operations. A typical example of this dilemma is virtual method dispatch: in Java and C#, unrestricted virtual method calls are allowed in constructors, with the same semantics as on fully constructed objects; in contrast, C++ takes object construction states into account when resolving virtual function calls, in a way that provides stronger soundness guarantees but complicates semantics and compilation. Section 2 reviews the main features of C++ object construction and destruction.

This paper reports on a formal, mechanized semantics for construction and destruction in the C++ object model. This model is especially rich: it features multiple inheritance (both shared and repeated), fields of structure and structure array types, as well as sub-tle interactions between construction states, virtual function calls, and dynamic casts. Our semantics, fully mechanized in the Coq proof assistant, is, to the best of our knowledge, the first to capture faithfully these interactions as intended by the C++ standard.

This semantics, described in section 3, is the first contribution of the paper.

The second contribution, in section 4, is the specification and formal verification of several expected properties of the construction/destruction protocol, ranging from common-sense properties such as “any subobject is constructed, or destroyed, at most once” to the first precise characterization of the properties that make the RAII programming idiom work in practice. We also study the evolutions of the dynamic types of objects throughout their life cycle and formally justify the program points where compilers must generate code to update dynamic types (v-tables).

As a third contribution, this work exposes some irregularities and apparent contradictions in the ISO C++03 and C++11 stan-

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II. No object construction should rely on parts yet to be con-
struction, and no object destruction should rely on parts already
destroyed.
III. Every object is destroyed in the exact reverse order it was
constructed. The C++ construction and destruction mechanism is rooted
in a few design principles:

I. Every object and each of its subobjects (if any) is constructed
everyone, and where the class’s member functions will operate

II. Object construction and destruction in C++
A constructor is a special function that turns “raw memory” into
an object. Its purpose is to create an environment where class in-
vants hold, and where the class’s member functions will operate

C++’s object construction and destruction mechanism is rooted
in a few design principles:

I. Every object and each of its subobjects (if any) is constructed

II. No object construction should rely on parts yet to be con-
structed, and no object destruction should rely on parts already
destroyed.
III. Every object is destroyed in the exact reverse order it was
constructed.

These principles, independently of implementation considerations,
enable support for reliable, modular, large-scale software develop-
ment.

Principle I supports the idea that a resource acquired by an
object (say a file lock) is predictably acquired exactly once.

Principle II embodies a notion of locality and copying. While the
constructor is creating the computation environment for member
functions, very few class guarantees can be made. It is desirable
to localize the complexity and/or convolution needed to correctly
call a function in a few specific places before an object begins its
lifetime. Furthermore, the author of a class should not have to worry
about which data members of possible derived classes are correctly
initialized during the execution of a constructor. On the other hand,
she should be able to rely on base-class invariants. Consider the follow-
ing example:

```cpp
struct Locus {
    Locus(int a, int b) : x(a), y(b) { show(); }  
    virtual void show() const {
        cout << x << ' ' << y << endl;
    }

    int x;
    int y;
};

struct FeaturedLocus : Locus {
    FeaturedLocus(int a, int b, const vector& v) : Locus(a, b), features(v) {
        show();
    }

    void show() const {
        cout << x << ' ' << y << ' ' << features << endl;
    }

    private:
    vector features;
};
```

Construction of a FeaturedLocus object entails constructing its
Locus base-class subobject, followed by copy-initialization of its
features field from the v parameter. If, in the Locus constructor,
the call to the virtual function show resolved to the final overrider
FeaturedLocus::show (as in Java or C#), it would access the yet-
to-be-constructed field FeaturedLocus::features—an undesirable
and unpleasant outcome. Consequently, Principle II argues for re-
solving the call (in the constructor) to an overrider not from a de-
rived class; here it is Locus::show.

Finally, Principle III supports predictability and reliability. For
instance, if an object acquires N resources through the construction
of its subobjects, in general one would want to release them in the
reverse order of acquisition, or else a deadlock might ensue.

Turning these general principles (and their implications) into
executable specification in the face of object-oriented language fea-
tures such as multiple inheritance (both repeated and shared), late
binding function dispatch (virtual function calls), type queries, etc.
is an interesting challenge. On the other hand, their fulfillment
leads to interesting soundness results and, more importantly, reli-
able software development techniques for the programmer.

Initialization versus assignment There is a difference between
initialization and “declaration followed by a first-time assignment”.
And it is not a stylistic distinction. Base-class subobjects and non-
static data members are constructed before the proper body of the
constructor is executed. Initializers for subobjects are speci-
fied in a comma-separated list before the opening brace of a con-
structor body (see the definition of the constructors for Locus and
FeaturedLocus in the previous example.) In particular, there is no
other way to initialize base-class subobjects, const or reference
nonstatic data members. A base-class subobject, or a nonstatic data
member, not mentioned in the member-initializer list is implicitly
initialized with a default constructor, i.e. a constructor that can be
called with no argument. Consequently, the language rules imply
that all subobjects are constructed by the time the first statement of
the constructor body (if not empty) is executed. The constructor for
FeaturedLocus could have been written as

```cpp
FeaturedLocus(int a, int b, const vector& v) :
    Locus(a, b) {
        features = v;
    }
```

In this variation, the Locus base-class subobject is initialized; the
nonstatic data member features is default constructed, and finally
the constructor body assigns the value of v to features. In C++,
assignments of objects of class types are generally implemented by
user-defined functions. These functions must assume that the left
hand side of the assignment is an object already constructed and
in a valid state. In particular, vector’s assignment function must
carefully check for self-assignment to avoid premature memory re-
lease; it must properly release the resources the object was manag-
aging before taking hold on the new ones. By contrast, during copy-
construction, the object being constructed has not acquired any re-
sources yet; so the implementation code of the copy-constructor is
usually far simpler than that for assignment.

Initialization order Principle III has an interesting implication on
the construction order of the constituents of an object. Observe that
there is exactly one destructor per class, and that there can be as
many constructors (per class) as deemed necessary by the program-
mer. Therefore, for a given class, subobjects in all constructors must
be initialized in the same order — for that order must be the reverse
destruction order of the (unique) destructor. Any well-defined order
can do. However, for simplicity, a natural choice is the declaration

```cpp
private:
    vector features;
};
```

II. Every object is destroyed in the exact reverse order it was
constructed. The Coq development is available
at [http://gallium.inria.fr/~tramanan/cxx/](http://gallium.inria.fr/~tramanan/cxx/) By lack of
space, some aspects of the semantics are only sketched in this
paper. A full description can be found in the first author’s Ph.D.
thesis [12, part 2].
order: initialization of all base-class subobjects in the (left-to-right) order of declaration in the class definition; followed by initialization of all nonstatic data members in their order of declarations in the class definition.

This construction order is simple, predictable, and reflects the compositional aspect of “class growth”. However, shared inheritance (virtual base classes) poses a problem for the principle of “base before derived” and “strict order of declaration construction”. Indeed, consider the following hierarchy of IO stream classes:

```
struct istream : virtual basic_ios { ... ;
struct ostream : virtual basic_ios { ... ;
struct iostream : istream, ostream { ... ;
```

where the class basic_ios maintains states and implements operations common to both input and output streams; the classes istream and ostream implement input and output stream functionalities. The class iostream combines both input and output facilities. If an iostream object was to be constructed according to the declaration order outlined above, the corresponding basic_ios base-class subobject would be constructed twice: once when the istream base-class subobject is constructed, and a second time when the ostream base-class subobject is constructed. This problem is resolved by executing constructors for virtual bases (in declaration order) before all other constructors. More generally, C++ retains the following *almost-declaration order* construction for a complete object, also depicted on Figure 1.

1. virtual base-class subobjects are constructed in a depth-first left-to-right traversal of the inheritance graph;
2. direct non-virtual base-class subobjects are constructed in declaration order;
3. nonstatic data members are constructed in declaration order.

**Built-in object types** The C++ programming language was designed with two competing ideals: a sound high-level object model with equal support for user-defined types and built-in types, and a near-total compatibility with C for system programming. The resulting tension has made the general model of object construction and destruction grow barnacles. Indeed, C lacks the notion of object construction so central to C++’s object model. But, in reality, both languages agree on the semantics of programs that read from uninitialized objects: undefined behavior, except in very limited cases where a read access is done as “raw memory”. In C, object initialization is usually expressed in terms of storage acquisition followed by assignment; C++ distinguishes assignment from construction. To achieve the same ultimate semantics and to support generic programming, C++ extended the notion of constructor (and destructor) to built-in types. A built-in data member can be explicitly initialized with default value using the default construction syntax:

```
struct Locus { Locus() : x(), y() { } ;
```

Here, the default constructor Locus explicitly constructs the data members x and y with a default value (zero) so that in the complete object declaration “Locus origin;”, the origin object has its coordinates initialized to zero. Would the semantics be the same where a read access is done as “raw memory”. In C, object initializers were x and y not explicitly listed in the member-initializer list? The answer is no: objects of built-in type with no explicit initializers are constructed but, left with indeterminate values. This irregularity was introduced as a way to satisfy the widespread practice in C where objects are given first-time values long after their declaration. This irregularity, and others related to destructors for built-in types, surely complicate the C++ semantics rules as well as formalization. However, they are not fundamental to the object model. In fact, the C++ standards committee is considering unifying initialization and lifetime rules in a post-C++11 standard. We hope this work will help in that endeavor.

### 3. Formal operational semantics

#### 3.1 Syntax of the core language

We focus on a core language of objects that features the main aspects of the C++ object model: construction and destruction; multiple inheritance (both virtual and non-virtual), virtual functions, and nonstatic data members (a.k.a. “fields”) of scalar, array or complete non-abstract object types. To simplify the presentation, we formalize only fields that are arrays of object types, viewing a field of object type T as a one-element array of type “T[1]”.

The core language is a language of statements operating over variables in 3-address style. We assume that type checking was performed, static overloading was resolved, and expressions were decomposed into elementary statements. The syntax of statements follows.

```
Op, . . . : Op
Var, . . . : Var
B, C, . . . : Class
fname : Field
mname : Method
Stmt := skip
      | var' := op(var*)
      | var' := var>Cfname
      | var' := &var[’var[’index]C
      | var' := dynamic_cast(B)C(var)
      | var' := C var[’var[’count] = (ObjInit*); Stmt
```

The Coq formalization also features simple control structures (if/then/else, infinite loops with early exits), as well as static casts. We leave these extra features out in this paper to concentrate on the essential features of the language; accesses to fields; virtual function calls; dynamic casts; and block-scoped objects. The statement `{ C var[N] = (ObjInit*); Stmt }` allocates an array of N objects of type C, constructs each of its elements according to the list of initializers ObjInit, binds the array to variable x, executes the block body Stmt, destructs each element of the array x, and finally deallocates the whole array.

Initializers are syntactically presented in C++ as constructor calls with expressions as arguments. Since our language lacks expressions, we model initializers as a statement (which evaluates the expression arguments into temporary variables) followed by an invocation of a constructor for object fields or the initialization of a scalar field.
Objects to functions and constructors can be scalar values, i.e.,
integers, or floating point data, or pointers to objects. We do not
model passing objects by value; this raises delicate issues with the
construction and destruction of temporary objects, discussed in \cite{13}.

\begin{equation}
\begin{aligned}
\text{ObjInit} & ::= \text{Stmt} ; C(\text{var}^*) & \quad \text{Class object initializer} \\
\text{FieldInit} & ::= (\text{Stmt} ; \text{fname}(\text{var})) & \quad \text{Scalar field initializer} \\
& | \text{fname} \{ \text{ObjInit}\} & \quad \text{Structure field} \\
& | \text{ofstream} & \quad \text{initializers (one for} \\
& & \text{each array cell)}
\end{aligned}
\end{equation}

Arguments to functions and constructors can be scalar values, i.e.,
integers, or floating point data, or pointers to objects. We do not
model passing objects by value; this raises delicate issues with the
construction and destruction of temporary objects, discussed in \cite{13}.

\begin{equation}
\begin{aligned}
\text{Constr} & ::= C(\text{var}^*) : \text{Init}^*(\text{Stmt}) & \quad \text{Constructor} \\
\text{Destr} & ::= \sim C()\{\text{Stmt}\} & \quad \text{Destructor} \\
\text{MethodDef} & ::= \text{virtual} \{\text{fname}(\text{var})\}\{\text{Stmt}\} & \quad \text{Virtual function} \\
& | \text{struct} C(\text{size})\{\text{fname};} & \quad \text{Data member} \\
& | \text{virtual} \{\text{fname}\} & \quad \text{(method)} \\
& | \text{FieldDef} & \quad \text{field} \\
\text{Base} & ::= B \mid \text{virtual} B & \quad \text{Base class} \\
\text{ClassDef} & ::= \text{struct} C : \text{Base}^* & \quad \text{Class definition} \\
& \{ \text{FieldDef}^* \mid \text{MethodDef}^* \} & \quad \text{Base class (one for each} \\
& \mid \text{Constr} \mid \text{Destr} & \quad \text{virtual base of} \\
\text{Program} & ::= \text{ClassDef}^* ; \quad \text{Program} \\
& | \text{main}()\{\text{Stmt}\} & \quad \text{Program}
\end{aligned}
\end{equation}

A complete program consists of a hierarchy of classes. Each class
definition contains a list of virtual and non-virtual base classes, a
list of data members (a.k.a. fields), definitions for virtual functions
(a.k.a. methods), one or several constructors, and one destructor.
Each constructor consists of a parameter list, a sequence of initi-
izers (for direct non-virtual bases, fields, and direct or indirect
virtual bases), and a constructor body (an arbitrary statement). De-
structors take no parameters and consist only of a body.

\subsection{Designating subobjects}

A crucial issue in formalizing the C++ object model is to capture the
fact that each object of a class \(C\) contains \textit{subobjects}, one for each
base and each field of \(C\). Subobjects can be arbitrarily nested, but
can also be shared along several inheritance paths, owing to virtual
inheritance. For this reason, a subobject cannot be identified by a
store locations \(\ell\); instead, it is described by a pair of the location \(\ell\)
of the array of complete objects containing it, and a \textit{path} from this
array to the desired subobject. Intuitively, a path is a sequence of
selection operations of the form “select a base class” or “select a
field” or “select an element of an array”. This path-based approach
was introduced by Rousie and Friedman \cite{14}, later mechanized in
Isabelle/HOL by Wasserrab et al. \cite{15}, and further extended with
structure array fields and mechanized in Coq by Ramananandro
et al. \cite{14}. We now briefly recall this path-based formalization,
referring the reader to \cite{15} for full details.

An \textit{inheritance path} \(\sigma\) is a pair \((h, l)\) of an inheritance kind
\(h \ ::= \text{Repeated} \mid \text{Shared} \mid \text{a list of class names} l\). Such a path
designates a \textit{base-class subobject} of some type \(A\) of an object \(C\) of
type \(C\). If \(h = \text{Repeated}\), it is a path through the \textit{repeated}, or \textit{non-
virtual}, inheritance graph. Each path from \(C\) to \(A\) corresponds to
a distinct copy of \(A\) within \(C\). If \(h = \text{Shared}\), it is a path from a
virtual base \(B\) of \(C\) to \(A\), regardless of how the virtual base \(B\) is
reached.

Not all paths are valid with respect to the class hierarchy. The
following inference rules define the relation \(C \sim (\text{Repeated}, C :: \epsilon) \to A\),
meaning that \((h, l)\) is a valid inheritance path from \(C\) to a
base-class subobject of \(C\) of static type \(A\).

\begin{equation}
\begin{aligned}
C \sim (\text{Repeated}, C :: \epsilon) \to A & \quad \text{B direct non-virtual base of } C \\
C \sim (\text{Repeated}, C :: l) \to A & \quad \text{C direct virtual base of } C
\end{aligned}
\end{equation}

An object is said to be a \textit{most-derived} object if, and only if, it
is not a base-class subobject of any other object. A most-derived
object of type \(C\) is designated by the trivial inheritance path
\((\text{Repeated}, C :: \epsilon)\).

Inheritance paths compose naturally: if \(C \sim (h, l) \overset{\sim}{\to} A\) and
\(B \sim (h', l') \overset{\sim}{\to} A\), we have \(C \sim (h, l) \overset{\sim}{\to} A\), whereas through virtual
inheritance, we have \((h, l) \overset{\sim}{\to} (\text{Shared}, l') = (\text{Shared}, l')\). (We
write \(=\) for list concatenation.)

In the presence of fields that are structures or arrays of structures,
the notions of paths and subobjects must be extended to allow
selecting elements of arrays of structures. Ramananandro et al.
\cite{13} define \textit{array paths} as lists of \((i, \sigma, F)\) triples, where \(i\) is
an array index, \(\sigma\) an inheritance path, and \(F\) the name of a structure
array field. An array path goes from an array of \(n\) structures of
type \(C\) to an array of \(n'\) structures of type \(C'\), which we write
\(C[n] \sim (\sigma) \sim C'[n']\) and define by the inference rules below. An
auxiliary predicate \(C[n'] \sim (\sigma, \epsilon) \sim C'[n']\) captures the selection of
the \(i\)-th element of an array followed by the extraction of a base-class
subobject \(\sigma\) of type \(A\).

\begin{equation}
\begin{aligned}
0 \leq i < n & \quad C[n] \overset{\sim}{\to} (\sigma) \overset{\sim}{\to} A & \quad 0 \leq n' \leq n \\
C[n] \overset{\sim}{\to} (\sigma) \overset{\sim}{\to} A & \quad C[n'] \overset{\sim}{\to} (\epsilon) \overset{\sim}{\to} A
\end{aligned}
\end{equation}

In the core language of \cite{13} a \textit{complete object} (bound to a
variable \(x\) by a block statement) is always an array of structures,
with type \(C[n]\). A \textit{subobject} of type \(A\) of such a complete object is.
therefore, a triple \((\alpha, i, \sigma)\) where \(\alpha\) is an array path from \(C[n]\)
to some \(C'[n']\) and \(i \in [0, n']\) is an index in the array of type \(C'[n']\)
and \(\sigma\) is the inheritance path for a base-class subobject of \(C'\)
of type \(A\). We write \(C[n] \sim (\alpha, i, \sigma) \overset{\sim}{\to} A\) to mean that \((\alpha, i, \sigma)\)
designates a valid subobject of type \(A\) of the array \(C[n]\). This
relation is defined by:

\begin{equation}
\begin{aligned}
C[n] \sim (\alpha) \overset{\sim}{\to} C'[n'] & \quad C[n'] \sim (i, \sigma) \overset{\sim}{\to} A \\
C[n] \sim (\alpha, i, \sigma) \overset{\sim}{\to} A & \quad C'[n'] \sim (i, \sigma) \overset{\sim}{\to} A
\end{aligned}
\end{equation}

Then, a subobject of a complete \(C\) object is a most-derived \(C'\)
object if, and only if, it can be written as \((\alpha, i, \sigma)\) \((\text{Repeated}, C' :: \epsilon)\)
where \(C[n] \sim (\alpha) \overset{\sim}{\to} C'[n']\) and \(0 \leq i < n'\). In practice, this means
that a most-derived object corresponds to a cell of a structure array,
the array being either the complete \(C\) object itself \((\alpha = \epsilon)\) or some
structure field of a subobject of the complete object.

Our operational semantics uses these notions to unambiguously
identify complete objects by locations \(\ell\) in the store, subobjects by
pairs \((\ell, (\alpha, i, \sigma))\) of a location and a subobject, and fields by triples
\((\ell, (\alpha, i, \sigma), f)\) of a subobject of some type \(A\) and a name \(f\) of
field declared in \(A\).

\subsection{Construction states}

In the C++ language, the behaviors of operations over objects depend
on the \textit{construction state} of these objects. For example,
it is not possible to invoke a virtual function of a class \(C\) if the
base classes of \(C\) have not been constructed yet, or are undergoing
destruction. Likewise, as described in §6, virtual method dispatch behaves differently when a most-derived object is fully constructed and when it is undergoing construction or destruction.

Our operational semantics therefore associates a construction state to every subobject and every field, and updates these states during construction and destruction steps. A given subobject can be in one of 7 construction states, whose meanings differ slightly depending on whether the subobject is a most-derived subobject (e.g., an element of a structure array) or a base-class subobject. For a most-derived object, the construction states and their meanings are:

1. Unconstructed: Construction has not started yet.
2. StartedConstructing: The construction of base-class subobjects has started, but not the fields.
3. BasesConstructed: The base-class subobjects are completely constructed. Now constructing the fields or executing the constructor body.
4. Constructed: The constructor body has returned, and destruction has not started yet.
5. StartedDestructing: The body of the destructor is executing or the fields are undergoing destruction.
6. DestructingBases: The fields have been completely destructed. Bases are undergoing destruction.
7. Destructed: All bases and fields have been destructed.

For a base-class subobject, we need to exclude virtual bases from the meaning of its construction state. Indeed, as discussed in §2 and shown in Figure 1, virtual bases are morally attached to the enclosing most-derived object, not to the base-class subobject. Therefore, for those base class subobjects that are not most-derived objects, we reinterpret four of the construction states as follows:

1. Unconstructed: Construction of the non-virtual part has not started yet. However, virtual bases may have been already constructed.
2. StartedConstructing: The construction of non-virtual base-class subobjects has started, but not the fields.
3. DestructingBases: The fields have been completely destructed. Non-virtual bases are undergoing destruction.
4. Destructed: All fields and non-virtual bases have been destructed.

Then, the lifetime of a subobject $\sigma$ can be defined as the set of execution states where its construction state is exactly Constructed.

Construction states are naturally ordered by chronology. We write $c < c'$ to say that state $c$ occurs earlier than state $c'$ in the enumeration above, and $S(c)$ to denote the state immediately following $c$, if it exists.

Finally, fields also carry a construction state: one among Unconstructed, StartedConstructing, Constructed, StartedDestructing, and Destructed, with similar meaning as for subobjects. As an example of use, writing to a scalar field is possible only if it is in state Constructed, therefore preventing accesses to an unconstructed or already destructed field.

### 3.4 Operational semantics

The semantics of the core language is stated in terms of evolutions of a global state $G$, which contains four partial maps:

- **LocType**: maps locations $\ell$ of complete objects to pairs $(C, n)$ representing the types $C[n]$ of the complete objects.
- **FieldValue**: associates values to pairs $(\pi, f)$ of a subobject $\pi$ and a scalar field $f$.
- **ConstrState**: associates construction states to subobjects $\pi$.
- **ConstrState**: associates construction states to fields $(\pi, f)$.
- **Codepoint** $(\text{Stmt}_1, \text{Stmt}_*)$: about to execute statement $\text{Stmt}_1$ followed by the list of statements $\text{Stmt}_*$.
- **ObjInit** $(\ell, \text{ObjInit}_*)$: a continuation $\ell$ operating over triples of a control point $P$, a continuation $\kappa$, and a global state $G$. We distinguish 5 kinds of control points $P$:
  - Codepoint $(\text{Stmt}_1, \text{Stmt}_*, \text{Env}, \text{Block})$: about to execute statement $\text{Stmt}_1$ followed by the list of statements $\text{Stmt}_*$ under variable environment $\text{Env}$. $\text{Block}$ is the list of all blocks enclosing the current statement, where a block is a pair $(\ell, \text{Stmt}_*)$ of a complete object $\ell$ to destruct at block exit and the remaining statements to execute after exiting from the block.
  - Constr$(\pi, \text{ItemKind}, \alpha, L, \text{Env})$: about to construct the list $L$ of the bases or fields of the subobject $\pi$. Initializers are to be looked for using constructor $\kappa$, and they operate on the variable environment $\text{Env}$ to pass arguments to their constructors. $\text{ItemKind}$ is one of Bases(DirectNonVirtual) or Bases(Virtual) or Fields, to request the construction of, respectively, direct non-virtual bases or virtual bases or fields of $\pi$.
  - ConstrArray$(\ell, \alpha, n, i, C, \text{ObjInit}_*)$: about to construct cells $i$ to $n - 1$ of type $C$, of the array $\alpha$ from the complete object $\ell$, using the initializers $\text{ObjInit}_*$ to initialize the cells, and $\text{Env}$ as variable environment to execute the initializers.
  - Destr$(\pi, \text{ItemKind}, L, \alpha)$: about to destruct the list $L$ of bases or fields of the subobject $\pi$.
  - DestrArray$(\ell, \alpha, i, C)$: about to destruct cells $i$ down to $0$ of type $C$, of the array $\alpha$ from the complete object $\ell$.

We omit the grammar of continuations $\kappa$, which can be found in [12] chapter 9.

The operational semantics is composed of 56 inference rules defining the transition relation $(P, K, G) \rightarrow (P', K', G')$, for a total of about 900 lines of Coq definitions. We show some represen-
tative rules to give the general flavor, and refer the reader to the first

Field accesses Reading from a scalar field is modeled as follows:

\[ \text{Env}(\text{var}) = \pi \quad \text{G} \vdash \pi : C \quad f = (\text{fid}, \text{Sc}, t) \in \mathcal{F}(C) \]
\[ \text{G}.\text{FieldValue}(\pi, f) = \text{res} \quad \text{Env}' = \text{Env}[\text{var}' \leftarrow \text{res}] \]

(Codepoint(var' := var->C f, L, Env, B, K, G) \rightarrow (Codepoint(skip, L, Env, B, K, G))

Likewise, for an assignment to a scalar field, we have:

\[ \text{Env}(\text{var}) = \pi \quad \text{G} \vdash \pi : C \quad f = (\text{fid}, \text{Sc}, t) \in \mathcal{F}(C) \]
\[ \text{G}.\text{ConstrState}^F(\pi, f) = \text{Constructed} \quad \text{Env}(\text{var'}) = \text{res} \quad \text{G}' = \text{G}[\text{FieldValue}(\pi, f) \leftarrow \text{res}] \]

(Codepoint(var' := var->C f, L, Env, B, K, G) \rightarrow (Codepoint(skip, L, Env, B, K, G'))

Note the side condition preventing assignment to a scalar field
that is not Constructed. For reads, this condition is not necessary:
Theorem \text{E} below shows that if a field has a value, then it is
Constructed.

Dynamic types Virtual function calls and dynamic casts both
involve the notion of dynamic type of a subobject, which the C++
standard defines as its most-derived object during the lifetime
of the latter. However, the standard also permits virtual function
calls and dynamic casts during the execution of the constructor
body, or field initializers, or destructor body corresponding
to the subobject. To unify these two cases, we introduce the
notion of generalized dynamic type. We define the predicate
gDynType(\alpha, i, \sigma, B, \sigma', \sigma'') meaning that the class-base
subobject \sigma' of static type B is the generalized dynamic type of
the subobject (\ell, \alpha, i, \sigma) with \sigma = \sigma''[\sigma']:

\[ \text{G}.\text{LocType}(\ell) = (D, n) \quad D[n] = \langle \alpha \rangle A \ C[m] = \langle (i, \sigma) \rangle \mathcal{F} B \]
\[ \text{G}.\text{ConstrState}(\ell, \alpha, i, \text{Repeate}(C, ::)) = \text{Constructed} \]

\[ \text{G} \vdash \text{gDynType}(\ell, \alpha, i, \sigma, C, \text{Repeate}(C, ::), \sigma) \]

The semantics of virtual function calls is similar to that given by
Wasserrab et al. [13], except that we use the generalized
dynamic type instead of the most-derived object. If \text{C}_0
is the generalized dynamic type of subobject \sigma', the predicate
VFDispatch(\text{C}_0, \sigma', f, B'', \sigma'') determines the subobject
sigma'' : B'' of \text{C}_0 containing the definition of virtual function f
that must be invoked, following the same algorithm as in [13]:

1. Determine the static resolving subobject \sigma_d declaring f.
2. Choose the final overrider for the method. The final overrider
is the inheritance subobject \sigma'' near to \text{C}_0, and declaring f.

The transition rule for a virtual function call is then,

\[ \text{Env}(\text{var}) = (\ell, \alpha, i, \sigma) \]
\[ \text{G} \vdash \text{gDynType}(\ell, \alpha, i, \sigma, \text{C}_0, \sigma_0, \sigma') \]
\[ \text{VFDispatch}(\text{C}_0, \sigma', f, B'', \sigma'') \]
\[ B''.f = f(\text{var}_1, \ldots, \text{var}_n)\{\text{body}\} \quad \forall j, \text{Env}(\text{var}_j) = v_j \]
\[ \text{Env}' = \emptyset[\text{var}_1 \leftarrow v_1, \ldots, \text{var}_n \leftarrow v_n][\text{this} \leftarrow (\ell, \alpha, i, \sigma)] \]

(Codepoint(var->B f(var_1, \ldots, var_n), L, Env, B, K, G) \rightarrow (Codepoint(body, \epsilon, \text{Env}', \epsilon), \text{KretnCall}(\text{var}, L, Env, B) \colon (\text{K}, \text{G}))

Similarly, dynamic casts are handled as in Wasserrab et al. [18],
using the generalized dynamic type instead of the most derived
object. The transition rule is omitted for brevity, but can be found
in [12] chapter 9]

**Destruction** We now give the flavor of the object construction
and destruction protocol, starting with the simpler of the two,
namely destruction. Destruction starts when the body of a block has
reduced to skip or return:

\[ (\text{st = skip} \wedge L = \epsilon) \vee \text{st = return} \]
\[ \text{G}.\text{LocType}(\ell) = (C, n) \]
\[ \text{(Codepoint(st, L, Env, (\ell, L') \colon B), K, G)} \rightarrow (\text{DestrArray}(\ell, L, n - 1, C), \text{Kcontinue}(st, L, Env, L', B) \colon (K, G)) \]

The DestrArray execution state requests the destruction of all
elements of the structure array C[n] at \ell, starting with the last element
(n - 1). Eventually, we reach a state where no more elements
remain to be destructed, in which case we effectively exit from
the block.

\[ \text{DestrArray}(\ell, \alpha, -1, C), \text{Kcontinue}(st, Env, B), K, G) \rightarrow (\text{Codepoint(st, L, Env, B), K, G)} \]

When the destruction of a most-derived object (i.e. a structure
array cell) is requested, we first enter the body of the associated
destructor in a variable environment that binds this to the object.

\[ 0 \leq i \sim C(\text{stmt}) \pi = (\ell, \alpha, i, (\text{Repeate}(C, ::)) \text{Env} = \emptyset[\text{this} \leftarrow \pi] \]
\[ \text{G}' = \text{G}[\text{ConstrState}(\pi) \leftarrow \text{StartedDestructing}] \]
\[ \text{DestrArray}(\ell, \alpha, i, \text{(h, l)}), \text{Kdestr}(\pi, \cdot) \colon \text{Kdestrcell}(\ell, \alpha, i, C) \colon K, G') \]

When the destructor body returns, the fields of the subobject have
to be destructed, in reverse declaration order.

\[ \pi = (\ell, \alpha, (\text{h, l})) \text{last}(l) = C \quad L = \text{rev}(\mathcal{F}(C)) \]
\[ \text{Codepoint(\text{return, Stmt}, Env, \epsilon), Kdestr(\pi, ::) K, G)} \rightarrow (Destr(\pi, \text{Fields}, L), K, G') \]

Destructing a scalar field erases its value and changes its construction
state to Destricted, before proceeding with the remaining
fields.

\[ f = (\text{fid}, \text{Sc}, t) \]
\[ \text{G}' = \text{G}[\text{FieldValue}(\pi, f) \leftarrow \bot][\text{ConstrState}(\pi, f) \leftarrow \text{Destricted}] \]
\[ \text{Destr(\pi, \text{Fields, f :: L), K, G')}} \rightarrow (Destr(\pi, \text{Fields, L}), K, G') \]

Destructing a structure array field changes its construction
state to StartedDestricted, then requests the destruction of the array,
starting from its last cell, and remembering the remaining fields
through Kdestrither in the continuation.

\[ \pi = (\ell, \alpha, (i, \sigma)) \]
\[ f = (\text{fid}, \text{St}, (C, n)) \quad \alpha' = \alpha + (i, \sigma) \colon \epsilon \]
\[ \text{G}' = \text{G}[\text{ConstrState}(\pi, f) \leftarrow \text{StartedDestricted}] \]
\[ \text{DestrArray}(\ell, \alpha, n - 1, C), \text{Kdestr(\pi, Fields, L) :: K, G')} \]

Then, once all cells have been destructed, the field enters the
Destricted state, and we proceed with the destruction of the remaining
fields.
\( G' = G'[\text{ConstrState}(\pi, f) \leftarrow \text{Destructed}] \)

\((\text{DestrArray}(\ell', \alpha', i, h(l)), C, \text{Kdestroyer}(\pi, \text{Fields}, f, L) :: K, G) \)
\( \rightarrow (\text{Destr}(\pi, \text{Fields}, L), K, G') \)

Eventually, all fields have been destructed. The subobject then changes its construction state to \( \text{DestructuringBases} \). At this point, no virtual function call nor dynamic casts may be used on this subobject. The destruction of the direct non-virtual bases starts in reverse declaration order.

\( \pi = (\ell, (\alpha, i, (h, l))) \quad \text{last}(l) = C \quad L = \text{rev}(D \cap V(C)) \)

\( G' = G'[\text{ConstrState}(\pi) \leftarrow \text{DestructuringBases}] \)

\((\text{Destr}(\pi, \text{Fields}, e), K, G) \)
\( \rightarrow (\text{Destr}(\pi, \text{Bases(DirectNonVirtual)}, L), K, G') \)

Destructing a (virtual or direct non-virtual) base \( B \) of \( \pi \) enters its destructor, remembering the other bases through \( \text{Kdestroyer} \).

\( \sim B (\{ \text{stmt} \}) \)

\( \pi' = \text{AddBase}(\pi, \beta, B) \quad \text{Env} = \emptyset \quad \text{[this} \leftarrow \pi'] \)

\( G' = G'[\text{ConstrState}(\pi') \leftarrow \text{StartedDestructing}] \)

\((\text{Destr}(\pi, \text{Bases}(\beta), B :: L), K, G) \)
\( \rightarrow (\text{Codepoint}(\text{stmt}, e, \text{Env}, e) \) \)

\( \text{Kdestr}(..., \pi') \leftarrow \text{Kdestroyer}(\pi, \text{Bases}(\beta), B, L) :: K, G' \)

Eventually, we reach a state where all direct non-virtual bases of \( \pi \) have been destructed. There are two cases to consider, depending on the top of the continuation stack. In the first case, the continuation stack starts with a \( \text{Kdestroyer}(\pi, \text{Bases}(\beta), B, L) \) indicating that \( \pi \) is a most-derived object. In this case, there is no need to destruct the virtual part of \( \pi \) (this will be done later by the enclosing most-derived object) and we are done with the subobject \( \pi \): its construction state becomes Destructed, and we proceed with the destruction of the remaining bases of \( \pi' \).

\( G' = G'[\text{ConstrState}(\pi) \leftarrow \text{Destructed}] \)

\((\text{Destr}(\pi, \text{Bases(DirectNonVirtual)}, e), K, G) \)
\( \rightarrow (\text{Destr}(\pi', \text{Bases}(\beta), B :: L), K, G') \)

The second case is when the continuation stack starts with a \( \text{Kdestruct} \). Then, \( \pi \) must be a most-derived object, and its direct and indirect virtual bases need to be destructed. According to the C++ standard, virtual bases must be destructed in reverse inheritance graph order. Consider the following recursive function:

\[ \text{list}(\{ \text{Repeated, Shared} \} \times C, V) \quad \text{list}(C) \]

\[ \forall O(e) = e \]

\[ \forall O(\text{Repeated}, B :: q) = \forall O(D(B)) \cup B :: q \]

\[ \forall O(\text{Shared}, B :: q) = \forall O(D(B)) \cup (B :: q) \]

where \( D(B) \) is the list of direct bases of \( B \), in declaration order, tagged with \( \text{Repeated} \) for (non-virtual) bases or \( \text{Shared} \) for (virtual bases), and \( \cup B :: q \) is list concatenation with elimination of duplicates \( (l_1 \cup l_2 = l_1 \cup (l_2 \setminus l_1)) \). It is easy to see that the list \( L = \forall O(D(C)) \) contains all the direct and indirect virtual bases of \( C \), exactly once each, and contains no other classes. Moreover, the order in which virtual bases appear in \( L \) is consistent with the inheritance graph order. In particular, if \( A \) and \( B \) are virtual bases of \( C \) such that \( A \) is a virtual base of \( B \), then \( A \) appears before \( B \) in \( L \).

\[ L' = \text{rev}(\forall O(D(C))) \]

\((\text{Destr}(\pi, \text{Bases(DirectNonVirtual)}, e), K, G) \)
\( \rightarrow (\text{Destr}(\pi, \text{Bases(Virtual)}, L'), K, G') \)

Finally, when all virtual bases have been destructed, the subobject under consideration (necessarily a most-derived object) becomes Destructed, and we proceed with the destruction of the preceding structure array cells.

\( \pi = (\ell, (\alpha, i, (h, l))) \quad \text{last}(l) = C \quad G' = G'[\text{ConstrState}(\pi) \leftarrow \text{Destructed}] \)

\((\text{Destr}(\pi, \text{Bases(Virtual)}, e), K, G) \)
\( \rightarrow (\text{DestrArray}(\ell, \alpha, i - 1, C), K, G') \)

**Construction** To execute a block statement, we allocate memory for the structure array declared in the block, then start the construction protocol by requesting the construction of the first element of this array:

\( \ell \not\in \text{dom}(G, \text{LocType}) \quad G' = G[\text{LocType}(\ell) \leftarrow (C, n)] \quad \text{Env}' = \text{Env}[e \leftarrow \text{Ptr}(\ell, e, \text{Repeated}, (C :: e))] \)

\((\text{Codepoint}(\{ C \mid n \} = \{ \ell \}; G, \text{Env}, B)), K, G) \)
\( \rightarrow (\text{ConstrArray}(\ell, e, n, 0, C, i, \text{Env}'), K \text{continue}(\text{stmt}, \text{Env}', B)) \)

The construction protocol implements the necessary traversal of all subobjects of \( C \) using the same “small-stepping” style, based on continuations, that was illustrated above in the case of destruction. There are two main differences. First, the construction order is the exact opposite of the destruction order: instead of enumerating array cells by decreasing indices, fields and non-virtual bases in reverse declaration order and virtual bases in reverse \( VO \) order, we enumerate array cells by increasing indices, fields and non-virtual bases in declaration order and virtual bases in \( VO \) order. Second and more importantly, we need to execute the initializers that compute initial values for scalar fields and the arguments to be passed to constructors, adding a number of transition rules. We refer the reader to [12] chapter 9 for full details.

4. Properties of construction and destruction

In this section, we state (and sometimes outline the proofs of) several semantic properties of interest for construction and destruction. Some are technical consequences of the definition of our semantics, but others capture higher-level properties that C++ programmers often rely on, such as the RAI L principle.

4.1 Run-time invariant

Our transition rules and grammars for execution states are lax in that they put very few constraints on the general shapes of states. However, in transition sequences starting from the initial state, the reachable states are a small subset of all possible states and enjoy many low-level properties that are essential to prove the high-level theorems in this section. We gathered about 20 such properties in one invariant \( INV' \) and proved that this invariant is satisfied by the initial state and preserved by the transition rules. This is the largest part of the Coq mechanization, totaling about 15000 lines of Coq and taking about 2 hours to re-check the proof.

A detailed explanation of the invariant is given in [12] section 10.1. Here, we just show the two most interesting consequences of the invariant, which relate the construction states of certain subobjects.

Let \( p, p' \) be two subobjects of the same complete object. We say that \( p \) is a direct subobject of \( p' \) if, either, \( (1) \) \( p \) is a direct non-virtual base of \( p' \); \( (2) \) or \( p \) is a most-derived object and \( p \) is a virtual base of \( p' \); \( (3) \) or \( p \) is a field subobject of \( p' \) (that is, \( p \) is a cell of a structure array field of \( p' \)).

**Lemma 1** (Vertical relations on construction states). Assume that \( p \) is a direct subobject of \( p' \). The construction states of \( p \) and \( p' \) in any execution state satisfying \( INV \) are related as follows:
Let \( p' \) be a subobject of static type \( C \), and \( p_1, p_2 \) be two direct subobjects of \( p' \). We say that \( p_1 \) occurs before \( p_2 \) if, either, (1) \( p' \) is a most-derived object and \( p_1, p_2 \) are two virtual bases of \( p' \) in inheritance graph order; (2) \( p_1 \) and \( p_2 \) are two direct non-virtual bases of \( p \) in declaration order; (3) \( p_1 \) and \( p_2 \) are two cells of the same array field, in the order of their indexes within the array; (4) \( p_1 \) and \( p_2 \) are two cells of two different fields in declaration order; (5) \( p' \) is a most-derived object and \( p_1 \) is a virtual base, and \( p_2 \) is a direct non-virtual base of \( p' \) or a cell of an array field; (6) \( p_1 \) is a direct non-virtual base of \( p' \) and \( p_2 \) is a cell of an array field.

**Lemma 2** (Horizontal relations on construction states). Assume that \( p_1 \) occurs before \( p_2 \). The construction states of \( p_1 \) and \( p_2 \) in any execution state satisfying \( INV \) are related as follows:

- **Unconstructed** \( \rightarrow \) **Unconstructed**
- **StartedConstructing** \( \rightarrow \) **Unconstructed**
- **BasesConstructed** \( \rightarrow \) **Unconstructed**
- **Constructed** \( \rightarrow \) **Unconstructed**
- **StartedDestructing** \( \rightarrow \) **Unconstructed**
- **DestructingBases** \( \rightarrow \) **Destructed**
- **Destructed** \( \rightarrow \) **Destructed**

In the remainder of this section, we only consider execution states that can be reached from the initial state and therefore satisfy the invariant \( INV \).

### 4.2 Progress

To check that our transition rules make sense and that no rule is missing, we prove a “progress” property of construction and destruction: once construction of a complete object starts, it always eventually reaches a point where the object is fully constructed, without getting stuck in the middle; and likewise for destruction. This result is false in general: since constructors, initializers and destructors can perform arbitrary computation, they can get stuck on e.g. an attempt to assign an unconstructed scalar field. However, we can prove the expected result if we restrict ourselves to nearly trivial constructors and trivial destructors.

We say that a class \( C \) has a nearly trivial constructor if (1) \( C \) has a default constructor with no arguments and return as its body; (2) initializers for bases and fields just call the default constructor, without any other computations; (3) scalar fields are initialized with constants; (4) for each structure array field \( f \) of \( C \), if \( f \) has type \( B \), then \( B \) has a nearly trivial constructor. This notion extends the concept of trivial constructor from the C++ standard, e.g. by allowing virtual bases and virtual functions.

**Theorem 3** (Construction progress). Let \( (P, K, G) \) be an execution state where \( P = \text{Codepoint}(\{C \mid C \in \mathbb{N}; s t \} = \ldots, \) i.e. we are about to execute a block statement. Assume that \( C \) is a class having a nearly trivial constructor and that the initializer list \( s \) calls the default constructor for every array cell. Then, there exists a state \((P', K', G')\) such that

- \((P, K, G) \rightarrow (P', K', G')\)
- \(P' = \text{Codepoint}(s, \ldots, \) i.e. construction has terminated and the block body is about to be executed;
- in state \( G' \), all cells of the array \( c \) are in the Constructed state.

A similar theorem holds for destruction. Here, we use unchanged the notion of trivial destructor from the C++ standard: a class \( C \) has a trivial destructor if (1) its destructor is just return; (2) all virtual bases and direct non-virtual bases of \( C \) have trivial destructors; (3) for each structure array field \( f \) of \( C \), if \( f \) has type \( B \), then \( B \) has a trivial destructor.

### 4.3 Safety of field accesses and virtual function calls

The rule for reading the contents of a scalar field puts no precondition on the initialization state of the field. We can, however, show that this rule gets stuck whenever the field is not in the Constructed state.

**Theorem 4.** A scalar field has a well-defined value only if it is Constructed.

Proof. Follows from \( INV \) and the fact that setting the value of a scalar field only occurs in two cases: either on an ordinary scalar field, which is forbidden if the field is not Constructed, or on scalar field initialization, which turns the field construction state to Constructed. Moreover, our semantics erases the value of the scalar field when destructing it.

Like C++ itself, our semantics allows fields to have no initializers and therefore remain without a defined value after construction. However, we also proved that if we remove the transition rule allowing fields without initializers to proceed, a scalar field has a well-defined value if and only if it is Constructed.

Virtual functions have no initialization state per se. However, the C++ semantics for virtual function calls provides a very useful guarantee concerning the construction state of the this subobject:

**Theorem 5.** Whenever a virtual function is called, the subobject bound to its this parameter is in state **BasesConstructed** or **Constructed** or **StartedDestructing**, and all its base-class subobjects are in state **Constructed**.

Proof. Consider a call to a virtual function \( f \) on a subobject \((\ell, p)\). Since this call does not go wrong, the generalized dynamic type \( p_0 \) of this subobject is defined. By definition of generalized dynamic types, \((\ell, p_0)\) is in state **BasesConstructed** or **Constructed** or **StartedDestructing**. Invariant \( INV \) then guarantees that all base-class subobjects of \((\ell, p_0)\) are **Constructed** (from Lemma 1). The final overrider for function \( f \) being either \((\ell, p_0)\) or one of its base-class subobjects, the result follows.

In other words, a virtual function can always safely assume that bases have been properly constructed. It cannot, however, assume that fields of its defining class are in the constructed state, since initializers for these fields can call the virtual function. As discussed in [2] and by Qi and Myers [11], Java does not provide a similar guarantee; through inheritance and method overriding, it is possible for a method to be invoked before its super classes have completed their initialization.

### 4.4 Evolution of construction states

**Lemma 6.** If \( s \rightarrow s' \) is a transition step of our small-step operational semantics, and if the construction state of the subobject \((\ell, p)\) is in \( s \) and \( c' \neq c \in s \), then \( c' = S(c) \) and any other subobject \((\ell', p') \neq (\ell, p)\) keeps its construction state unchanged.

Proof. By case analysis on the transition rules, with the help of invariant \( INV \).

**Corollary 7.** Any subobject is never constructed or destructed more than once.
In particular, any virtual base subobject is constructed or destructed at most once, despite being potentially reachable through several inheritance paths. Also, if an object goes from one construction state to another, then it must go through all construction states in between:

**Theorem 8 (Intermediate values theorem).** If \( s \rightarrow s' \), then for any subobject \((\ell, p)\) and for any construction state \( c \) such that:

\[
\text{ConstrState}_c(\ell, p) \leq c < S(c) \leq \text{ConstrState}_{c'}(\ell, p)
\]

there exist “changing states” \( s_1, s_2 \) such that \( s \rightarrow s_1 \rightarrow s_2 \rightarrow s' \) and \( \text{ConstrState}_c(\ell, p) = c \) and \( \text{ConstrState}_{c'}(\ell, p) = S(c) \).

(Here, for a state \( s = (P, K, G) \), we write \( \text{ConstrState}_c(\pi) \) for \( G.\text{ConstrState}(\pi) \).)

**4.5 Object lifetimes**

An important design principle of C++ is that destruction is performed in the exact reverse order of construction. We now formalize and prove this property, along with more general properties about the relative lifetimes of two subobjects.

**Two subobjects of the same complete object** Let \( \ell \) be a complete object of type \( C[n] \).

**Theorem 9.** If \( p_1 \) and \( p_2 \) are two subobjects of the complete object \( \ell \), either the lifetime of \( p_1 \) is included in that of \( p_2 \), or the lifetime of \( p_2 \) is included in that of \( p_1 \).

To prove this theorem, we need to characterize the construction order between subobjects. We write \( p_1 \preceq C[n] p_2 \) to say that \( p_1 \) occurs before \( p_2 \) in the depth-first, left-to-right traversal of the construction tree in Figure 1.

**Lemma 10** (The construction order is total). If \( C[n] \rightarrow (p_1) \rightarrow B_1 \) and \( C[n] \rightarrow (p_2) \rightarrow B_2 \), then either \( p_1 \preceq C[n] p_2 \) or \( p_2 \preceq C[n] p_1 \).

**Lemma 11** (Construction order and lifetimes). For any reachable execution state \( s \) and any complete object \( \ell \) of type \( C[n] \), if \( p_1 \preceq C[n] p_2 \) and \( \text{ConstrState}(\ell, p_2) = \text{ConstrState}(\ell, p_1) = \text{Constructed} \), then \( \text{ConstrState}(\ell, p_2) = \text{ConstrState}(\ell, p_1) = \text{Constructed} \). In other words, if \( p_1 \preceq C[n] p_2 \), then the lifetime of \( p_2 \) is included in the lifetime of \( p_1 \).

**Theorem 9** then follows directly from the two lemmas above. Using Lemma 11 and the definition of \( \preceq C[n] \), we have the following stronger special case:

**Theorem 12.** If \( p_2 \) is a subobject of \( p_1 \), then the lifetime of \( p_1 \) is included in that of \( p_2 \).

As a corollary of Theorem 9, it follows that if \( p_1 \) is constructed before \( p_2 \), then \( p_2 \) is destructed before \( p_1 \).

**Theorem 13** (Deconstruction in reverse order of construction). Let \( \ell \) be a complete object of type \( C[n] \) and \( p_1, p_2 \) be two subobjects of \( \ell \). Consider the reduction sequence below where \( p_1 \) is constructed before \( p_2 \), then later \( p_1 \) is destructed:

\[
s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow s_4 \rightarrow s_5
\]

(We write \( s_i \) below a state \( s \) to denote that \( p_i \) is Constructed in state \( s \), and \( \neg c_i \) to mean that \( p_i \) is not Constructed.) Then, there exist intermediate states \( s'_1, s'_3 \) such that \( p_2 \) stops being Constructed between these two states:

\[
s_0 \rightarrow s_1 \rightarrow s'_2 \rightarrow s'_3 \rightarrow s'_4 \rightarrow s_4 \rightarrow s_5\]

**Proof.** At state \( s_2, p_1 \) is Constructed but \( p_2 \) is not. Hence, the lifetime of \( p_1 \) cannot be included in that of \( p_2 \). By theorem 9, the lifetime of \( p_2 \) is therefore included in that of \( p_1 \). Since \( p_1 \) is no longer Constructed at state \( s_3 \), it is \( p_2 \) at state \( s_3 \). Since at most one subobject changes construction state during a given transition (Lemma 6), \( p_1 \neq p_2 \) and \( p_2 \) is no longer Constructed at state \( s_4 \). The result then follows from the the intermediate values theorem (Theorem 8).

**Subobjects of different complete objects** In the full C++ language, including dynamic allocation, the lifetimes of two subobjects of different complete objects are, in general, unrelated: new and delete operations can be interleaved arbitrarily. In our core language, complete objects can only be created by block statements and therefore follow a stack discipline.

**Theorem 14.** The lifetimes of two subobjects \((\ell_1, p_1)\) and \((\ell_2, p_2)\) of different complete objects \(\ell_1 \neq \ell_2\) are either disjoint or included in one another.

This result follows from Theorem 9 and the stronger property below, which shows that throughout the execution of a block, the construction states of subobjects of already-allocated complete objects do not change:

**Lemma 15.** Let \( s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow s_4 \) be the execution of a block: the transition \( s_1 \rightarrow s_2 \) enters the block and allocates a fresh complete object \( \ell \); the transition \( s_3 \rightarrow s_4 \) exits this block. For all complete objects \( \ell' \) already allocated in state \( s_1 \), the allocation states of its subobjects \((\ell', p')\) are identical in \( s_1 \) and \( s_4 \).

**4.6 RAI1: Resource Acquisition Is Initialization**

RAI1 is a programming discipline where precious program resources (such as file descriptors) are systematically encapsulated in classes, all acquisitions of such resources are performed within constructors of the corresponding class, and all releases of such resources are performed within destructors of the corresponding class. We cannot prove a general result guaranteeing the proper encapsulation of resources in classes: this is a matter of program verification. We can, however, prove that in a terminating program every construction of a subobject is correctly matched by a destruction.

**Theorem 16** (RAII). Consider a partial program execution \( s_{\text{visit}} \rightarrow s_1 \rightarrow s_2 \) where the transition \( s_1 \rightarrow s_2 \) marks the end of a block statement that allocated the complete object \( \ell \). Then, between the initial state \( s_{\text{visit}} \) and \( s_1 \), the following events occurred, in this order:

- Every subobject of \( \ell \) was constructed exactly once.
- Every subobject of \( \ell \) was destructed exactly once, in reverse order of construction.

**Proof.** The invariant INV implies that, at state \( s_1 \), all cells of the structure array \( \ell \) are Destructed, and so are all of their subobjects. Consider a subobject \((\ell, p)\). Its state is Unconstructed in the initial state and Destructed in \( s_1 \). Therefore, by the intermediate value theorem (Theorem 8), it must have entered state Constructed at some point, then left state Constructed at some later point, meaning that \((\ell, p)\) has been initialized once, then destructed once. The claim on construction and destruction order follows from Theorem 13.

**4.7 Generalized dynamic types**

We finish this section with interesting properties of generalized dynamic types, which were introduced in [3, 4] to give semantics to virtual function calls and dynamic casts.
Virtual functions calls during object construction and destruction

The formulation of ISO C++03 [12] of the behavior of the abstract machine when a virtual function is called during construction (or destruction) was unclear and did not clearly support the original intent (correctly modeled in this paper). This was reported to the ISO C++ committee as CWG issue number 1202. The formulation was clarified in time for adoption in C++11.

Conflicting description of end of object lifetime

Although the language formally defined in this paper does not allow explicit management of object lifetime, coming up with a simple, coherent, unified, and faithful description of object lifetime led us to discover conflicts and unintended semantics in the ISO C++ documents (both C++03 and C++11). The C++11 standard [7] has a conflicting description of the effect of calling a destructor. Two paragraphs (3.8p1 and 3.8p4) claim that an object’s lifetime ends when a call to a non-trivial destructor occurs or its storage is reused or released. However, another paragraph (14.2p4) claims that once a destructor is invoked (its triviality notwithstanding), “the object no longer exists”. This issue will be resolved after C++11 is published.

We expect that for consistency, the resolution will not consider “triviality” of the destructor to determine when an object’s lifetime ends.

Effect of calling destructor for builtin types

C++ allows an expression of the form p->˜T(0) where T is a non-class type name and p is an expression that points to a T object. This form was introduced to support function templates explicitly managing object lifetime without forcing the author to distinguish between builtin types and class types. It was also intended to bring uniformity. However, the formulation of the behavior of the abstract machine appears to indicate that the following program fragment has a well-defined meaning, for any scalar type T:

```cpp
def T f(T x) {
    T t = x;
    t.˜T(0);
    return t;
}
```

This is in a clear conflict with the case where T is a class type. Indeed, for every class type T, that function leads to an undefined behavior, as it attempts to destroy the local variable t twice: once explicitly through the call to the destructor and a second time implicitly when the function exits. Finally, it appears that the program is ill-formed (and a diagnostic is required) when T is an array type.

Lifetime of array objects

The C++ standards explicitly indicate that the lifetime of an array object starts as soon as storage for it has been allocated, regardless of when the lifetime of its elements starts. In general, a complete object’s lifetime starts after all its subobjects have been constructed. This irregularity appears to be a hand-over from C in its formulation. It will be reconsidered after publication of C++11 along with a more unified treatment of the lifetime of objects of builtin types.

6. Application to verified compilation

To strengthen confidence in the semantics presented here and stress its usability, the first author developed and proved correct a simple compiler that translates the core language presented in this paper.
to a simple, non-object-oriented intermediate language similar to CompCert’s Cminor [8]. This verification is described in [12 chapter 11]. The compiler proceeds in two passes, using as intermediate language the CoreC++ language of Wasserrab et al. [19] extended with a setDynType operation that explicitly modifies the dynamic type of an object.

The first translation pass is broadly similar to that outlined in Wasserrab’s thesis [17], turning constructors, initializers and destructors into non-virtual function calls. However, setDynType operations are inserted at the program points characterized by Theorem 18 to implement the proper semantics for virtual function calls and dynamic casts. Following a popular optimization, two versions of every constructor are generated, one for the “most derived” case, the other for the “inheritance subobject” case. The second translation pass extends our earlier work on object layout [13].

The proofs of semantic preservation are standard arguments by forward simulation diagrams [8] §3.7. The proofs are rather big (about 8000 lines of Coq for each pass) because there are many cases to consider, along with complex invariants relating execution states, but present no major conceptual difficulties.

7. Related work

**Formal semantics for C++** Norrish [10] describes a formal semantics for C++ that was mechanized in HOL. His semantics describes a much larger subset of C++ than ours, including in particular expressions with side effects and partially-specified evaluation order, exceptions, free store (new and delete), and temporary objects. Construction and destruction are modeled by “dynamic translation”: the reduction rule for the construction of an object produces “on the fly” a statement containing the necessary invocations of initializers and constructors for fields and bases; this statement is, then, reduced normally. As a way to state the semantics, Norrish’s approach is arguably simpler than our “small-stepping” of the construction/destruction protocol. However, we suspect that Norrish’s approach would make it more difficult to prove meta-properties about construction states and lifetimes, in the style of [4] Additionally, we suspect that Norrish’s semantics does not correctly capture the interaction between construction, destruction, and virtual function calls. Consider:

```c
struct B {
    B* b;
    virtual int f() { return 42; }
    B() : b(this) {} }
};
```

struct D : B {
    virtual int f() { return 42; }
};

```c
int main () { D d; return d.b->f(); }
```

In B’s constructor, the initialization b(this) saves in b a pointer whose dynamic type is B (correctly, at that time). However, after completion of B’s constructor, the dynamic type of *b is not updated to B, causing the wrong f virtual function to be dispatched in main.

The CoreC++ semantics of Wasserrab, Nipkow, Snelting and Tip [18] is a major starting point for our work. It does not cover object construction and destruction. Wasserrab’s Ph.D. thesis [17] describes this semantics and its Isabelle/HOL formalization in greater details, as well as a static, unverified translation of construction and destruction into non-virtual function calls. This translation fails to correctly implement C++’s semantics for virtual function calls: in the translated program, the dynamic type of a subobject is always its most derived object, regardless of construction state.

We are not aware of any other formal semantics for C++ that addresses construction and destruction.

**Type systems for safe object initialization** Several research projects develop type systems for object-oriented languages that enforce safety guarantees about object initialization, such as the fact that well-typed programs never read fields of an uninitialized object. Fahndrich and Xia [3] introduce a type system to remove useless field initializations to null while still ensuring safe object initialization. Qi and Myers [11] introduce a more general type system to precisely and statically determine, at each program point, which fields may be read or not. Hubert et al. [4] formalize a type system for safe Java object initialization using the Coq proof assistant. Their type system shares with our operational semantics the use of construction states for objects, but in their case, construction states are lifted to the type level and maintained at compile-time. This enables their system to statically check contracts over methods that constrain the construction states of some of the arguments, for instance.

Our work makes no attempt at providing static typing safety properties beyond the few offered by C++. Instead, we aim at a precise description of the dynamic semantics of construction and destruction in the presence of multiple inheritance. The type systems mentioned above are based on the Java and C# single-inheritance object models. Moreover, they only deal with object initialization, without object destruction or finalization. Indeed, in Java, object finalization is weakly specified: although the Java language specification [4] requires objects to be finalized, it does
not describe more precisely when object finalization should occur. C# offers a destruction mechanism, namely object disposal, but it must be called explicitly by the programmer.

8. Extending the semantics

Our semantics presents the core features of C++ object construction and destruction as faithfully as possible towards the Standard. However, it can be extended in a number of directions.

**Manual memory management** We anticipate no difficulties with supporting free store objects, i.e. the new and delete operators. Only slight modifications to the operational semantics appear necessary. Of course, Theorem 14 would be invalidated, since objects no longer follow a stack discipline. However, it appears very difficult to formalize more general manual memory management, allowing for instance explicit destructor calls and the use of placement operators such as “new(p) C” to construct an object at a given memory location.

**Temporary objects of class types** Expression evaluation, passing arguments by value to functions, or returning results by value entail construction and destruction of *temporary objects*. While the lifetime of these objects are well-defined by the C++ standard (and they follow a first-constructed-last-destroyed discipline), their storage durations are not specified. In fact, we found inconsistencies between the definitions of storage duration as specified by the C++11 standards and the C99 standards. Accounting for temporary objects beyond scalar values returned by functions or passed as arguments will require nontrivial extensions to our semantics.

**Copy constructor elision** More challenging is to give semantics to functions that return values of class types. They are objects constructed in the callee but destroyed in the caller at the end of the full expression containing the call. For decades, C++ has allowed elision of copy constructors (even if they have observable behavior) that would normally copy a local object to the (temporary) return value, provided certain non-aliasing conditions (easy to check) are met. These program transformations are necessary in practice to obtain good performance but are not semantics-preserving in the traditional sense. The same caveat applies for the C++11 notion of “move constructors”.

**Exceptions** It is easy to capture a key aspect of C++ exceptions in our semantics: block-scoped objects are properly destroyed when an exception is thrown. Exception objects are temporary objects with lifetime dynamically controlled by exception handlers acting much like function invocations with the exception object as argument. C++ allows catching exceptions by value, so our observations for function call argument by value apply here. Furthermore, the semantics of constructors need to be altered to invoke destructors for completely constructed subobjects in presence of exception. Similarly, the semantics for destructors should be altered to include program abortion if a subobject destructor raises an exception. Finally, interaction between construction of dynamic objects and exceptions (both of which reflect related design decisions) should be investigated. These features are at the basis of generalized RAII techniques for dynamically controlled resources; popular examples include smart pointers such as unique_ptr and smart_ptr.

9. Concluding remarks

We hope that this work sheds light on the precise semantics of construction and destruction in C++ and what they actually guarantee to the working programmer. Several features remain to be addressed, but the subset that was formalized is already quite realistic and similar to recommended subsets for critical embedded systems [9]. The semantics implements a pattern for “small-stepping” a tree traversal which could perhaps be generalized and abstracted over. Finally, it would be interesting to exploit this semantics in the context of type systems and other static analyses that verify stronger safety properties about initialization.

References