
Model checking and performance evaluation with CADP illustrated on shared-memory mutual exclusion protocols

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Overview

- Mutual exclusion on shared-memory machines
- Formal specification using LNT
- Functional analysis by model checking using MCL
- Performance evaluation using IMCs
- Conclusion

Mutual exclusion on shared-memory machines

- Long-standing problem in concurrent programming [Dijkstra-65]:
Protect a shared resource against concurrent non-atomic accesses from competing processes, which communicate by atomic read/write operations on shared variables
- Mutual exclusion protocols:
 - Ensure that at most one process accesses the resource
 - Guarantee the progress of execution
- Dozens of protocols proposed in the literature (see survey in [Anderson-Kim-Herman-03])
- Performance assessment mainly by experimental measures
→ *our goal: provide model-based quantitative analysis*

Mutual exclusion protocols

- Structure of a process P competing for the access to the shared resource:

loop

non-critical section ; ➔ *may loop forever*

entry section ; ➔ *access shared variables*

critical section ; ➔ *access resource*
 (must terminate)

exit section ➔ *access shared variables*

end loop

Study of 27 protocols

- black-white bakery protocol [Taubenfeld-04]
- Anderson [03]
- Burns & Lynch [80]
- Craig and Landin & Hagersten (CLH) [93,94]
- Dekker [68]
- Dijkstra [65]
- Kessels [82]
- Knuth [66]
- Lamport [87]
- Mellor-Crummey & Scott (MCS) [91]
- Peterson [81]
- Szymanski [88]
- Test-and-Set
- Test—Test-and-Set
- 12 automatically generated protocols for two processes [Bar-David-Taubenfeld-03]
- trivial (incorrect) one-bit protocol (for benchmarking)

Interactive Markov Chains

[Hermanns-02]

- Single model for both
 - **functional verification:**
extension of labeled transition systems (hide delay)
 - **performance analysis:**
extension of Markov chains (hide actions)
- Enrich functional model with (exponential) delays by composition with additional processes
- Tool support by CADP (<http://cadp.inria.fr>)
 - functional verification:
generation, model checking, equivalence checking, ...
 - performance analysis:
steady-state/transient analysis, minimization, ...

LNT (LOTOS NT)

[Champelovier-Clerc-Garavel-et-al-10]

- Integration of the features of
 - process algebras
 - imperative programming languages
- User-friendly syntax and formal semantics
- Input language of CADP (via Int.open tool)
 - translation into LOTOS
 - generation of the labeled transition system (LTS)
 - connection to on-the-fly exploration tools

Knuth's protocol for two processes

[Knuth-66]

three shared
variables
 $A[0]$, $A[1]$, B

entry section

exit section

Process P_i

loop

non-critical section ;

loop

$A[i] := 1;$

await $(B == i) \text{ or } (A[j] == 0);$

$A[i] := 2;$

if $A[j] != 2$ **then break**;

end loop ;

$B := i;$

critical section ;

$B := j;$

$A[i] := 0$

end loop

$i \in \{0, 1\}$
other process:
 $j = 1 - i$

Knuth's protocol in LNT

process P [NCS:Pid, CS:Access, A, B:Operation] (i:Nat) **is**

var k, a_k, b: Nat **in** k := 1 - i;

loop

NCS (i);

loop L1 **in**

A (Write, i, 1 of Nat, i);

loop L2 **in**

B (Read, ?b, i); A (Read, j, ?a_j, i);

if (b == i) or (a_j == 0) **then break** L2 **end if**

end loop;

A (Write, i, 2 of Nat, i);

A (Read, j, ?a_j, i); **if** a_j != 2 **then break** L1 **end if**

end loop;

B (Write, i, i);

entry section

CS (Enter, i); CS (Leave, i);

B (Write, j, i);

A (Write, i, 0 of Nat, i)

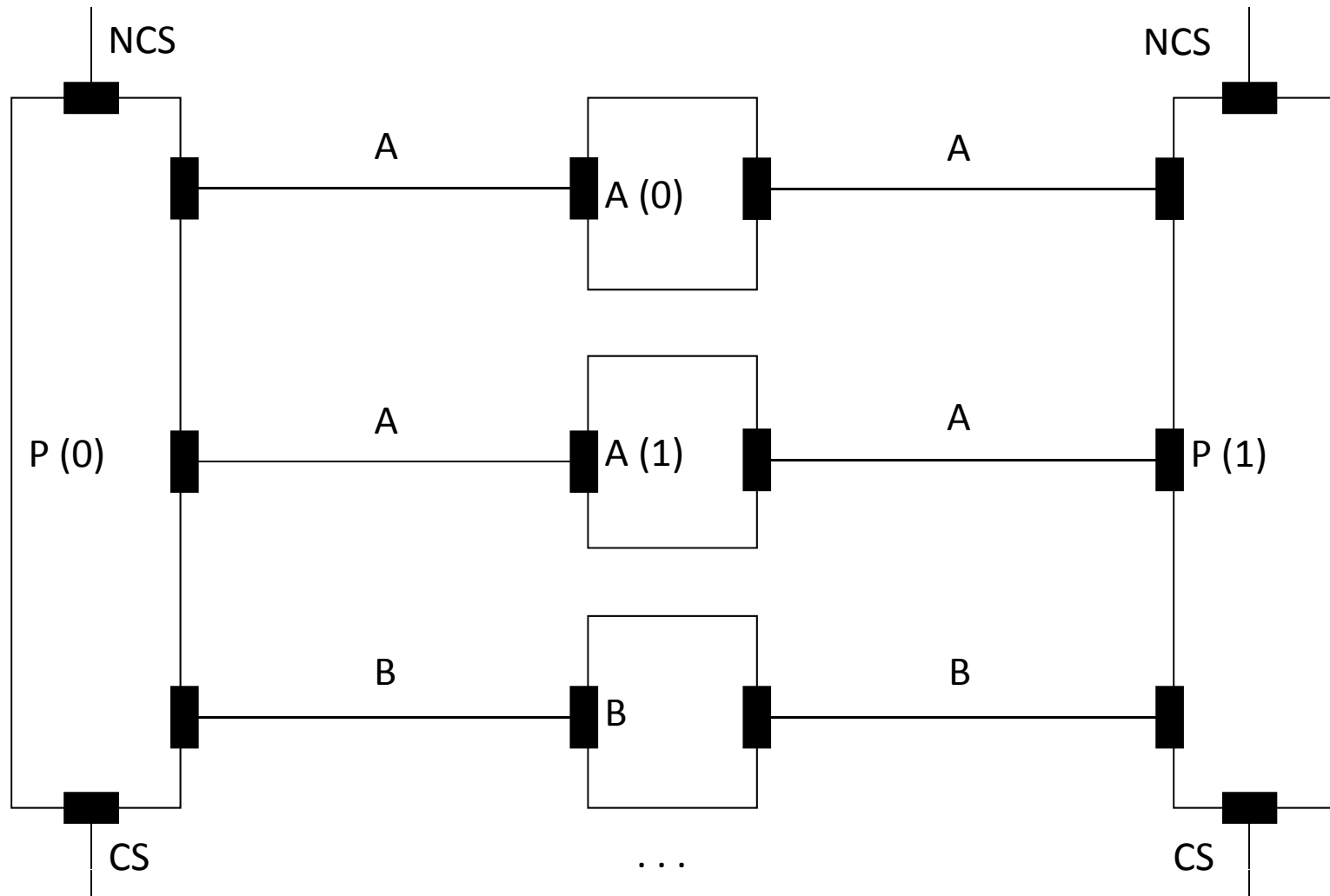
exit section

end loop

end var end process

Architecture of the system

(three shared variables)



LNT specification (architecture of the system)

```
par A, B, CS, NCS in
  par A, B in
    par
      P [NCS, CS, A, B] (0 of Nat)
    || P [NCS, CS, A, B] (1 of Nat)
    end par
  ||
    par
      A [A] (0 of Nat, 0 of Nat)
    || A [A] (1 of Nat, 0 of Nat)
    || B [B] (0 of Nat)
    end par
  end par
|| L [A, B, CS, NCS, MU]
end par
```

all shared variables
are initially 0

LNT specification (shared variables)

process A [A:Operation] (index, val:Nat) **is**

loop select

A (!Read, !index, !val, ?**any** Nat)

[] A (!Write, !index, ?val, ?**any** Nat)

end select end loop

end process

process B [B:Operation] (val:Nat) **is**


loop select

B (!Read, !val, ?**any** Nat)

[] B (!Write, ?val, ?**any** Nat)

end select end loop

end process



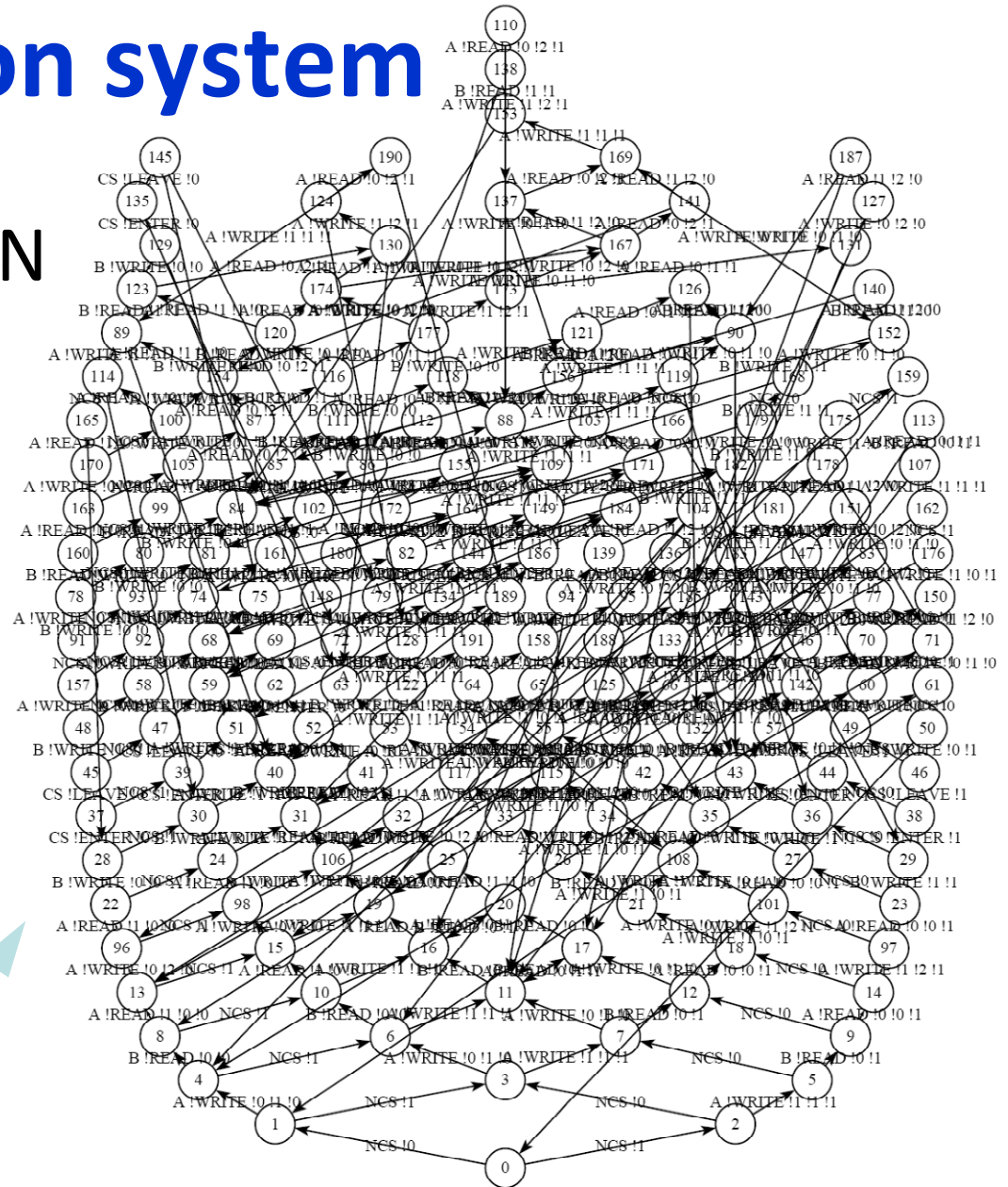
index (0, 1) of the
two-cell array

Labeled transition system

Tool support: LNT.OPEN

- OPEN/CAESAR compliant compiler for LNT
- Allows an on-the-fly exploration of the LTSs corresponding to LNT specifications

LTS of Knuth's protocol
192 states, 384 transitions



Functional analysis by model checking

- Express the essential properties of mutual exclusion protocols in an action-based setting:
 - Mutual exclusion (safety)
 - Livelock freedom (liveness)
 - Starvation freedom (fairness)
 - Amount of overtaking
 - Independent progress
- Verify the properties on the LOTOS NT specification
 - Express properties in MCL
 - Use LNT.OPEN and EVALUATOR 4.0
 - Interpret diagnostics

MCL (Model Checking Language)

[Mateescu-Thivolle-08]

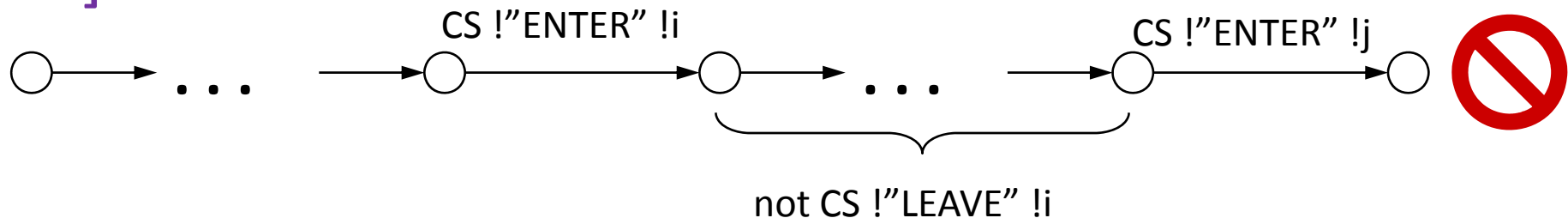
- Extension of modal μ -calculus with:
 - Regular expressions over action sequences
[Mateescu-Sighireanu-03]
 - Modalities that extract data values from LTS labels
 - Fixed point operators parameterized by data variables
 - Constructs inspired from programming languages
- Tool support: **EVALUATOR 4.0**
 - On-the-fly verification of MCL formulas on LTSs
 - Diagnostic generation (examples and counterexamples)
 - Reusable libraries of derived operators (CTL, ACTL, ...) and property patterns [Dwyer-et-al-99]

Mutual exclusion (*safety*)

Two processes can never execute simultaneously their critical sections.

```
[ true* .  
  { CS !"ENTER" ?i:Nat } .  
  (not { CS !"LEAVE" !i })* .  
  { CS !"ENTER" ?j:Nat where j <> i }  
] false
```

data-capture from
the transition label



Livelock freedom (*liveness*)

(first formulation)

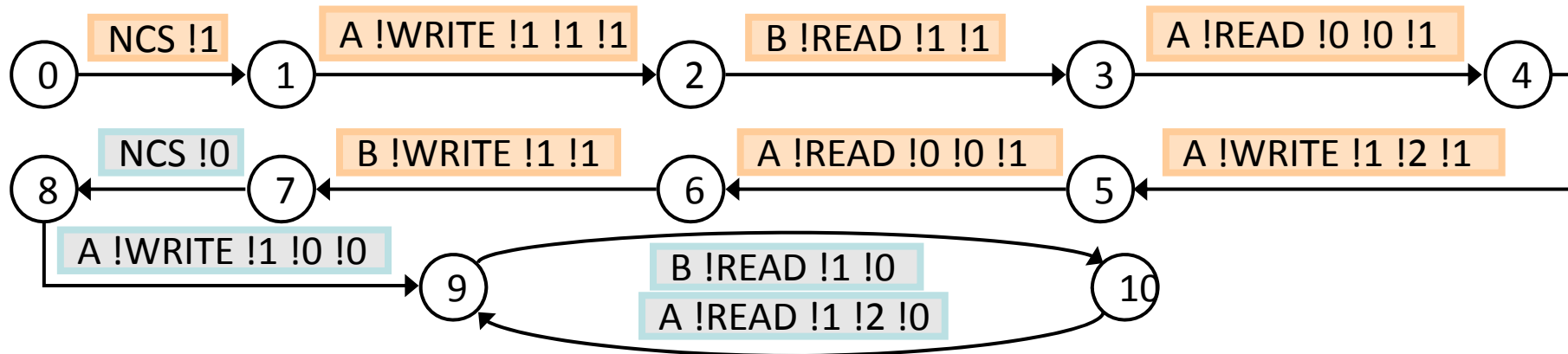
*Each time a process is in its entry section, then **some** process will eventually enter its critical section.*

$$\begin{aligned} & [\text{true}^* . \{ \text{NCS } ?i:\text{Nat} \} . \\ & \quad (\text{not } \{ ?G:\text{String} \dots !i \text{ where } G \neq \text{"CS"} \text{ and } G \neq \text{"NCS"} \})^* . \\ & \quad \{ ?G:\text{String} \dots !i \text{ where } G \neq \text{"CS"} \text{ and } G \neq \text{"NCS"} \} \\ &] \text{ mu } X . (< \text{true} > \text{true} \text{ and } [\text{not } \{ \text{CS !\"ENTER\" } ?\text{any} \}] X) \end{aligned}$$

➔ *this formula fails on all mutex protocols!*

Livelock freedom (first formulation)

Counterexample for Knuth's protocol:



loop

non-critical section ;

loop

A[0] := 1 ;

await B == 0 or A[1] == 0 ;

A[0] := 2 ;

if A[1] != 2 then break ;

end loop ;

B := 0 ;

critical section ;

B := 1 ; A[0] := 0

end loop

P₀

loop

non-critical section ;

loop

A[1] := 1 ;

await B == 1 or A[0] == 0 ;

A[1] := 2 ;

if A[0] != 2 then break ;

end loop ;

B := 1 ;

critical section ;

B := 0 ; A[1] := 0

end loop

P₁

Livelock freedom (second formulation)

Starvation freedom (fairness)

There is no cycle in which every process executes an instruction but no one enters its critical section.

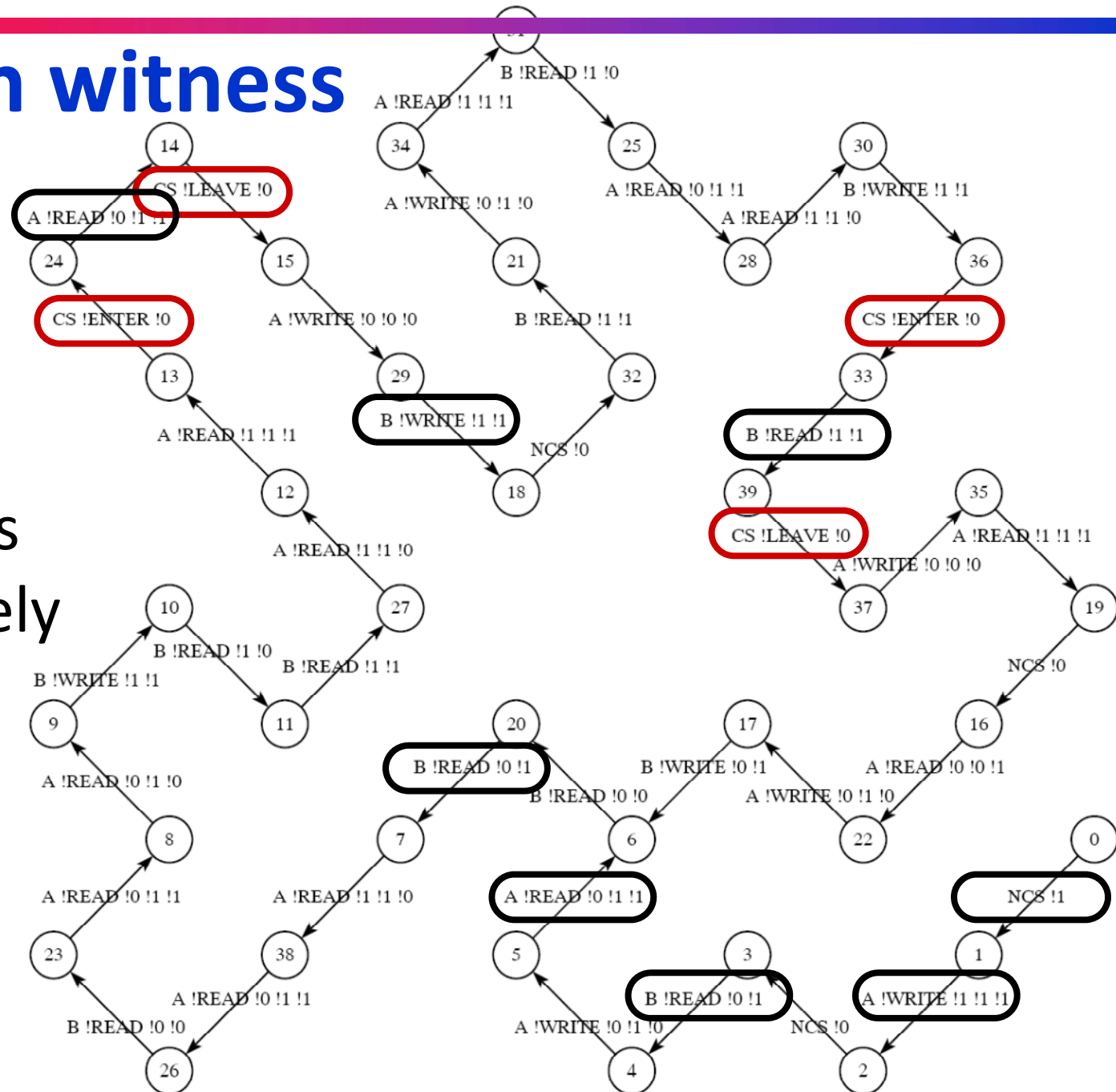
```
[ true* . { NCS ?i:Nat } .  
  (not { ?G:String ... !i where G <> "CS" and G <> "NCS" })* .  
  { ?G:String ... !i where G <> "CS" and G <> "NCS" }  
]  
not < for j:Nat from 0 to N-1 do  
  (not { CS ... !i })* .  
  { ?G:String ... ?j:Nat where ((G <> "CS") or (j <> i)) } .  
end for > @
```

→ holds on all mutex protocols

→ holds on some mutex protocols

Starvation witness

- Protocol
3b_p2
[BDT-03]
- P_0 overtakes
 P_1 indefinitely



Bounded overtaking

How many times a process i can be overtaken by process j in accessing the critical section?

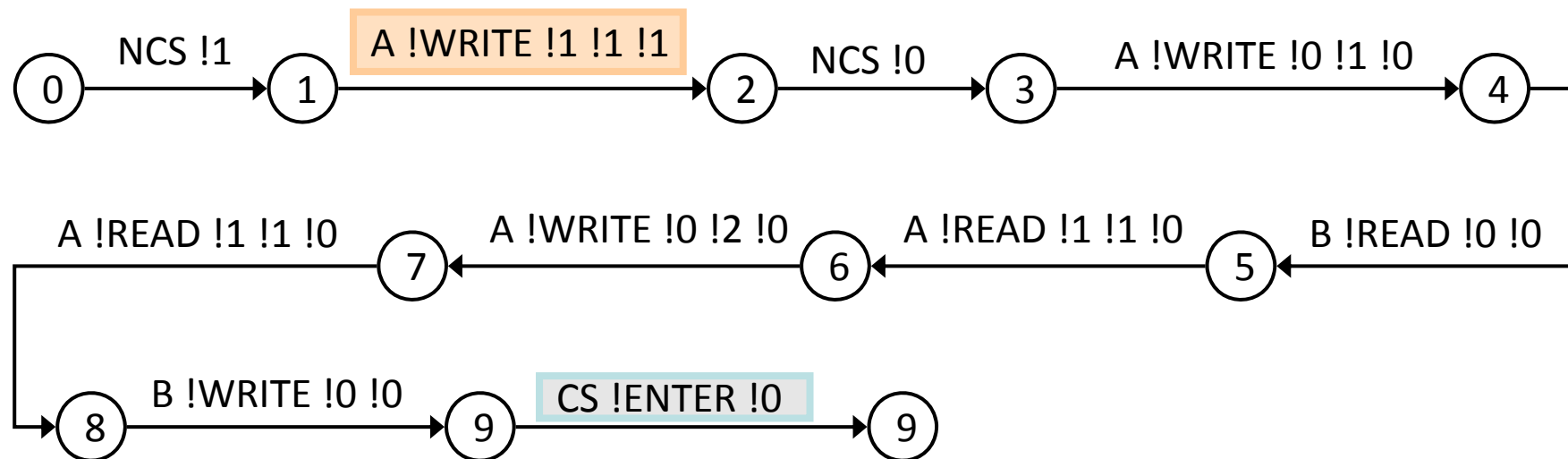
```
< true* . { NCS !i } .  
  (not { ?G:String ... !i where G <> "CS" and G <> "NCS" })* .  
  { ?G:String ... !i where G <> "CS" and G <> "NCS" } .  
  ( for k:Nat from 0 to N-1 do  
    (not { CS ?any !i })* .  
    { ?G:String ... !k where k = i implies G <> "CS" }  
  end for .  
  (not { CS ?any !i })* . { CS !"ENTER" !j }  
) { Max }  
> true
```

P_i overtakes P_j

Witness of bounded overtaking

For Knuth's protocol:

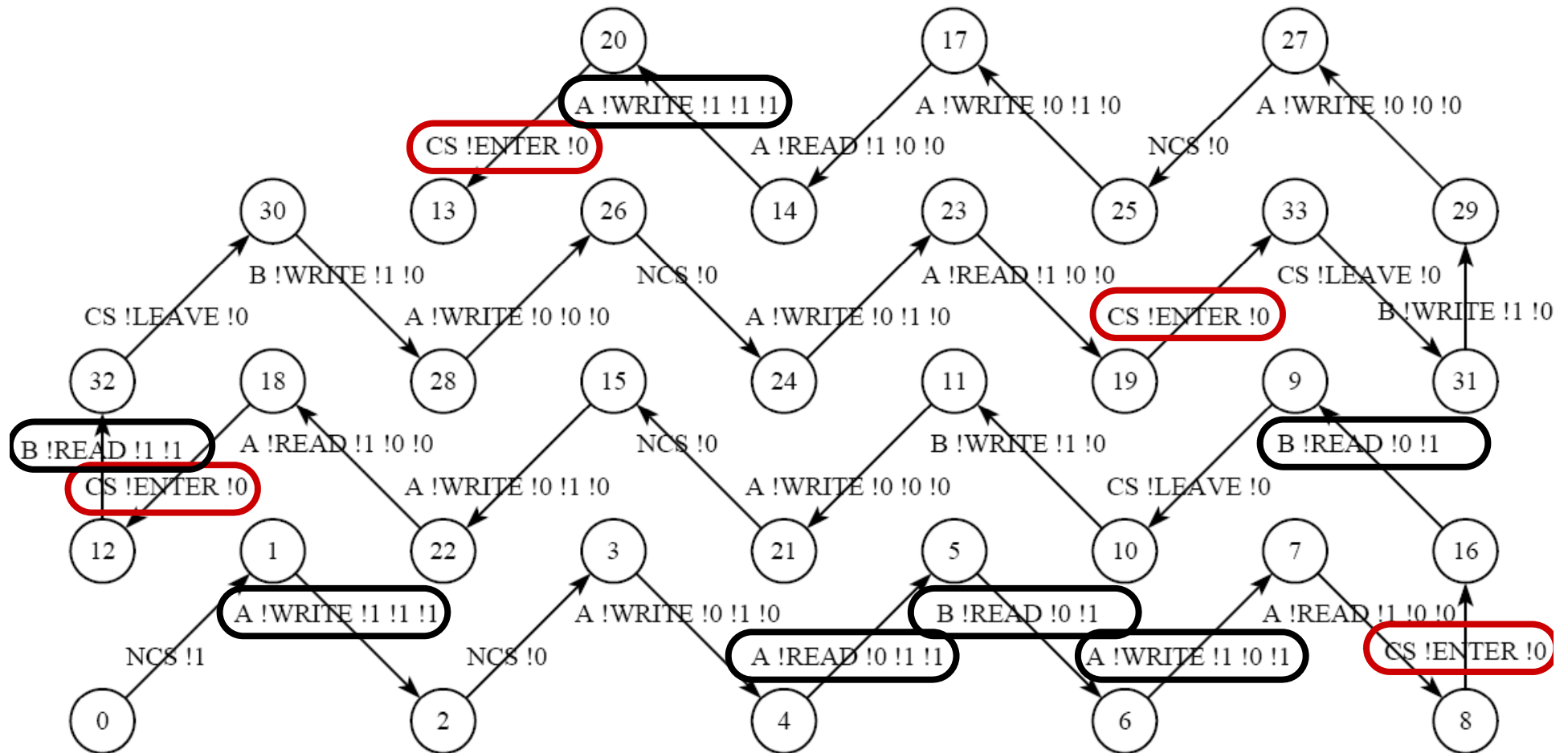
• witness with one overtake of P_1 by P_0 (max = 1):



• no witness with more overtakes of P_1 by P_0 found

Witness of bounded overtaking

Dekker's protocol: at most 4 overtakes of P_1 by P_0



First-Come First-Served

Independent progress

[Dijkstra-65]

*If a process stops in its **non-critical** section, the other processes can still access their critical sections.*

forall $i:\text{Nat}$ among $\{0 \dots 1\}$.

[true*] (

< { NCS !1 - i } > true

implies

< { ... !i }* . { CS !"ENTER" !i } .

{ ... !i }* . { CS !"LEAVE" !i }

> @

)

P_{1-i} stops at the beginning of its entry section

➔ *holds on all mutex protocols, but should be checked separately*

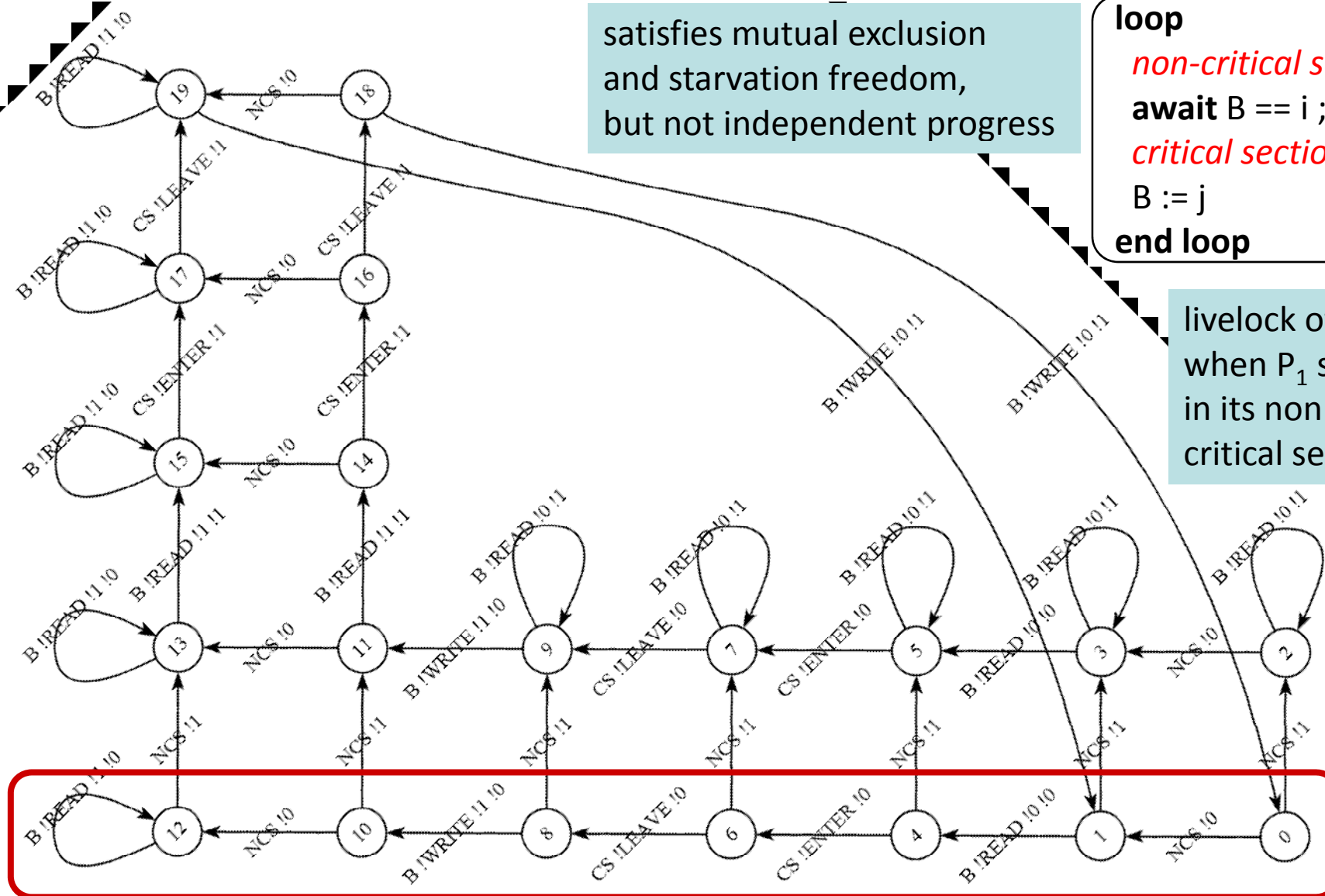
Trivial one-bit protocol

satisfies mutual exclusion
and starvation freedom,
but not independent progress

```

loop
  non-critical section ;
  await B == i ;
  critical section ;
  B := j
end loop
Pj
    
```

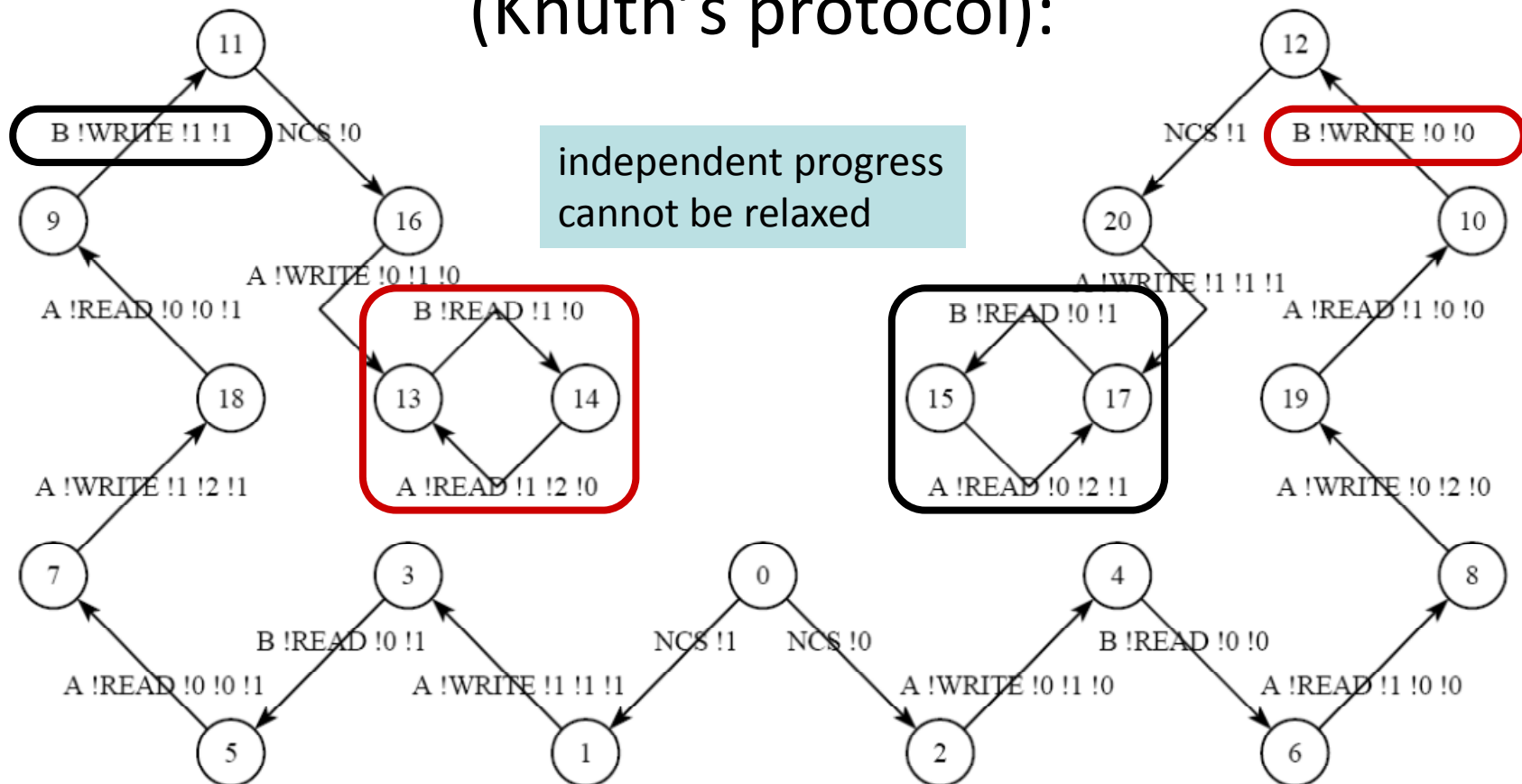
livelock of P_0
when P_1 stops
in its non
critical section



Livelock upon crash

(outside the non critical sections)

Livelock of each process when the other one
“has decided to stop” in its entry section
(Knuth’s protocol):



Model checking summary (2 processes)

| Protocol | star- vation | ind. prog | overtaking P_0/P_1 P_1/P_0 | |
|-------------|-----------------|--------------|-------------------------------------|----------|
| Anderson | all | all | 1 | 1 |
| Burns&Lynch | P_0 | all | ∞ | 1 |
| B&W Bakery | all | all | 2 | 2 |
| CLH | all | all | 1 | 1 |
| Dekker | all | all | 4 | 4 |
| Dijkstra | none | all | ∞ | ∞ |
| Kessels | all | all | 2 | 2 |
| Knuth | all | all | 1 | 1 |
| Lamport | none | all | ∞ | ∞ |
| MCS | all | all | 1 | 1 |
| Peterson | all | all | 1 | 1 |
| Peterson_t | all | all | 1 | 1 |
| Szymanski | all | all | 2 | 1 |
| TAS | none | all | ∞ | ∞ |
| TTAS | none | all | ∞ | ∞ |
| trivial | all | none | 1 | 1 |

| Protocol | star- vation | ind. prog | overtaking P_0/P_1 P_1/P_0 | |
|----------------|-----------------|--------------|-------------------------------------|----------|
| 2b_p1 | P_0 | all | ∞ | 1 |
| 2b_p2 | P_0 | all | ∞ | 1 |
| 2b_p3 | P_1 | all | 1 | ∞ |
| 3b_p1 | all | all | 2 | 2 |
| 3b_p2 | P_0 | all | ∞ | 1 |
| 3b_c_p1 (orig) | all | all | 1 | 1 |
| 3b_c_p1 | all | all | 1 | 1 |
| 3b_c_p2 | all | all | 1 | 1 |
| 4b_p1 | P_0 | all | ∞ | 1 |
| 4b_p2 | all | all | 2 | 2 |
| 4b_c_p1 | P_0 | all | ∞ | 1 |
| 4b_c_p2 | P_1 | all | 1 | ∞ |

mutual exclusion and livelock freedom satisfied by all protocols

Model checking summary (3 processes)

| Protocol | starvation-free | independ. progress | overtaking | | | | | |
|-------------|-----------------|--------------------|------------|-----------|-----------|-----------|-----------|-----------|
| | | | P_0/P_1 | P_0/P_2 | P_1/P_0 | P_1/P_2 | P_2/P_0 | P_2/P_1 |
| Anderson | all | all | 1 | 1 | 1 | 1 | 1 | 1 |
| Burns&Lynch | P_0 | all | ∞ | ∞ | | ∞ | | ∞ |
| B&W Bakery | all | all | 2 | 2 | 2 | 2 | 2 | 2 |
| CLH | all | all | 1 | 1 | 1 | 1 | 1 | 1 |
| Dijkstra | none | all | ∞ | ∞ | ∞ | ∞ | ∞ | ∞ |
| Knuth | all | all | 1 | 2 | 2 | 1 | 1 | 2 |
| Lamport | none | all | ∞ | ∞ | ∞ | ∞ | ∞ | ∞ |
| MCS | all | all | 1 | 1 | 1 | 1 | 1 | 1 |
| Peterson | all | all | 6 | 6 | 6 | 6 | 6 | 6 |
| Peterson_t | all | all | 1 | 1 | 1 | 1 | 12 | 12 |
| Szymanski | all | all | 2 | 2 | 1 | 2 | 1 | 1 |
| TAS | none | all | ∞ | ∞ | ∞ | ∞ | ∞ | ∞ |
| TTAS | none | all | ∞ | ∞ | ∞ | ∞ | ∞ | ∞ |
| trivial | all | none | 1 | 1 | 1 | 1 | 1 | 1 |

mutual exclusion and livelock freedom satisfied by all protocols

Performance evaluation using IMCs

- Verification and performance analysis on the same model
- Enrich functional model with (exponential) delays
 - constraint-oriented style: composition with a process “L”
 - each action corresponds to the begin of a delay
 - process L enforces alternation of delays and actions
- Compute transient/steady-state probabilities on the underlying Markov chain
- Tool support by CADP
 - **BCG_MIN**: minimization
 - **BCG_STEADY**: computation of steady-state probabilities
 - **BCG_TRANSIENT**: computation of transient probabilities

LNT specification

(auxiliary process for delay insertion)

```
process L [A, B: Operation, CS: Access, NCS: Pid, MU: Latency] is  
  var index, pid:Nat, sig:Signal in  
    loop  
      select  
        A (!Read, ?index, ?any Nat, ?pid); MU (!Read, !index, !pid)  
        [] A (!Write, ?index, ?any Nat, ?pid); MU (!Write, !index, !pid)  
        [] B (!Read, ?any Nat, ?pid); MU (!Read, !pid)  
        [] B (!Write, ?any Nat, ?pid); MU (!Write, !pid)  
        [] CS (?sig, ?pid); if sig == Enter then MU (!sig, !pid) end if  
        [] NCS (?pid); MU (!Work, !pid)  
      end select  
    end loop  
  end var  
end process
```

Continuous-Time Markov Chains (CTMCs) in the BCG format

- Syntax of actions (transition labels):

- Stochastic transition “**rate %f**”
- Labeled stochastic transition “**action; rate %f**”
- Internal transition “i”

strictly positive
floating-point
number

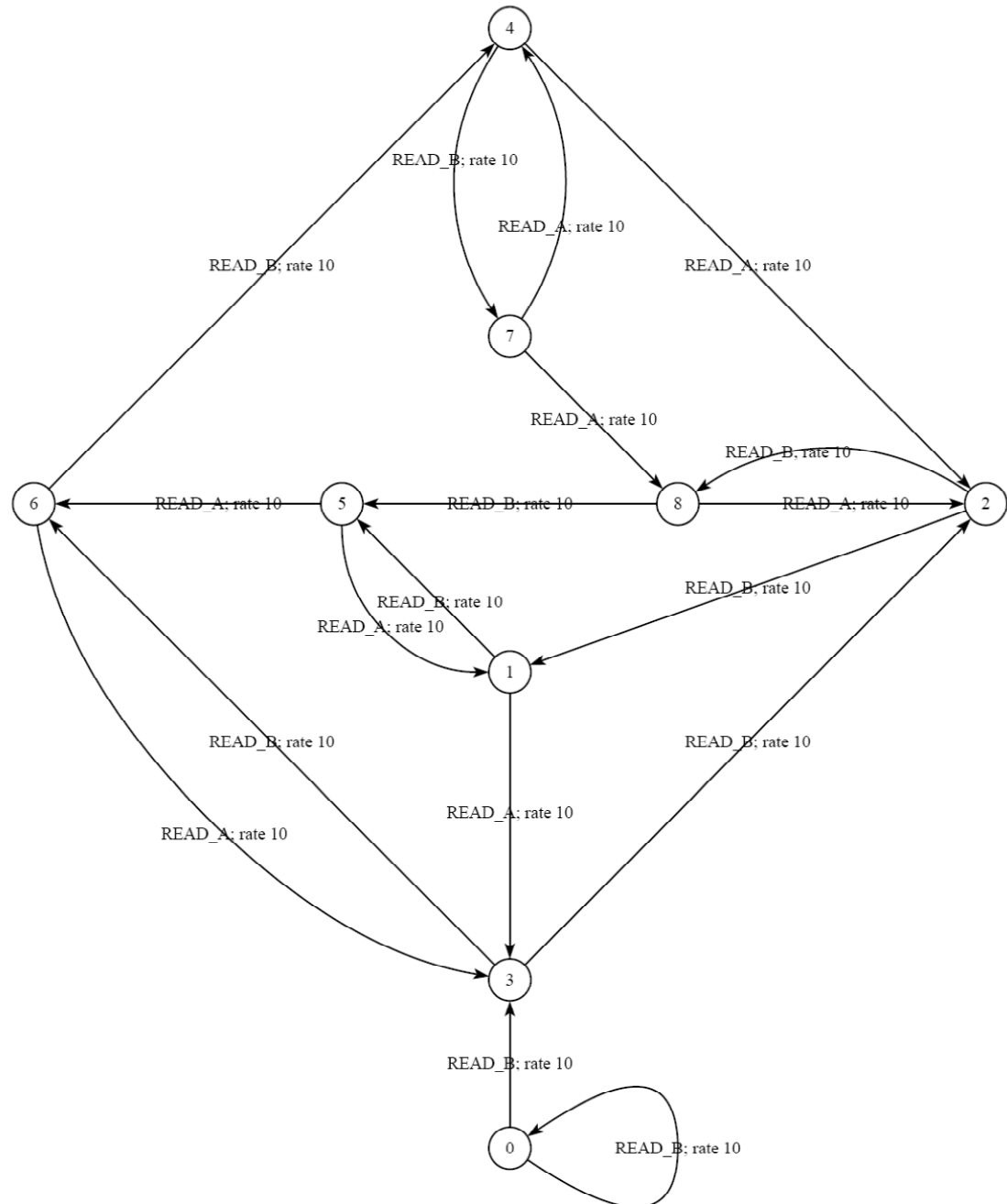
character string
without ‘;’

- Terminology for states:

- **Stable** state: without i-successors
- **Unstable** state: with some i-successors
- **Nondeterministic** state: with at least two i-successors

Example CTMC

- Mutual exclusion protocol with three shared variables
- CTMC contains only read accesses to shared variables



Dealing with nondeterminism

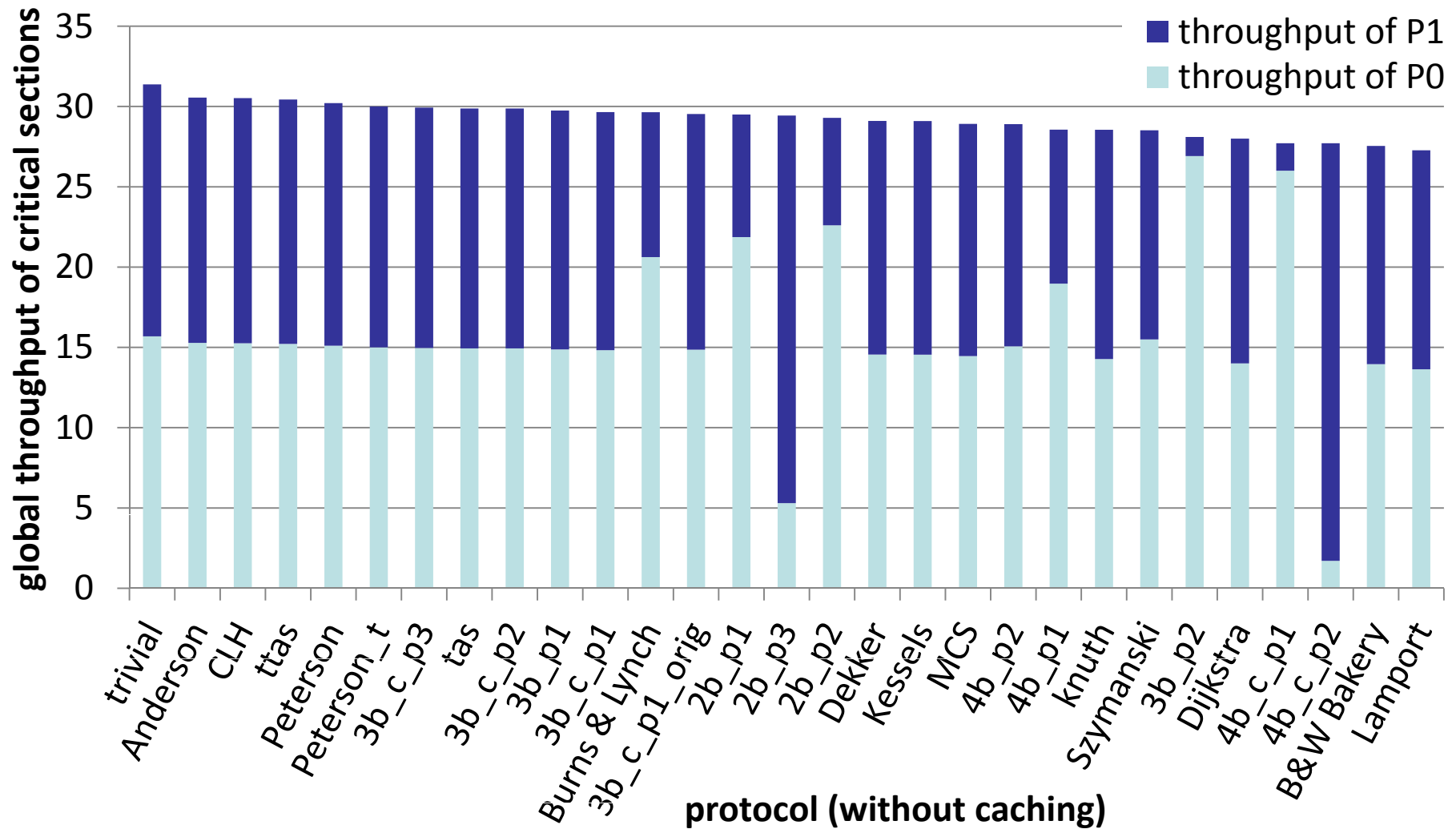
- Numerous nondeterministic (2-branch) choices due to concurrent accesses of P_0 , P_1 to shared variables
- Work-around: model a *fair scheduler* replacing an equiprobable probabilistic choice
- Performance evaluation approach:
 - hide accesses to shared variables
 - minimize for stochastic branching bisimulation
 - rename remaining “i”-transitions into “**prob 0.5**”
 - ➔ yields a “continuous-time probabilistic Markov chain”
a graph with stochastic and probabilistic transitions
 - compute steady-state throughputs using BCG_STEADY

Performance experiments

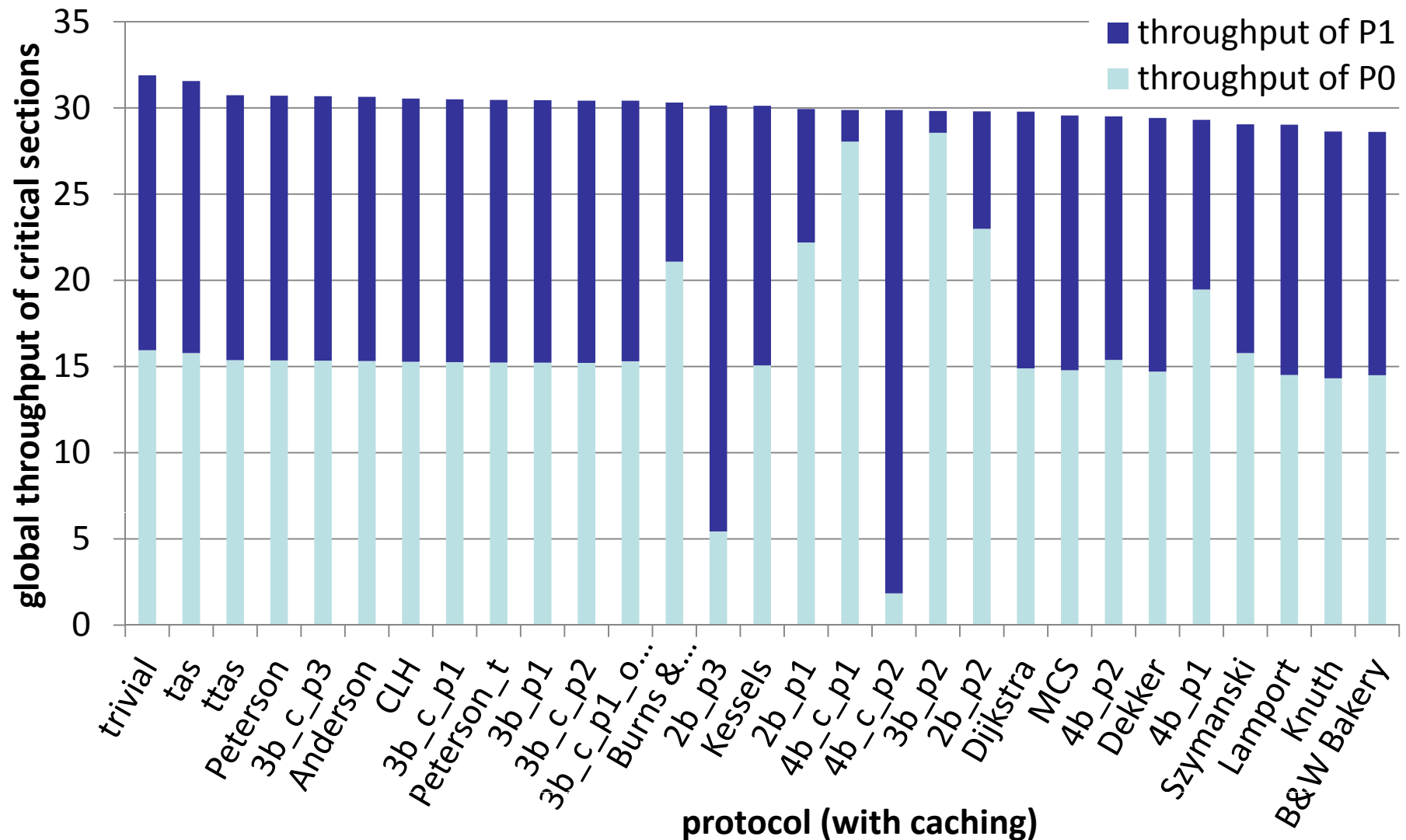
- Goal: detect tendencies, no absolute values
- Throughput of the critical section:
 - relative (one process only)
 - cumulative (sum of both processes)
- Cache access 50 times faster than memory access
- Rate parameters
 - critical section: 100
 - variable access
- Varying rate for the non-critical section(s)

| rates | local cache | remote cache | memory |
|----------|-------------|--------------|--------|
| read | 150,000 | 1,200 | 3000 |
| write | 135,000 | 2,000 | 2000 |
| test&set | 71,052 | 750 | 1,200 |

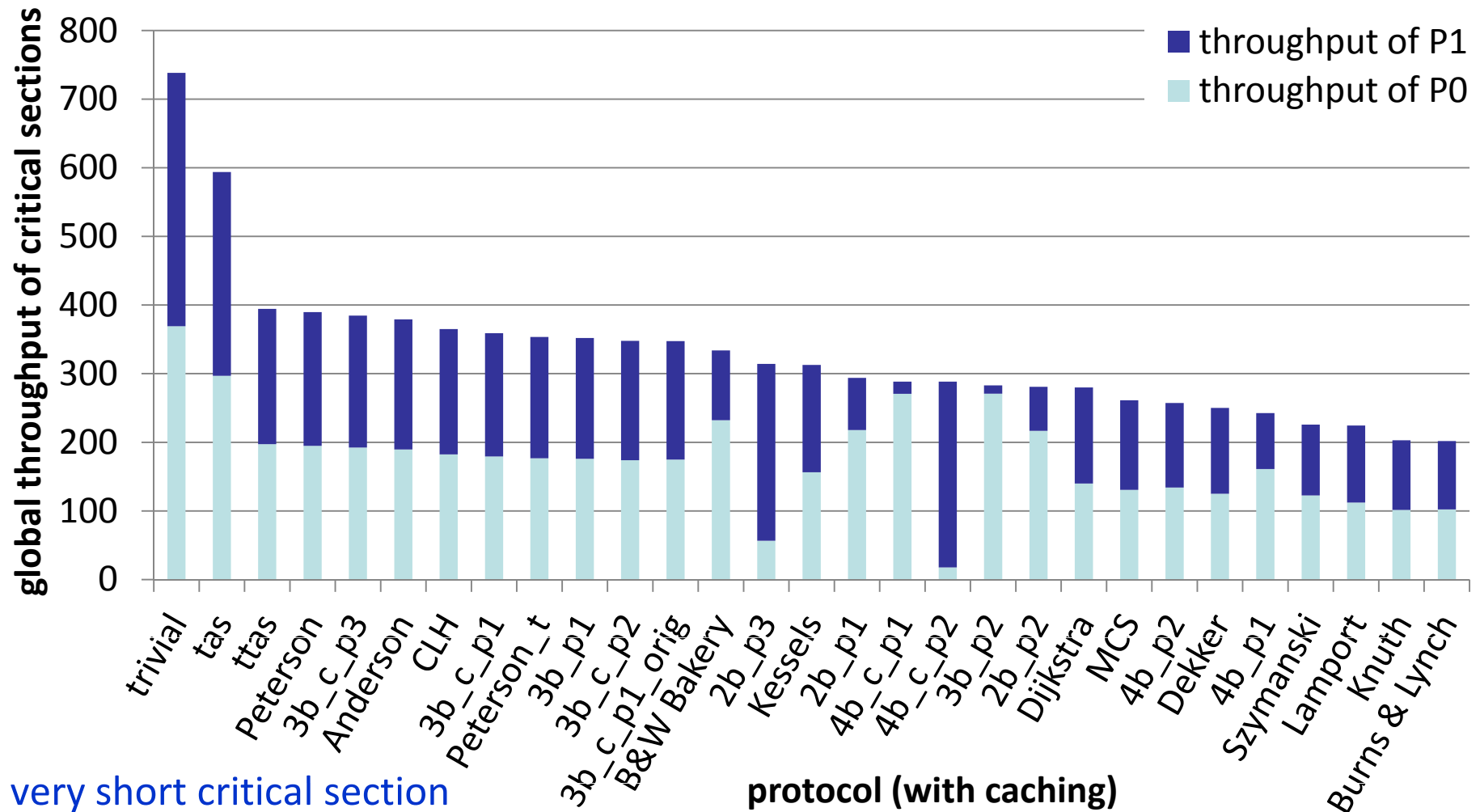
Comparison of the protocols (2 processes)



Comparison of the protocols (2 processes)

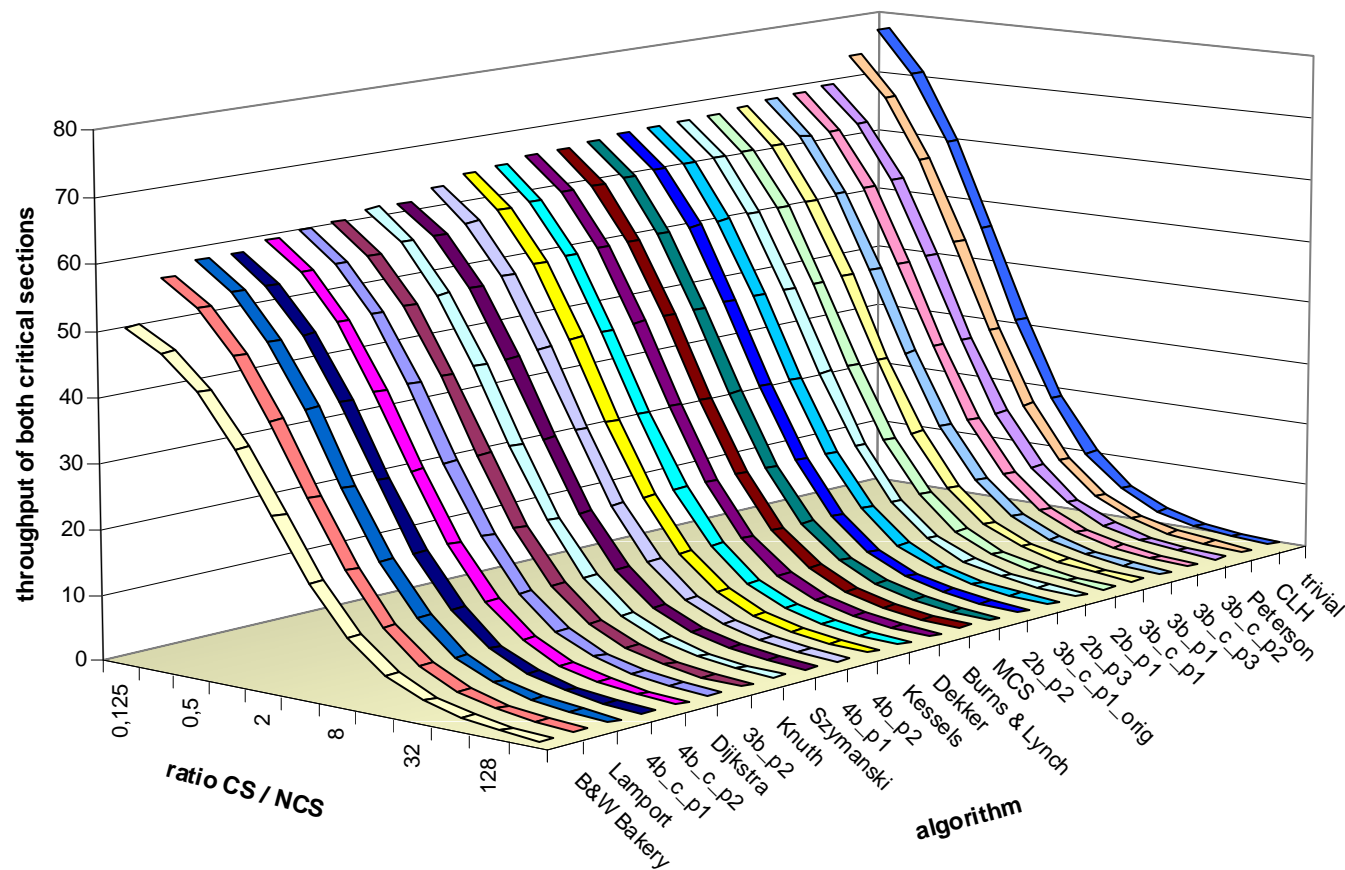


Comparison of the protocols (2 processes)

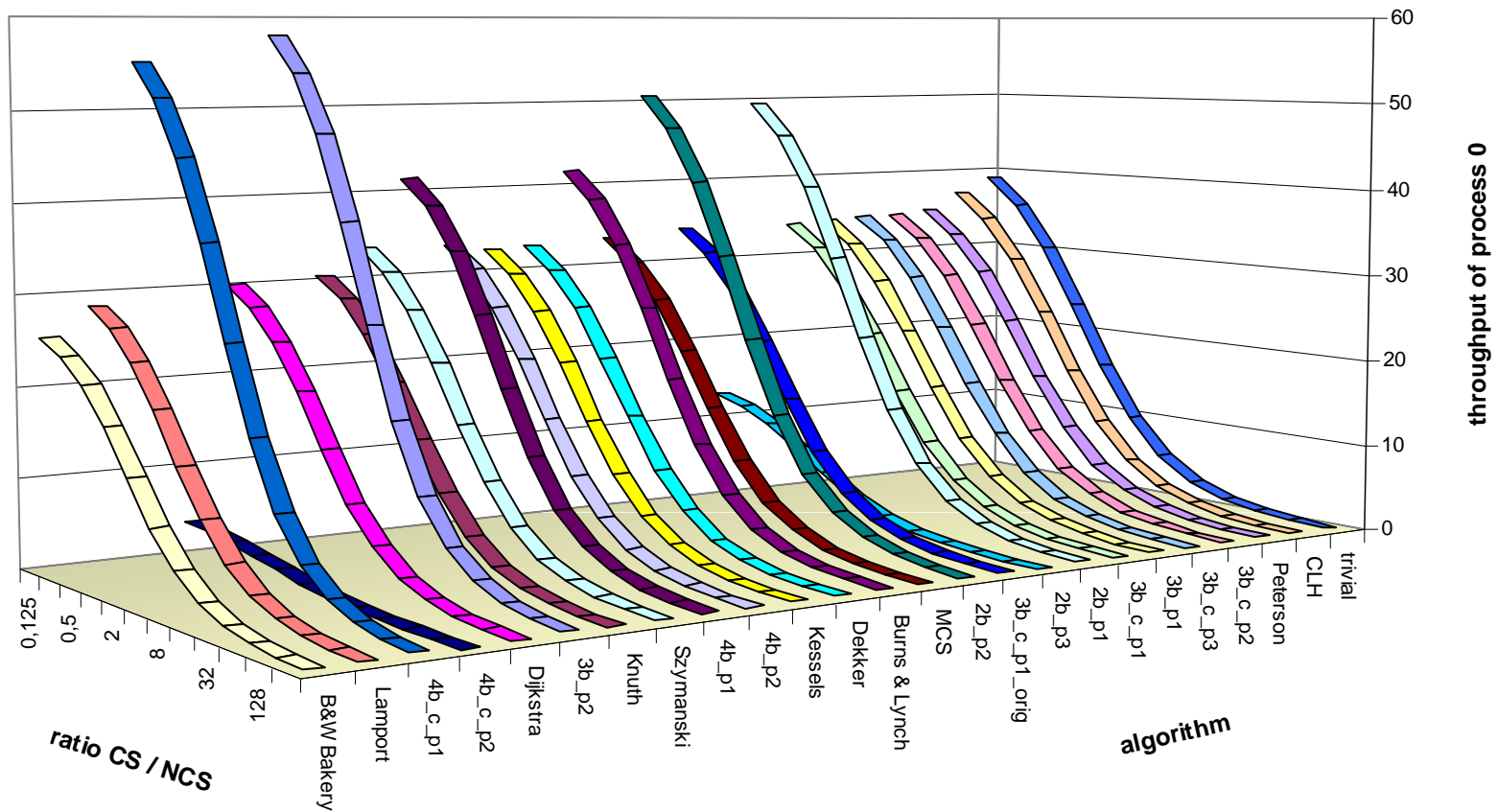


very short critical section
(rate ten million)

Varying ratio critical/non-critical section

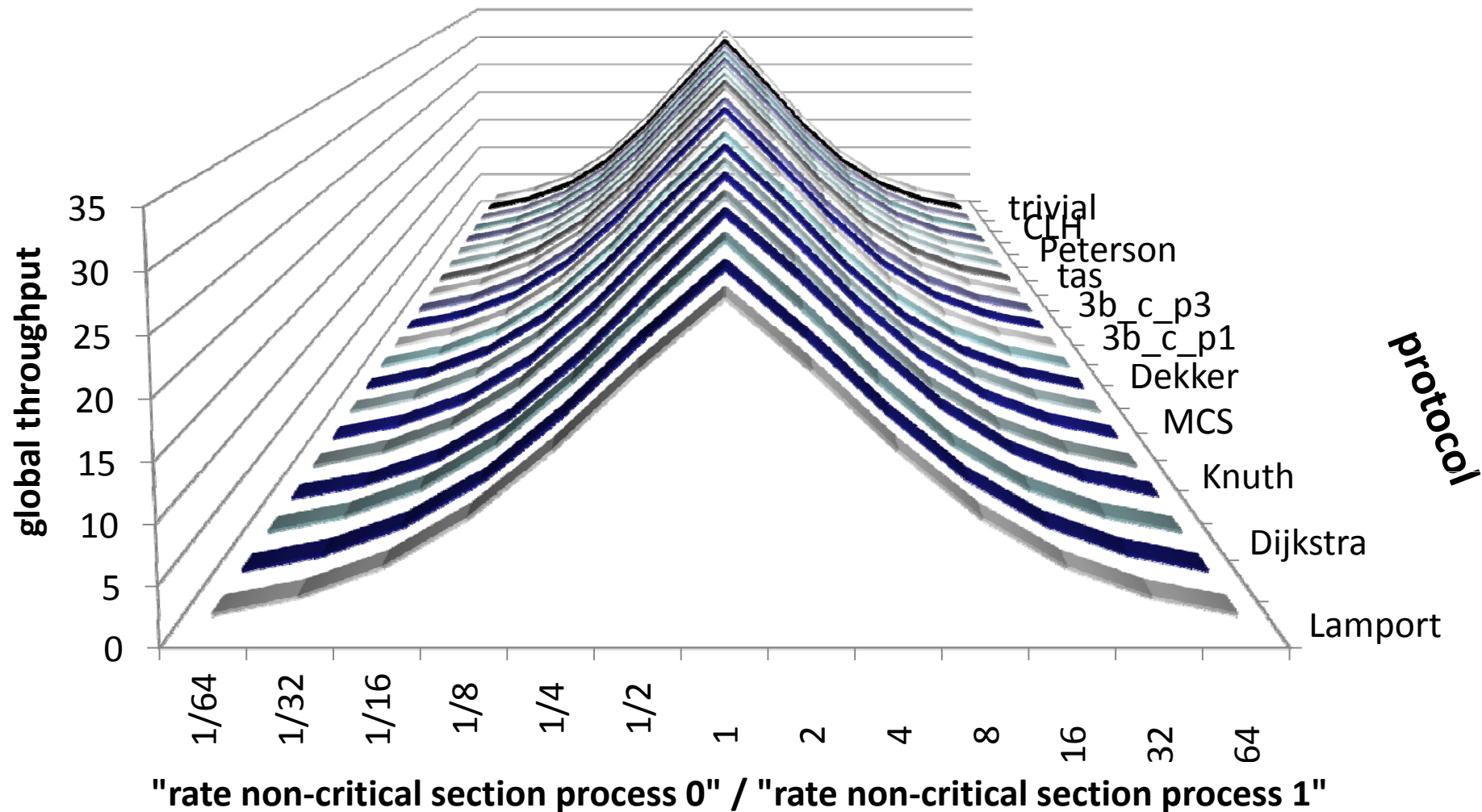


Varying ratio critical/non-critical section



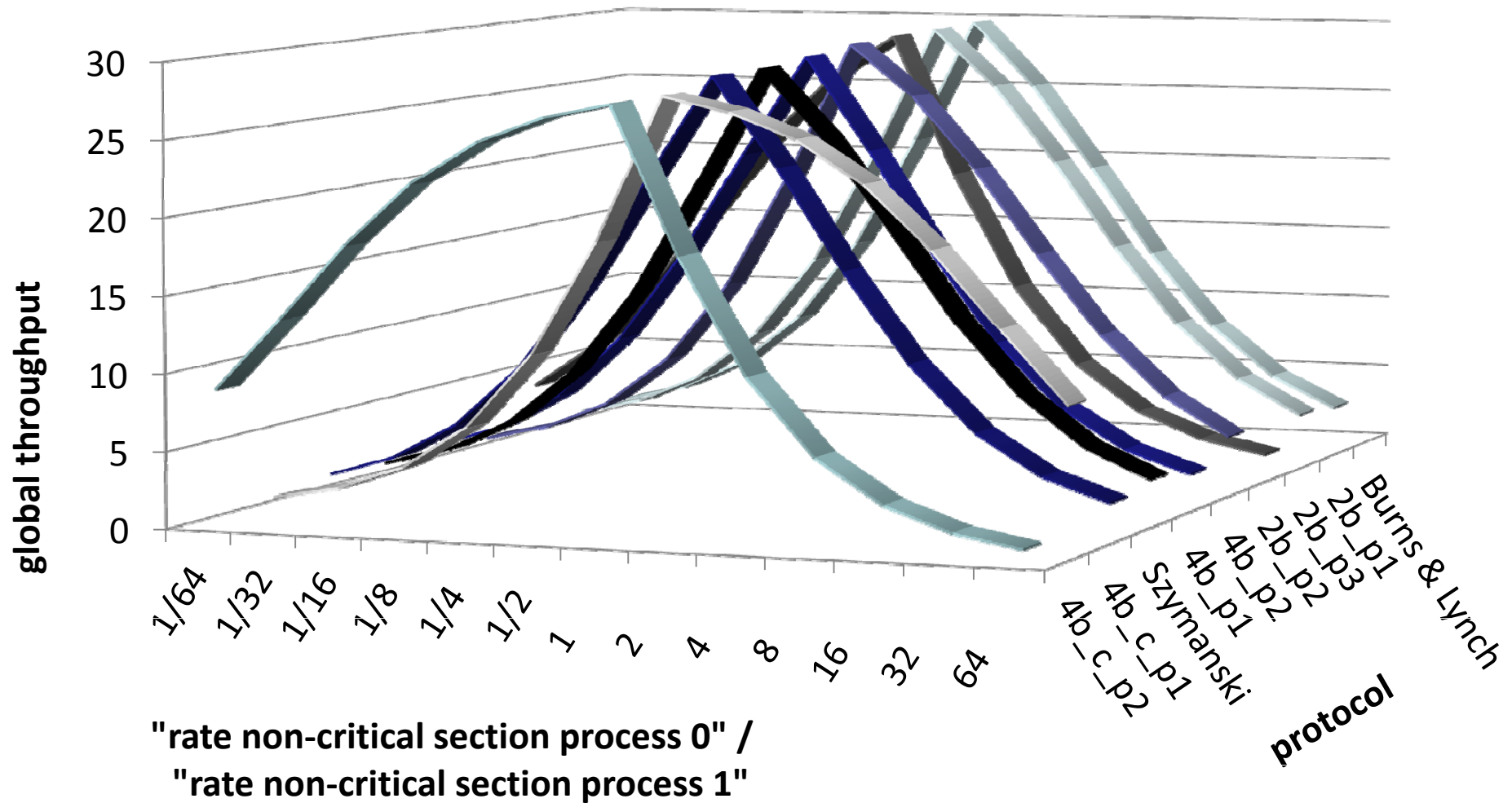
Varying ratio of non-critical sections

(cumulated throughput for symmetric protocols)



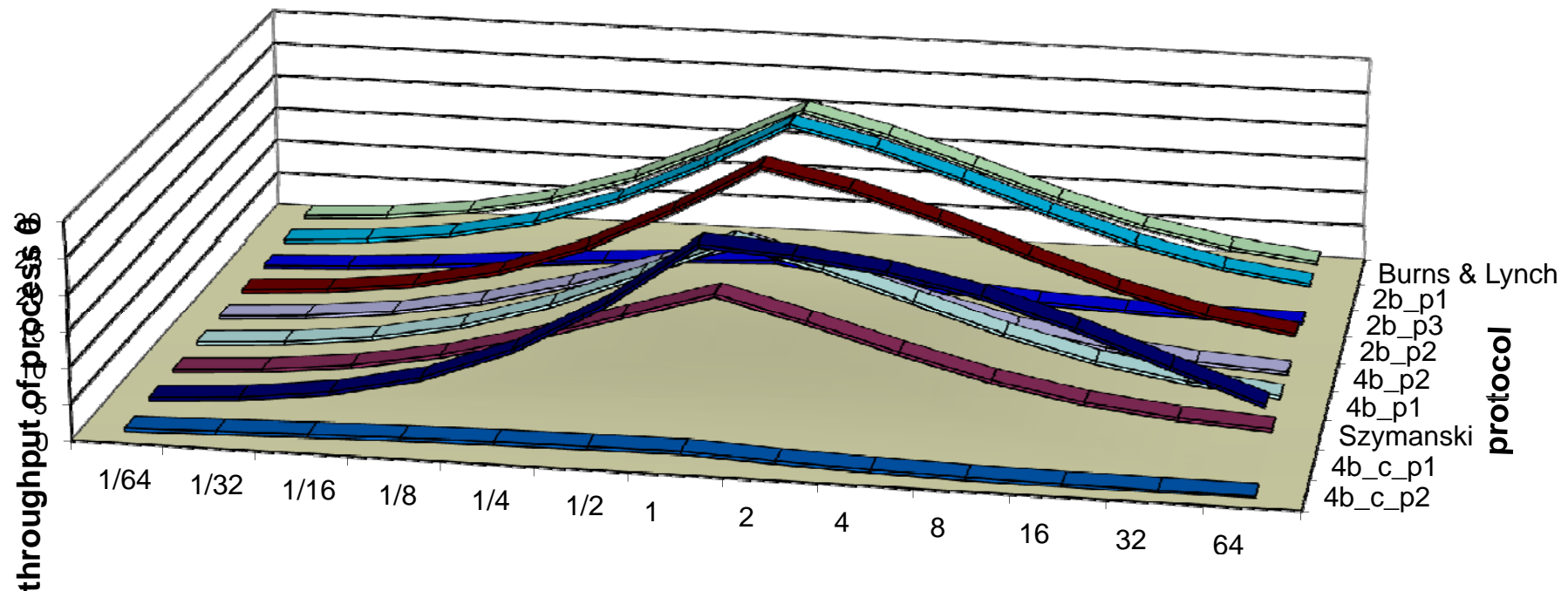
Varying ratio of non-critical sections

(cumulated throughput for asymmetric protocols)



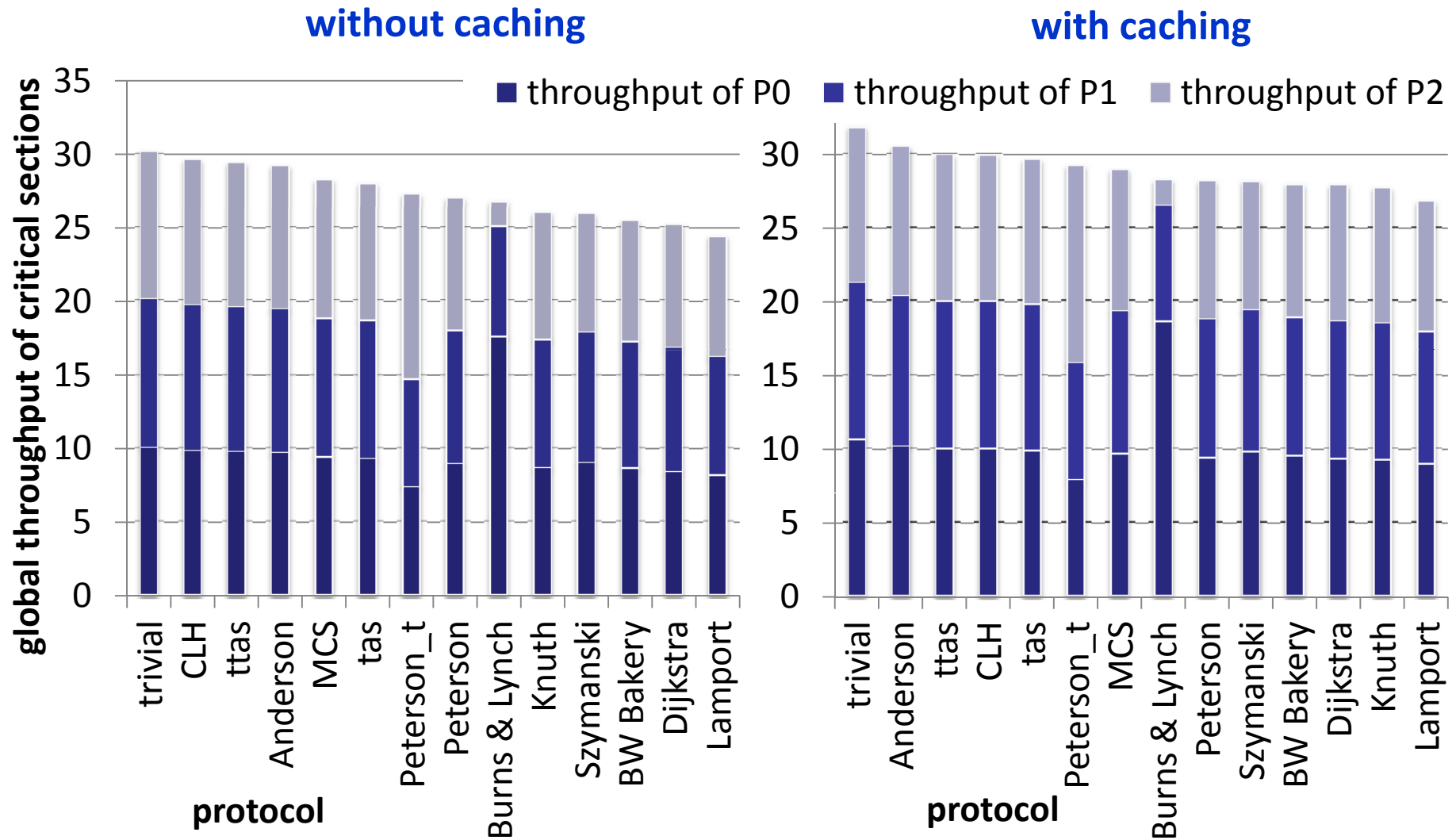
Varying ratio of non-critical sections

(throughput of process 0 for asymmetric protocols)

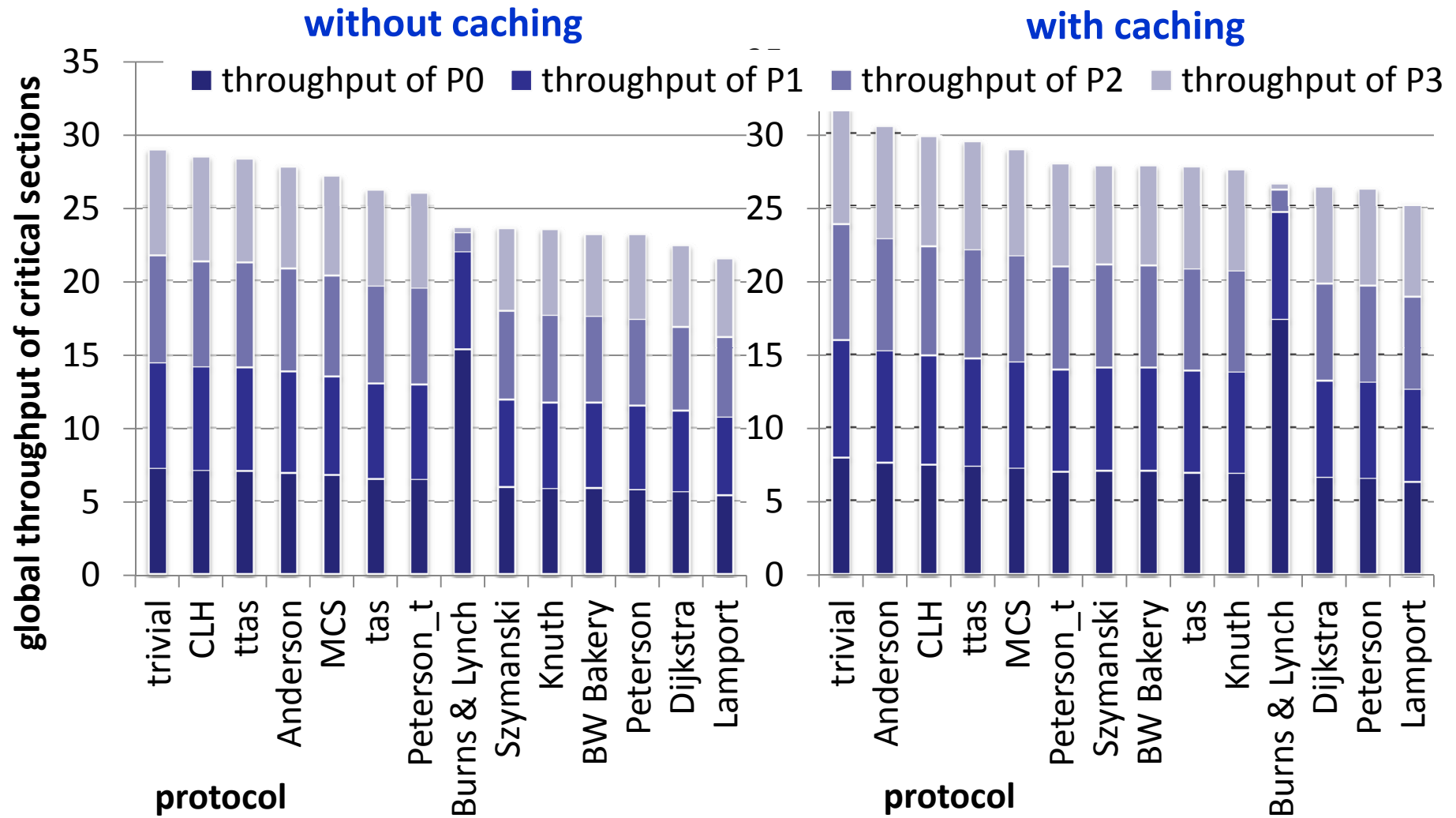


"rate non-critical section process 0" / "rate non-critical section process 1"

Comparison of the protocols (3 processes)

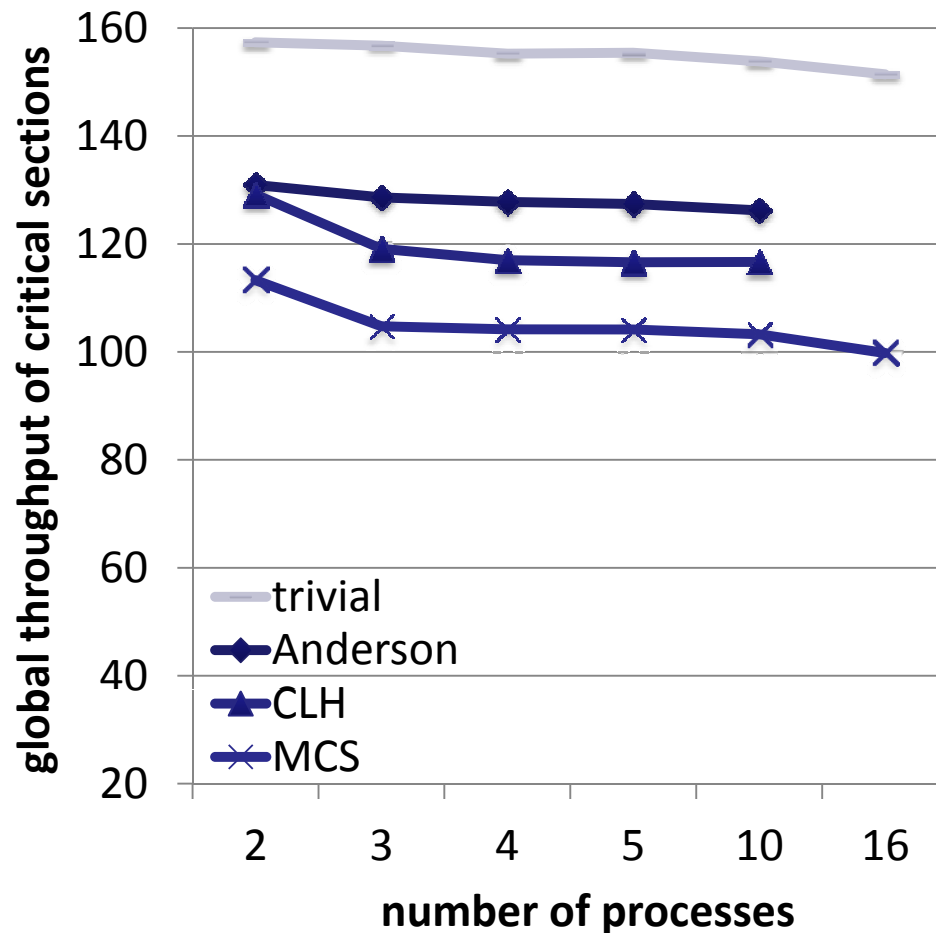


Comparison of the protocols (4 processes)

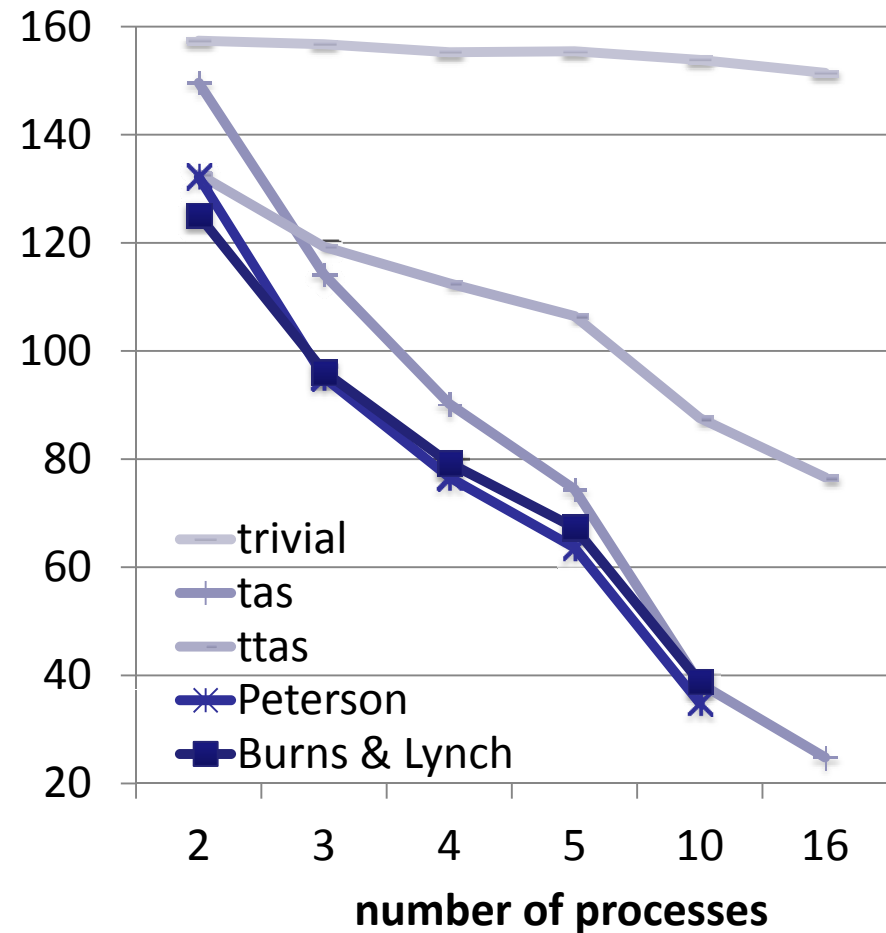


Scalability-Comparison

scalable protocols



non-scalable protocols



Conclusion

- Formal analysis and performance evaluation of mutual exclusion protocols on a single model
- Automated analysis using CADP tools
- Corroboration of experimental results

More information about CADP

<http://cadp.inria.fr>

and

<http://cadp.forumotion.com>

Steps to obtain a CADP license:

1. register <http://cadp.inria.fr/registration>
(with an academic email address)
2. download and install CADP
3. request a license