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► **To cite this version:**

Yaozhong Hu, Maria Jolis, Samy Tindel. On Stratonovich and Skorohod stochastic calculus for Gaussian processes. *Annals of Probability*, 2013, 41 (3), pp.1656-1693. 10.1214/12-AOP751 . hal-00556955

HAL Id: hal-00556955

<https://inria.hal.science/hal-00556955v1>

Submitted on 18 Jan 2011

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ON STRATONOVICH AND SKOROHOD STOCHASTIC CALCULUS FOR GAUSSIAN PROCESSES

YAOZHONG HU, MARIA JOLIS, AND SAMY TINDEL

ABSTRACT. In this article, we derive a Stratonovich and Skorohod type change of variables formula for a multidimensional Gaussian process with low Hölder regularity γ (typically $\gamma \leq 1/4$). To this aim, we combine tools from rough paths theory and stochastic analysis.

1. INTRODUCTION

Starting from the seminal paper [7], the stochastic calculus for Gaussian processes has been thoroughly studied during the last decade, fractional Brownian motion being the main example of application of the general results. The literature on the topic includes the case of Volterra processes corresponding to a fBm with Hurst parameter $H > 1/4$ (see [1, 12]), with some extensions to the whole range $H \in (0, 1)$ as in [2, 6, 11]. It should be noticed that all those contributions concern the case of real valued processes, this feature being an important aspect of the computations.

In a parallel and somewhat different way, the rough path analysis opens the possibility of a pathwise type stochastic calculus for general (including Gaussian) stochastic processes. Let us recall that this theory, initiated by T. Lyons in [20] (see also [9, 21, 13] for introductions to the topic), states that if a γ -Hölder process x allows to define sufficient number of iterated integrals then:

- (1) One gets a Stratonovich type change of variable for $f(x)$ when f is smooth enough.
- (2) Differential equations driven by x can be reasonably defined and solved.

In particular, the rough path method is still the only way to solve differential equations driven by Gaussian processes with Hölder regularity exponent less than $1/2$, except for some very particular (e.g. Brownian, linear or one-dimensional) situations.

More specifically, the rough path theory relies on the following set of assumptions:

Hypothesis 1.1. *Let $\gamma \in (0, 1)$ and $x : [0, T] \rightarrow \mathbb{R}^d$ be a γ -Hölder process. Consider also the n^{th} order simplex $\mathcal{S}_{n,T} = \{(u_1, \dots, u_n) : 0 \leq u_1 < \dots < u_n \leq T\}$ on $[0, T]$. The process x is supposed to generate a rough path, which can be understood as a stack $\{\mathbf{x}^n; n \leq \lfloor 1/\gamma \rfloor\}$ of functions of two variables satisfying the following three properties:*

- (1) *Regularity: Each component of \mathbf{x}^n is $n\gamma$ -Hölder continuous (in the sense of the Hölder norm introduced in (10)) for all $n \leq \lfloor 1/\gamma \rfloor$, and $\mathbf{x}_{st}^1 = x_t - x_s$.*

Date: January 18, 2011.

2000 Mathematics Subject Classification. Primary 60H35; Secondary 60H07, 60H10, 65C30.

Key words and phrases. Gaussian processes, rough paths, Malliavin calculus, Itô's formula.

S. Tindel is partially supported by the (French) ANR grant ECRU. M. Jolis is partially supported by grant MTM2009-08869 Ministerio de Ciencia e Innovación and FEDER.

(2) *Multiplicativity*: Letting $(\delta \mathbf{x}^n)_{sut} := \mathbf{x}_{st}^n - \mathbf{x}_{su}^n - \mathbf{x}_{ut}^n$ for $(s, u, t) \in \mathcal{S}_{3,T}$, one requires

$$(\delta \mathbf{x}^n)_{sut}(i_1, \dots, i_n) = \sum_{n_1=1}^{n-1} \mathbf{x}_{su}^{n_1}(i_1, \dots, i_{n_1}) \mathbf{x}_{ut}^{n-n_1}(i_{n_1+1}, \dots, i_n). \quad (1)$$

(3) *Geometricity*: For any n, m such that $n + m \leq \lfloor 1/\gamma \rfloor$ and $(s, t) \in \mathcal{S}_{2,T}$, we have:

$$\mathbf{x}_{st}^n(i_1, \dots, i_n) \mathbf{x}_{st}^m(j_1, \dots, j_m) = \sum_{\bar{k} \in Sh(\bar{i}, \bar{j})} \mathbf{x}_{st}^{n+m}(k_1, \dots, k_{n+m}), \quad (2)$$

where, for two tuples \bar{i}, \bar{j} , $\Sigma_{(\bar{i}, \bar{j})}$ stands for the set of permutations of the indices contained in (\bar{i}, \bar{j}) , and $Sh(\bar{i}, \bar{j})$ is a subset of $\Sigma_{(\bar{i}, \bar{j})}$ defined by:

$$Sh(\bar{i}, \bar{j}) = \{ \sigma \in \Sigma_{(\bar{i}, \bar{j})}; \sigma \text{ does not change the orderings of } \bar{i} \text{ and } \bar{j} \}.$$

With this set of abstract assumptions in hand, one can define integrals like $\int f(x) dx$ in a natural way (as recalled later in the article), and more generally set up the basis of a differential calculus with respect to x . Notice that according to T. Lyons terminology [21], the family $\{\mathbf{x}^n; n \leq \lfloor 1/\gamma \rfloor\}$ is said to be a weakly geometric rough path above x .

Without any surprise, some substantial efforts have been made in the last past years in order to construct rough paths above a wide class of Gaussian processes, among which emerges the case of fractional Brownian motion. Let us recall that a fractional Brownian motion B with Hurst parameter $H \in (0, 1)$, defined on a complete probability space $(\Omega, \mathcal{F}, \mathbf{P})$, is a d -dimensional centered Gaussian process. Its law is thus characterized by its covariance function, which is given by

$$\mathbf{E}[B_t(i)B_s(i)] = \frac{1}{2}(t^{2H} + s^{2H} - |t - s|^{2H}) \mathbf{1}_{(i=j)}, \quad s, t \in \mathbb{R}_+. \quad (3)$$

The variance of the increments of B is then given by

$$\mathbf{E}[(B_t(i) - B_s(i))^2] = (t - s)^{2H}, \quad (s, t) \in \mathcal{S}_{2,T}, \quad i = 1, \dots, d,$$

and this implies that almost surely the trajectories of the fBm are γ -Hölder continuous for any $\gamma < H$. Furthermore, for $H = 1/2$, fBm coincides with the usual Brownian motion, converting the family $\{B = B^H; H \in (0, 1)\}$ into the most natural generalization of this classical process. This is why B can be considered as one of the canonical examples of application of the abstract rough path theory.

Until very recently, the rough path constructions for fBm were based on pathwise type approximations of B , as in [4, 24, 29]. Namely, these references all use an approximation of B by a regularization B^ε , consider the associated (Riemann) iterated integrals $\mathbf{B}^{n,\varepsilon}$ and show their convergence, yielding the existence of a geometric rough path above B . These approximations all fail for $H \leq 1/4$. Indeed, the oscillations of B are then too heavy to define even \mathbf{B}^2 following this kind of argument, as illustrated by [5]. Nevertheless, the article [22] asserts that a rough path exists above any γ -Hölder function, and the recent progresses [26, 29] show that different concrete rough paths above fBm (and more general processes) can be exhibited, even if those rough paths do not correspond to a regularization of the process at stake.

Summarizing what has been said up to now, there are (at least) two ways to handle stochastic calculus for Gaussian processes: (i) Stochastic analysis tools, mainly leading to a Skorohod type integral (ii) Rough paths analysis, based on the pathwise convergence

of some Riemann sums and giving rise to a Stratonovich type integral. Though some efforts have been made in [3] in order to relate the two approaches (essentially for a fBm with Hurst parameter $H > 1/4$), the current article proposes to delve deeper into this direction. Namely, we plan to tackle three different problems:

(1) We show that, starting from a given rough path of order N above a d -dimensional process x , one can derive a Stratonovich change of variables of the form

$$f(x_t) - f(x_s) = \sum_{i=1}^d \int_s^t \partial_i f(x_u) dx_u(i) := \mathcal{J}_{st}(\nabla f(x_u) dx_u), \quad (4)$$

for any $f \in C^{N+1}(\mathbb{R}^d; \mathbb{R})$, and where $\partial_i f$ stands for $\partial f / \partial x_i$. This formula is not new, and is in fact an immediate consequence of the powerful stability theorems which can be derived from the abstract rough paths theory (see e.g [9]). However, we have included these considerations here for several reasons: (i) This paper not being dedicated to rough paths specialists, we find it useful to include a self contained, short and simple enough introduction to equation (4) (ii) Our proof is slightly different from the original one, in the sense that we only rely on the algebraic and analytic assumptions of Hypothesis 1.1 rather than on a limiting procedure (iii) Proving (4) is also a way for us to introduce all the objects and structures needed later on for the Skorohod type calculus. In particular, we derive the following representation for the integral $\mathcal{J}_{st}(\nabla f(x_u) dx_u)$: consider a family of partitions $\Pi_{st} = \{s = t_0, \dots, t_n = t\}$ of $[s, t]$, whose mesh tends to 0. Then, denoting by $N = \lfloor \frac{1}{\gamma} \rfloor$,

$$\mathcal{J}_{st}(\nabla f(x_u) dx_u) = \lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \sum_{k=0}^{N-1} \frac{1}{k!} \partial_{i_k \dots i_1 i}^{k+1} f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i_k) \cdots \mathbf{x}_{t_q t_{q+1}}^1(i_1) \mathbf{x}_{t_q t_{q+1}}^1(i). \quad (5)$$

These modified Riemann sums will also be essential in the analysis of Skorohod type integrals.

(2) We then specialize our considerations to a Gaussian setting, and use Malliavin calculus tools (in particular some elaborations of [2, 6]). Namely, supposing that x is a Gaussian process, plus mild additional assumptions on its covariance function, we are able to prove the following assertions:

(i) Consider a $C^2(\mathbb{R}^d; \mathbb{R})$ function f with exponential growth, and $0 \leq s < t < \infty$. Then the function $u \mapsto \mathbf{1}_{[s,t]}(u) \nabla f(x_u)$ lies into the domain of an extension of the divergence operator (in the Malliavin calculus sense) called δ° .

(ii) The following Skorohod type formula holds true:

$$f(x_t) - f(x_s) = \delta^\circ(\mathbf{1}_{[s,t]} \nabla f(x)) + \frac{1}{2} \int_s^t \Delta f(x_u) R'_u du, \quad (6)$$

where Δ stands for the Laplace operator, $u \mapsto R_u := \mathbf{E}[|x_u(1)|^2]$ is assumed to be a differentiable function, and R' stands for its derivative.

It should be emphasized here that formula (6) is obtained by means of stochastic analysis methods only, independently of the Hölder regularity of x . Otherwise stated, as in many instances of Gaussian analysis, pathwise regularity can be replaced by a regularity on the underlying Wiener space. When both, regularity of the paths and on the underlying Wiener space, are satisfied we obtain the relation between the Stratonovich type integral and the extended divergence operator.

Let us mention at this point the recent work [19] that considers similar problems as ours. In that article, the authors define also an extended divergence type operator for Gaussian processes (in the one-dimensional case only) with very irregular covariance and study its relation with a Stratonovich type integral. For the definition of the extended divergence, some conditions on the distributional derivatives of the covariance function R are imposed, one of them being that $\partial_{st}^2 R_{st}$ satisfies that $\bar{\mu}(ds, dt) := \partial_{st}^2 R_{st}(t-s)$ (that is well defined) is the difference of two Radon measures. Our conditions on R are of different nature, we suppose more regularity but only for the first partial derivative of R and the variance function. On the other hand, the definition of the Stratonovich type integral in [19] is obtained through a regularization approach instead of rough paths theory. As a consequence, some additional regularity conditions on the Gaussian process have to be imposed, while we just rely on the existence of a rough path above x .

(3) Finally, one can relate the two stochastic integrals introduced so far by means of modified Wick-Riemann sums. Indeed, we shall show that the integral $\delta^\diamond(\mathbf{1}_{[s,t]}\nabla f(x))$ introduced at relation (6) can also be expressed as

$$\delta^\diamond(\mathbf{1}_{[s,t]}\nabla f(x)) = \lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \sum_{k=0}^{N-1} \frac{1}{k!} \partial_{i_k \dots i_1 i}^{k+1} f(x_{t_q}) \diamond \mathbf{x}_{t_q t_{q+1}}^1(i_k) \diamond \dots \diamond \mathbf{x}_{t_q t_{q+1}}^1(i_1) \diamond \mathbf{x}_{t_q t_{q+1}}^1(i), \quad (7)$$

where the (almost sure) limit is still taken along a family of partitions $\Pi_{st} = \{s = t_0, \dots, t_n = t\}$ of $[s, t]$ whose mesh tends to 0, and where \diamond stands for the usual Wick product of Gaussian analysis. This result can be seen as the main contribution of our paper, and is obtained by a combination of rough paths and stochastic analysis methods. Specifically, we have mentioned that the modified Riemann sums in (5) can be proved to be convergent by means of rough paths analysis. Our main additional technical task will thus consist in computing the correction terms between those Riemann sums and the Wick-Riemann sums which appear in (7). This is the aim of the general Proposition 6.7 on Wick products, which has an interest in its own right, and is the key ingredient of our proof. It is worth mentioning at this point that Wick products are usually introduced within the landmark of white noise analysis. We rather rely here on the introduction given in [17], using the framework of Gaussian spaces. Let us also mention that Riemann-Wick sums have been used in [8] to study Skorohod stochastic calculus with respect to (one-dimensional) fBm for H greater than $1/2$, the case of $1/4 < H \leq 1/2$ being treated in [27]. We go beyond these case in Theorem 6.8, and will go back to the link between our formulas and the one produced in [27] at Section 6.3.

In conclusion, this article is devoted to show that Stratonovich and Skorohod stochastic calculus are possible for a wide range of Gaussian processes. A link between the integrals corresponding to those stochastic calculus is made through the introduction of Riemann-Wick modified sums. On the other hand, the reader might have noticed that the integrands considered in our stochastic integrals are restricted to processes of the form $\nabla f(x)$. The symmetries of this kind of integrand simplify the analysis of the Stratonovich-Skorohod corrections, reducing all the calculations to corrections involving \mathbf{x}^1 only. An extension to more general integrands would obviously require a lot more in terms of Wick type computations, especially for the terms involving \mathbf{x}^k for $k \geq 2$, and is deferred to a subsequent publication.

Here is how our paper is organized: Section 2 recalls some basic elements of rough paths theory which will be useful in the sequel. Then, as a warmup for the non initiated reader, we derive a Stratonovich change of variable formula in the case of a rough path of order 2 at Section 3. The case of a rough path of arbitrary order is then treated at Section 4. We obtain a Skorohod change of variable with Malliavin calculus tools only at Section 5. Finally, the representation of this Skorohod integral by Wick-Riemann sums is performed at Section 6.

2. SOME ELEMENTS OF ALGEBRAIC INTEGRATION

As already mentioned in the introduction, our stochastic calculus will appeal to the algebraic integration theory, which is a variant of the rough paths theory introduced in [13], and for which we also refer to [15] for a detailed introduction.

2.1. Increments. The extended pathwise integration we will deal with is based on the notion of ‘increments’, together with an elementary operator δ acting on them. The algebraic structure they generate is described in [13, 15], but here we present directly the definitions of interest for us, for sake of conciseness. First of all, for an arbitrary real number $T > 0$, a vector space V and an integer $k \geq 1$ we denote by $\mathcal{C}_k(V)$ the set of functions $g : [0, T]^k \rightarrow V$ such that $g_{t_1 \dots t_k} = 0$ whenever $t_i = t_{i+1}$ for some $i \leq k-1$. Such a function will be called a $(k-1)$ -*increment*, and we set $\mathcal{C}_*(V) = \cup_{k \geq 1} \mathcal{C}_k(V)$. We can now define the announced elementary operator δ on $\mathcal{C}_k(V)$:

$$\delta : \mathcal{C}_k(V) \rightarrow \mathcal{C}_{k+1}(V), \quad (\delta g)_{t_1 \dots t_{k+1}} = \sum_{i=1}^{k+1} (-1)^{k-i} g_{t_1 \dots \hat{t}_i \dots t_{k+1}}, \quad (8)$$

where \hat{t}_i means that this particular argument is omitted. A fundamental property of δ , which is easily verified, is that $\delta\delta = 0$, where $\delta\delta$ is considered as an operator from $\mathcal{C}_k(V)$ to $\mathcal{C}_{k+2}(V)$. We denote $\mathcal{Z}\mathcal{C}_k(V) = \mathcal{C}_k(V) \cap \text{Ker}\delta$ and $\mathcal{B}\mathcal{C}_k(V) = \mathcal{C}_k(V) \cap \text{Im}\delta$.

Some simple examples of actions of δ , which will be the ones we will really use throughout the paper, are obtained by letting $g \in \mathcal{C}_1$ and $h \in \mathcal{C}_2$. Then, for any $s, u, t \in [0, T]$, we have

$$(\delta g)_{st} = g_t - g_s, \quad \text{and} \quad (\delta h)_{sut} = h_{st} - h_{su} - h_{ut}. \quad (9)$$

Furthermore, it is easily checked that $\mathcal{Z}\mathcal{C}_{k+1}(V) = \mathcal{B}\mathcal{C}_k(V)$ for any $k \geq 1$. In particular, the following basic property holds:

Lemma 2.1. *Let $k \geq 1$ and $h \in \mathcal{Z}\mathcal{C}_{k+1}(V)$. Then there exists a (non unique) $f \in \mathcal{C}_k(V)$ such that $h = \delta f$.*

Proof. This elementary proof is included in [13], and will be omitted here. However, let us mention that $f_{t_1 \dots t_k} = (-1)^{k+1} h_{0t_1 \dots t_k}$ is a possible choice. \square

Observe that Lemma 2.1 implies that all the elements $h \in \mathcal{C}_2(V)$ such that $\delta h = 0$ can be written as $h = \delta f$ for some (non unique) $f \in \mathcal{C}_1(V)$. Thus we get a heuristic interpretation of $\delta|_{\mathcal{C}_2(V)}$: it measures how much a given 1-increment is far from being an exact increment of a function, i.e., a finite difference.

Notice that our future discussions will mainly rely on k -increments with $k \leq 2$, for which we will make some analytical assumptions. Namely, we measure the size of these increments by Hölder norms defined in the following way: for $f \in \mathcal{C}_2(V)$ let

$$\|f\|_\mu = \sup_{s,t \in [0,T]} \frac{|f_{st}|}{|t-s|^\mu}, \quad \text{and} \quad \mathcal{C}_2^\mu(V) = \{f \in \mathcal{C}_2(V); \|f\|_\mu < \infty\}. \quad (10)$$

Obviously, the usual Hölder spaces $\mathcal{C}_1^\mu(V)$ will be determined in the following way: for a continuous function $g \in \mathcal{C}_1(V)$, we simply set

$$\|g\|_\mu = \|\delta g\|_\mu, \quad (11)$$

and we will say that $g \in \mathcal{C}_1^\mu(V)$ iff $\|g\|_\mu$ is finite. Notice that $\|\cdot\|_\mu$ is only a semi-norm on $\mathcal{C}_1(V)$, but we will generally work on spaces of the type

$$\mathcal{C}_{1,a}^\mu(V) = \{g : [0,T] \rightarrow V; g_0 = a, \|g\|_\mu < \infty\}, \quad (12)$$

for a given $a \in V$, on which $\|g\|_\mu$ defines a distance in the usual way. For $h \in \mathcal{C}_3(V)$ set in the same way

$$\begin{aligned} \|h\|_{\gamma,\rho} &= \sup_{s,u,t \in [0,T]} \frac{|h_{sut}|}{|u-s|^\gamma |t-u|^\rho} \\ \|h\|_\mu &= \inf \left\{ \sum_i \|h_i\|_{\rho_i, \mu - \rho_i}; h = \sum_i h_i, 0 < \rho_i < \mu \right\}, \end{aligned} \quad (13)$$

where the last infimum is taken over all sequences $\{h_i \in \mathcal{C}_3(V)\}$ such that $h = \sum_i h_i$ and for all choices of the numbers $\rho_i \in (0, \mu)$. Then $\|\cdot\|_\mu$ is easily seen to be a norm on $\mathcal{C}_3(V)$, and we set

$$\mathcal{C}_3^\mu(V) := \{h \in \mathcal{C}_3(V); \|h\|_\mu < \infty\}.$$

Eventually, let $\mathcal{C}_3^{1+}(V) = \cup_{\mu > 1} \mathcal{C}_3^\mu(V)$, and notice that the same kind of norms can be considered on the spaces $\mathcal{Z}\mathcal{C}_3(V)$, leading to the definition of some spaces $\mathcal{Z}\mathcal{C}_3^\mu(V)$ and $\mathcal{Z}\mathcal{C}_3^{1+}(V)$.

With these notations in mind the following proposition is a basic result, which belongs to the core of our approach to pathwise integration. Its proof may be found in a simple form in [15].

Proposition 2.2 (The Λ -map). *There exists a unique linear map $\Lambda : \mathcal{Z}\mathcal{C}_3^{1+}(V) \rightarrow \mathcal{C}_2^{1+}(V)$ such that*

$$\delta\Lambda = \text{Id}_{\mathcal{Z}\mathcal{C}_3^{1+}(V)} \quad \text{and} \quad \Lambda\delta = \text{Id}_{\mathcal{C}_2^{1+}(V)}.$$

In other words, for any $h \in \mathcal{C}_3^{1+}(V)$ such that $\delta h = 0$ there exists a unique $g = \Lambda(h) \in \mathcal{C}_2^{1+}(V)$ such that $\delta g = h$. Furthermore, for any $\mu > 1$, the map Λ is continuous from $\mathcal{Z}\mathcal{C}_3^\mu(V)$ to $\mathcal{C}_2^\mu(V)$ and we have

$$\|\Lambda h\|_\mu \leq \frac{1}{2^\mu - 2} \|h\|_\mu, \quad h \in \mathcal{Z}\mathcal{C}_3^\mu(V). \quad (14)$$

Let us mention at this point a first link between the structures we have introduced so far and the problem of integration of irregular functions.

Corollary 2.3. *For any 1-increment $g \in \mathcal{C}_2(V)$ such that $\delta g \in \mathcal{C}_3^{1+}$, set $\delta f = (Id - \Lambda\delta)g$. Then*

$$(\delta f)_{st} = \lim_{|\Pi_{st}| \rightarrow 0} \sum_{i=0}^{n-1} g_{t_i t_{i+1}},$$

where the limit is over any partition $\Pi_{st} = \{t_0 = s, \dots, t_n = t\}$ of $[s, t]$, whose mesh tends to zero. Thus, the 1-increment δf is the indefinite integral of the 1-increment g .

Proof. Just consider the equation $g = \delta f + \Lambda\delta g$ and write

$$\begin{aligned} S_{\Pi_{st}} &= \sum_{i=0}^{n-1} g_{t_i t_{i+1}} = \sum_{i=0}^{n-1} (\delta f)_{t_i t_{i+1}} + \sum_{i=0}^{n-1} (\Lambda\delta g)_{t_i t_{i+1}} \\ &= (\delta f)_{st} + \sum_{i=0}^{n-1} (\Lambda\delta g)_{t_i t_{i+1}}. \end{aligned}$$

Then observe that, due to the fact that $\Lambda\delta g \in \mathcal{C}_2^{1+}(V)$, the last sum converges to zero. \square

2.2. Computations in \mathcal{C}_* . Let us specialize now to the case $V = \mathbb{R}$, and just write \mathcal{C}_k^γ for $\mathcal{C}_k^\gamma(\mathbb{R})$. Then (\mathcal{C}_*, δ) can be endowed with the following product: for $g \in \mathcal{C}_n$ and $h \in \mathcal{C}_m$ let gh be the element of \mathcal{C}_{n+m-1} defined by

$$(gh)_{t_1, \dots, t_{m+n+1}} = g_{t_1, \dots, t_n} h_{t_n, \dots, t_{m+n-1}}, \quad t_1, \dots, t_{m+n-1} \in [0, T]. \quad (15)$$

In this context, we have the following useful properties.

Proposition 2.4. *The following differentiation rules hold true:*

(1) *Let $g \in \mathcal{C}_1$ and $h \in \mathcal{C}_1$. Then $gh \in \mathcal{C}_1$ and*

$$\delta(gh) = \delta g h + g \delta h. \quad (16)$$

(2) *Let $g \in \mathcal{C}_1$ and $h \in \mathcal{C}_2$. Then $gh \in \mathcal{C}_2$ and*

$$\delta(gh) = \delta g h - g \delta h. \quad (17)$$

(3) *Let $g \in \mathcal{C}_2$ and $h \in \mathcal{C}_1$. Then $gh \in \mathcal{C}_2$ and*

$$\delta(gh) = \delta g h + g \delta h. \quad (18)$$

Proof. We will just prove (16), the other relations being just as simple. If $g, h \in \mathcal{C}_1$, then

$$[\delta(gh)]_{st} = g_t h_t - g_s h_s = g_s (h_t - h_s) + (g_t - g_s) h_t = g_s (\delta h)_{st} + (\delta g)_{st} h_t,$$

which proves our claim. \square

The iterated integrals of smooth functions on $[0, T]$ are particular cases of elements of \mathcal{C}_2 , which will be of interest

for us. Let us recall some basic rules for these objects: consider $f \in \mathcal{C}_1^\infty$ and $g \in \mathcal{C}_1^\infty$, where \mathcal{C}_1^∞ denotes the set of smooth functions on $[0, T]$. Then the integral $\int f dg$, which will be denoted indistinctly by $\int f dg$ or $\mathcal{J}(f dg)$, can be considered as an element of \mathcal{C}_2^∞ . Namely, for $(s, t) \in \mathcal{S}_{2,T}$ we set

$$\mathcal{J}_{st}(f dg) = \left(\int f dg \right)_{st} = \int_s^t f_u dg_u.$$

The multiple integrals can also be defined in the following way: given a smooth element $h \in \mathcal{C}_2^\infty$ and $(s, t) \in \mathcal{S}_{2,T}$, we set

$$\mathcal{J}_{st}(h dg) \equiv \left(\int h dg \right)_{st} = \int_s^t h_{su} dg_u.$$

In particular, for $f^1 \in \mathcal{C}_1^\infty$, $f^2 \in \mathcal{C}_1^\infty$ and $f^3 \in \mathcal{C}_1^\infty$ the double integral $\mathcal{J}_{st}(f^3 df^2 df^1)$ is defined as

$$\mathcal{J}_{st}(f^3 df^2 df^1) = \left(\int f^3 df^2 df^1 \right)_{st} = \int_s^t \mathcal{J}_{su}(f^3 df^2) df_u^1.$$

Now suppose that the n th order iterated integral of $f^{n+1} df^n \dots df^2$, which is denoted by $\mathcal{J}(f^{n+1} df^n \dots df^2)$, has been defined for $f^j \in \mathcal{C}_1^\infty$. Then, if $f^1 \in \mathcal{C}_1^\infty$, we set

$$\mathcal{J}_{st}(f^{n+1} df^n \dots df^2 df^1) = \int_s^t \mathcal{J}_{su}(f^{n+1} df^n \dots df^2) df_u^1, \quad (19)$$

which recursively defines the iterated integrals of smooth functions. Observe that an n th order integral $\mathcal{J}(df^n \dots df^2 df^1)$ can be defined along the same lines, starting with

$$\begin{aligned} \mathcal{J}(df) &= \delta f, \\ \mathcal{J}_{st}(df^2 df^1) &= \int_s^t \mathcal{J}_{su}(df^2) df_u^1 = \int_s^t (\delta f^2)_{su} df_u^1, \end{aligned}$$

and so on.

The following relations between multiple integrals and the operator δ will also be useful. The reader is sent to [15] for its elementary proof.

Proposition 2.5. *Let $f \in \mathcal{C}_1^\infty$ and $g \in \mathcal{C}_1^\infty$. Then it holds that*

$$\delta g = \mathcal{J}(dg), \quad \delta(\mathcal{J}(fdg)) = 0, \quad \delta(\mathcal{J}(dfdg)) = (\delta f)(\delta g) = \mathcal{J}(df)\mathcal{J}(dg),$$

and

$$\delta(\mathcal{J}(df^n \dots df^1)) = \sum_{i=1}^{n-1} \mathcal{J}(df^n \dots df^{i+1}) \mathcal{J}(df^i \dots df^1).$$

3. STRATONOVICH CALCULUS OF ORDER 2

This section is devoted to establish an Itô-Stratonovich change of variable formula for a process $x \in \mathcal{C}_1^\gamma(\mathbb{R}^d)$, with $1/3 < \gamma \leq 1/2$, provided this process generates a (weakly geometric) Lévy area. It is intended as a warm up for the general change of variable of the next section, especially for those readers who might not be acquainted to rough paths techniques.

3.1. Weakly controlled processes. Recall that we have in mind to give a change of variable formula for $f(x)$ when x is a function in $\mathcal{C}_1^\gamma(\mathbb{R}^d)$ with $\gamma > 1/3$ and f is a sufficiently smooth function. In this case, the rough path above x is reduced to a second order iterated integral, and the multiplicative property (1) of the path can be read as:

Hypothesis 3.1. *The path x is \mathbb{R}^d -valued γ -Hölder with $\gamma > 1/3$ and admits a Lévy area, that is a process $\mathbf{x}^2 \in \mathcal{C}_2^{2\gamma}(\mathbb{R}^{d,d})$ satisfying*

$$\delta \mathbf{x}^2 = \mathbf{x}^1 \otimes \mathbf{x}^1, \quad i. e. \quad [(\delta \mathbf{x}^2)_{sut}] (i, j) = [\mathbf{x}^1(i)]_{su} [\mathbf{x}^1(j)]_{ut},$$

for $s, u, t \in \mathcal{S}_{3,T}$ and $i, j \in \{1, \dots, d\}$.

Let us now be more specific about the global strategy we will adopt in order to obtain our Stratonovich type formula. First of all, we shall define integrals with respect to x for a class of integrands called weakly controlled processes, that we proceed to define. Notice that in the following definition we use for the first time the convention of summation over repeated indices, which will prevail until the end of Section 4.

Definition 3.2. *Let z be a process in $\mathcal{C}_1^\gamma(\mathbb{R}^n)$ with $1/3 < \gamma \leq 1/2$ (that is, $N := \lfloor 1/\gamma \rfloor = 2$). We say that z is a weakly controlled path based on x and starting from a if $z_0 = a$, which is a given initial condition in \mathbb{R}^n , and $\delta z \in \mathcal{C}_2^\gamma(\mathbb{R}^n)$ can be decomposed into*

$$\delta z(i) = \zeta(i, i_1) \mathbf{x}^1(i_1) + r(i), \quad \text{i. e.} \quad (\delta z(i))_{st} = \zeta_s(i, i_1) \mathbf{x}_{st}^1(i_1) + r_{st}(i), \quad (20)$$

for all $(s, t) \in \mathcal{S}_{2,T}$. In the previous formula, we assume $\zeta \in \mathcal{C}_1^\gamma(\mathbb{R}^{n,d})$, and r is a regular part such that $r \in \mathcal{C}_2^{2\gamma}(\mathbb{R}^n)$. The space of weakly controlled paths starting from a will be denoted by $\mathcal{Q}_{\gamma,a}(\mathbb{R}^n)$, and a process $z \in \mathcal{Q}_{\gamma,a}(\mathbb{R}^n)$ can be considered in fact as a couple (z, ζ) . The natural semi-norm on $\mathcal{Q}_{\kappa,a}(\mathbb{R}^k)$ is given by

$$\mathcal{N}[z; \mathcal{Q}_{\gamma,a}(\mathbb{R}^n)] = \mathcal{N}[z; \mathcal{C}_1^\gamma(\mathbb{R}^n)] + \mathcal{N}[\zeta; \mathcal{C}_1^\infty(\mathbb{R}^{n,d})] + \mathcal{N}[\zeta; \mathcal{C}_1^\gamma(\mathbb{R}^{n,d})] + \mathcal{N}[r; \mathcal{C}_2^{2\gamma}(\mathbb{R}^n)],$$

with $\mathcal{N}[g; \mathcal{C}_1^\kappa]$ defined by (11) and $\mathcal{N}[\zeta; \mathcal{C}_1^\infty(V)] = \sup_{0 \leq s \leq T} |\zeta_s|_V$.

With this definition at hand, we will try to obtain our change of variables formula in the following way:

- (1) Study the decomposition of $f(x)$ as weakly controlled process, when f is a smooth function.
- (2) Define rigorously the integral $\int z_u dx_u = \mathcal{J}(z dx)$ for a weakly controlled path z and compute its decomposition (20).
- (3) Compare the decompositions of $f(x)$ and $\int \nabla f(x) dx$, and show that they coincide, up to a term with Hölder regularity greater than 1.

In this section, we will concentrate on the first point of the program.

Let us see then how to decompose $f(x)$ as a controlled process when f is a smooth enough function, for which we first introduce a convention which will hold true until the end of the paper: for any smooth function $f : \mathbb{R}^d \rightarrow \mathbb{R}$, $k \geq 1$, $(i_1, \dots, i_k) \in \{1, \dots, d\}^k$ and $\xi \in \mathbb{R}^d$, we set

$$\partial_{i_1 \dots i_k} f(\xi)^k = \frac{\partial^k f}{\partial x_{i_1} \dots \partial x_{i_k}}(\xi). \quad (21)$$

With this notation in hand, our decomposition result is the following:

Proposition 3.3. *Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a C_b^2 function such that $f(x_0) = a$, and set $z = f(x)$. Then $z \in \mathcal{Q}_{\gamma,a}$, and it can be decomposed into $\delta z = \zeta \delta x + r$, with*

$$\zeta(i) = \partial_i f(x) \quad \text{and} \quad r = \delta f(x) - \partial_i f(x) \mathbf{x}^1(i).$$

Furthermore,

$$\mathcal{N}[z; \mathcal{Q}_{\gamma,a}] \leq c_{f,T} (1 + \mathcal{N}^2[x; \mathcal{C}_1^\gamma(\mathbb{R}^d)]). \quad (22)$$

Proof. The algebraic part of the assertion is straightforward. Just write

$$(\delta z)_{st} = f(x_t) - f(x_s) = \partial_i f(x_s) \mathbf{x}_{st}^1(i) + r_{st}, \quad (23)$$

which is the desired decomposition.

In order to give an estimate for $\mathcal{N}[z; \mathcal{Q}_{\gamma,a}(\mathbb{R}^n)]$, one has of course to establish bounds for $\mathcal{N}[z; \mathcal{C}_1^\gamma(\mathbb{R}^n)]$, $\mathcal{N}[\zeta; \mathcal{C}_1^\gamma(\mathbb{R}^d)]$, $\mathcal{N}[\zeta; \mathcal{C}_1^\infty(\mathbb{R}^d)]$ and $\mathcal{N}[r; \mathcal{C}_2^{2\gamma}]$. These estimates are readily obtained from decomposition (23), and details are left to the reader. \square

Remark 3.4. The algebraic part of the above proposition remains true if we only suppose that $f \in \mathcal{C}^2(\mathbb{R}^d)$. Indeed, since f together with its first and second order partial derivatives and x are continuous functions on a compact set, we have that $\zeta(i) = \partial_i f(x) \in \mathcal{C}_1^\gamma$ and $r = \delta f(x) - \partial_i f(x) \mathbf{x}^1(i) \in \mathcal{C}_2^\gamma$. Nevertheless, the inequality norm (22) fails and $\mathcal{N}[z; \mathcal{Q}_{\gamma,a}]$ cannot be bounded by terms only depending on the Hölder norm of x .

3.2. Integration of weakly controlled paths. Let us now turn to the integration of weakly controlled paths, which is summarized in the following theorem.

Theorem 3.5. *For a given $1/3 < \gamma \leq 1/2$, let x be a process satisfying Hypothesis 3.1. Furthermore, let $m \in \mathcal{Q}_{\gamma,b}(\mathbb{R}^d)$ with decomposition $m_0 = b \in \mathbb{R}^d$ and*

$$\delta m(i) = \mu(i, i_1) \mathbf{x}^1(i_1) + r(i), \quad \text{where } \mu \in \mathcal{C}_1^\gamma(\mathbb{R}^{d,d}), r \in \mathcal{C}_2^{2\gamma}(\mathbb{R}^d). \quad (24)$$

Define z by $z_0 = a \in \mathbb{R}$ and

$$\delta z = m(i) \mathbf{x}^1(i) + \mu(i, i_1) \mathbf{x}^2(i_1, i) - \Lambda(r(i) \mathbf{x}^1(i) + \delta \mu(i, i_1) \mathbf{x}^2(i_1, i)). \quad (25)$$

Finally, set

$$\mathcal{J}_{st}(m dx) = \int_s^t \langle m_u, dx_u \rangle_{\mathbb{R}^d} \triangleq (\delta z)_{st}.$$

Then:

(1) z is well-defined as an element of $\mathcal{Q}_{\gamma,a}(\mathbb{R})$, and coincides with the Riemann-Stieltjes integral of z with respect to x whenever these two functions are smooth.

(2) The semi-norm of z in $\mathcal{Q}_{\gamma,a}(\mathbb{R})$ can be estimated as

$$\mathcal{N}[z; \mathcal{Q}_{\gamma,a}(\mathbb{R})] \leq c_x (1 + \mathcal{N}[m; \mathcal{Q}_{\gamma,b}(\mathbb{R}^d)]), \quad (26)$$

for a positive constant c_x which can be bounded as follows:

$$c_x \leq c \left(\mathcal{N}[\mathbf{x}^1; \mathcal{C}_2^\gamma(\mathbb{R}^d)] + \mathcal{N}[\mathbf{x}^2; \mathcal{C}_2^{2\gamma}(\mathbb{R}^{d^2})] \right), \quad \text{for a universal constant } c.$$

(3) It holds

$$\mathcal{J}_{st}(m dx) = \lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \left[m_{t_q}(i) \mathbf{x}_{t_q, t_{q+1}}^1(i) + \mu_{t_q}(i, i_1) \mathbf{x}_{t_q, t_{q+1}}^2(i_1, i) \right], \quad (27)$$

for any $0 \leq s < t \leq T$, where the limit is taken over all partitions $\Pi_{st} = \{s = t_0, \dots, t_n = t\}$ of $[s, t]$, as the mesh of the partition goes to zero.

Before going into the technical details of the proof, let us see how to recover (25) in the smooth case, in order to justify our definition of the integral. (Notice however that (27) corresponds to the usual definition in the rough paths theory [21], which gives another kind of justification.)

Let us assume for the moment that x is a smooth function and that $m \in \mathcal{C}_1^\infty(\mathbb{R}^d)$ admits

the decomposition (24) with $\mu \in \mathcal{C}_1^\infty(\mathbb{R}^{d,d})$ and $r \in \mathcal{C}_2^\infty(\mathbb{R}^d)$. Then $\int_s^t \langle m_u, dx_u \rangle$ is well-defined, and we have

$$\int_s^t \langle m_u, dx_u \rangle_{\mathbb{R}^d} = m_s(i) [x_t(i) - x_s(i)] + \int_s^t [m_u(i) - m_s(i)] dx_u(i)$$

for $s \leq t$, respectively

$$\mathcal{J}(m dx) = m(i) \mathbf{x}^1(i) + \mathcal{J}(\delta m(i) dx(i)).$$

Let us now plug the decomposition (24) into this expression, which yields

$$\begin{aligned} \mathcal{J}_{st}(m dx) &= m_s(i) \mathbf{x}_{st}^1(i) + \int_s^t \mu_s(i, i_1) \mathbf{x}_{su}^1(i_1) dx_u(i) + \mathcal{J}(r dx) \\ &= m_s(i) \mathbf{x}_{st}^1(i) + \mu_s(i, i_1) \mathbf{x}_{st}^2(i_1, i) + \mathcal{J}(r dx). \end{aligned} \quad (28)$$

Notice that the terms $m \delta x$ and $\mu \mathbf{x}^2$ in (28) are well-defined as soon as x and \mathbf{x}^2 are defined themselves. In order to push forward our analysis to the rough case, it remains to handle the term $\mathcal{J}(r dx)$. Thanks to (28) we can write

$$\mathcal{J}(r dx) = \mathcal{J}(m dx) - m(i) \mathbf{x}^1(i) - \mu(i, i_1) \mathbf{x}^2(i_1, i),$$

and let us analyze this relation by applying δ to both sides. Using the second part of Proposition 2.4 and the Proposition 2.5 yields

$$\begin{aligned} \delta [\mathcal{J}(r dx)] &= -\delta [m(i) \mathbf{x}^1(i)] - \delta [\mu(i, i_1) \mathbf{x}^2(i_1, i)] \\ &= -\delta m(i) \mathbf{x}^1(i) - \delta \mu(i, i_1) \mathbf{x}^2(i_1, i) + \mu(i, i_1) \mathbf{x}^1(i_1) \mathbf{x}^1(i) \\ &= -[\mu(i, i_1) \mathbf{x}^1(i_1) + r(i)] \mathbf{x}^1(i) - \delta \mu(i, i_1) \mathbf{x}^2(i_1, i) + \mu(i, i_1) \mathbf{x}^1(i_1) \mathbf{x}^1(i) \\ &= -\delta \mu(i, i_1) \mathbf{x}^2(i_1, i) - r(i) \mathbf{x}^1(i). \end{aligned} \quad (29)$$

Assuming now that the increments $\delta \mu(i, i_1) \mathbf{x}^2(i_1, i)$ and $r(i) \mathbf{x}^1(i)$ are all elements of \mathcal{C}_2^μ with $\mu > 1$, $\delta \mu(i, i_1) \mathbf{x}^2(i_1, i) + r(i) \mathbf{x}^1(i)$ becomes an element of $\text{Dom}(\Lambda)$, and inserting (29) into (28) we obtain

$$\delta z = \mathcal{J}(m dx) \equiv m(i) \mathbf{x}^1(i) + \mu(i, i_1) \mathbf{x}^2(i_1, i) - \Lambda(r(i) \mathbf{x}^1(i) + \delta \mu(i, i_1) \mathbf{x}^2(i_1, i)),$$

which is the expression (25) of our Theorem 3.5. Thus (25) is a natural expression for $\mathcal{J}(m dx)$.

Proof of Theorem 3.5. We will divide this proof into two steps.

Step 1: Recalling the assumption $3\gamma > 1$, let us analyze the three terms in the right hand side of (25) and show that they define an element of $\mathcal{Q}_{\gamma,a}$ such that $\delta z = \zeta(i) \mathbf{x}^1(i) + \hat{r}$ with

$$\zeta(i) = m(i) \quad \text{and} \quad \hat{r} = \mu(i, i_1) \mathbf{x}^2(i_1, i) - \Lambda(r(i) \mathbf{x}^1(i) + \delta \mu(i, i_1) \mathbf{x}^2(i_1, i)).$$

Indeed, on one hand $m \in \mathcal{C}_1^\gamma(\mathbb{R}^d)$ and thus $\zeta = m$ is of the desired form for an element of $\mathcal{Q}_{\gamma,a}$. On the other hand, if $m \in \mathcal{Q}_{\gamma,b}$, μ is assumed to be bounded and since $\mathbf{x}^2 \in \mathcal{C}_2^{2\gamma}(\mathbb{R}^{d,d})$ we get that $\mu(i, i_1) \mathbf{x}^2(i_1, i) \in \mathcal{C}_2^{2\gamma}$. Along the same lines we can prove that $r(i) \mathbf{x}^1(i) \in \mathcal{C}_3^{3\gamma}$ and $\delta \mu(i, i_1) \mathbf{x}^2(i_1, i) \in \mathcal{C}_3^{3\gamma}$. Since $3\gamma > 1$, we obtain that $r(i) \mathbf{x}^1(i) + \delta \mu(i, i_1) \mathbf{x}^2(i_1, i) \in \text{Dom}(\Lambda)$ and

$$\Lambda(r \delta x + \delta \mu \mathbf{x}^2) \in \mathcal{C}_2^{3\gamma}.$$

Thus we have proved that

$$\hat{r} = \mu(i, i_1) \mathbf{x}^2(i_1, i) - \Lambda (r(i) \mathbf{x}^1(i) + \delta\mu(i, i_1) \mathbf{x}^2(i_1, i)) \in \mathcal{C}_2^{2\gamma}$$

and hence that $z \in \mathcal{Q}_{\gamma, a}(\mathbb{R})$. The estimate (26) is now obtained using the same kind of considerations and are left to the reader for the sake of conciseness.

Step 2: The same kind of computations as those leading to (29) also show that

$$\delta (m(i) \mathbf{x}^1(i) + \mu(i, i_1) \mathbf{x}^2(i_1, i)) = - [r(i) \mathbf{x}^1(i) + \delta\mu(i, i_1) \mathbf{x}^2(i_1, i)].$$

Hence equation (25) can also be read as

$$\mathcal{J}(m dx) = [\text{Id} - \Lambda\delta] (m(i) \mathbf{x}^1(i) + \mu(i, i_1) \mathbf{x}^2(i_1, i)),$$

and a direct application of Corollary 2.3 yields (27), which ends our proof. \square

3.3. Itô-Stratonovich formula. We are now ready to obtain a change of variable formula for $f(x)$, according to the strategy given in Section 3.1. For this, we need to assume, on top of the multiplicative Hypothesis 3.1, the following geometric rule which is (2) in the case $N = \lfloor \frac{1}{\gamma} \rfloor = 2$:

Hypothesis 3.6. *Let \mathbf{x}^2 be the area process defined in Hypothesis 3.1. Then we assume that, for all $(s, t) \in \mathcal{S}_{2, T}$, we have*

$$\mathbf{x}_{st}^1(i) \mathbf{x}_{st}^1(j) = \mathbf{x}_{st}^2(i, j) + \mathbf{x}_{st}^2(j, i).$$

With these assumptions in mind, our change of variable formula reads as follows:

Proposition 3.7. *Assume that x satisfies Hypothesis 3.1 and 3.6. Let f be a $C^3(\mathbb{R}^d; \mathbb{R})$ function. Then*

$$[\delta(f(x))]_{st} = \mathcal{J}_{st}(\nabla f(x) dx) = \int_s^t \langle \nabla f(x_u), dx_u \rangle_{\mathbb{R}^d}, \quad (30)$$

where the integral above has to be understood in the sense of Theorem 3.5.

Proof. Consider a partition $\Pi_{st} = \{s = t_0 < \dots < t_n = t\}$ of $[s, t]$. We have that

$$\begin{aligned} f(x_t) - f(x_s) &= \sum_{q=0}^{n-1} f(x_{t_{q+1}}) - f(x_{t_q}) \\ &= \sum_{q=0}^{n-1} \partial_i f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i) + \frac{1}{2} \sum_{q=0}^{n-1} \sum_{i_1, i_2=1}^d \partial_{i_1 i_2}^2 f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i_1) \mathbf{x}_{t_q t_{q+1}}^1(i_2) \\ &\quad + \frac{1}{3!} \sum_{q=0}^{n-1} \sum_{i_1, i_2, i_3=1}^d \partial_{i_1 i_2 i_3}^3 f(x_{\xi_{i_1 i_2 i_3}^q}) \mathbf{x}_{t_q t_{q+1}}^1(i_1) \mathbf{x}_{t_q t_{q+1}}^1(i_2) \mathbf{x}_{t_q t_{q+1}}^1(i_3), \end{aligned} \quad (31)$$

for a certain element $\xi_{i_1 i_2 i_3}^q \in [t_q, t_{q+1}]$. Invoking now Hypothesis 3.6 and Schwarz rule, one can express the sum $\frac{1}{2} \sum_{i_1, i_2=1}^d \partial_{i_1 i_2}^2 f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i_1) \mathbf{x}_{t_q t_{q+1}}^1(i_2)$ as

$$\frac{1}{2} \sum_{i_1, i_2=1}^d \partial_{i_1 i_2}^2 f(x_{t_q}) [\mathbf{x}_{t_q t_{q+1}}^2(i_1, i_2) + \mathbf{x}_{t_q t_{q+1}}^2(i_2, i_1)] = \sum_{i_1, i_2=1}^d \partial_{i_1 i_2}^2 f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^2(i_1, i_2).$$

So, going back to our convention on repeated indices, one can thus recast expression (31) into

$$f(x_t) - f(x_s) = \sum_{q=0}^{n-1} \partial_i f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i) + \sum_{q=0}^{n-1} \partial_{i_1 i_2}^2 f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^2(i_1, i_2) + R_{st}, \quad (32)$$

where R_{st} can be written as $R_{st} = \frac{1}{3!} \sum_{q=0}^{n-1} \rho_{t_q t_{q+1}}$ with

$$\rho_{t_q t_{q+1}} = \partial_{i_1 i_2 i_3}^3 f(x_{\xi_{i_1 i_2 i_3}^q}) \mathbf{x}_{t_q t_{q+1}}^1(i_1) \mathbf{x}_{t_q t_{q+1}}^1(i_2) \mathbf{x}_{t_q t_{q+1}}^1(i_3).$$

Furthermore, it is readily checked that for any $0 \leq q \leq n-1$ we have $\rho_{t_q t_{q+1}} \leq C |t_{q+1} - t_q|^{3\gamma}$, with C a constant depending on f and x , owing to the fact that f is a C^3 function and x is continuous on $[0, T]$. Thus, since $3\gamma > 1$, it is easily seen that $\lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \rho_{t_q t_{q+1}} = 0$. Plugging this relation into (32), we have proved that

$$f(x_t) - f(x_s) = \lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \partial_i f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i) + \sum_{q=0}^{n-1} \partial_{i_1 i_2}^2 f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^2(i_1, i_2). \quad (33)$$

On the other hand, Proposition 3.3 asserts that the decomposition of $\nabla f(x)$ as a weakly controlled path is given by

$$(\delta \nabla f(x)(i))_{st} = (\delta \partial_i f(x))_{st} = \partial_{i, i_1}^2 f(x_s) \mathbf{x}_{st}^1(i_1) + r_{st}(i),$$

where r lies into $\mathcal{C}_2^{2\gamma}$. Hence, using formula (27), we have that

$$\mathcal{J}_{st}(\nabla f(x) dx) = \lim_{|\Pi_{st}| \rightarrow 0} \left[\sum_{q=0}^{n-1} \partial_i f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i) + \sum_{q=0}^{n-1} \partial_{i_1 i_2}^2 f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^2(i_1, i_2) \right]. \quad (34)$$

Comparing this equality with (33), one obtain easily the desired Itô-Stratonovich formula. \square

Remark 3.8. The following formula:

$$\begin{aligned} & \mathcal{J}_{st}(\nabla f(x) dx) \\ &= \lim_{|\Pi_{st}| \rightarrow 0} \left[\sum_{q=0}^{n-1} \partial_i f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i) + \frac{1}{2} \sum_{q=0}^{n-1} \sum_{i_1, i_2=1}^d \partial_{i_1 i_2}^2 f(x_{t_q}) \mathbf{x}_{t_q t_{q+1}}^1(i_1) \mathbf{x}_{t_q t_{q+1}}^1(i_2) \right] \end{aligned} \quad (35)$$

is also an interesting byproduct of the proof of Proposition 3.7.

4. GENERAL STRATONOVICH CALCULUS

We will now handle the case of a weakly geometric rough path based on $x \in \mathcal{C}_1^\gamma(\mathbb{R}^d)$ as defined in the introduction, and we set $N = \lfloor 1/\gamma \rfloor$. We shall define an integration theory and show an Itô-Stratonovich formula for this kind of process. This being done along the same lines as in Section 3, we may skip some details of computations here. In any case, recall that we suppose the existence of a family $\{\mathbf{x}^n; n \leq N\}$ of increments in \mathcal{C}_2 satisfying the regularity, multiplicative and geometric properties given at Section 1.

4.1. Weakly controlled processes. With respect to the case of order 2, the notion of controlled process is obviously obtained here by introducing more iterated integrals of the process x . A new kind of cascade relation is also required, which is reminiscent of the Heisenberg type structure of [21].

Definition 4.1. Let z be a process in $\mathcal{C}_1^\gamma(\mathbb{R}^n)$ with $1/(N+1) < \gamma \leq 1/N$. We say that z is a weakly controlled path based on x and starting at $a \in \mathbb{R}^n$, if $z_0 = a$ and $\delta z \in \mathcal{C}_2^\gamma(\mathbb{R}^n)$ can be decomposed into

$$\delta z(i) = \sum_{k=1}^{N-1} \zeta^k(i, i_1, \dots, i_k) \mathbf{x}^k(i_k, \dots, i_1) + r^0(i), \quad (36)$$

for all $(s, t) \in \mathcal{S}_{2,T}$. In the previous formula, we assume $\zeta^k \in \mathcal{C}_1^\gamma(\mathbb{R}^n \times \mathbb{R}^{d^k})$, and r^0 is a regular part such that $r \in \mathcal{C}_2^{N\gamma}(\mathbb{R}^n)$. We also suppose that for any $1 \leq k \leq N-2$, the increment ζ^k can be further decomposed into

$$\delta \zeta^k(i, i_1, \dots, i_k) = \sum_{l=1}^{N-1-k} \zeta^{k+l}(i, i_1, \dots, i_{k+l}) \mathbf{x}^l(i_{k+l}, \dots, i_{k+1}) + r^k(i, i_1, \dots, i_k), \quad (37)$$

where the remainder r belongs to $\mathcal{C}_2^{(N-k)\gamma}(\mathbb{R}^n \times \mathbb{R}^{d^k})$.

As in Section 3, the space of weakly controlled paths will be denoted by $\mathcal{Q}_{\gamma,a}(\mathbb{R}^n)$, and a process $z \in \mathcal{Q}_{\gamma,a}(\mathbb{R}^n)$ can be considered in fact as a tuple $(z, \zeta^1, \dots, \zeta^{N-1})$. The natural semi-norm on $\mathcal{Q}_{\kappa,a}(\mathbb{R}^n)$ is given by

$$\begin{aligned} \mathcal{N}[z; \mathcal{Q}_{\gamma,a}(\mathbb{R}^n)] &= \mathcal{N}[z; \mathcal{C}_1^\gamma(\mathbb{R}^n)] + \sum_{k=1}^{N-1} \mathcal{N}[\zeta^k; \mathcal{C}_1^\infty(\mathbb{R}^n \times \mathbb{R}^{d^k})] \\ &\quad + \mathcal{N}[\zeta^k; \mathcal{C}_1^\gamma(\mathbb{R}^n \times \mathbb{R}^{d^k})] + \sum_{k=0}^{N-1} \mathcal{N}[r^k; \mathcal{C}_2^{(N-k)\gamma}(\mathbb{R}^n)], \end{aligned}$$

with $\mathcal{N}[g; \mathcal{C}_1^\kappa]$ defined by (11) and $\mathcal{N}[\zeta; \mathcal{C}_1^\infty(V)] = \sup_{0 \leq s \leq T} |\zeta_s|_V$.

The decomposition of $f(x)$ as a controlled process for a smooth enough function f can now be read as follows:

Proposition 4.2. Let x be a path satisfying Hypothesis 1.1 and let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a C_b^N function such that $f(x_0) = a$, and set $z = f(x)$. Then $z \in \mathcal{Q}_{\gamma,a}$, and it can be decomposed into

$$\delta z = \sum_{k=1}^{N-1} \zeta^k(i_1, \dots, i_k) \mathbf{x}^k(i_k, \dots, i_1) + r^0, \quad (38)$$

with

$$\zeta_s^k(i_1, \dots, i_k) = \partial_{i_k \dots i_1}^k f(x_s), \quad r_{st}^0 = [\delta f(x)]_{st} - \sum_{k=1}^{N-1} \frac{\partial_{i_1 \dots i_k}^k f(x_s)}{k!} \prod_{j=1}^k \mathbf{x}_{st}^1(i_j), \quad (39)$$

and

$$r_{st}^k(i_1, \dots, i_k) = \delta [\partial_{i_1 \dots i_k}^k f(x)]_{st} - \sum_{p=1}^{N-k-1} \frac{\partial_{i_1 \dots i_k j_1 \dots j_p}^{k+p} f(x_s)}{p!} \prod_{q=1}^p \mathbf{x}_{st}^1(j_q), \quad (40)$$

where we recall our convention (21) for $\partial_{i_1 \dots i_k}^k f$. Furthermore,

$$\mathcal{N}[z; \mathcal{Q}_{\gamma, a}] \leq c_{f, T} \left(1 + \mathcal{N}^N[x; \mathcal{C}_1^\gamma(\mathbb{R}^d)] \right). \quad (41)$$

Proof. The algebraic part of the assertion is obtained by combining a simple Taylor expansion and our geometric assumption (2). Indeed, Taylor's expansion directly yields

$$[\delta f(x)]_{st} = D_{st} + r_{st}^0, \quad \text{with} \quad D_{st} = \sum_{k=1}^{N-1} \frac{\partial_{i_1 \dots i_k}^k f(x_s)}{k!} \prod_{j=1}^k \mathbf{x}_{st}^1(i_j), \quad (42)$$

where $r^0 \in \mathcal{C}_2^{N\gamma}$. Moreover, appealing to (2), we have

$$D_{st} = \sum_{k=1}^{N-1} \frac{1}{k!} \sum_{i_1, \dots, i_k=1}^d \partial_{i_1 \dots i_k}^k f(x_s) \prod_{j=1}^k \mathbf{x}_{st}^1(i_j) \quad (43)$$

$$= \sum_{k=1}^{N-1} \frac{1}{k!} \sum_{i_1, \dots, i_k=1}^d \partial_{i_1 \dots i_k}^k f(x_s) \sum_{\sigma \in \Sigma_k} \mathbf{x}^k(i_{\sigma(1)}, \dots, i_{\sigma(k)}), \quad (44)$$

and invoking the symmetry properties for the derivatives of f we obtain

$$\begin{aligned} D_{st} &= \sum_{k=1}^{N-1} \frac{1}{k!} \sum_{i_1, \dots, i_k=1}^d \sum_{\sigma \in \Sigma_k} \partial_{i_{\sigma(k)} \dots i_{\sigma(1)}}^k f(x_s) \mathbf{x}^k(i_{\sigma(1)}, \dots, i_{\sigma(k)}) \\ &= \sum_{k=1}^{N-1} \sum_{i_1, \dots, i_k=1}^d \partial_{i_k \dots i_1}^k f(x_s) \mathbf{x}^k(i_1, \dots, i_k). \end{aligned} \quad (45)$$

Going back to our convention on repeated indices, we end up with

$$[\delta f(x)]_{st} = \sum_{k=1}^{N-1} \partial_{i_k \dots i_1}^k f(x_s) \mathbf{x}^k(i_1, \dots, i_k) + r_{st}^0,$$

which is the announced formula (38). Further expansions of the coefficients $\partial_{i_k \dots i_1}^k f(x)$, leading to a relation of type (37), are performed in the same way and are left to the reader for sake of conciseness.

In order to give an estimate for $\mathcal{N}[z; \mathcal{Q}_{\gamma, a}(\mathbb{R}^n)]$, one has of course to establish bounds for $\mathcal{N}[z; \mathcal{C}_1^\gamma(\mathbb{R}^n)]$, $\mathcal{N}[\zeta^k; \mathcal{C}_1^\gamma(\mathbb{R}^d)]$, $\mathcal{N}[\zeta^k; \mathcal{C}_1^\infty(\mathbb{R}^d)]$ and $\mathcal{N}[r^k; \mathcal{C}_2^{2\gamma}]$. These estimates are readily obtained from the expressions in decomposition (39), and details are left to the reader. The analytic bound (41) is also obtained in a straightforward manner. \square

Remark 4.3. As in the case $n = 2$, we point out that the algebraic conclusion of this proposition is still true for a $f \in \mathcal{C}^N(\mathbb{R}^d)$, without boundedness restrictions. However, inequality (41) would take a different form, since the multiplicative constants depend on the derivatives of f composed with x .

4.2. Integration of weakly controlled paths. The formula which defines the integral of a controlled process with respect to x is now defined similarly to the one in Theorem 3.5, in spite of the roughness of x .

Theorem 4.4. *For a given $\gamma > 0$ with $\lfloor 1/\gamma \rfloor = N$ (that is, $1/(N+1) < \gamma \leq 1/N$), let x be a process satisfying Hypothesis 1.1. Furthermore, let $m \in \mathcal{Q}_{\gamma,b}(\mathbb{R}^d)$ with decomposition $m_0 = b \in \mathbb{R}^d$ and*

$$\delta m(i) = \sum_{k=1}^{N-1} \mu^k(i, i_1, \dots, i_k) \mathbf{x}^k(i_k, \dots, i_1) + r^0(i), \quad (46)$$

where the increments μ^k satisfy the further assumptions of Definition 4.1. Define z by $z_0 = a \in \mathbb{R}$ and

$$\begin{aligned} \delta z &= m(i) \mathbf{x}^1(i) + \sum_{k=1}^{N-1} \mu^k(i, i_1, \dots, i_k) \mathbf{x}^{k+1}(i_k, \dots, i_1, i) \\ &\quad - \Lambda \left(\sum_{k=0}^{N-2} r^k(i, i_1, \dots, i_k) \mathbf{x}^{k+1}(i_k, \dots, i_1, i) + \delta \mu^{N-1}(i, i_1, \dots, i_{N-1}) \mathbf{x}^N(i_{N-1}, \dots, i_1, i) \right). \end{aligned} \quad (47)$$

Finally, set

$$\mathcal{J}_{st}(m dx) = \int_s^t \langle m_u, dx_u \rangle_{\mathbb{R}^d} \triangleq (\delta z)_{st}.$$

Then:

(1) z is well-defined as an element of $\mathcal{Q}_{\kappa,a}(\mathbb{R})$, and coincides with the Riemann integral of z with respect to x whenever these two functions are smooth.

(2) The semi-norm of z in $\mathcal{Q}_{\kappa,a}(\mathbb{R})$ can be estimated as

$$\mathcal{N}[z; \mathcal{Q}_{\gamma,a}(\mathbb{R})] \leq c_x (1 + \mathcal{N}[m; \mathcal{Q}_{\gamma,b}(\mathbb{R}^d)]), \quad (48)$$

for a positive constant c_x which can be bounded as $c_x \leq c \sum_{k=1}^N \mathcal{N}[\mathbf{x}^k; \mathcal{C}_2^{k\gamma}]$, where c stands for a universal constant.

(3) It holds

$$\mathcal{J}_{st}(m dx) = \lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \left[m_{t_q}(i) \mathbf{x}_{t_q, t_{q+1}}^1(i) + \sum_{k=1}^{N-1} \mu_{t_q}^k(i, i_1, \dots, i_k) \mathbf{x}_{t_q, t_{q+1}}^{k+1}(i_k, \dots, i_1, i) \right] \quad (49)$$

for any $0 \leq s < t \leq T$, where the limit is taken over all partitions $\Pi_{st} = \{s = t_0, \dots, t_n = t\}$ of $[s, t]$, as the mesh of the partition goes to zero.

Proof. Relying on what has been done at Section 3, we mainly derive here the expression (47) for $\mathcal{J}(m dx)$. Once this expression is obtained, the other estimates follow like in Theorem 3.5, except for the higher number of terms which have to be taken care of.

Hence let us assume for the moment that m and x are smooth functions, and try to define $\mathcal{J}(m dx)$ in an appropriate way for generalizations to rougher cases: one can write, using decomposition (46),

$$\mathcal{J}(m dx) = m(i) \mathbf{x}^1(i) + \mathcal{J}(\delta m(i) dx) \quad (50)$$

$$= m(i) \mathbf{x}^1(i) + \sum_{k=1}^{N-1} \mu^k(i, i_1, \dots, i_k) \mathbf{x}^{k+1}(i_k, \dots, i_1, i) + \mathcal{J}(r^0 dx). \quad (51)$$

Hence, like for equation (29), one can deduce that

$$\begin{aligned} \delta(\mathcal{J}(r^0 dx)) &= -\delta m(i) \mathbf{x}^1(i) - \sum_{k=1}^{N-1} \delta \mu^k(i, i_1, \dots, i_k) \mathbf{x}^{\mathbf{k}+1}(i_k, \dots, i_1, i) \\ &\quad + \sum_{k=1}^{N-1} \mu^k(i, i_1, \dots, i_k) \delta \mathbf{x}^{\mathbf{k}+1}(i_k, \dots, i_1, i). \end{aligned}$$

We now plug relation (46) for δm , relation (37) for $\delta \mu^k$ and the multiplicative relation (1) for $\delta \mathbf{x}^{\mathbf{k}+1}$ into the latter equation. This yields

$$\begin{aligned} \delta(\mathcal{J}(r^0 dx)) &= - \sum_{k=1}^{N-1} \mu^k(i, i_1, \dots, i_k) \mathbf{x}^{\mathbf{k}}(i_k, \dots, i_1) \mathbf{x}^1(i) - r^0(i) \mathbf{x}^1(i) - M \\ &\quad - \delta \mu^{N-1}(i, i_1, \dots, i_{N-1}) \mathbf{x}^{\mathbf{N}}(i_{N-1}, \dots, i_1, i) - \sum_{k=1}^{N-2} r^k(i, i_1, \dots, i_k) \mathbf{x}^{\mathbf{k}+1}(i_k, \dots, i_1, i) \\ &\quad + \sum_{k=1}^{N-1} \mu^k(i, i_1, \dots, i_k) \sum_{l=1}^k \mathbf{x}^1(i_k, \dots, i_{k-l+1}) \mathbf{x}^{\mathbf{k}+1-l}(i_{k-l}, \dots, i_1, i), \end{aligned} \quad (52)$$

where

$$M = \sum_{k=1}^{N-2} \left(\sum_{l=1}^{N-1-k} \mu^{k+l}(i, i_1, \dots, i_{k+l}) \mathbf{x}^1(i_{k+l}, \dots, i_{k+1}) \right) \mathbf{x}^{\mathbf{k}+1}(i_k, \dots, i_1, i).$$

Moreover, a simple change of index allows to write

$$M = \sum_{q=2}^{N-1} \mu^q(i, i_1, \dots, i_q) \sum_{l=1}^{q-1} \mathbf{x}^1(i_q, \dots, i_{q-l+1}) \mathbf{x}^{\mathbf{q}+1-l}(i_{q-l}, \dots, i_1, i),$$

and hence (52) simplifies into

$$\begin{aligned} \delta(\mathcal{J}(r^0 dx)) &= - \sum_{k=0}^{N-2} r^k(i, i_1, \dots, i_k) \mathbf{x}^{\mathbf{k}+1}(i_k, \dots, i_1, i) - \delta \mu^{N-1}(i, i_1, \dots, i_{N-1}) \mathbf{x}^{\mathbf{N}}(i_{N-1}, \dots, i_1, i). \end{aligned} \quad (53)$$

It is now readily checked that the operator Λ can be applied to the latter increment whenever $x \in \mathcal{C}_1^\gamma$ and generates a weakly geometric rough path. Putting together relations (50) and (53) we thus end up with expression (47) for the integral $\mathcal{J}(m dx)$.

The analytic bounds are now a matter of standard calculations, and are left to the reader for sake of conciseness. \square

4.3. Itô-Stratonovich formula. Now that we know how to define integrals of controlled processes with respect to x , our change of variable formula for $f(x)$ is obtained quite in the same way as in the second order setting. The formula can then be read as follows:

Theorem 4.5. *For a given $\gamma > 0$ with $\lfloor 1/\gamma \rfloor = N$, let x be a process satisfying the regularity, multiplicative and geometric hypotheses of Section 1. Let f be a $C^{N+1}(\mathbb{R}^d; \mathbb{R})$ function. Then*

$$[\delta(f(x))]_{st} = \mathcal{J}_{st}(\nabla f(x) dx) = \int_s^t \langle \nabla f(x_u), dx_u \rangle_{\mathbb{R}^d}, \quad (54)$$

where the integral above has to be understood in the sense of Theorem 4.4. Moreover,

$$\begin{aligned} \mathcal{J}_{st}(\nabla f(x) dx) &= \lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \left[\partial_i f(x_{t_q}) \mathbf{x}_{t_q, t_{q+1}}^1(i) + \sum_{k=1}^{N-1} \partial_{i_k \dots i_1}^{k+1} f(x_{t_q}) \mathbf{x}_{t_q, t_{q+1}}^{\mathbf{k}+1}(i_k, \dots, i_1, i) \right] \\ &= \lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \left[\partial_i f(x_{t_q}) \mathbf{x}_{t_q, t_{q+1}}^1(i) + \sum_{k=1}^{N-1} \frac{1}{k!} \partial_{i_k \dots i_1}^{k+1} f(x_{t_q}) \mathbf{x}_{t_q, t_{q+1}}^1(i_k) \cdots \mathbf{x}_{t_q, t_{q+1}}^1(i_1) \mathbf{x}_{t_q, t_{q+1}}^1(i) \right] \end{aligned} \quad (55)$$

for any $0 \leq s < t \leq T$, where the limit is taken over all partitions $\Pi_{st} = \{s = t_0, \dots, t_n = t\}$ of $[s, t]$, as the mesh of the partition goes to zero.

Proof. The proof goes exactly along the same lines as for Proposition 3.7. The first expression for $\mathcal{J}(\nabla f(x) dx)_{st}$ given in (55) is a consequence of the decomposition as a weakly controlled path of $\nabla f(x)$ and Theorem 4.4. The second one follows from the first one by using Schwarz rule and the geometric property (2).

On the other hand, applying Taylor's formula up to order N to the decomposition

$$f(x_t) - f(x_s) = \sum_{q=0}^{n-1} f(x_{t_{q+1}}) - f(x_{t_q}),$$

comparing it with (55) and using that $(N+1)\gamma > 1$, one obtain easily the Stratonovich type formula. □

5. SKOROHOD TYPE FORMULA VIA MALLIAVIN CALCULUS

We take now a completely different direction in our considerations: the pointwise point of view which had been adopted previously is abandoned in this section, and we try to construct an integral with respect to a (Gaussian) process x by means of stochastic analysis tools. We then prove that for any $0 \leq s < t < \infty$, the function $\mathbf{1}_{[s,t)} \nabla f(x)$ is in the domain of an extended divergence operator with respect to x , and prove an associated Skorohod type formula. As we shall see, this mainly stems from an extension of [2] to the d -dimensional case, which is allowed thanks to the symmetries of $\nabla f(x)$.

5.1. Preliminaries on Gaussian processes. From now on, we specialize our setting to a centered Gaussian process $x = (x(1), \dots, x(d))$ with i.i.d coordinates, and covariance function

$$R_{st} := \mathbf{E}[x_s(1)x_t(1)], \quad \text{and} \quad R_t := \mathbf{E}[|x_t(1)|^2] = R_{tt}, \quad s, t \in [0, T]. \quad (56)$$

We will add later some hypotheses on these functions. We can also assume that $x_0(j) = 0$.

The Gaussian integration theory is based on a completion (in $L^2(\Omega)$) of elementary integrals with respect to x , which can be summarized as follows (see [25] for more details): consider the space of d -dimensional elementary functions

$$\mathcal{S} = \left\{ f = (f_1, \dots, f_d); f_j = \sum_{i=0}^{n_j-1} \alpha_i^j \mathbf{1}_{[t_i^j, t_{i+1}^j)}, \quad 0 = t_0 < t_1^j < \dots < t_{n_j-1}^j < t_{n_j}^j = T, \right. \\ \left. \text{for } j = 1, \dots, d \right\}.$$

For any element f in \mathcal{S} , we define the integral of first order of f with respect to x as

$$I_1(f) := \sum_{j=1}^d \sum_{i=0}^{n_j-1} \alpha_i^j (x_{t_{i+1}^j}(j) - x_{t_i^j}(j)).$$

For $\theta : \mathbb{R} \rightarrow \mathbb{R}$, and $j \in \{1, \dots, d\}$, denote by $\theta^{[j]}$ the function with values in \mathbb{R}^d having all the coordinates equal to zero, except the j^{th} coordinate which is equal to θ . It is readily seen that

$$\mathbf{E}[I_1(\mathbf{1}_{[0,s]}^{[j]})I_1(\mathbf{1}_{[0,t]}^{[k]})] = \mathbf{1}_{(j=k)} R_{st}.$$

So, we can define for some indicator functions of \mathcal{S} the following symmetric and semi-definite form

$$\langle \mathbf{1}_{[0,s]}^{[j]}, \mathbf{1}_{[0,t]}^{[k]} \rangle_{\mathcal{S}} = \mathbf{1}_{(j=k)} R_{st},$$

and extend it to all elements of \mathcal{S} by linearity. If we identify two functions f and g in \mathcal{S} when $\langle f - g, f - g \rangle_{\mathcal{S}} = 0$, then $\langle \cdot, \cdot \rangle_{\mathcal{S}}$ becomes an inner product on \mathcal{S} (actually, on the quotient space obtained by this identification). Therefore, for f and g in \mathcal{S} we have that

$$\mathbf{E}[I_1(f)I_1(g)] = \langle f, g \rangle_{\mathcal{S}}$$

and I_1 defines an isometric map from \mathcal{S} , endowed with the inner product $\langle \cdot, \cdot \rangle_{\mathcal{S}}$ into a subspace of $L^2(\Omega)$. This map can be extended in the standard way to an isometric map, denoted also as I_1 , from a real Hilbert space that we will denote by \mathcal{H} into a closed subspace of $L^2(\Omega)$. From now on, denote the inner product of this extended isometry by $\langle \cdot, \cdot \rangle_{\mathcal{H}}$. We will assume that \mathcal{H} is a separable Hilbert space (which is satisfied whenever R_{st} is continuous).

Let $\{e_1, e_2, \dots\}$ be an orthonormal basis of \mathcal{H} and let $\hat{\otimes}$ denote the symmetric tensor product. Then

$$f_n = \sum_{\text{finite}} f_{i_1, \dots, i_n} e_{i_1} \hat{\otimes} \dots \hat{\otimes} e_{i_n}, \quad f_{i_1, \dots, i_n} \in \mathbb{R} \quad (57)$$

is an element of $\mathcal{H}^{\hat{\otimes} n}$ with the Hilbert norm

$$\|f_n\|_{\mathcal{H}^{\hat{\otimes} n}}^2 = \sum_{\text{finite}} |f_{i_1, \dots, i_n}|^2. \quad (58)$$

Moreover, $\mathcal{H}^{\hat{\otimes} n}$ is the completion of all the elements like (57) with respect to the norm (58).

For an element $f_n \in \mathcal{H}^{\hat{\otimes} n}$, the multiple Itô integral of order n is well-defined. First, any element of the form given by (57) can be rewritten as

$$f_n = \sum_{\text{finite}} f_{j_1 \dots j_m} e_{j_1}^{\hat{\otimes} k_1} \hat{\otimes} \dots \hat{\otimes} e_{j_m}^{\hat{\otimes} k_m}, \quad (59)$$

where the j_1, \dots, j_m are different and $k_1 + \dots + k_m = n$. Then, if $f_n \in \mathcal{H}^{\hat{\otimes} n}$ is given under the form (59), define its multiple integral as:

$$I_n(f_n) = \sum_{\text{finite}} f_{j_1, \dots, j_m} H_{k_1}(I_1(e_{j_1})) \cdots H_{k_m}(I_1(e_{j_m})), \quad (60)$$

where H_k denotes the k -th normalized Hermite polynomial given by

$$H_k(x) = (-1)^k e^{\frac{x^2}{2}} \frac{d^k}{dx^k} e^{-\frac{x^2}{2}} = \sum_{j \leq k/2} \frac{(-1)^j k!}{2^j j! (k-2j)!} x^{k-2j}.$$

It holds that the multiple integrals of different order are orthogonal and that

$$\mathbf{E}|I_n(f_n)|^2 = n! \|f_n\|_{\mathcal{H}^{\hat{\otimes} n}}^2.$$

This last isometric property allows to extend the multiple integral for a general $f_n \in \mathcal{H}^{\hat{\otimes} n}$ by $L^2(\Omega)$ convergence (notice once again that this kind of closure is different in spirit from the pathwise convergences considered at Sections 3 and 4). Finally, one can define the integral of $f_n \in \mathcal{H}^{\otimes n}$ by putting $I_n(f_n) := I_n(\tilde{f}_n)$, where $\tilde{f}_n \in \mathcal{H}^{\hat{\otimes} n}$ denotes the symmetrized version of f_n . Moreover, the chaos expansion theorem states that any square integrable random variable $F \in L^2(\Omega, \mathcal{G}, P)$, where \mathcal{G} is the σ -field generated by x , can be written as

$$F = \sum_{n=0}^{\infty} I_n(f_n) \quad \text{with} \quad \mathbf{E}[F^2] = \sum_{n=0}^{\infty} n! \|f_n\|_{\mathcal{H}^{\hat{\otimes} n}}^2. \quad (61)$$

We will introduce now the (iterated) derivative and divergence operators of the Malliavin calculus. We denote by $\mathcal{C}_p^\infty(\mathbb{R}^n)$ the set of infinitely continuously differentiable functions $f : \mathbb{R}^n \rightarrow \mathbb{R}$ such that f and all its partial derivatives have polynomial growth. Let \mathbf{S} denote the class of smooth random variables of the form

$$F = f(I_1(h_1), \dots, I_1(h_n)), \quad (62)$$

where $f \in \mathcal{C}_p^\infty(\mathbb{R}^n)$, h_1, \dots, h_n are in \mathcal{H} , and $n \geq 1$. The derivative of a smooth random variable $F \in \mathbf{S}$ of the form (62) is the \mathcal{H} -valued random variable given by

$$DF = \sum_{i=1}^n \partial_i f(I_1(h_1), \dots, I_1(h_n)) h_i, \quad (63)$$

where ∂_i denotes as usual $\frac{\partial}{\partial x_i}$. One can also define for $h \in \mathcal{H}$ and $F \in \mathbf{S}$ the derivative of F in the direction of h as $D_h F = \langle F, h \rangle_{\mathcal{H}}$.

The iteration of the operator D is defined in such a way that for a smooth random variable $F \in \mathbf{S}$ the iterated derivative $D^k F$ is a random variable with values in $\mathcal{H}^{\otimes k}$. We also consider for $h^k \in \mathcal{H}^{\otimes k}$ the k -th derivative of F in the direction of h^k defined as

$$D_{h^k}^k F = \langle D^k F, h^k \rangle_{\mathcal{H}^{\otimes k}}.$$

Let us fix now a notation for the domain of the iterated derivative D^k : for every $p \geq 1$ and any natural number $k \geq 1$ we introduce the seminorm on \mathbf{S} given by

$$\|F\|_{k,p} = \left[\mathbf{E}(|F|^p) + \sum_{j=1}^k \mathbf{E}(\|D^j F\|_{\mathcal{H}^{\otimes j}}^p) \right]^{\frac{1}{p}}.$$

It is well-known that the operator D^k is closable from \mathbf{S} into $L^p(\Omega; \mathcal{H}^{\otimes k})$. We will denote by $\mathbb{D}^{k,p}$ the completion of the family of smooth random variables \mathbf{S} with respect to the norm $\|\cdot\|_{k,p}$. We will also refer the space $\mathbb{D}^{k,2}$ as the domain of the operator D^k and denote it by $\text{Dom } D^k$. If F has the chaotic representation (61), we have that

$$\mathbf{E}\left(\|D^k F\|_{\mathcal{H}^{\otimes k}}^2\right) = \sum_{n=k}^{\infty} n(n-1)\cdots(n-k+1)n! \|f_n\|_{\mathcal{H}^{\otimes n}}^2$$

and a useful characterization of $\text{Dom } D^k$ is the following: $F \in \text{Dom } D^k$ if and only if

$$\sum_{n=1}^{\infty} n^k n! \|f_n\|_{\mathcal{H}^{\otimes n}}^2 < \infty.$$

We will denote by δ° the adjoint of the operator D (this operator is also referred as the *divergence operator*) and more generally, we denote by $\delta^{\circ k}$ the adjoint of D^k . The operator $\delta^{\circ k}$ is closed and its domain, denoted by $\text{Dom } \delta^{\circ k}$, is the set of $\mathcal{H}^{\otimes k}$ -valued square integrable random variables $u \in L^2(\Omega; \mathcal{H}^{\otimes k})$ such that

$$|\mathbf{E}(\langle D^k F, u \rangle_{\mathcal{H}^{\otimes k}})| \leq C \|F\|_2,$$

for all $F \in \text{Dom } D^k$, where C is some constant depending on u . Moreover, for $u \in \text{Dom } \delta^{\circ k}$, $\delta^{\circ k}(u)$ is the element of $L^2(\Omega)$ characterized by the duality relationship:

$$\mathbf{E}(F \delta^{\circ k}(u)) = \mathbf{E}(\langle D^k F, u \rangle_{\mathcal{H}^{\otimes k}}), \quad (64)$$

for any $F \in \text{Dom } D^k$. For $u \in \text{Dom } \delta^\circ$, the random variable $\delta^\circ(u)$ is usually called *Skorohod integral* of u , because it coincides with the usual integral of u with respect to x for a large class of elementary processes u (see [25] for further details).

5.2. An operator associated to x . Along this section we will consider a d -dimensional continuous process satisfying the following set of assumptions:

Hypothesis 5.1. *The process $x = (x(1), \dots, x(d))$ is a centered Gaussian process with i.i.d. coordinates. Letting R_{st} and R_t being defined as in (56), we suppose that those two functions are continuous and the following two conditions hold:*

- (1) *The variance function $R_t := R_{tt}$ is differentiable at any point $t \in (0, T)$ and satisfies that*

$$\int_0^T |R'_t| dt < \infty.$$

- (2) *The first partial derivative $\partial_s R_{st}$ of R_{st} is well-defined a.e. on $[0, T]^2$ and verifies*

$$\int_0^T \int_0^T |\partial_s R_{sy}| ds dy < \infty. \quad (65)$$

We will try now to identify a useful operator for our future Gaussian computations.

Let $\varphi = (\varphi(1), \dots, \varphi(d)) \in (\mathcal{D}_T)^d$, where \mathcal{D}_T is the space of \mathcal{C}^∞ functions with compact support contained in $(0, T)$. We have that (see for instance [18], where the 1-dimensional case is considered) that $\varphi \in \mathcal{H}$ and that

$$I_1(\varphi) = - \int_0^T \langle x_s, \varphi'_s \rangle ds,$$

where $\langle \cdot, \cdot \rangle$ denotes the ordinary Euclidean product in \mathbb{R}^d . Moreover, $(\mathcal{D}_T)^d$ is a dense subset of \mathcal{H} . From now on, we use also the notation $x(f)$ for $I_1(f)$.

Given a function $h : [0, T] \rightarrow \mathbb{R}$, recall that $h^{[j]}$ denotes the function with values in \mathbb{R}^d in which all the coordinates except the j -th one are equal to 0 and the j -th coordinate equals to h . Therefore, for $\beta \in \mathcal{D}_T$ and $0 \leq a < b \leq T$, we have that

$$\begin{aligned} \langle \mathbf{1}_{[a,b]}^{[l]}, \beta^{[j]} \rangle_{\mathcal{H}} &= \mathbf{E} [I_1(\mathbf{1}_{[a,b]}^{[l]})I_1(\beta^{[j]})] = -\mathbf{E} \left[(x_b(l) - x_a(l)) \int_0^T \langle x_t, [\beta^{[j]}]_t' \rangle dt \right] \\ &= -\mathbf{1}_{(j=l)} \int_0^T (R_{bt} - R_{at}) \beta_t' dt = -\mathbf{1}_{(j=l)} \int_0^T \left(\int_a^b \partial_s R_{st} ds \right) \beta_t' dt \\ &= -\mathbf{1}_{(j=l)} \int_a^b \left(\int_0^T \partial_s R_{sy} \beta_y' dy \right) ds. \end{aligned} \quad (66)$$

We will consider the first iterated integral appearing on the right hand side of (66) as a linear operator defined on \mathcal{D}_T . That is, we consider for $s \in [0, T]$ and $\beta \in \mathcal{D}_T$, the following function:

$$\mathbf{A}\beta(s) =: - \int_0^T \partial_s R_{sy} \beta_y' dy.$$

We will suppose from now on that the following hypothesis holds.

Hypothesis 5.2. For any $\beta \in \mathcal{D}_T$, $\mathbf{A}\beta \in L^2([0, T])$.

Remark 5.3. Condition (65) on R_{st} , stated in Hypothesis 5.1, implies that $\mathbf{A}\beta$ belongs to $L^1([0, T])$ whenever $\beta \in \mathcal{D}_T$. We have imposed the additional condition $\mathbf{A}\beta \in L^2([0, T])$ in order to guarantee the integrability of many terms appearing in the sequel. Although one can weaken Hypothesis 5.2, this would complicate some of the next statements. We have thus chosen to impose it for the sake of simplicity.

Example 5.4. Hypothesis 5.2 is satisfied by the fractional Brownian motion. In fact,

$$\begin{aligned} \mathbf{A}\beta(s) &= - \int_0^T \frac{\partial}{\partial s} R_{sy} \beta'(y) dy = - \int_0^T H (s^{2H-1} - |s-y|^{2H-1} \text{sign}(s-y)) \beta'(y) dy \\ &= \int_0^T H (|s-y|^{2H-1} \text{sign}(s-y)) \beta'(y) dy, \end{aligned}$$

because $\beta \in \mathcal{D}_T$. And from this, it is easily seen that $\mathbf{A}\beta \in L^\infty([0, T])$ if $\beta \in \mathcal{D}_T$.

Let us now relate our operator \mathbf{A} to the inner product in \mathcal{H} : equation (66) tells us that for any elementary function $g = (g(1), \dots, g(d)) \in \mathcal{S}$ and $\beta \in \mathcal{D}_T$ we have that

$$\langle \beta^{[j]}, g(l)^{[l]} \rangle_{\mathcal{H}} = \mathbf{1}_{(j=l)} \int_0^T g_s(l) \mathbf{A}\beta(s) ds.$$

Since for $\varphi \in (\mathcal{D}_T)^d$, $g \in \mathcal{S}$, we have $\varphi = \sum_{j=1}^d \varphi(j)^{[j]}$ and $g = \sum_{l=1}^d g(l)^{[l]}$, we obtain that

$$\langle \varphi, g \rangle_{\mathcal{H}} = \sum_{j=1}^d \int_0^T g_s(j) \mathbf{A}\varphi(j)(s) ds = \int_0^T \langle g_s, \mathbf{A}\varphi(s) \rangle ds, \quad (67)$$

where we use the notation $\mathbf{A}\varphi = (\mathbf{A}\varphi(1), \dots, \mathbf{A}\varphi(d))$. Extending this last relation by continuity, the following useful representation for the inner product in \mathcal{H} is readily obtained:

Lemma 5.5. *For any $g \in \mathcal{H} \cap (L^2([0, T]))^d$ and $\varphi \in \mathcal{D}_T$, one can write*

$$\langle \varphi, g \rangle_{\mathcal{H}} = \int_0^T \langle g_s, \mathbf{A}\varphi(s) \rangle ds, \quad (68)$$

where $\langle \cdot, \cdot \rangle$ stands for the inner product in \mathbb{R}^d .

Going back to our example 5.4, notice that expression (68) is similar to the following one pointed out in [2] for the one-dimensional fractional Brownian motion with Hurst parameter $H < 1/2$:

$$\langle \varphi, g \rangle_{\mathcal{H}} = c_H^2 \int_0^T g(s) \mathbf{D}_+^\alpha \mathbf{D}_-^\alpha \varphi(s) ds,$$

where $\alpha = \frac{1}{2} - H$; \mathbf{D}_+^α and \mathbf{D}_-^α are the Marchaud fractional derivatives (see [28] for more details about these objects), and c_H is a certain positive constant.

5.3. Extended divergence operator. Let us take up here the notations of Section 5.1. Having noticed that fBm gives rise to an operator $\mathbf{D}_+^\alpha \mathbf{D}_-^\alpha$ which is a particular case of our operator \mathbf{A} (see Example 5.10), one can naturally try to define an extension of the operator δ° using similar arguments to those of [2]. The idea is to consider first $u \in \text{Dom } \delta^\circ \cap (L^2(\Omega \times [0, T]))^d$ and $F = H_n(x(\varphi))$ where H_n is the n -th normalized Hermite polynomial, and $\varphi \in (\mathcal{D}_T)^d$. Since $(L^2(\Omega \times [0, T]))^d \equiv L^2(\Omega; L^2([0, T]; \mathbb{R}^d))$ and $\text{Dom } \delta^\circ \subset L^2(\Omega; \mathcal{H})$, we have that $u \in (L^2(\Omega \times [0, T]))^d \cap \mathcal{H}$ almost surely. Moreover, $DH_{n-1}(x(\varphi)) = H_{n-1}(x(\varphi))\varphi \in (\mathcal{D}_T)^d$, a.s.. So, using (68), the usual duality relationship between D and δ° can be written in the following way:

$$\begin{aligned} \mathbf{E} [\delta^\circ(u) H_n(x(\varphi))] &= \mathbf{E} [\langle u, DH_n(x(\varphi)) \rangle_{\mathcal{H}}] = \mathbf{E} [H_{n-1}(x(\varphi)) \langle u, \varphi \rangle_{\mathcal{H}}] \\ &= \mathbf{E} \left[H_{n-1}(x(\varphi)) \int_0^T \langle u_s, \mathbf{A}\varphi(s) \rangle ds \right] = \int_0^T \langle \mathbf{E} [H_{n-1}(x(\varphi)) u_s], \mathbf{A}\varphi(s) \rangle ds, \end{aligned} \quad (69)$$

and this motivates the following definition.

Definition 5.6. *We say that $u \in \text{Dom}^* \delta^\circ$ if $u \in (L^2(\Omega \times [0, T]))^d$ and there exists an element of $L^2(\Omega)$, that will be denoted by $\delta^\circ(u)$, such that for any $\varphi \in (\mathcal{D}_T)^d$ and any $n \geq 0$, the following is satisfied:*

$$\mathbf{E} [\delta^\circ(u) H_n(x(\varphi))] = \int_0^T \langle \mathbf{E} [H_{n-1}(x(\varphi)) u_s], \mathbf{A}\varphi(s) \rangle ds. \quad (70)$$

Remark 5.7. Since the linear span of the set $\{H_n(\varphi) : n \geq 0, \varphi \in (\mathcal{D}_T)^d\}$ is dense in $L^2(\Omega)$, the element $\delta^\circ(u)$, if it exists, is uniquely defined.

Remark 5.8. One can easily see from our definition of the extended divergence that it is a closed operator in the following sense: if $\{u^k\}_{k \in \mathbb{N}} \subset \text{Dom}^* \delta^\circ$ and satisfies (1) $u^k \rightarrow u$ in $(L^2(\Omega \times [0, T]))^d$ and (2) $\delta^\circ(u^k) \rightarrow X$ in $L^2(\Omega)$, then $u \in \text{Dom}^* \delta^\circ$ and $\delta^\circ(u) = X$.

We show in the following proposition that the extended operator δ° defined above is actually an extension of the divergence operator of the Malliavin calculus.

Proposition 5.9. *The domain $\text{Dom}^* \delta^\circ$ is an extension of $\text{Dom } \delta^\circ$ in the following sense:*

$$\text{Dom } \delta^\circ \cap (L^2(\Omega \times [0, T]))^d = \text{Dom}^* \delta^\circ \cap L^2(\Omega; \mathcal{H}).$$

Furthermore, the extended operator δ° restricted to $\text{Dom} \delta^\circ \cap (L^2(\Omega \times [0, T]))^d$ coincides with the standard divergence operator.

Proof. If $u \in \text{Dom} \delta^\circ \cap (L^2(\Omega \times [0, T]))^d$ then $u \in (L^2([0, T]))^d \cap \mathcal{H}$ almost surely. Thus (68) can be applied to u and (69) holds true for $\delta^\circ(u)$ (the standard divergence operator). This proves that $\text{Dom} \delta^\circ \cap (L^2(\Omega \times [0, T]))^d \subset \text{Dom}^* \delta^\circ \cap L^2(\Omega; \mathcal{H})$ and that δ° is an extension of the standard divergence operator on $\text{Dom} \delta^\circ \cap (L^2(\Omega \times [0, T]))^d$.

To see the other inclusion, take $u \in \text{Dom}^* \delta^\circ \cap L^2(\Omega; \mathcal{H})$. By our Definition 5.6 of $\text{Dom}^* \delta^\circ$, u belongs also to $(L^2(\Omega \times [0, T]))^d$. We will show that $u \in \text{Dom} \delta^\circ$. First, we will prove that the element $\delta^\circ(u)$ defined by the equality (70) satisfies, for any $\varphi \in (\mathcal{D}_T)^d$ and any $n \geq 0$, that

$$\mathbf{E} [\delta^\circ(u) H_n(x(\varphi))] = \mathbf{E} [\langle u, DH_n(x(\varphi)) \rangle_{\mathcal{H}}]. \quad (71)$$

Indeed, since $u \in (L^2([0, T]))^d \cap \mathcal{H}$ a.s. by assumption, we can apply again identity (68) and so,

$$\langle u, DH_n(x(\varphi)) \rangle_{\mathcal{H}} = H_{n-1}(x(\varphi)) \int_0^T \langle u_s, \mathbf{A}\varphi(s) \rangle ds.$$

Hence, using Fubini's theorem and (70) we end up with

$$\mathbf{E} \langle u, DH_n(x(\varphi)) \rangle_{\mathcal{H}} = \int_0^T \langle \mathbf{E} [H_{n-1}(x(\varphi)) u_s], \mathbf{A}\varphi(s) \rangle ds = \mathbf{E} [\delta^\circ(u) H_n(x(\varphi))],$$

which is exactly (71).

By using density arguments (the linear space generated by the elements of the form $H_n(x(\varphi))$, with $\varphi \in (\mathcal{D}_T)^d$, $n \geq 0$, is dense in $\text{Dom} D$) we obtain that

$$\mathbf{E} [\langle u, DF \rangle_{\mathcal{H}}] = \mathbf{E} [\delta^\circ(u) F]$$

for any $F \in \text{Dom} D$, and this finishes the proof. \square

Example 5.10. Go back to our fBm Example 5.4, and let us compare the extended divergence operator introduced above with the one defined in [2]. First of all, we must point out that in [2], the (standard) divergence operator is presented in a more general setting than ours: the divergence can belong to any $L^p(\Omega)$, for $p > 1$. In our paper, we will only consider this divergence over L^2 spaces for sake of conciseness.

According to the computations carried out in [16] (see identity (5.30) of that work), for any element ψ in the space of test functions \mathcal{D}_T one has

$$c_H^2 \mathbf{D}_+^\alpha \mathbf{D}_-^\alpha \psi(s) = \int_0^T H |s - y|^{2H-1} \text{sign}(s - y) \psi'(y) dy.$$

On the other hand, we have already seen at Example 5.4 that $\mathbf{A}\psi(s) = \int_0^T H |s - y|^{2H-1} \text{sign}(s - y) \psi'(y) dy$. That is, on \mathcal{D}_T , we have the following identity of operators: $c_H^2 \mathbf{D}_+^\alpha \mathbf{D}_-^\alpha = \mathbf{A}$. Moreover, these operators can be extended (and coincide) by density arguments to $I_-^\alpha(\mathcal{E}_H)$ (see [2] for the definition of this space). Finally, in this case, $\mathcal{H} = I_-^\alpha(L^2([0, T]))$ is a subset of $L^2([0, T])$. Using these observations, it is readily checked that the extended divergence operator defined above coincides with the extended divergence given in [2], restricted to L^2 spaces.

5.4. Change of variable formula for Skorohod integrals. We can now turn to the main aim of this section, namely the proof of a change of variable formula for $f(x)$ based on our extended divergence operator δ° . Interestingly enough, this will be achieved under some non restrictive exponential growth conditions on f .

Definition 5.11. *We will say that a function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ satisfies the growth condition (GC) if there exist positive constants C and λ such that*

$$\lambda < \frac{1}{4d \max_{t \in [0, T]} R_t}, \quad \text{and} \quad |f(x)| \leq C e^{\lambda |x|^2} \quad \text{for all } x \in \mathbb{R}^d. \quad (72)$$

Notice that $\max_{t \in [0, T]} R_t = \max_{t \in [0, T]} E[|x_t|^2]$. Thus the growth condition above implies that

$$\mathbf{E} \left[\max_{t \in [0, T]} |f(x_t)|^r \right] \leq C^r \mathbf{E} \left(e^{r\lambda \max_{t \in [0, T]} |x_t|^2} \right),$$

and this last expectation is finite (see, for instance [23], Corollary 5.4.6) if and only if

$$r\lambda < \frac{1}{2 \max_{t \in [0, T]} E(|x_r|^2)} = \frac{1}{2d \max_{t \in [0, T]} R_t}.$$

So, if condition (72) is satisfied, there exists $r > 2$ such that

$$\mathbf{E} \left[\max_{t \in [0, T]} |f(x_t)|^r \right] < \infty. \quad (73)$$

With these preliminaries in hand, we first state a Skorohod type change of variable formula for a very regular function f .

Proposition 5.12. *Let $f \in C^\infty(\mathbb{R}^d)$ such that f and all its derivatives satisfy the growth condition (GC) (with possibly different λ 's and C 's). Then, for any $0 \leq s < t \leq T$,*

$$\mathbf{1}_{[s, t)}(\cdot) \nabla f(x) \in \text{Dom}^* \delta^\circ$$

and

$$\delta^\circ \left[\mathbf{1}_{[s, t)}(\cdot) \nabla f(x) \right] = f(x_t) - f(x_s) - \frac{1}{2} \int_s^t \Delta f(x_\rho) R'_\rho d\rho.$$

Proof. Since f and all its derivatives satisfy growth condition (GC), the process $\mathbf{1}_{[s, t)} \nabla f(x)$ is an element of $(L^2(\Omega \times [0, T]))^d$ and we also have

$$f(x_t) - f(x_s) - \frac{1}{2} \int_s^t \Delta f(x_\rho) R'_\rho d\rho \in L^2(\Omega).$$

So, we only need to show that for any $n \geq 0$ and any $\varphi \in (\mathcal{D}_T)^d$ the following equality is satisfied:

$$\begin{aligned} \mathbf{E} \left[\left(f(x_t) - f(x_s) - \frac{1}{2} \int_s^t \Delta f(x_\rho) R'_\rho d\rho \right) H_n(x(\varphi)) \right] \\ = \int_s^t \langle \mathbf{E} [H_{n-1}(x(\varphi)) \nabla f(x_\rho)], \mathbf{A}\varphi(\rho) \rangle d\rho. \end{aligned} \quad (74)$$

The proof of this fact is similar to that of [2, Lemma 4.3], although some technical complications arise from the fact that here we deal with the multidimensional case.

Consider thus the Gaussian kernel

$$p(\sigma, y) = (2\pi\sigma)^{-\frac{d}{2}} \exp\left(-\frac{1}{2} \frac{|y|^2}{\sigma}\right), \quad \text{for } \sigma > 0, y \in \mathbb{R}^d. \quad (75)$$

It is a well-known fact that $\partial_\sigma p = \frac{1}{2} \Delta p$. Moreover, $\mathbf{E}[g(x_t)] = \int_{\mathbb{R}^d} p(R_t, y) g(y) dy$ for any regular function $g : \mathbb{R}^d \rightarrow \mathbb{R}$ such that g and all its derivatives satisfy (GC). Using these identities, we can perform the following computations:

$$\begin{aligned} \frac{d}{dt} \mathbf{E}[g(x_t)] &= \frac{d}{dt} \int_{\mathbb{R}^d} p(R_t, y) g(y) dy = \int_{\mathbb{R}^d} \frac{\partial}{\partial \sigma} p(R_t, y) R'_t g(y) dy \\ &= \frac{1}{2} R'_t \int_{\mathbb{R}^d} \Delta p(R_t, y) g(y) dy = \frac{1}{2} R'_t \int_{\mathbb{R}^d} p(R_t, y) \Delta G(y) dy \\ &= \frac{1}{2} R'_t \mathbf{E}[\Delta g(x_t)]. \end{aligned} \quad (76)$$

This shows that the function $\frac{d}{dt} \mathbf{E}[g(x_t)]$ is defined in all $t \in (0, T)$ and is integrable on $[0, T]$. As a consequence, $\mathbf{E}[g(x_t)]$ is absolutely continuous. Using this fact and identity (76), we can now prove (74) when $n = 0$. Indeed, observe that in this case $H_0(x) \equiv 1$ and, by definition, $H_{-1}(x) \equiv 0$. Hence, the right-hand side of (74) is equal to 0 while the left-hand side gives:

$$\mathbf{E}\left[f(x_t) - f(x_s) - \frac{1}{2} \int_s^t \Delta f(x_\rho) R'_\rho d\rho\right] = \int_s^t \frac{d}{d\rho} \mathbf{E}[f(x_\rho)] d\rho - \frac{1}{2} \int_s^t \mathbf{E}[\Delta f(x_\rho)] R'_\rho d\rho,$$

and this last quantity vanishes due to (76).

Let now $n \geq 1$. Define for $j \in \{1, \dots, d\}$ and $t \in [0, T]$,

$$G_\varphi^j(\rho) = \int_0^\rho \mathbf{A}\varphi(j)(s) ds = \langle \mathbf{1}_{[0, \rho]}^{[j]}, \varphi(j)^{[j]} \rangle_{\mathcal{H}}. \quad (77)$$

Clearly, G_φ^j is absolutely continuous and $(G_\varphi^j)' = \mathbf{A}\varphi(j)$ (a.e). Moreover, for a regular function g satisfying (GC) together with all its derivatives and for any multiindex $(j_1, \dots, j_n) \in \{1, \dots, d\}^n$ we have

$$\begin{aligned} \frac{d}{d\rho} (\mathbf{E}[g(x_\rho)] G_\varphi^{j_1}(\rho) \cdots G_\varphi^{j_n}(\rho)) &= \frac{1}{2} \mathbf{E}[\Delta g(x_\rho)] R'_\rho G_\varphi^{j_1}(\rho) \cdots G_\varphi^{j_n}(\rho) \\ &\quad + \mathbf{E}[g(x_\rho)] \sum_{r=1}^n \mathbf{A}\varphi(j_r)(\rho) \left[\prod_{l:l \neq r} G_\varphi^{j_l}(\rho) \right], \end{aligned} \quad (78)$$

where we have used (76). Recall now our convention (21), allowing to write $\partial_{j_1 \dots j_n}^n f$ for $\frac{\partial^n}{\partial y_{j_1} \dots \partial y_{j_n}} f$, and set $M_t^{j_1 \dots j_n} \equiv \mathbf{E}[\partial_{j_1 \dots j_n}^n f(x_\rho)] \prod_{l=1}^n G_\varphi^{j_l}(\rho)$ for $\rho \in [s, t]$. By integrating (78) from s to t and taking $g = \partial_{j_1 \dots j_n}^n f$ we obtain that

$$\begin{aligned} M_t^{j_1 \dots j_n} - M_s^{j_1 \dots j_n} &= \frac{1}{2} \int_s^t \left(\mathbf{E}[\Delta \partial_{j_1 \dots j_n}^n f(x_\rho)] R'_\rho \prod_{l=1}^n G_\varphi^{j_l}(\rho) \right) d\rho \\ &\quad + \int_s^t \left(\mathbf{E}[\partial_{j_1 \dots j_n}^n f(x_\rho)] \left(\sum_{r=1}^n \mathbf{A}\varphi(j_r)(\rho) \prod_{l:l \neq r} G_\varphi^{j_l}(\rho) \right) \right) d\rho. \end{aligned}$$

Summing these expressions over all the multiindices $(j_1, \dots, j_n) \in \{1, \dots, d\}^n$ and owing to the fact that

$$\begin{aligned} \sum_{j_1, \dots, j_n} \int_s^t \mathbf{E} [\partial_{j_1 \dots j_n}^n f(x_\rho)] \left(\sum_{r=1}^n \mathbf{A}\varphi(j_r) \prod_{l:l \neq r} G_\varphi^{j_l}(\rho) \right) d\rho \\ = n \sum_{j_1, \dots, j_n} \int_s^t \mathbf{E} [\partial_{j_1 \dots j_n}^n f(x_\rho)] \prod_{l=1}^{n-1} G_\varphi^{j_l}(\rho) \mathbf{A}\varphi(j_n)(\rho) d\rho, \end{aligned}$$

we end up with an expression of the form

$$\begin{aligned} \sum_{j_1, \dots, j_n} [M_t^{j_1 \dots j_n} - M_s^{j_1 \dots j_n}] &= \frac{1}{2} \sum_{j_1, \dots, j_n} \int_s^t \mathbf{E} [\Delta \partial_{j_1 \dots j_n}^n f(x_\rho)] R'_\rho \prod_{l=1}^n G_\varphi^{j_l}(\rho) d\rho \\ &+ n \sum_{j_1, \dots, j_n} \int_s^t \mathbf{E} [\partial_{j_1 \dots j_n}^n f(x_\rho)] \prod_{l=1}^{n-1} G_\varphi^{j_l}(\rho) \mathbf{A}\varphi(j_n)(\rho) d\rho. \quad (79) \end{aligned}$$

It should be observed at this point that, as in identity (55), the symmetries of the partial derivatives of f play a crucial role in the proof of the current proposition. This symmetry property appears precisely in the computations above.

We will see now how to obtain the desired identity (74) from (79). Indeed, it is a well known fact (see [25] again) that $H_{n-1}(x(\varphi)) \varphi \in \text{Dom} \delta^\diamond$ and $\delta^\diamond [H_{n-1}(x(\varphi)) \varphi] = n H_n(x(\varphi))$. Using these last two facts, the duality relationship between D and δ^\diamond and the definition (77) of G_j^φ we have that, for g satisfying (GC) as well as its derivatives,

$$\begin{aligned} \mathbf{E} [H_n(x(\varphi))g(x_t)] &= \frac{1}{n} \mathbf{E} \langle H_{n-1}(x(\varphi)) \varphi, Dg(x_t) \rangle_{\mathcal{H}} \\ &= \frac{1}{n} \mathbf{E} \langle H_{n-1}(x(\varphi)) \varphi, \mathbf{1}_{[0,t)} \nabla g(x_t) \rangle_{\mathcal{H}} \\ &= \frac{1}{n} \mathbf{E} \left[H_{n-1}(x(\varphi)) \sum_{j=1}^d \int_0^t \partial_j g(x_t) \mathbf{A}\varphi(j)(\rho) d\rho \right] \\ &= \frac{1}{n} \sum_{j=1}^d \mathbf{E} [H_{n-1}(x(\varphi)) \partial_j g(x_t)] G_\varphi^j(t). \end{aligned}$$

Iterating this procedure n times, one ends up with the identity

$$\mathbf{E} [H_n(x(\varphi))g(x_t)] = \frac{1}{n!} \sum_{j_1, \dots, j_n} \mathbf{E} [\partial_{j_1 \dots j_n}^n g(x_t)] G_\varphi^{j_1}(t) \cdots G_\varphi^{j_n}(t).$$

As an application of this general calculation, we can deduce the following equalities:

$$\mathbf{E} [H_n(x(\varphi))f(x_t)] = \frac{1}{n!} \sum_{j_1, \dots, j_n} \mathbf{E} [\partial_{j_1 \dots j_n}^n f(x_t)] G_\varphi^{j_1}(t) \cdots G_\varphi^{j_n}(t) \quad (80)$$

$$\mathbf{E} [H_n(x(\varphi))f(x_s)] = \frac{1}{n!} \sum_{j_1, \dots, j_n} \mathbf{E} [\partial_{j_1 \dots j_n}^n f(x_s)] G_\varphi^{j_1}(s) \cdots G_\varphi^{j_n}(s) \quad (81)$$

$$\mathbf{E} [H_n(x(\varphi))\Delta f(x_\rho)] = \frac{1}{n!} \sum_{j_1, \dots, j_n} \mathbf{E} [\partial_{j_1 \dots j_n}^n \Delta f(x_\rho)] G_\varphi^{j_1}(\rho) \cdots G_\varphi^{j_n}(\rho), \quad (82)$$

and

$$\mathbf{E} [H_{n-1}(x(\varphi)) \partial_j f(x_\rho)] = \frac{1}{(n-1)!} \sum_{j_1, \dots, j_{n-1}} \mathbf{E} [\partial_{j_1 \dots j_{n-1}} f(x_\rho)] G_\varphi^{j_1}(\rho) \cdots G_\varphi^{j_{n-1}}(\rho). \quad (83)$$

Substituting now (80)–(83) in (79), we obtain

$$\begin{aligned} n! \mathbf{E} [H_n(x(\varphi)) f(x_t)] - n! \mathbf{E} [H_n(x(\varphi)) f(x_s)] &= \frac{1}{2} n! \int_s^t \mathbf{E} [H_n(x(\varphi)) \Delta f(x_\rho)] R'_\rho d\rho \\ &+ n(n-1)! \int_s^t \sum_{j_n=1}^d \mathbf{E} [H_{n-1}(x(\varphi)) \partial_{j_n} f(x_\rho)] \mathbf{A}\varphi(j_n)(\rho) d\rho, \end{aligned}$$

and this is actually equality (74). The proof is now finished. \square

Since the Skorohod divergence operator is closable, we can now generalize our change of variable formula:

Theorem 5.13. *The conclusions of Proposition 5.12 still hold true whenever f is an element of $\mathcal{C}^2(\mathbb{R}^d)$ such that f and its partial derivatives up to second order verify the growth condition (GC).*

Proof. Let λ be the constant appearing in the growth condition (GC). Given $k > 2\lambda$, denote by $p_k(y) = p(\frac{1}{k}, y)$ the Gaussian kernel defined in (75) and introduce $f_k(y) = (f * p_k)(y)$ where, as usual, $*$ denotes the convolution product.

We first claim that there exist $k_0 \in \mathbb{N}$, $C' > 0$ and λ' satisfying $\lambda < \lambda' < \frac{1}{4d \max_{t \in [0, T]} R_t}$, such that

$$\sup_{k \geq k_0} |f_k(y)| \leq C' e^{\lambda' |y|^2}. \quad (84)$$

Indeed, condition (GC) easily yields

$$\begin{aligned} |f_k(y)| &\leq \left(\frac{k}{2\pi}\right)^{d/2} \int_{\mathbb{R}^d} |f(y-z)| e^{-\frac{k|z|^2}{2}} dz \\ &\leq \left(\frac{k}{2\pi}\right)^{d/2} C \int_{\mathbb{R}^d} e^{\lambda|y-z|^2} e^{-\frac{k|z|^2}{2}} dz = C \prod_{i=1}^d \left(\sqrt{\frac{k}{2\pi}} \int_{\mathbb{R}} e^{\lambda(y_i-z_i)^2} e^{-\frac{kz_i^2}{2}} dz_i \right). \end{aligned}$$

On the other hand,

$$\sqrt{\frac{k}{2\pi}} \int_{\mathbb{R}} e^{\lambda(y_i-z_i)^2} e^{-\frac{kz_i^2}{2}} dz_i = \sqrt{\frac{k}{k-2\lambda}} \exp \left\{ \left(\frac{\lambda k}{k-2\lambda} \right) y_i^2 \right\},$$

and $\lim_{k \rightarrow \infty} \frac{\lambda k}{k-2\lambda} = \lambda$. Hence, given $\lambda' \in (\lambda, \frac{1}{4d \max_{t \in [0, T]} R_t})$, there exists $k_0 \in \mathbb{N}$ such that for any $k \geq k_0$ the following inequalities are satisfied:

$$\lambda < \frac{\lambda k}{k-2\lambda} < \lambda' < \frac{1}{4d \max_{t \in [0, T]} R_t}.$$

Our claim (84) is now easily deduced.

Notice that (84) means that for $k \geq k_0$, f_k also satisfies the growth condition (GC) (with C' and λ' substituting C and λ , respectively). Moreover, we have that

$$\mathbf{E} \left[\sup_{\rho \in [0, T]} \sup_{k \geq k_0} |f_k(x_\rho)|^2 \right] < \infty.$$

Thanks to this inequality, as well as similar ones involving the derivatives of f , one can easily see that:

- (1) $f_k(x_s) \rightarrow f(x_s)$ and $f_k(x_t) \rightarrow f(x_t)$ in $L^2(\Omega)$,
- (2) $\int_s^t \Delta f_k(x_\rho) R'_\rho d\rho \rightarrow \int_s^t \Delta f(x_\rho) R'_\rho d\rho$ in $L^2(\Omega)$ and
- (3) $\mathbf{1}_{[s, t]} \nabla f_k(x_\cdot) \rightarrow \mathbf{1}_{[s, t]} \nabla f(x_\cdot)$ in $(L^2(\Omega \times [0, T]))^d$.

The result is finally obtained by applying Proposition 5.12 and the closeness of the extended operator δ^\diamond alluded to at Remark 5.8. \square

6. REPRESENTATION OF THE SKOROHOD INTEGRAL

Up to now, we have given two unrelated change of variable formulas for $f(x)$: one based on pathwise considerations (Theorem 4.5) and the other one by means of Malliavin calculus (Theorem 5.13). We propose now to make a link between the two formulas and integrals by means of Riemann sums.

Namely, let x be a process generating a rough path of order N . We have seen at equation (55) that the Stratonovich integral $\mathcal{J}_{st}(\nabla f(x) dx)$ is given by $\lim_{|\Pi_{st}| \rightarrow 0} S^{\Pi_{st}}$, where

$$S^{\Pi_{st}} := \sum_{q=0}^{n-1} \sum_{k=1}^N \frac{1}{k!} \partial_{i_k \dots i_1}^k f(x_{t_q}) \mathbf{x}_{t_q, t_{q+1}}^1(i_1) \mathbf{x}_{t_q, t_{q+1}}^1(i_2) \cdots \mathbf{x}_{t_q, t_{q+1}}^1(i_k).$$

In a Gaussian setting, it is thus natural to think that a natural candidate for the Skorohod integral $\delta^\diamond(\nabla f(x))$ is also given by $\lim_{|\Pi_{st}| \rightarrow 0} S^{\Pi_{st}, \diamond}$, with

$$S^{\Pi_{st}, \diamond} := \sum_{q=0}^{n-1} \sum_{k=1}^N \frac{1}{k!} \partial_{i_k \dots i_1}^k f(x_{t_q}) \diamond \mathbf{x}_{t_q, t_{q+1}}^1(i_1) \diamond \cdots \diamond \mathbf{x}_{t_q, t_{q+1}}^1(i_k), \quad (85)$$

where \diamond denotes the Wick product. We shall see that this is indeed the case, with the following strategy:

(i) One should thus first check that $\lim_{|\Pi_{st}| \rightarrow 0} S^{\Pi_{st}, \diamond}$ exists. In order to check this convergence, we shall use extensively Wick calculus, in order to write

$$\partial_{i_k \dots i_1}^k f(x_{t_q}) \diamond \mathbf{x}_{t_q, t_{q+1}}^1(i_1) \diamond \cdots \diamond \mathbf{x}_{t_q, t_{q+1}}^1(i_k) = \partial_{i_k \dots i_1}^k f(x_{t_q}) \mathbf{x}_{t_q, t_{q+1}}^1(i_1) \cdots \mathbf{x}_{t_q, t_{q+1}}^1(i_k) + \rho_{t_q, t_{q+1}},$$

where ρ is a certain correction increment which can be computed explicitly. Plugging this relation into (85), we obtain

$$S^{\Pi_{st}, \diamond} = S^{\Pi_{st}} + \sum_{q=0}^{n-1} \rho_{t_q, t_{q+1}}. \quad (86)$$

(ii) Manipulating the exact expression of the remainder ρ , we will be able to prove that $\lim_{|\Pi_{st}| \rightarrow 0} \sum_{q=0}^{n-1} \rho_{t_q, t_{q+1}} = -\frac{1}{2} \int_s^t \Delta f(x_v) R'_v dv$. Hence, going back to (86) and invoking the

fact that $S^{\Pi_{st}}$ converges to $\mathcal{J}_{st}(\nabla f(x) dx)$, we obtain

$$\lim_{|\Pi_{st}| \rightarrow 0} S^{\Pi_{st}, \diamond} = \mathcal{J}_{st}(\nabla f(x) dx) - \frac{1}{2} \int_s^t \Delta f(x_v) R'_v dv = [\delta f(x)]_{st} - \frac{1}{2} \int_s^t \Delta f(x_v) R'_v dv.$$

This gives both the convergence of $S^{\Pi_{st}, \diamond}$ and an Itô-Skorohod formula of the form:

$$[\delta f(x)]_{st} = \lim_{|\Pi_{st}| \rightarrow 0} S^{\Pi_{st}, \diamond} + \frac{1}{2} \int_s^t \Delta f(x_v) R'_v dv.$$

(iii) Putting together this last equality and Theorem 5.13, it can be deduced that under Hypotheses 5.1 and 5.2, the limit of $S^{\Pi_{st}, \diamond}$ coincides with the Skorohod integral $\delta^\diamond(\nabla f(x))$. This gives our link relating the Stratonovich integral $\mathcal{J}(\nabla f(x) dx)$ and the Skorohod integral $\delta^\diamond(\nabla f(x))$.

This relatively straightforward strategy being set, we turn now to the technical details of its realization. To this end, the main issue is obviously the computation of the corrections between Wick and ordinary products in sums like $S^{\Pi_{st}, \diamond}$. We thus start by recalling some basic facts of Wick computations.

6.1. Notions of Wick calculus. We present here the notions of Wick calculus needed later on, basically following [17]. We also use extensively the notations introduced in Section 5.1.

One way to introduce Wick products on a Wiener space is to impose the relation

$$I_n(f_n) \diamond I_m(g_m) = I_{n+m}(f_n \hat{\otimes} g_m)$$

for any $f_n \in \mathcal{H}^{\otimes n}$ and $g_m \in \mathcal{H}^{\otimes m}$, where the multiple integrals $I_n(f_n)$ and $I_m(g_m)$ are defined by (60). If $F = \sum_{n=1}^{N_1} I_n(f_n)$ and $G = \sum_{m=1}^{N_2} I_m(g_m)$, we define $F \diamond G$ by

$$F \diamond G = \sum_{n=1}^{N_1} \sum_{m=1}^{N_2} I_{n+m}(f_n \hat{\otimes} g_m).$$

By a limit argument, we can then extend the Wick product to more general random variables (see [17] for further details). In this paper, we will take the limits in the $L^2(\Omega)$ topology.

For $f \in \mathcal{H}$ we define its exponential vector $\mathcal{E}(f)$ by

$$\begin{aligned} \mathcal{E}(f) &:= e^{\diamond I_1(f)} = \exp\left(I_1(f) - \frac{\|f\|_{\mathcal{H}}^2}{2}\right) = \exp\left(I_1(f) - \frac{1}{2} \mathbf{E}(I_1(f))^2\right) \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} I_n(f^{\otimes n}) = \sum_{n=0}^{\infty} \frac{1}{n!} I_1(f)^{\diamond n}. \end{aligned}$$

In a similar way we can define the complex exponential vector of f by (\imath denotes here the imaginary unity)

$$e^{\diamond \imath I_1(f)} = \exp\left(\imath I_1(f) + \frac{\|f\|_{\mathcal{H}}^2}{2}\right) = \sum_{n=0}^{\infty} \frac{\imath^n}{n!} I_1(f)^{\diamond n}. \quad (87)$$

With these notations in hand, an important property of Wick product is the following relation: for any two elements f and g in \mathcal{H} , we have

$$\mathcal{E}(f) \diamond \mathcal{E}(g) = \mathcal{E}(f + g), \quad (88)$$

an analogous property for the complex exponential vector being also satisfied.

We now state a result which is a generalization of [17, Proposition 4.8].

Proposition 6.1. *Let $F \in \text{Dom } D^k$ and $g \in \mathcal{H}^{\otimes k}$. Then*

- (1) $F \diamond I_k(g)$ is well defined in $L^2(\Omega)$.
- (2) $Fg \in \text{Dom } \delta^{\otimes k}$.
- (3) $F \diamond I_k(g) = \delta^{\otimes k}(Fg)$.

Proof. Let $F \in \text{Dom } D^k$. This implies that F admits the chaos decomposition $F = \sum_{n=0}^{\infty} I_n(f_n)$, with

$$\sum_{n=0}^{\infty} n^k n! \|f_n\|_{\mathcal{H}^{\otimes n}}^2 < \infty. \quad (89)$$

Define then $F_N = \sum_{n=0}^N I_n(f_n)$. Consider also $g \in \mathcal{H}^{\otimes k}$. In order to check (1), we shall see that the limit in $L^2(\Omega)$ of $F_N \diamond I_k(g)$ exists, as $N \rightarrow \infty$. But $F_N \diamond I_k(g) = \sum_{n=0}^N I_{n+k}(f_n \hat{\otimes} g)$, and the limit in $L^2(\Omega)$ of this expression exists if and only if

$$\sum_{n=0}^{\infty} (n+k)! \|f_n \hat{\otimes} g\|_{\mathcal{H}^{\otimes n+k}}^2 < \infty.$$

This last condition is clearly satisfied thanks to (89).

Now we will prove our claims (2) and (3) for F with a finite chaos decomposition and $g = g_1 \otimes \cdots \otimes g_k$, with $g_i \in \mathcal{H}$, for $i = 1, \dots, k$. More precisely, we will see that for any $G \in \mathbf{S}$ the following relationship holds:

$$\mathbf{E} \left[(F \diamond I_k(g)) G \right] = \mathbf{E} \left[\langle Fg, D^k G \rangle_{\mathcal{H}^{\otimes k}} \right]. \quad (90)$$

This will be done by an induction argument. For $k = 1$, this is a consequence of [17, Proposition 4.8] since $F \diamond I_1(g) = \delta^{\otimes}(Fg)$. Suppose now that (90) is satisfied for $k = K$. Therefore,

$$\begin{aligned} \mathbf{E} \left[[F \diamond I_{K+1}(g)] G \right] &= \mathbf{E} \left[(F \diamond I_1(g_1) \diamond I_K(g_2 \otimes \cdots \otimes g_{K+1})) G \right] \\ &= \mathbf{E} \left[\langle (F \diamond I_1(g_1)) g_2 \otimes \cdots \otimes g_{K+1}, D^K G \rangle_{\mathcal{H}^{\otimes K}} \right], \end{aligned}$$

where in the last equality we have used that $F \diamond I_1(g_1)$ has a finite chaos expansion and the induction hypothesis. The last expression can be rewritten as

$$\mathbf{E} \left[(F \diamond I_1(g_1)) D_{g_2 \otimes \cdots \otimes g_{K+1}}^K G \right].$$

Since $D_{g_2 \otimes \cdots \otimes g_{K+1}}^K G \in \mathbf{S}$, we can apply the case $k = 1$ to the above expression and we obtain

$$\begin{aligned} \mathbf{E} \left[[F \diamond I_{K+1}(g)] G \right] &= \mathbf{E} \left[\langle Fg_1, D_{g_2 \otimes \cdots \otimes g_{K+1}}^K G \rangle_{\mathcal{H}} \right] = \mathbf{E} \left[F D_{g_1}^1 (D_{g_2 \otimes \cdots \otimes g_{K+1}}^K G) \right] \\ &= \mathbf{E} \left[F D_{g_1 \otimes g_2 \otimes \cdots \otimes g_{K+1}}^{K+1} G \right] = \mathbf{E} \left[\langle Fg_1 \otimes \cdots \otimes g_{K+1}, D^{K+1} G \rangle_{\mathcal{H}^{\otimes K+1}} \right], \end{aligned}$$

which finishes our induction procedure. Thus, (90) is satisfied for F with a finite chaos expansion and g a tensor product of elements of \mathcal{H} .

To extend the result to a general $F \in \text{Dom}(D^k)$ and $g \in \mathcal{H}^{\otimes k}$, we first consider the case $F \in \text{Dom}(D^k)$ and $g = g_1 \otimes \cdots \otimes g_k$. In this situation, identity (90) is a consequence

of the fact that this relationship holds for $F_N = \sum_{n=0}^N I_n(f_n)$ defined above and of the part (1) of the proposition. Finally, for a general $g \in \mathcal{H}^{\otimes k}$, using the fact that both sides of (90) are linear in g , we can generalize this identity to g belonging to the linear span of elements of the form $g_1 \otimes \cdots \otimes g_k$, which is a dense subspace of $\mathcal{H}^{\otimes k}$. So if $g \in \mathcal{H}^{\otimes k}$ and $\{g^M\}_{M \in \mathbb{N}}$ is a sequence of elements of this linear span of tensor products such that $g^M \rightarrow g$ in $\mathcal{H}^{\otimes k}$, one can easily see (by using (89)) that

$$F \diamond I_k(g^M) \rightarrow F \diamond I_k(g),$$

as $M \rightarrow \infty$ in $L^2(\Omega)$. Since

$$E \left[(F \diamond I_k(g^M)) G \right] = E \left[\langle F g^M, D^k G \rangle_{\mathcal{H}^{\otimes k}} \right],$$

the proof is completed by a limiting argument. \square

6.2. One-dimensional case. In order to simplify a little our presentation, we first show the identification of $\delta^\diamond(\nabla f(x))$ with $\lim_{|\Pi_{st}| \rightarrow 0} S^{\Pi_{st}, \diamond}$ when $d = 1$, that is when x is a one-dimensional Gaussian process satisfying Hypothesis 5.1. The first step in this direction is a general formula for Wick products of the form $G(X) \diamond Y^{\circ p}$, where X and Y are elements of the first chaos (see Section 5.1 for a definition). Notice that the proof of this proposition is deferred to the Appendix for sake of clarity.

Proposition 6.2. *Let $g, h \in \mathcal{H}$ and let $G : \mathbb{R} \rightarrow \mathbb{R}$ be differentiable up to order p such that all its derivatives $G^{(j)}$ are elements of $L^r(\mu_g)$ for any $j = 0, \dots, p$ and for some $r > 2$, with $\mu_g = \mathcal{N}(0, \|g\|_{\mathcal{H}}^2)$. Define $X = I_1(g)$ and $Y = I_1(h)$. Then the Wick product $G(X) \diamond Y^{\circ p}$ can be expressed in terms of ordinary products as*

$$\begin{aligned} G(X) \diamond Y^{\circ p} &= G(X) Y^p \\ &+ \sum_{0 < l+2m \leq p} \frac{(-1)^{m+l} p!}{2^m m! (p-2m-l)!} G^{(l)}(X) [\mathbf{E}(XY)]^l [\mathbf{E}(Y^2)]^m Y^{p-2m-l}. \end{aligned} \quad (91)$$

Example 6.3. In order to illustrate the kind of correction terms we obtain, let us write formula (91) for $p = 1, 2, 3$:

$$\begin{aligned} G(X) \diamond Y &= G(X) Y - G'(X) \mathbf{E}(XY) \\ G(X) \diamond Y^{\circ 2} &= G(X) Y^2 - G(X) \mathbf{E}(Y^2) - 2G'(X) \mathbf{E}(XY) Y + G''(X) [\mathbf{E}(XY)]^2 \\ G(X) \diamond Y^{\circ 3} &= G(X) Y^3 - 3G(X) \mathbf{E}(Y^2) Y + 3G'(X) \mathbf{E}(XY) \mathbf{E}(Y^2) \\ &\quad - 3G'(X) \mathbf{E}(XY) Y^2 + 3G''(X) [\mathbf{E}(XY)]^2 Y - G'''(X) [\mathbf{E}(XY)]^3. \end{aligned}$$

We are now ready to state our representation of the Skorohod integral by Riemann-Wick sums:

Theorem 6.4. *Let x be a 1-dimensional centered Gaussian process with continuous covariance function fulfilling Hypotheses 5.1 and 5.2, and assume that x also satisfies Hypotheses 1.1. Let f be a function in $C^{2N}(\mathbb{R})$ such that $f^{(k)}$ verifies the growth condition (GC) for $k = 1, \dots, 2N$. Then, the Skorohod integral $\delta^\diamond(\nabla f(x))$ (whose existence is ensured by Theorem 5.13) can be represented as a.s. $-\lim_{|\Pi_{st}| \rightarrow 0} S^{\Pi_{st}, \diamond}$, where $S^{\Pi_{st}, \diamond}$ is defined by*

$$S^{\Pi_{st}, \diamond} = \sum_{i=0}^{n-1} \sum_{k=1}^N \frac{1}{k!} f^{(k)}(x_{t_i}) \diamond (\mathbf{x}_{t_i t_{i+1}}^1)^{\diamond k}.$$

Moreover, we have

$$\delta^\diamond(f'(x)) = \int_s^t f'(x_\rho) dx_\rho - \int_s^t f'(x_\rho) R'_\rho d\rho \quad (92)$$

Proof. As mentioned at the beginning of the section, our main task is to compute $S^{\Pi_{st}, \diamond}$ in terms of ordinary products. This will be achieved by applying Proposition 6.2 to each term in the above sum, with $G = f$, $X = x_{t_i}$ and $Y = \mathbf{x}_{t_i t_{i+1}}^1 = x_{t_{i+1}} - x_{t_i}$.

To this end, notice first that the integrability conditions on f required at Proposition 6.2 are fulfilled as soon as condition (GC) (see Definition 5.11) is met. Fix then $i \in \{0, \dots, n-1\}$, recall that we set $X = x_{t_i}$ and $Y = \mathbf{x}_{t_i t_{i+1}}^1$, and consider the quantity $\mathcal{S}_k^i := \frac{1}{k!} f^{(k)}(x_{t_i}) \diamond (\mathbf{x}_{t_i t_{i+1}}^1)^{\diamond, k}$. A direct application of Proposition 6.2 yields

$$\sum_{k=1}^N \mathcal{S}_k^i = \sum_{k=1}^N \sum_{l+2m \leq k} \frac{(-1)^{l+m}}{2^m m! l! (k-2m-l)!} f^{(k+l)}(X) [\mathbf{E}(XY)]^l [\mathbf{E}(Y^2)]^m Y^{k-2m-l}.$$

Making a substitution $q = k + l$ and $l + m = u$, this expression can be simplified into

$$\begin{aligned} \sum_{k=1}^N \mathcal{S}_k^i &= \sum_{q=1}^{2N} f^{(q)}(X) \sum_{l+m \leq q/2} \frac{(-1)^{l+m}}{2^m m! l! (q-2l-2m)!} [\mathbf{E}(XY)]^l [\mathbf{E}(Y^2)]^m Y^{q-2l-2m} \\ &= \sum_{q=1}^{2N} f^{(q)}(X) \sum_{u=0}^{[q/2]} \frac{(-1)^u}{(q-2u)!} \sum_{l+m=u} \frac{1}{m! l!} [\mathbf{E}(XY)]^l \left[\frac{\mathbf{E}(Y^2)}{2} \right]^m Y^{q-2u} \\ &= \sum_{q=1}^{2N} f^{(q)}(X) \sum_{u=0}^{[q/2]} \frac{(-1)^u}{(q-2u)! u!} \left[\mathbf{E}(XY) + \frac{\mathbf{E}(Y^2)}{2} \right]^u Y^{q-2u}. \end{aligned} \quad (93)$$

Moreover, recalling again that $X = x_{t_i}$ and $Y = x_{t_{i+1}} - x_{t_i}$, it is easily seen that

$$\mathbf{E}(XY) + \frac{\mathbf{E}(Y^2)}{2} = \frac{1}{2} \left[\mathbf{E}(x_{t_{i+1}}^2) - \mathbf{E}(x_{t_i}^2) \right] = \frac{1}{2} \delta R_{t_i t_{i+1}}, \quad (94)$$

where we recall that $\delta R_{t_i t_{i+1}}$ stands for $R_{t_{i+1}} - R_{t_i}$. Therefore, summing now over $i \in \{i, \dots, n-1\}$ we get

$$S^{\Pi_{st}, \diamond} = \sum_{i=0}^{n-1} \sum_{k=1}^N \mathcal{S}_k^i = \sum_{q=1}^{2N} \sum_{u=0}^{[q/2]} \frac{(-1)^u}{(q-2u)! u! 2^u} \sum_{i=0}^{n-1} \mathcal{T}_i^{q,u}, \quad (95)$$

where the quantity $\mathcal{T}_i^{q,u}$ is defined by

$$\mathcal{T}_i^{q,u} = f^{(q)}(x_{t_i}) (\delta R_{t_i t_{i+1}})^u (\mathbf{x}_{t_i, t_{i+1}}^1)^{q-2u}. \quad (96)$$

We now separate the study into different cases.

Case 1: If $u = 1$ and $q - 2u = 0$ (namely $q = 2$), then

$$\sum_{i=0}^{n-1} \mathcal{T}_i^{q,u} = -\frac{1}{2} \sum_{i=0}^{n-1} f''(x_{t_i}) [R_{t_{i+1}} - R_{t_i}] = -\frac{1}{2} \int_s^t \left(\sum_{i=0}^{n-1} f''(x_{t_i}) \mathbf{1}_{[t_i, t_{i+1})}(\rho) \right) R'_\rho d\rho,$$

where in the last equality we resort to the fact that R_ρ is absolutely continuous (see Hypothesis 5.1). From this expression, by a dominated convergence argument one easily gets $\lim_{n \rightarrow \infty} \sum_{i=0}^{n-1} \mathcal{T}_i^{q,u} = -\frac{1}{2} \int_s^t f''(x_\rho) R'_\rho d\rho$.

Case 2: If $u \geq 2$ or $u = 1$, $q - 2u \geq 1$, then $\lim_{n \rightarrow \infty} \sum_{i=0}^{n-1} \mathcal{T}_i^{q,u} = 0$. Indeed, recalling definition (96) of $\mathcal{T}_i^{q,u}$, we observe that

$$\sum_{i=0}^{n-1} \mathcal{T}_i^{q,u} \leq \max_{0 \leq i \leq n-1} \left\{ |\mathbf{x}_{t_i t_{i+1}}^1|^{q-2u}, |\delta R_{t_i t_{i+1}}|^{u-1} \right\} \int_s^t \left(\sum_{i=0}^{n-1} |f^{(q)}(x_{t_i})| \mathbf{1}_{[t_i, t_{i+1})}(\rho) \right) |R'(\rho)| d\rho.$$

In the right hand side of the above inequality, it is now easily seen that

$$\lim_{n \rightarrow \infty} \max_{0 \leq i \leq n-1} \left\{ |\mathbf{x}_{t_i t_{i+1}}^1|^{q-2u}, |\delta R_{t_i t_{i+1}}|^{u-1} \right\} = 0,$$

while the integral term remains bounded by $C \int_s^t |R'_\rho| d\rho$, which is bounded by assumption. This completes the proof of our claim.

Case 3: If $u = 0$, then

$$\sum_{i=0}^{n-1} \mathcal{T}_i^{q,u} = \sum_{i=0}^{n-1} \sum_{q=1}^N \frac{1}{q!} f^{(q)}(x_{t_i}) (\mathbf{x}_{t_i t_{i+1}}^1)^q + \sum_{i=0}^{n-1} \sum_{q=N+1}^{2N} \frac{1}{q!} f^{(q)}(x_{t_i}) (\mathbf{x}_{t_i t_{i+1}}^1)^q.$$

Thus Theorem 4.5 asserts that the first sum above converges to $\int_s^t f'(x_u) dx_u$, while it is easy to see that the second sum converges to 0, thanks to the regularity properties of x .

Plugging now the study of our 3 cases into equation (95), the proof of our theorem is easily completed. \square

6.3. Relationship with existing results. Several results exist on the convergence of Riemann-Wick sums, among which emerges [27], dealing with a situation which is similar to ours in the case of a one-dimensional process.

In order to compare our results with those of [27], let us specialize our situation to the case of a dyadic partition of an interval $[s, t]$ with $s < t$ (the case of a general partition is handled in [27], but this restriction will be more convenient for our purposes). Namely, for $n \geq 1$, we consider the partition $\Pi_{st}^n = \{t_k^n; 0 \leq k \leq 2^n\}$, where $t_k^n = s + k(t - s)/2^n$. For notational sake, we often write t_k instead of t_k^n . We shall also restrict our study to the case of a fBm B , though [27] deals with a rather general Gaussian process.

Let us first quote some results about weighted sums taken from [12, 10]:

Proposition 6.5. *Let B be a one-dimensional fractional Brownian motion, whose covariance function is defined by (3). Let g be a \mathcal{C}^4 function satisfying Hypothesis (GC) together with all its derivatives.*

(i) For $n \geq 1$, set

$$V_n^{(2)}(g) = \sum_{k=0}^{2^n-1} g(B_{t_k}) \left[\left(\mathbf{B}_{t_k t_{k+1}}^1 \right)^2 - 2^{-2nH} \right].$$

Then if $1/4 < H < 3/4$, we have

$$\mathcal{L} - \lim_{n \rightarrow \infty} n^{2H-1/2} V_n^{(2)}(g) = \sigma_H \int_0^{t-s} g(B_s) dW_s, \quad (97)$$

where $\mathcal{L} - \lim$ stands for a convergence in law, σ_H is a positive constant depending only on H , and W is a Brownian motion independent of B .

(ii) For $n \geq 1$, set

$$\tilde{V}_n^{(3)}(g) = \sum_{k=0}^{2^n-1} g(B_{t_k}) \left(\mathbf{B}_{t_k t_{k+1}}^1 \right)^3.$$

Then if $H < 1/2$ we have

$$L^2(\Omega) - \lim_{n \rightarrow \infty} n^{4H-1} \tilde{V}_n^{(3)}(g) = -\frac{3}{2} \int_0^{t-s} g'(B_s) ds.$$

We can now recall the main result of [27], to which we would like to compare our own computations, is the following:

Proposition 6.6. *Let B be a one-dimensional fBm with Hurst parameter $1/4 < H \leq 1/2$ and f be a \mathcal{C}^4 function satisfying Hypothesis (GC) together with all its derivatives. For $0 \leq s < t \leq T$, consider the set of dyadic partitions $\{\Pi_{st}^n; n \geq 1\}$ and set*

$$\tilde{S}^{n,\diamond} = \sum_{k=0}^{2^n-1} f'(B_{t_k}) \diamond \mathbf{B}_{t_k t_{k+1}}^1. \quad (98)$$

Then $\tilde{S}^{n,\diamond}$ converges in $L^2(\Omega)$ to $\delta^\diamond(f'(B))$ (which is the Skorohod integral introduced at Theorem 5.13).

Proof. Our aim here is not to reproduce the proof contained in [27], but to give a version compatible with our formalism. We shall focus on the case $1/4 < H \leq 1/3$, the other one being easier.

Consider first $0 \leq u < v \leq T$. According to Example 6.3, we have

$$\begin{aligned} f'(B_s) \diamond \mathbf{B}_{uv}^1 &= f'(B_u) \mathbf{B}_{uv}^1 - \frac{1}{2} f''(B_u) \mathbf{E} [B_u \mathbf{B}_{uv}^1] \\ &= f'(B_u) \mathbf{B}_{uv}^1 - \frac{1}{2} f''(B_u) [v^{2H} - u^{2H}] + \frac{1}{2} f''(B_u) |t-s|^{2H}. \end{aligned}$$

In a rather artificial way, we shall recast this identity into

$$f'(B_s) \diamond \mathbf{B}_{uv}^1 = \sum_{j=1}^3 \frac{1}{j!} f^{(j)}(B_u) (\mathbf{B}_{uv}^1)^j - R_{uv}^1 - R_{uv}^2, \quad (99)$$

with

$$R_{uv}^1 = \frac{1}{2} f''(B_u) \left[(\mathbf{B}_{uv}^1)^2 - |v-u|^{2H} \right], \quad \text{and} \quad R_{uv}^2 = \frac{1}{6} f^{(3)}(B_u) (\mathbf{B}_{uv}^1)^3.$$

Plugging (99) into the definition of $\tilde{S}^{n,\diamond}$, we thus obtain

$$\tilde{S}^{n,\diamond} = S^{\Pi_{st}^n} - \frac{1}{2} \sum_{k=0}^{2^n-1} f''(B_{t_k}) [t_{k+1}^{2H} - t_k^{2H}] + \frac{1}{2} V_n^{(2)}(f'') + \frac{1}{6} \tilde{V}_n^{(3)}(f^{(3)}). \quad (100)$$

Now, invoking Proposition 6.5, it is readily checked that both $V_n^{(2)}(f'')$ and $\tilde{V}_n^{(3)}(f^{(3)})$ converge to 0 in $L^2(\Omega)$ as $n \rightarrow \infty$. Hence

$$L^2(\Omega) - \lim_{n \rightarrow \infty} \tilde{S}^{n,\diamond} = \mathcal{J}_{st}(f'(B) dB) - H \int_s^t f''(B_u) u^{2H-1} du,$$

which ends the proof. □

The aim of the computations above was to prove that the results of [27] do not contradict ours for $H > 1/4$. Note however the following points:

(i) Having a look at Proposition 6.6, one might think that the first order Riemann-Wick sums $\tilde{S}^{m,\diamond}$ are always convergent in $L^2(\Omega)$. However, when $H < 1/4$, relation (97) still holds true. This means that the term $V_n^{(2)}(f'')$ appearing in equation (100) is now divergent, due to the fact that $2H - 1/2 < 0$. The same kind of arguments also yield the divergence of $\tilde{V}_n^{(3)}(f^{(3)})$ in (100). It is thus reasonable to think that first order Riemann-Wick sums will be divergent for $H < 1/4$, justifying our higher order expansions.

(ii) In light of Proposition 6.6, it is however possible that expansions of lower order than ours are sufficient to guarantee the convergence of sums like $S^{\Pi_{st},\diamond}$ in Theorem 6.4. We haven't followed this line of investigation for sake of conciseness, but let us stress the fact that almost sure convergences of our Wick-Riemann sums are obtained in Theorem 6.4 and Theorem 6.8 (for any sequence of partitions whose mesh tends to 0), while only $L^2(\Omega)$ convergences are considered in Proposition 6.6.

(iii) It is also worth reminding that we aim at considering a general d -dimensional Gaussian process, while [12, 27] focus on 1-dimensional situations. It is an open question for us to know if the methods of the aforementioned papers could be easily adapted to a multidimensional process.

6.4. Multidimensional case. We shall now give the representation theorem for Skorohod's integral in the multidimensional case. Technically speaking, this will be an elaboration of the one-dimensional case, relying on tensorization and cumbersome notations.

We first need an analogous of Proposition 6.2 in the multidimensional case, whose proof is also postponed to the Appendix. To this aim, let us introduce some additional notation: given $g_1, \dots, g_d \in \mathcal{H}$ define $\bar{g} = (g_1, \dots, g_d)$ and denote by $\mu_{\bar{g}}$ the law in \mathbb{R}^d of the random vector $(I_1(g_1), \dots, I_1(g_d))$.

Proposition 6.7. *Using the notations introduced above, let $g_1, \dots, g_d, h_1, \dots, h_d \in \mathcal{H}$. Consider the random variables $X_1 = I_1(g_1), \dots, X_d = I_1(g_d)$, and $Y_1 = I_1(h_1), \dots, Y_d = I_1(h_d)$. Suppose that Y_1, \dots, Y_d are independent and also that X_j and Y_k are independent for $k \neq j$. Let $p = (p_1, \dots, p_d)$ be a multiindex and set $|p| = \sum_{j=1}^d p_j$. Assume that $G \in \mathcal{C}^{|p|}(\mathbb{R}^d)$ is such that $\partial^\alpha G \in L^r(\mu_{\bar{g}})$ for any multiindex $\alpha = (\alpha_1, \dots, \alpha_d)$ and for some $r > 2$, with $\alpha_k \leq p_k$, $k = 1, \dots, d$. Then $G(X_1, \dots, X_d) \diamond Y_1^{\diamond p_1} \diamond \dots \diamond Y_d^{\diamond p_d}$ is well defined in $L^2(\Omega)$ and the following formula holds:*

$$\begin{aligned} G(X_1, \dots, X_d) \diamond Y_1^{\diamond p_1} \diamond \dots \diamond Y_d^{\diamond p_d} &= \sum_{l_1+2m_1 \leq p_1} \dots \sum_{l_d+2m_d \leq p_d} \partial^{l_1, \dots, l_d} G(X_1, \dots, X_d) \\ &\times \prod_{k=1}^d \left[\frac{(-1)^{(m_k+l_k)} p_k!}{2^{m_k} m_k! l_k! (p_k - 2m_k - l_k)!} (\mathbf{E}(X_k Y_k))^{l_k} (\mathbf{E}(Y_k^2))^{m_k} Y_k^{p_k - 2m_k - l_k} \right], \end{aligned} \quad (101)$$

where $\partial^{j_1, \dots, j_d}$ denotes $\frac{\partial^{j_1 + \dots + j_d}}{\partial x_1^{j_1} \dots \partial x_d^{j_d}}$.

As in the one-dimensional case, the proposition above is the key ingredient in order to establish the following representation formula for Skorohod's integral:

Theorem 6.8. *Let x be a d -dimensional centered Gaussian process with continuous covariance function fulfilling Hypotheses 5.1 and 5.2, and assume that x also satisfies Hypothesis 1.1. Let f be a function in $C^{2N}(\mathbb{R}^d)$ such that $\partial_\alpha f$ verifies the growth condition (GC) for any multiindex α such that $|\alpha| \leq 2N$. Then the Skorohod integral $\delta^\diamond(\nabla f(x))$ (whose existence is ensured by Theorem 5.13) can be represented as a.s. $-\lim_{\Pi_{st} \rightarrow 0} S^{\Pi_{st}, \diamond}$, where $S^{\Pi_{st}, \diamond}$ is defined by*

$$S^{\Pi_{st}, \diamond} = \sum_{i=0}^{n-1} \sum_{k=1}^N \frac{1}{k!} \partial_{i_k, \dots, i_1}^k f(x_{t_i}) \diamond \mathbf{x}_{t_i t_{i+1}}^1(i_1) \diamond \dots \diamond \mathbf{x}_{t_i t_{i+1}}^1(i_k).$$

Proof. We mimic here the proof of Theorem 6.4: decompose first $S^{\Pi_{st}, \diamond}$ into $\sum_{i=0}^{n-1} \sum_{u=0}^N \sum_{j_1 + \dots + j_d = u} \mathcal{S}_{j_1, \dots, j_d}^i$, where

$$\mathcal{S}_{j_1, \dots, j_d}^i = \frac{1}{j_1! \dots j_d!} \partial_{j_1, \dots, j_d}^u f(x_{t_i}(1), \dots, x_{t_i}(d)) \diamond (\mathbf{x}_{t_i t_{i+1}}^1(1))^{\diamond j_1} \diamond \dots \diamond (\mathbf{x}_{t_i t_{i+1}}^1(d))^{\diamond j_d}.$$

For a fixed $i \in \{0, \dots, n-1\}$ and $k \in \{0, \dots, d\}$, set now

$$X_k = x_{t_i}(k), \quad \text{and} \quad Y_k = \mathbf{x}_{t_i t_{i+1}}^1(k).$$

As in the one dimensional case, it is readily checked that if $\partial_\alpha f$ satisfies the growth condition (GC) for any $|\alpha| \leq 2N$, then the integrability conditions of Proposition 6.7 are also fulfilled for $x_{t_i} = (x_{t_i}(1), \dots, x_{t_i}(d)) = (I_1(\mathbf{1}_{[0, t_i]}^{[1]}), \dots, I_1(\mathbf{1}_{[0, t_i]}^{[d]}))$. This allows to write

$$\begin{aligned} \sum_{u=1}^N \sum_{j_1 + \dots + j_d = u} \mathcal{S}_{j_1, \dots, j_d}^i &= \sum_{u=1}^N \sum_{j_1 + \dots + j_d = u} \sum_{l_1 + 2m_1 \leq j_1} \dots \sum_{l_d + 2m_d \leq j_d} \partial_{l_1 + j_1, \dots, l_d + j_d} f(X_1, \dots, X_d) \\ &\times \left(\prod_{k=1}^d \frac{(-1)^{(m_k + l_k)}}{2^{m_k} m_k! l_k! (j_k - 2m_k - l_k)!} \mathbf{E}(X_k Y_k)^{l_k} (\mathbf{E}(Y_k^2))^{m_k} Y_k^{j_k - 2m_k - l_k} \right). \end{aligned}$$

Making substitution $l_k + j_k = q_k$ for $k = 1, 2, \dots, d$, or $j_k = q_k - l_k$, the condition $l_k + 2m_k \leq j_k$ can be written as $l_k + m_k = u_k$ with $0 \leq u_k \leq q_k/2$ and therefore the same kind of manipulations as in (93) yield

$$\begin{aligned} \sum_{u=1}^N \sum_{j_1 + \dots + j_d = u} \mathcal{S}_{j_1, \dots, j_d}^i &= \sum_{1 \leq q_1 + \dots + q_d \leq 2N} \partial_{q_1, \dots, q_d} f(X_1, \dots, X_d) \\ &\times \prod_{k=1}^d \left(\sum_{u_k=0}^{\lfloor q_k/2 \rfloor} \frac{(-1)^{u_k}}{u_k! (q_k - 2u_k)!} \left(\mathbf{E}(X_k Y_k) + \frac{\mathbf{E}(Y_k^2)}{2} \right)^{u_k} Y_k^{q_k - 2u_k} \right). \end{aligned}$$

Furthermore, like in the proof of Theorem 6.4, we have $\mathbf{E}(X_k Y_k) + \frac{\mathbf{E}(Y_k^2)}{2} = \delta R_{t_i t_{i+1}}/2$. Summing over $i \in \{1, \dots, n-1\}$ we thus end up with

$$\begin{aligned}
S^{\Pi_{st}, \diamond} &= \sum_{i=0}^{n-1} \sum_{1 \leq q_1 + \dots + q_d \leq N} \partial_{q_1, \dots, q_d} f(x_{t_i}(1), \dots, x_{t_i}(d)) \prod_{k=1}^d \frac{1}{(q_k)!} (\mathbf{x}_{t_i, t_{i+1}}^1(k))^{q_k} \\
&+ \sum_{i=0}^{n-1} \sum_{N+1 \leq q_1 + \dots + q_d \leq 2N} \partial_{q_1, \dots, q_d} f(x_{t_i}(1), \dots, x_{t_i}(d)) \prod_{k=1}^d \frac{1}{(q_k)!} (\mathbf{x}_{t_i, t_{i+1}}^1(k))^{q_k} \\
&- \frac{1}{2} \sum_{i=0}^{n-1} \sum_{k=1}^d \partial_{kk}^2 f(x_{t_i}(1), \dots, x_{t_i}(d)) (R_{t_{i+1}} - R_{t_i}) + \tilde{\Theta}_{st}^{\Pi} \\
&:= \Theta_1^{\Pi_{st}} + \Theta_2^{\Pi_{st}} + \sum_{k=1}^d \Theta_{3,k}^{\Pi_{st}} + \tilde{\Theta}^{\Pi_{st}}.
\end{aligned}$$

In the last sum, the variables Θ correspond to the 3 cases we have distinguished in the proof of Theorem 6.4: $\Theta_1^{\Pi_{st}}$ denotes the sums in which the u_k are equal to 0 and $1 \leq q_1 + \dots + q_d \leq N$; $\Theta_2^{\Pi_{st}}$ are the terms with $u_k = 0$ and $N+1 \leq q_1 + \dots + q_d \leq 2N$; $\Theta_{3,k}^{\Pi_{st}}$ corresponds to the terms with $q_k = 2$, $q_j = 0$ for all $j \neq k$ and $u_k = 1$ (so that $u_j = 0$ if $j \neq k$). Finally, $\tilde{\Theta}^{\Pi_{st}}$ denotes the sums with either $u_1 + \dots + u_d \geq 2$ or some $u_k = 1$ (and $u_j = 0$ for $j \neq k$) but $q_k \geq 3$. Referring again to the proof of Theorem 6.4, it is then easy to argue that $\tilde{\Theta}^{\Pi_{st}}$ and $\Theta_2^{\Pi_{st}}$ converge to 0, $\Theta_1^{\Pi_{st}}$ converges to $\int_s^t \langle \nabla f(x_\rho), dx_\rho \rangle_{\mathbb{R}^d}$, and $\sum_{k=1}^d \Theta_{3,k}^{\Pi_{st}}$ converges to $-\frac{1}{2} \int_s^t \Delta f(x_\rho) R'_\rho d\rho$. \square

7. APPENDIX

In this Appendix, we prove Propositions 6.2 and 6.7. For this, we will need the following analytical lemma.

Lemma 7.1. *Let μ be a finite measure on $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d))$ and let $G \in \mathcal{C}^p(\mathbb{R}^d)$ be such that $\partial^\alpha G \in L^r(\mu)$ for some $r \geq 1$ and any multiindex α such that $|\alpha| := \sum_{j=1}^d \alpha_j \leq p$. Then, there exists a sequence $(G_n)_{n \in \mathbb{N}}$ such that*

- (1) *Each G_n is a trigonometric polynomial of several variables, that is $G_n(x_1, \dots, x_d) = \sum_{\text{finite}} a_{l_1, \dots, l_d}^n e^{i \xi_{l_1}^n x_1 + \dots + i \xi_{l_d}^n x_d}$, and where a_{l_1, \dots, l_d}^n and $\xi_{l_j}^n$ are real numbers.*
- (2) *We have $\lim_{n \rightarrow \infty} \partial^\alpha G_n = \partial^\alpha G$ in $L^r(\mu)$ for any α such that $|\alpha| \leq p$.*

Proof. This lemma is folklore, but we haven't been able to find it in any standard text book. For this reason and for the sake of completeness, we give here the main ideas of its proof. First, given $G \in \mathcal{C}^p(\mathbb{R}^d)$, there exists a sequence of $\mathcal{C}^\infty(\mathbb{R}^d)$ functions with compact support that converge, jointly with their derivatives, to G in $L^r(\mu)$. So, one only needs to approximate a function $G \in \mathcal{C}^\infty(\mathbb{R}^d)$ with support contained in a rectangle of \mathbb{R}^d , say K . Moreover, given $\varepsilon > 0$, we can suppose that $\mu(K^c) < \varepsilon$. For a such function, consider its Fourier partial sums on the rectangle K that converge uniformly, jointly with their derivatives to G and its derivatives. Since these partial sums are periodic functions with the same period, their sup-norm on all \mathbb{R}^d is the same that the sup-norm on the compact K . With these ingredients, the result is easily obtained.

□

Proof of Proposition 6.2. We start with $G(x) = e^{i\xi x}$, for an arbitrary $\xi \in \mathbb{R}$, which means that we wish to evaluate the Wick product $e^{i\xi X} \diamond Y^{\circ p}$.

Recall that $X = I_1(g)$ and $Y = I_1(h)$. For $\xi, \eta \in \mathbb{R}$, consider the random variable

$$\begin{aligned} M(\xi, \eta) &= \exp\left(-\frac{\xi^2}{2}\mathbf{E}(X^2)\right) \mathcal{E}(i\xi g + i\eta h) = \exp\left(-\frac{\xi^2}{2}\mathbf{E}(X^2)\right) \mathcal{E}(i\xi g) \diamond \mathcal{E}(i\eta h) \\ &= \exp(i\xi X) \diamond \mathcal{E}(i\eta h) = \sum_{p=0}^{\infty} \frac{i^p \eta^p}{p!} \exp(i\xi X) \diamond Y^{\circ p}, \end{aligned}$$

where we have invoked relation (88) for the second equality and relation (87) for the last one. It is thus obvious that $e^{i\xi X} \diamond Y^{\circ p}$ can be expressed as

$$\frac{p!}{i^p} \times \text{the coefficient of } \eta^p \text{ in the expansion of } M(\xi, \eta).$$

We now proceed to this expansion: we have

$$\begin{aligned} M(\xi, \eta) &= \exp\left\{i\xi X + i\eta Y + \frac{\eta^2}{2}\mathbf{E}(Y^2) + \xi\eta\mathbf{E}(XY)\right\} \\ &= e^{i\xi X} \sum_{k=0}^{\infty} \frac{(i\eta Y)^k}{k!} \sum_{m=0}^{\infty} \frac{\eta^{2m}}{2^m m!} [\mathbf{E}(Y^2)]^m \sum_{l=0}^{\infty} \frac{\xi^l \eta^l}{l!} [\mathbf{E}(XY)]^l. \end{aligned}$$

Hence, by computing the coefficient of η^p in the above expression, it is easily checked that

$$\begin{aligned} e^{i\xi X} \diamond Y^{\circ p} &= e^{i\xi X} Y^p + e^{i\xi X} \sum_{0 < l+2m \leq p} \frac{i^{-2m-l} \xi^l p!}{2^m m! l! (p-2m-l)!} [\mathbf{E}(XY)]^l [\mathbf{E}(Y^2)]^m Y^{p-2m-l} \\ &= e^{i\xi X} Y^p + \sum_{0 < l+2m \leq p} \left(\frac{d^l}{dx^l} e^{i\xi X}\right) \frac{(-1)^{m+l} p!}{2^m m! l! (p-2m-l)!} [\mathbf{E}(XY)]^l [\mathbf{E}(Y^2)]^m Y^{p-2m-l}, \end{aligned}$$

which is the desired formula (91) for $G(x) = e^{i\xi x}$.

Let us now see how to extend this relation to a more general function G . By linearity, we first obtain the result for any trigonometric polynomial G . Now, let G be such that $G^{(j)} \in L^r(\mu_g)$ for any $j = 0, \dots, p$ and some $r > 2$. By Lemma 7.1, there exists a sequence $(G_n)_{n \in \mathbb{N}}$ of trigonometric polynomials such that

$$G_n^{(j)} \rightarrow G^{(j)} \quad \text{in } L^r(\mu_g) \quad \text{for any } j = 0, \dots, p.$$

This implies that $G(X) \in \text{Dom}(D^p)$ and that

$$D^j G(X) = G^{(j)}(X) g^{\otimes j} \quad \text{for any } j = 0, \dots, p.$$

Indeed, $G_n(X) \in \mathbf{S}$ and $D^j G_n(X) = G_n^{(j)}(X) g^{\otimes j}$ for any $j = 0, \dots, p$. Moreover, since

$$\mathbf{E}[|G_n^{(j)}(X) - G^{(j)}(X)|^r] = \|G_n^{(j)} - G^{(j)}\|_{L^r(\mu_g)}^r$$

we have that

$$D^j G_n(X) \rightarrow G^{(j)}(X) g^{\otimes j} \quad \text{in } L^r(\Omega; \mathcal{H}^{\otimes j}).$$

Using that the $D^{(j)}$ are closed operators we obtain that $G(X) \in \text{Dom}(D^p)$ and that $D^j G(X) = G^{(j)}(X)g^{\otimes j}$ for any $j = 0, \dots, p$. In particular, owing to Proposition 6.1 we have that

$$G(X) \diamond Y^{\circ p} = G(X) \diamond I_p(h^{\otimes p}) = \delta^{\circ p}(G(X)h^{\otimes p}). \quad (102)$$

Let us go back now to our approximating sequence $(G_n)_{n \in \mathbb{N}}$. It is readily checked that relation (102) also holds for any G_n . Thus, putting together the relation $G_n(X) \diamond I_p(h^{\otimes p}) = \delta^{\circ p}(G_n(X)h^{\otimes p})$ with equation (91) for a trigonometric polynomial, we get that

$$\begin{aligned} & \delta^{\circ p}(G_n(X)g^{\otimes p}) \\ &= G_n(X)Y^p + \sum_{0 < l+2m \leq p} \frac{(-1)^{m+l}p!}{2^m m! l! (p-2m-l)!} G_n^{(l)}(X) [\mathbf{E}(XY)]^l [\mathbf{E}(Y^2)]^m Y^{p-2m-l} \end{aligned} \quad (103)$$

Since $G_n^{(l)}(X) \rightarrow G^{(l)}(X)$ in $L^r(\Omega)$ with $r > 2$ and the Y^{k-2m-l} belong to all the $L^q(\Omega)$, the right-hand side of (103) converges in $L^2(\Omega)$, as $n \rightarrow \infty$, to

$$G(X)Y^p + \sum_{0 < l+2m \leq p} \frac{(-1)^{m+l}p!}{2^m m! l! (p-2m-l)!} G^{(l)}(X) [\mathbf{E}(XY)]^l [\mathbf{E}(Y^2)]^m Y^{p-2m-l}.$$

Finally we obtain the general case of equation (91) by taking limits in both sides of equation (103) and by resorting to the closeness of the operator $\delta^{\circ p}$. \square

As in the previous section, the extension of Proposition 6.2 to the multidimensional case is now an elaboration of the previous computations relying on some notational technicalities.

Proof of Proposition 6.7. As for Proposition 6.2, we first consider $G(x) = e^{\iota\langle \xi, x \rangle}$, where $x = (x_1, \dots, x_d)$ and $\xi = (\xi_1, \dots, \xi_d)$ are arbitrary vectors in \mathbb{R}^d . The extension of the formula to a G satisfying the general integrability conditions of our hypotheses is then obtained following the same approximation scheme as in the one-dimensional case, and is left to the reader for sake of conciseness.

In order to treat the case of $G(x) = e^{\iota\langle \xi, x \rangle}$, set

$$M(\xi, \eta) = \exp(\iota\langle \xi, X \rangle) \diamond \exp\left(\iota\langle \eta, Y \rangle + \frac{1}{2} \sum_{k=1}^d \eta_k Y_k^2\right).$$

Along the same lines as for Proposition 6.2, one can then identify $e^{\iota\langle \xi, X \rangle} \diamond Y_1^{\circ p_1} \diamond \dots \diamond Y_d^{\circ p_d}$ with $\frac{p_1! \dots p_d!}{i^{p_1 + \dots + p_d}} \times$ the coefficient of $\eta_1^{p_1} \dots \eta_d^{p_d}$ in the expansion of $M(\xi, \eta)$. Moreover, thanks to relation (88) and invoking the fact that X_j and Y_k are independent for $k \neq j$, we get that

$$M(\xi, \eta) = \exp\left(\iota \sum_{k=1}^d \xi_k X_k + \iota \sum_{k=1}^d \eta_k Y_k + \frac{1}{2} \sum_{k=1}^d \eta_k^2 \mathbf{E}(Y_k^2) + \sum_{k=1}^d \xi_k \eta_k \mathbf{E}(X_k Y_k)\right).$$

Expanding now the exponential according to formula (87), we end up with

$$M(\xi, \eta) = \sum_{p_1, \dots, p_d=0}^{\infty} \left[\sum_{l_1+2m_1 \leq p_1} \cdots \sum_{l_d+2m_d \leq p_d} \prod_{k=1}^d \left\{ (\imath \xi_k)^{l_k} e^{\imath \xi_k X_k} \frac{\imath^{(p_k-2m_k-2l_k)}}{2^{m_k} m_k! l_k! (p_k-2m_k-l_k)!} \right. \right. \\ \left. \left. \times (\mathbf{E}(X_k Y_k))^{l_k} (\mathbf{E}(Y_k^2))^{m_k} Y_k^{p_k-2m_k-l_k} \right\} \right] \eta_1^{p_1} \cdots \eta_d^{p_d}.$$

Taking into account the fact that $\prod_{k=1}^d (\imath \xi_k)^{l_k} e^{\imath \sum_{k=1}^d \xi_k X_k} = \partial^{l_1, \dots, l_d} e^{\imath \sum_{k=1}^d \xi_k X_k}$, our formula (101) is now easily deduced, which ends the proof. \square

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