

A mathematical approach to retinal waves

Bruno Cessac, Dora Karvouniari

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A mathematical approach to retinal waves

B. Cessac, D. Karvouniari Biovision team, INRIA, Sophia Antipolis





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Visual system and retinal waves





retinal ganglion cells

amacrine cells

bipolar cells

horizontal cells

photoreceptors

Visual system and retinal waves



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retinal ganglion cells

amacrine cells

bipolar cells

horizontal cells

photoreceptors

<u>Spontaneous</u> spatio-temporal "waves" during development

Disappear short after birth



Spatio-Temporal evolution of a retinal wave in mice during development, Maccione et al. 2014

Stages of Retinal Waves During Development



- Chemical synapses <u>not</u> formed yet
- Gap juctionmediated

Stages of Retinal Waves During Development

Stage II



- Chemical synapses <u>not</u> formed yet
- Gap juctionmediated

Stages of Retinal Waves During Development

Stage II



- Chemical synapses <u>not</u> formed yet
- Gap juctionmediated

Focus on stage II retinal waves

Stage II retinal waves are well studied experimentally and there is already existing work on their modelling



Starburst Amacrine

Goal of this lecture

Idea:

Identify generic mechanisms generating stage II retinal waves and analyze them mathematically.

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Motivation:

• Retinal waves instruct the shaping of the visual system

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Idea:

Identify generic mechanisms generating stage II retinal waves and analyze them mathematically.

Motivation:

- Retinal waves instruct the shaping of the visual system
- Understanding the mechanisms that generate them may help to control them
- New mathematical problems and new techniques.

Retinal waves require three components: i) Spontaneous bursting activity



Zheng et al., 2006, Nature

Retinal waves require three components:

- i) Spontaneous bursting activity
- ii) Refractory mechanism (slow After HyperPolarisation-sAHP)



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- ii) Refractory mechanism (slow After HyperPolarisation- sAHP)

iii) Coupling (through Acetylcholine neurotransmitter)



Experiment for coupled and isolated neurons, Zheng et al., 2006, Nature

Retinal waves require three components:

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From the non linear physics perspective a retinal wave is a spatiotemporal activity which:

 is generated by the conjunction of local (cell level) nonlinear characteristics and network effects

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From the non linear physics perspective a retinal wave is a spatiotemporal activity which:

- is generated by the conjunction of local (cell level) nonlinear characteristics and network effects
- can have different forms (fronts, spiral, standing waves, spatio-temporal chaos)
- is induced by generic mechanisms that can be studied in the context of dynamical systems theory
- can be associated with bifurcations

- Model biophysically the dynamics of isolated neurons (SACs)
 - Carefully model all currents involved
 - Fix parameters from experiments

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- Model biophysically the dynamics of isolated neurons (SACs)
 - Carefully model all currents involved
 - Fix parameters from experiments
- Bifurcation analysis of the non-linear dynamical system for isolated neurons
- Extract a generic biophysical mechanism of spontaneous bursting activity for SACs
- Model the network interactions:
 - Study the effects of synaptic coupling to synchrony and wave initiation
 - Search for biophysical parameters which control spatiotemporal patterns

Modelling the bursting of individual Starburst Amacrine Cells

Bruno Cessac and Dora Karvouniari

Biovision Team, INRIA Sophia Antipolis, France.

15-01-2017

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2 Model analysis



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From biophysics to modelling

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Biophysics of bursting SAC

Retinal waves require three components:

- Spontaneous bursting activity
- Refractory mechanism (slow After HyperPolarisation- sAHP)
- Coupling (through Acetylcholine neurotransmitter)

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Biophysics of bursting SAC



Figure: Zheng et al., Nature, 2006. Grey curve: Fast oscillations due to voltage-gated Ca^{+2} channels and Ca^{+2} dependent K^+ channels. Black curve: Application of Cd^+ blocking Ca^{+2} related channels.

Biophysics of bursting SAC

Morris-Lecar model with fast Potassium.

$$\begin{cases} C_m \frac{dV}{dt} = -g_L(V - V_L) - g_C M_\infty(V)(V - V_C) - g_K N(V - V_K) \\ + I_{ex}(\bullet) \end{cases}$$
$$\tau_N \frac{dN}{dt} = \Lambda(V)(N_\infty(V) - N) \tag{1}$$

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- Definition
 - Slow After Hyperpolarisation Current
 - <u>Calcium-dependent</u> slow potassium channels
- Mechanism
 - Model SK-like channels (Abel et al. 2004)
 - Gating Mechanism: Four ions Ca²⁺ bind to Calmodulin (CaM)



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- Four *Ca*²⁺ions bound to calmodulin bind to a terminal
- *I sAHP* current depends on gating variable R as follows:

$$I_{sAHP} = g_{sAHP}^m R^4 (V - V_K)$$
 (Hennig et al. 2009)

The conductance is proportional to the fourth power of R because four terminals are needed to open the channel.

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C : <u>Intracellular</u> Calcium concentration



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Model analysis

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Dynamics

$$C_{m} \frac{dV}{dt} = -g_{L}(V - V_{L}) - g_{C}M_{\infty}(V)(V - V_{C}) - g_{K}N(V - V_{K}) -g_{sAHP}R^{4}(V - V_{K})$$

$$\tau_{N} \frac{dN}{dt} = \Lambda(V)(N_{\infty}(V) - N) \tau_{C} \frac{dC}{dt} = -\frac{H_{X}}{\alpha_{C}}C + C_{0} - \delta_{C}g_{C}M_{\infty}(V)(V - V_{C}) \tau_{S} \frac{dS}{dt} = \alpha_{S}(1 - S)C^{4} - S \tau_{R} \frac{dR}{dt} = \alpha_{R}S(1 - R) - R$$
(2)

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Dynamics

$$C_{m} \frac{dV}{dt} = -g_{L}(V - V_{L}) - g_{C}M_{\infty}(V)(V - V_{C}) - g_{K}N(V - V_{K}) -g_{sAHP}R^{4}G_{sAHP}(R)(V - V_{K})$$

$$\tau_{N} \frac{dN}{dt} = \Lambda(V)(N_{\infty}(V) - N) \tau_{C} \frac{dC}{dt} = -\frac{H_{X}}{\alpha_{C}}C + C_{0} - \delta_{C}g_{C}M_{\infty}(V)(V - V_{C}) \tau_{S} \frac{dS}{dt} = \alpha_{S}(1 - S)C^{4} - S \tau_{R} \frac{dR}{dt} = \alpha_{R}S(1 - R) - R$$
(3)

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Dynamics

Leak time scale: $\tau_L = \frac{C}{g_L}$. Conductances rescaling: $\tilde{g}_X = \frac{g_X}{g_I}$.

$$\begin{aligned} \tau_L \frac{dV}{dt} &= -\tilde{g}_L (V - V_L) - \tilde{g}_C M_\infty (V) (V - V_C) - \tilde{g}_K N (V - V_K) \\ &- \tilde{G}_{sAHP} (R) (V - V_K) \end{aligned}$$
$$\begin{aligned} \tau_N \frac{dN}{dt} &= \Lambda (V) (N_\infty (V) - N) \\ \tau_C \frac{dC}{dt} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty (V) (V - V_C) \\ \tau_S \frac{dS}{dt} &= \alpha_S (1 - S) C^4 - S \\ \tau_R \frac{dR}{dt} &= \alpha_R S (1 - R) - R \end{aligned}$$

Multi-scale dynamics

Fast V, N.
$$\tau_L = 11$$
 ms, $\tau_N = 5$ ms.
Medium C. $\tau_C = 2$ s.
Slow S, R. $\tau_R = \tau_S = 44$ s.

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Fast-scale

$$t_f = \frac{t}{\tau_L} \Rightarrow dt = \tau_L dt_f$$

$$\frac{dV}{dt_f} = -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K)
- \tilde{G}_{sAHP}(R)(V - V_K)$$

$$\frac{\tau_N}{\tau_L} \frac{dN}{dt_f} = \Lambda(V)(N_\infty(V) - N)$$

$$\frac{\tau_C}{\tau_L} \frac{dC}{dt_f} = -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$

$$\frac{\tau_S}{\tau_L} \frac{dS}{dt_f} = \alpha_S(1 - S)C^4 - S$$

$$\frac{\tau_R}{\tau_L} \frac{dR}{dt_f} = \alpha_R S(1 - R) - R$$

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Fast-scale

Set
$$\epsilon_X = \frac{\tau_L}{\tau_X}$$
, $X = C, R, S$.
 $\epsilon_C = \frac{11}{2} \times 10^{-3} \sim 5.5 \times 10^{-3}$, $\epsilon_S = \epsilon_R = \frac{11}{44} \times 10^{-3} \sim 2.5 \times 10^{-4}$

$$\begin{cases}
\frac{dV}{dt_f} = -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\
-\tilde{G}_{sAHP}(R)(V - V_K)
\end{cases}$$

$$\frac{dN}{dt_f} = \frac{\tau_L}{\tau_N} \Lambda(V)(N_\infty(V) - N)$$

$$\frac{dC}{dt_f} = \epsilon_C \left[-\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty(V)(V - V_C) \right]$$

$$\frac{dS}{dt_f} = \epsilon_S \left[\alpha_S (1 - S) C^4 - S \right]$$

$$\frac{dR}{dt_f} = \epsilon_R \left[\alpha_R S(1 - R) - R \right]$$

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Fast-scale: approximation

$$\frac{dV}{dt_f} = -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) - \tilde{G}_{sAHP}(R)(V - V_K)$$
$$\frac{dN}{dt_f} = \frac{\tau_L}{\tau_N} \Lambda(V)(N_\infty(V) - N)$$
$$\frac{dC}{dt_f} = 0$$
$$\frac{dS}{dt_f} = 0$$
$$\frac{dR}{dt_f} = 0$$

C, R, S are constant at this time scale.

Morris-Lecar model analysis

$$\begin{cases} \frac{dV}{dt_f} = -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \\ \frac{dN}{dt_f} = \frac{\tau_L}{\tau_N} \Lambda(V)(N_\infty(V) - N) \end{cases}$$
(4)

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Morris-Lecar model analysis

$$\begin{cases} \frac{dV}{dt_f} = -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) + I_{ext} \\ \frac{dN}{dt_f} = \frac{\tau_L}{\tau_N} \Lambda(V)(N_\infty(V) - N) \end{cases}$$
(5)

Bifurcation analysis when varying the parameter I_{ext} .

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Morris-Lecar model analysis

Karvouniari et al, submitted to Plos Comp. Bio.



The saddle-node bifurcation



Figure: From https://elmer.unibas.ch/pendulum/bif.htm and https://it.wikipedia.org/wiki/Biforcazione_a_nodo_sella.

The Hopf bifurcation



Figure: From Navarro et al, "Control of the Hopf bifurcation in the Takens-Bogdanov bifurcation", CDC2008

The homoclinic bifurcation





Finite amplitude, small frequency, infinite period

Figure: From J.Tyson, http://slideplayer.com/slide/8870556/

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Karvouniari et al, ICMNS, 2016



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Back to Zhou experiment



Figure: Zheng et al., Nature, 2006. Grey curve: Fast oscillations due to voltage-gated Ca^{+2} channels and Ca^{+2} dependent K^+ channels. Black curve: Application of Cd^+ blocking Ca^{+2} related channels.

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Back to Zhou experiment

Karvouniari et al, submitted to Plos Comp. Bio.



Back to Zhou experiment

Karvouniari et al, submitted to Plos Comp. Bio.



Figure: Left. Green. Application of a current step pulse of 150 pA for 60ms. Orange: Oscillations disappear when Ca^{+2} related conductances are set to zero. Red. Blocking the oscillations upon setting the voltage-gated K+ conductance to zero. Right: Zheng et al. 2006 experimental figure. Grey curve: Fast oscillations due to voltage-gated Ca^{+2} channels and Ca^{+2} dependent K^+ channels. Black curve: Application of Cd^+ blocking Ca^{+2} related channels.

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Dynamics of bursting

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Dynamics of bursting

$$\begin{cases} \tau_L \frac{dV}{dt} &= -\tilde{g}_L (V - V_L) - \tilde{g}_C M_\infty (V) (V - V_C) - \tilde{g}_K N (V - V_K) \\ -\tilde{G}_{SAHP} (R) (V - V_K) \end{cases}$$
$$\tau_N \frac{dN}{dt} &= \Lambda (V) (N_\infty (V) - N)$$
$$\tau_C \frac{dC}{dt} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty (V) (V - V_C) \\ \tau_S \frac{dS}{dt} &= \alpha_S (1 - S) C^4 - S \\ \tau_R \frac{dR}{dt} &= \alpha_R S (1 - R) - R \end{cases}$$

Fast V, N. $\tau_L = 11 \text{ ms}, \tau_N = 5 \text{ ms}.$ Medium C. $\tau_C = 2 \text{ s}.$ Slow S, R. $\tau_R = \tau_S = 44 \text{ s}.$ Bruno Cessac and Dora Karvouniari Modelling the bursting of individual Starburst Amacrine Cells

Slow time-scale

$$t_s = \frac{t}{\tau_S} \Rightarrow dt = \tau_S dt_s$$

$$\begin{cases} \frac{\tau_L}{\tau_S} \frac{dV}{dt_s} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ -\tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$

$$\frac{\tau_N}{\tau_S} \frac{dN}{dt_s} &= \Lambda(V)(N_\infty(V) - N)$$

$$\frac{\tau_C}{\tau_S} \frac{dC}{dt_s} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$

$$\frac{dS}{dt_s} &= \alpha_S(1 - S)C^4 - S$$

$$\frac{dR}{dt_s} &= \alpha_R S(1 - R) - R$$

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Slow time-scale

$$\begin{split} \epsilon_V &= \frac{\tau_L}{\tau_S} \sim 2.5 \times 10^{-4}, \quad \epsilon_N = \frac{\tau_N}{\tau_S} \sim 1 \times 10^{-3} \\ \epsilon_C &= \frac{\tau_C}{\tau_S} \sim 4.5 \times 10^{-2} \end{split}$$

$$\begin{cases} \epsilon_V \frac{dV}{dt_s} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ &- \tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$
$$\epsilon_N \frac{dN}{dt_s} &= \Lambda(V)(N_\infty(V) - N)$$
$$\epsilon_C \frac{dC}{dt_s} &= -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$
$$\frac{dS}{dt_s} &= \alpha_S(1 - S)C^4 - S$$
$$\frac{dR}{dt_s} &= \alpha_R S(1 - R) - R \end{cases}$$

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Slow time-scale approximation

$$\begin{array}{rcl}
\left(\begin{array}{ccc}
0 &=& -\tilde{g}_L(V-V_L) - \tilde{g}_C M_{\infty}(V)(V-V_C) - \tilde{g}_K N(V-V_K) \\
& & -\tilde{G}_{sAHP}(R)(V-V_K)
\end{array} \\
0 &=& \Lambda(V)(N_{\infty}(V) - N) \\
0 &=& -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_{\infty}(V)(V-V_C) \\
& & \frac{dS}{dt_s} &=& \alpha_S(1-S)C^4 - S \\
& & \frac{dR}{dt_s} &=& \alpha_R S(1-R) - R
\end{array}$$

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Steady state

$$V = rac{V_{ML}(V) + ilde{G}_{sAHP}(R)V_K}{ ilde{g}_{ML}(V) + ilde{G}_{sAHP}(R)}$$

where:

$$V_{ML}(V) = V_L + \tilde{g}_C M_{\infty}(V) V_C + \tilde{g}_K N_{\infty}(V) V_K;$$

$$\tilde{g}_{ML}(V) = 1 + \tilde{g}_C M_{\infty}(V) + \tilde{g}_K N_{\infty}(V),$$

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Steady state

V follows "adiabatically" R.

$$V \equiv f(V,R) = \frac{V_{ML}(V) + \tilde{G}_{sAHP}(R)V_{K}}{\tilde{g}_{ML}(V) + \tilde{G}_{sAHP}(R)}$$
(6)

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Steady state

V follows "adiabatically" R.

$$V \equiv f(V,R) = \frac{V_{ML}(V) + \tilde{G}_{sAHP}(R)V_{K}}{\tilde{g}_{ML}(V) + \tilde{G}_{sAHP}(R)}$$
(6)

Implicit function theorem.

Wherever $\frac{\partial f}{\partial V} \neq 1$ V follows a unique and differentiable branch $V \equiv V(R)$. At points R where $\frac{\partial f}{\partial V} = 1$ this branch may disappear or several branch may appear simultaneously (bifurcation).

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Hint

$$V \equiv f(V, R) = \frac{V_{ML}(V) + \tilde{G}_{sAHP}(R)V_K}{\tilde{g}_{ML}(V) + \tilde{G}_{sAHP}(R)}$$
(7)

Taking the differential gives:

$$dV\left(1-\frac{\partial f}{\partial V}\right) = \frac{\partial f}{\partial R}dR$$

 \Rightarrow

$$\frac{dV}{dR} = \frac{\frac{\partial f}{\partial R}}{1 - \frac{\partial f}{\partial V}}$$

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Morris-Lecar model analysis

V follows adiabatically $\tilde{G}_{sAHP}(R)$.



Morris-Lecar model analysis



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Morris-Lecar model analysis



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Complete dynamics

Complete dynamics



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Medium and fast dynamics



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Medium and fast dynamics



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Medium-scale

$$t_m = \frac{t}{\tau_C} \Rightarrow dt = \tau_C dt_m$$

$$\begin{cases} \frac{\tau_L}{\tau_C} \frac{dV}{dt_m} &= -\tilde{g}_L (V - V_L) - \tilde{g}_C M_\infty(V) (V - V_C) - \tilde{g}_K N (V - V_K) \\ - \tilde{G}_{sAHP}(R) (V - V_K) \end{cases}$$

$$\frac{\tau_N}{\tau_C} \frac{dN}{dt_m} &= \Lambda(V) (N_\infty(V) - N)$$

$$\frac{dC}{dt_m} &= -\frac{H_X}{\alpha_C} C + C_0 - \delta_C g_C M_\infty(V) (V - V_C)$$

$$\frac{\tau_S}{\tau_C} \frac{dS}{dt_m} &= \alpha_S (1 - S) C^4 - S$$

$$\frac{\tau_R}{\tau_C} \frac{dR}{dt_m} &= \alpha_R S (1 - R) - R$$

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Medium-scale

$$\begin{array}{ll} \epsilon_V = \frac{\tau_L}{\tau_C} \sim 5 \times 10^{-3}, & \epsilon_N = \frac{\tau_N}{\tau_C} \sim 2.5 \times 10^{-3} \\ \epsilon_S = \epsilon_R = \frac{\tau_C}{\tau_S} \sim 4.5 \times 10^{-2} \end{array}$$

$$\begin{cases} \epsilon_V \frac{dV}{dt_m} &= -\tilde{g}_L(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) - \tilde{g}_K N(V - V_K) \\ &- \tilde{G}_{sAHP}(R)(V - V_K) \end{cases}$$
$$\epsilon_N \frac{dN}{dt_m} &= \Lambda(V)(N_\infty(V) - N) \\ \frac{dC}{dt} &= -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_\infty(V)(V - V_C) \\ \frac{dS}{dt_m} &= \epsilon_S \left[\alpha_S(1 - S)C^4 - S \right] \\ \frac{dR}{dt_m} &= \epsilon_R \left[\alpha_R S(1 - R) - R \right] \end{cases}$$

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Medium-scale approximation

$$\begin{array}{rcl} 0 & = & -\tilde{g}_L(V-V_L) - \tilde{g}_C M_\infty(V)(V-V_C) - \tilde{g}_K N(V-V_K) \\ & -\tilde{G}_{sAHP}(R)(V-V_K) \end{array}$$
$$\begin{array}{rcl} 0 & = & \Lambda(V)(N_\infty(V) - N) \\ \\ \frac{dC}{dt_m} & = & -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_\infty(V)(V-V_C) \end{array}$$
$$\begin{array}{rcl} \frac{dS}{dt} & = & 0 \\ \\ \frac{dR}{dt} & = & 0 \end{array}$$

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Medium-scale approximation

At this time scale:

- *R*, *S* are constant;
- V follows the variations of R;

•
$$\frac{dC}{dt_m} = -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_\infty(V)(V - V_C)$$

 \Rightarrow

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Medium-scale approximation

Rapid (medium time scale between upper/lower branch) "Outer dynamics".



Slow time-scale approximation

$$\begin{array}{rcl}
\left(\begin{array}{ccc}
0 &=& -\tilde{g}_L(V-V_L) - \tilde{g}_C M_{\infty}(V)(V-V_C) - \tilde{g}_K N(V-V_K) \\
& & -\tilde{G}_{sAHP}(R)(V-V_K)
\end{array} \\
0 &=& \Lambda(V)(N_{\infty}(V) - N) \\
0 &=& -\frac{H_X}{\alpha_C}C + C_0 - \delta_C g_C M_{\infty}(V)(V-V_C) \\
& & \frac{dS}{dt_s} &=& \alpha_S(1-S)C^4 - S \\
& & \frac{dR}{dt_s} &=& \alpha_R S(1-R) - R
\end{array}$$

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"Inner dynamics"

- V follows R;
- C follows V;
- Note $P(R) \equiv C^4$, the average value of C^4 for a given value of R.

 \Rightarrow

Dynamics on the slow branches.

$$\begin{cases} \frac{dR}{dt_s} = \alpha_R S(1-R) - R \\ \frac{dS}{dt_s} = \alpha_S (1-S) P(R) - S \end{cases}$$

"Inner dynamics"

Nullclines.

R Nullcline:
$$\frac{dR}{dt_s} = 0 \Rightarrow$$

The vector field is vertical on the line $S = \frac{R}{\alpha_R(1-R)}$

S Nullcline:
$$\frac{dS}{dt_s} = 0 \Rightarrow$$

The vector field is horizontal on the line $S = \frac{\alpha_S P(R)}{1 + \alpha_S P(R)}$

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Inner dynamics





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Bruno Cessac and Dora Karvouniari Modelling the bursting of individual Starburst Amacrine Cells

• We have now a model reproducing individual SACs bursting.

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- We have now a model reproducing individual SACs bursting.
- Here SACs burst periodically with a frequency determined by the parameters of the model (mainly τ_R).

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- We have now a model reproducing individual SACs bursting.
- Here SACs burst periodically with a frequency determined by the parameters of the model (mainly τ_R).
- A small change of parameters make them into a rest state where they burst only upon an external excitation (noise).

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- We have now a model reproducing individual SACs bursting.
- Here SACs burst periodically with a frequency determined by the parameters of the model (mainly τ_R).
- A small change of parameters make them into a rest state where they burst only upon an external excitation (noise).
- What happens when they cells are coupled with Acetylcholine ?

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Modelling stage II retinal waves

Bruno Cessac and Dora Karvouniari

Biovision Team, INRIA Sophia Antipolis, France.

15-01-2017

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- 2 Dynamical systems analysis
- 3 A simplified setting to mathematically study retinal waves

Generalisations

5 Conclusions

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Coupling SACs with Acetylcholine

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Figure: SACs network.

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- Molecular nicotinic receptors (nAchR)
- Two molecules of acetylcholine bind to open a nicotinic channel
- The nicotinic conductance depends on the second power of the acetylcholine neurotransmitter concentration A

$$g_{Ach} = g_{Ach}^m \frac{A^2}{K_d^2 + A^2}$$



Figure: Nicotinic receptors and conductance.



Intensity of Acetylcholine current for three Voltage clamp levels Experimental fits from Zhou et al. 2004, Neuron

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Figure: Ach production.



Figure: Equation of membrane potential.

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Dynamical systems analysis

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Main currents

$$G_{sAHP}(R_i) = g_{sAHP}R_i^4, \qquad (1)$$

sAHP conductance,

$$G_A(\{A_k\}_{k\in\mathcal{B}_i}) = g_A \sum_{k\in\mathcal{B}_i} U(A_k), \qquad (2)$$

Ach synaptic conductance with:

$$U(A) = \frac{A^2}{\gamma_A + A^2},\tag{3}$$

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 \mathcal{B}_i is the set of index of neurons connected to *i*.

Dynamics

$$C_{m} \frac{dV_{i}}{dt} = -g_{L}(V_{i} - V_{L}) - g_{C}M_{\infty}(V_{i})(V_{i} - V_{C}) - g_{K}N_{i}(V_{i} - V_{K}) - G_{sAHP}(R_{i})(V_{i} - V_{K}) - G_{A}(\{A_{k}\}_{k \in \mathcal{B}_{i}})(V_{i} - V_{A})$$

$$\tau_{N} \frac{dN_{i}}{dt} = \Lambda(V_{i})(N_{\infty}(V_{i}) - N_{i})$$

$$\tau_{C} \frac{dC_{i}}{dt} = -\frac{\alpha_{C}}{H_{X}}C_{i} + C_{0} - \delta_{C}g_{C}M_{\infty}(V_{i})(V_{i} - V_{C})$$

$$\tau_{S} \frac{dS_{i}}{dt} = \alpha_{S}(1 - S_{i})C_{i}^{4} - S_{i}$$

$$\tau_{R} \frac{dR_{i}}{dt} = \alpha_{R}S_{i}(1 - R_{i}) - R_{i}$$

$$\frac{dA_{i}}{dt} = -\mu A_{i} + \beta_{A}T_{A}(V_{i}),$$

Dynamics

Leak time scale:
$$\tau_L = \frac{C}{g_L}$$
. Ach time scale: $\tau_A = \frac{1}{\mu}$.
Conductances rescaling: $\tilde{g}_X = \frac{g_X}{g_L}$.

$$\begin{aligned} \tau_L \frac{dV_i}{dt} &= -(V_i - V_L) - \tilde{g}_C M_\infty(V_i)(V_i - V_C) - \tilde{g}_K N_i(V_i - V_K) \\ &- \tilde{G}_{sAHP}(R_i)(V_i - V_K) - \tilde{G}_A(\{A_k\}_{k \in \mathcal{B}_i})(V_i - V_A); \end{aligned}$$

$$\begin{aligned} \tau_N \frac{dN_i}{dt} &= \Lambda(V_i)(N_\infty(V_i) - N_i); \\ \tau_C \frac{dC_i}{dt} &= -\frac{\alpha_C}{H_X}C_i + C_0 - \delta_C g_C M_\infty(V_i)(V_i - V_C); \\ \tau_S \frac{dS_i}{dt} &= \alpha_S(1 - S_i)C_i^4 - S_i; \\ \tau_R \frac{dR_i}{dt} &= -A_i + \frac{\beta_A}{\mu}T_A(V_i); \end{aligned}$$

Multi-scale dynamics

Fast V, N. $\tau_L = 11$ ms, $\tau_N = 5$ ms. Medium C, A. $\tau_C = 2$ s, $\tau_A = 1.86$ s. Slow S, R. $\tau_R = \tau_S = 44$ s.

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Inspired from Lansdell et al, Plos. Comp. Bio, 2014

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Main hypotheses:

1) We neglect the fast Potassium current. V_i has only two stable states: low and high. In the high state SAC does not burst.

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Main hypotheses:

- 2) To switch from low to high state, neuron *i* needs an external excitatory current. This can be:
 - The Ach current coming from neighbours;
 - A "shot noise" current of the form:

$$g_N B_i (V_i - V_C)$$

where $B \in \{0, 1\}$ is a Bernoulli variable with probability *Prob* [$B_i(s) = 1, s \in [t, t + dt$] = pdt, with $p \sim \frac{1}{\tau_R}$.

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Main hypotheses:

3) sAHP has a simplified form (does not depend on Calcium). We only keep the variables S, R where S depends directly on V:

$$\tau_S \frac{dS_i}{dt} = -S_i + \gamma G(V_i)$$

with:

$$G(V_i)=rac{1}{1+e^{-\kappa(V-V_0)}}.$$

Main hypotheses:

4) Acetylcholine synapses are assumed not to be yet functional (Ford-Feller, 2011). The main source of Ach coupling is Ach *diffusion*.

$$\tau_A \frac{dA_i}{dt} = -A_i + \frac{\beta_A}{\mu} T_A(V_i) + D\Delta A_i;$$

where Δ is the Laplacian on a square lattice. Boundary conditions are ignored.

The Ach current depends only on the local Ach: $I_A = -g_A U(A)(V - V_A)$.

Main hypotheses:

- Two state voltage.
- O Shot noise.
- **3** Simplified form for sAHP.
- Ach diffusion.

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Dynamics

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From now we consider that variables depend continuously on space $\Rightarrow \frac{d}{dt} \rightarrow \frac{\partial}{\partial t}$

$$\begin{cases} \tau_L \frac{\partial V}{\partial t} &= -(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) + \tilde{g}_N B(V - V_C) \\ &- \tilde{G}_{sAHP}(R)(V - V_K) - \tilde{g}_A U(A)(V - V_A); \end{cases} \\ \\ \tau_S \frac{\partial S}{\partial t} &= -S + \gamma G(V); \\ \\ \tau_R \frac{\partial R}{\partial t} &= \alpha_R S(1 - R) - R; \\ \\ \tau_A \frac{\partial A}{\partial t} &= -A + \frac{\beta_A}{\mu} T_A(V) + D\Delta A(V); \end{cases}$$

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Medium-scale

$$t_m = rac{t}{ au_A} \Rightarrow dt = au_A dt_m$$

 $\epsilon_V = rac{ au_L}{ au_A} \sim 5 imes 10^{-3}; \quad \epsilon_S = \epsilon_R = rac{ au_A}{ au_S} \sim 4.5 imes 10^{-2}$

$$\begin{aligned} \mathcal{E} & \epsilon_{V} \frac{\partial V}{\partial t_{m}} &= -(V - V_{L}) - \tilde{g}_{C} M_{\infty}(V)(V - V_{C}) - g_{N} B(V - V_{C}) \\ & - \tilde{G}_{sAHP}(R)(V - V_{K}) - \tilde{g}_{A} U(A)(V - V_{A}); \end{aligned}$$

$$\begin{aligned} \frac{\partial S}{\partial t_{m}} &= \epsilon_{S} \left[-S + \gamma G(V) \right]; \\ \frac{\partial R}{\partial t_{m}} &= \epsilon_{R} \left[\alpha_{R} S(1 - R) - R \right]; \\ \frac{\partial A}{\partial t_{m}} &= -A + \frac{\beta_{A}}{\mu} T_{A}(V) + D\Delta A; \end{aligned}$$

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Medium-scale approximation

$$\begin{pmatrix}
0 &= -(V - V_L) - \tilde{g}_C M_\infty(V)(V - V_C) + g_N B(V - V_C) \\
- \tilde{G}_{sAHP}(R)(V - V_K) - \tilde{g}_A U(A)(V - V_A);
\\
\frac{\partial S}{\partial t_m} &= 0;
\\
\frac{\partial R}{\partial t_m} &= 0;
\\
\frac{\partial A}{\partial t_m} &= -A + \frac{\beta_A}{\mu} T_A(V) + D\Delta A;
\end{cases}$$

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Medium-scale approximation

At this time scale:

- R, S are constant;
- V follows the variations of R, A;

$$V = \frac{V_L + \tilde{g}_C M_{\infty}(V) V_C + \tilde{g}_N B V_C + \tilde{G}_{sAHP}(R) V_K + \tilde{g}_A U(A) V_A}{1 + \tilde{g}_C M_{\infty}(V) + \tilde{g}_N B + \tilde{G}_{sAHP}(R) + \tilde{g}_A U(A)}$$

From the implicit functions theorem: V = f(R, A, B).

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We consider here a propagation in 1 dimension.

$$rac{\partial A}{\partial t_m} = -A + rac{eta_A}{\mu} T_A(V) + D\Delta A \Rightarrow$$

 $rac{\partial A}{\partial t_m} = -A + rac{eta_A}{\mu} T_A(V) + D rac{\partial^2 A}{\partial x^2}$

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Spatially homogeneous state

Low voltage state. If all neurons are in the low voltage state, V_{-} , $\Delta A = 0 \Rightarrow A$ reaches a stationary homogeneous state on the medium time scale.

$$A_{-}=\frac{\beta_{A}}{\mu}T_{A}(f(R,A_{-},0)),$$

where 0 means that B = 0 everywhere (no shot noise current).

In this state, the S production $G(V_{-}) \sim 0$ so there is no sAHP on the slow time scale.

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Spatially homogeneous state

High voltage state. If all neurons are in the high voltage state, V_+ , $\Delta A = 0 \Rightarrow A$ reaches a stationary homogeneous state on the medium time scale.

$$A_+ = \frac{\beta_A}{\mu} T_A(f(R, A_+, B)).$$

Here, the state can be reached either due to shot noise or to Ach current.

In this state, the S production $G(V_+) >> 0$ so there is an sAHP on the slow time scale.

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Local perturbation of the low state. At some point x_0 we induce a shot noise current at time 0 ($B(x_0, 0) = 1$).

- This raises the voltage to its upper value V_+ .
- This increases the Ach production at x_0 .
- Ach diffuses to neighbours and induces an excitatory current.
- If g_A conductance is large enough this current raises the neighbours voltage to V₊.
- This can lead to a propagating wave.

Under which conditions?

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Moving frame:

 $\xi = x - ct_m$ where c is a constant $\Rightarrow d\xi = dx - cdt_m$.

For a function $A(x, t_m) \equiv A(\xi)$ we have:

$$dA = \frac{\partial A}{\partial \xi} d\xi = \frac{\partial A}{\partial \xi} (dx - cdt_m) \Rightarrow$$
$$\frac{\partial A}{\partial x} = \frac{\partial A}{\partial \xi}; \quad ; \frac{\partial^2 A}{\partial x^2} = \frac{\partial^2 A}{\partial \xi^2}; \quad \frac{\partial A}{\partial t_m} = -c\frac{\partial A}{\partial \xi}$$
$$-c\frac{\partial A}{\partial \xi} = -A + \frac{\beta_A}{\mu}T_A(f(R, A, B)) + D\frac{\partial^2 A}{\partial \xi^2}$$

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Potential well:
$$\frac{\partial \mathcal{V}}{\partial A} = A - \frac{\beta_A}{\mu} T_A(f(R, A, B))$$

 $\mathcal{V}(A) = \frac{A^2}{2} - \frac{\beta_A}{\mu} \int T_A(f(R, a, B)) da + K$
Rest states: $\frac{\partial \mathcal{V}}{\partial A} = 0$

Rest states: $\frac{\partial V}{\partial A} = 0$.

Newton equation

$$D\frac{\partial^2 A}{\partial \xi^2} = -c\frac{\partial A}{\partial \xi} - \frac{\partial \mathcal{V}}{\partial A}$$

We note $\frac{\partial A}{\partial \xi} \equiv \dot{A}; \frac{\partial A^2}{\partial \xi^2} \equiv \ddot{A}$

$$D\ddot{A} = -c\dot{A} - \frac{\partial \mathcal{V}}{\partial A}.$$

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$$D\ddot{A} = -c\dot{A} - \frac{\partial \mathcal{V}}{\partial A}.$$

Formally, this is the equation of motion of a particle, with mass D, in a potential well \mathcal{V} , with a friction coefficient c.

 \mathcal{V} has 3 extrema, given by $\frac{\partial \mathcal{V}}{\partial A} = A - \frac{\beta_A}{\mu} T_A(f(R, A, B)) = 0 \Rightarrow$:

$$A = \frac{\beta_A}{\mu} T_A(f(R, A, B))$$

These are the fixed points of the medium scale local dynamics ($\Delta A = 0$). Maxima of \mathcal{V} correspond to stable fixed points.
Heteroclinic connection

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Effect of sAHP



Figure: Bifurcation diagram in the space I - V

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Effect of sAHP



Figure: Trajectory in the space I - V.

Effect of sAHP



Figure: Pulse propagation.

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Effect of sAHP

Time and space scales

- Ach raising and propagation, controlled by g_{Ach} and D (Diffusion);
- sAHP controlled by g_{sAHP} (Local);
- Time of excitation controlled by characteristic times and conductances;
- Time of propagation controlled by *c* depending on the other parameters.
- \Rightarrow Characteristic wave length depending on parameters.

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Generalisations

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Main hypotheses:

- Two state voltage.
- O Shot noise.
- **3** Simplified form for sAHP.
- Ach diffusion.

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Main hypotheses:

- **1** Two state voltage. \Rightarrow Fast bursting in the high voltage state.
- O Shot noise.
- **3** Simplified form for sAHP.
- Ach diffusion.

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Main hypotheses:

- **1** Two state voltage. \Rightarrow Fast bursting in the high voltage state.
- **2** Shot noise. \Rightarrow Spontaneous bursting.
- **3** Simplified form for sAHP.
- Ach diffusion.

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Main hypotheses:

- **1** Two state voltage. \Rightarrow Fast bursting in the high voltage state.
- **2** Shot noise. \Rightarrow Spontaneous bursting.
- Simplified form for sAHP. Role of Ca?
- Ach diffusion.

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Main hypotheses:

- **1** Two state voltage. \Rightarrow Fast bursting in the high voltage state.
- **2** Shot noise. \Rightarrow Spontaneous bursting.
- Simplified form for sAHP.Role of Ca?
- Ach diffusion. \Rightarrow Ach nicotinic coupling.

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Ach nicotinic coupling

$$C_m \frac{dV_i}{dt} = -g_L(V_i - V_L) - g_C M_\infty(V_i)(V_i - V_C) - g_K N_i(V_i - V_K)$$

$$-G_{sAHP}(R_i)(V_i-V_{\mathcal{K}}) - g_{\mathcal{A}}(V_i-V_{\mathcal{A}})\sum_{k\in\mathcal{B}_i}U(A_k)$$

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Karvouniari et al, ICMNS 2016



Figure: Synchronisation of two bursting cells.

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Karvouniari et al, ICMNS 2016

- There is a competition between 2 mechanisms:
 - Interburst variability which tends to desynchronise
 - Acetylcholine which tends to synchronise

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Karvouniari et al, ICMNS 2016

- There is a competition between 2 mechanisms:
 - Interburst variability which tends to desynchronise
 - Acetylcholine which tends to synchronise
- There is an intermediate regime of coupling, where variability is maximum

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- Therefore there is a wide repertoire of patterns

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- There is a competition between 2 mechanisms:
 - Interburst variability which tends to desynchronise
 - Acetylcholine which tends to synchronise
- There is an intermediate regime of coupling, where variability is maximum
- Therefore there is a wide repertoire of patterns
 - Weak coupling leads to small localised activity
 - Moderate coupling leads to propagating patterns
 - Strong coupling leads to complete synchrony of neurons

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Spatio temporal patterns

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Isolated Neurons



gach=0.126 nS

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Spatio temporal patterns

Karvouniari et al, ICMNS 2016





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Modelling stage II retinal waves

Figure:

Nearest neighbours interactions

- Neurons are located on a lattice with step a.
- A depends smoothly on coordinates.

$$\sum_{k\in\mathcal{B}_i}U(A_k)\sim 4U(A(x_i,y_i))+a^2\Delta U(A)$$

Non linear diffusion !

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Conclusions

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Conclusions

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More ??

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 \Rightarrow invite Dora as a speaker to the next LACONEU conference

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